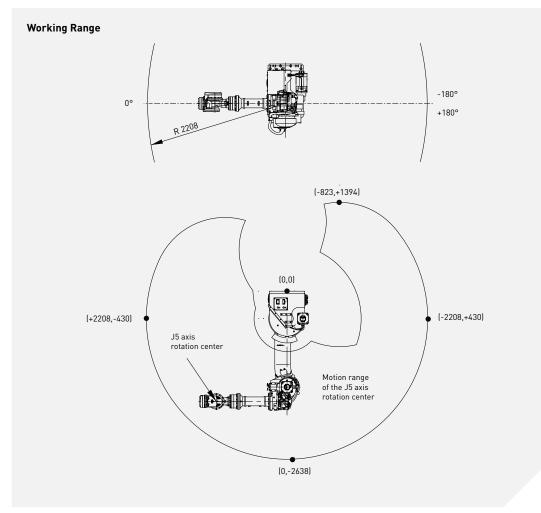
R-2000*i*B/200T (Top mount)



Max. load capacity at wrist: **200 kg**



			Motion range (°)						Maximum speed (°/s)								
Controlled axes	Repeatability (mm)	Mechanical weight (kg)	J1	J2	J3	J4	J5	J6	J1	J2	J3	J4	J5	J6	J4 Moment/ Inertia (Nm/kgm²)	J5 Moment/ Inertia (Nm/kgm²)	J6 Moment/ Inertia (Nm/kgm²)
6	± 0.3	1100	*1)	245	406	720	250	720	*1)	70	90	110	110	155	1274/117.6	1274/117.6	686/58.8



□ Robot □	R-2000 <i>i</i> B/2001
Robot footprint [mm]	845 x 553
Mounting position Floor	-
Mounting position Upside down	•
Mounting position Angle	•
Controller	30 <i>i</i> B
Open air cabinet	-
Mate cabinet	-
A-cabinet	•
B-cabinet	0
iPendant Touch	•
Electrical connections	
Voltage 50/60Hz 3phase [V]	380-575
Voltage 50/60Hz 1phase [V]	-
Average power consumption [kW]	3
Integrated services	
Integrated signals on upper arm In/Out	8/8
Integrated air supply	2
Environment	
Acoustic noise level [dB]	78.1
Ambient temperature [° C]	0-45
Protection	
Body standard/optional	IP54/IP56
Wrist & J3 arm standard/optional	IP67

^{*1)} depending on rail specification

[•] standard o on request - not available () with hardware and/or software option