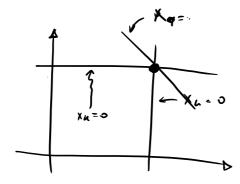
loops with constant objective function With the simplex method, were more from a base B to B', decreasing the objective purchau All bosis B have different cost and are different # of perible bones $\approx (m)$ - loope but fink number For some iterations, the change in the doj function can be o It could happour that we revisit the some bon's (the objective function,, storying the same) Creating a loop (infinite) Con hoppen!!! (very often) $|\Delta z| = |\overline{c}_{k}| \sqrt{2}$ $|\Delta z| = |\overline{c}_{k}| \sqrt{2}$

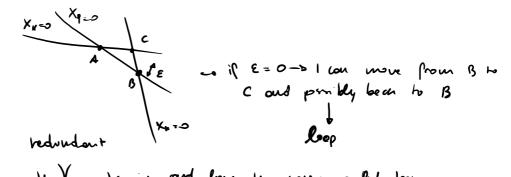
if bi=0, the cost won't change

Depenvery



linding of vertex between $X_h = 0$ and $X_u = 0 \Longrightarrow$ could be that $X_q = 0$ too in that point

I can move the line of Xo we can we better what happens:

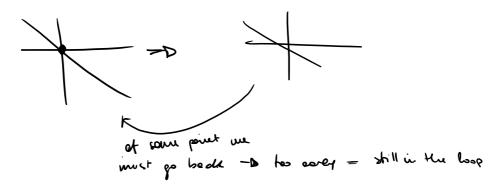


I could remove the V constraint and have the same polyhedron

We con't remove constraints that have Xa = 0 = 15 We may change the polyhedron in more dimmons.

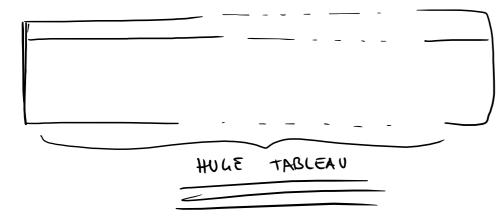
how to died with deputinecy:

- 1) Rondon privot _ P(loop)~0
- 2) Have roudomly the costraints when we filled a dependency



3) Bland's rule -> Guarantees no loop

Revised simplex method



Probable contrainers: Xi+X; ≤1 → Lots of Os

I don't keep the matrix in manary but a sporse version of the toblice

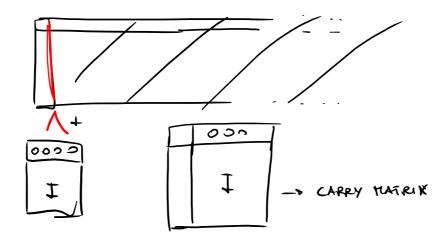
portion and whe of the non-zero elevens

Unally we store columns : the cost and elements to

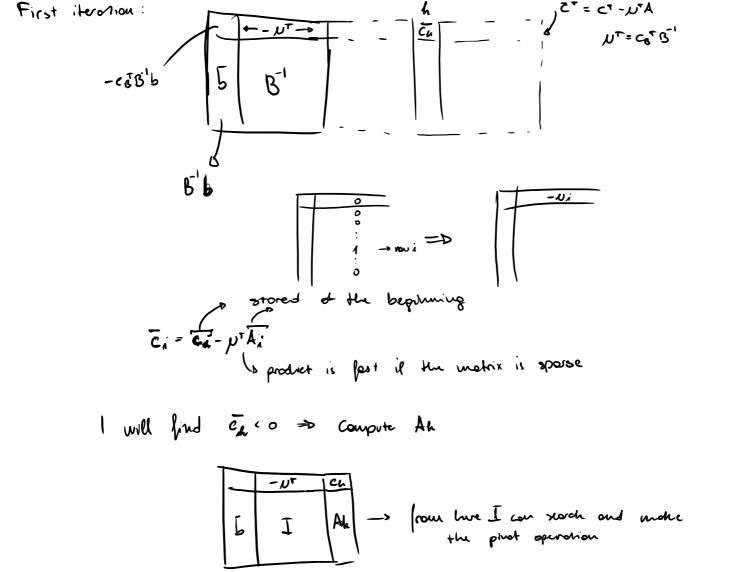
$$A_{j} = \begin{bmatrix} C_{j} \\ \vdots \\ \vdots \\ k \\ + \end{bmatrix} \longrightarrow \begin{bmatrix} C_{j} \\ (k:1) \\ + \vdots \\ (+:5) \end{bmatrix} \longrightarrow (position k) = 1$$

After lots of iterations -> lots of non-wo.. >> con't keep the sporse format

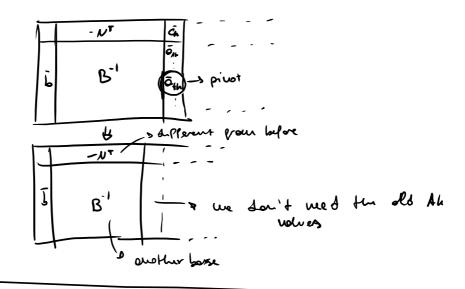
I get the tobleau and store only he left part



the vest of the tobleau can be computed from the carry matrix



I will need to apalote j'est the mxm motion'x



Tipically: # pinot aprohion needed ~ 3n

(# iterations)

Host of the variables will probably reason mon-ben's