

1.

$$G_1(s) = \frac{s-1}{s+2}$$

$$s+2=0 \Rightarrow \text{Pole at } s = -2$$

\Rightarrow the system is BIBO stable

$$G_2(s) = \frac{1}{s^2 + 2s}$$

$$s^2 + 2s = 0$$

$$s(s+2) = 0 \Rightarrow \text{Poles at } s=0 \text{ and } s=-2$$

\Rightarrow the system is not BIBO stable.

$$G_3(s) = \frac{1}{s^2 + 3s + 2}$$

$$s^2 + 3s + 2 = 0$$

$$(s+1)(s+2) = 0 \Rightarrow \text{Poles at } s=-1 \text{ and } s=-2$$

\Rightarrow the system is BIBO stable.

$$G_4(s) = \frac{1}{s}$$

$s=0 \Rightarrow$ Pole at $s=0$

\Rightarrow the system is not BIBD stable.

$$G_5(s) = \frac{s+2}{s^2 - 1}$$

$$s^2 - 1 = 0$$

$(s-1)(s+1)=0 \Rightarrow$ Poles at $s=1$ and $s=-1$

\Rightarrow the system is not BIBD stable.

$$G_6(s) = \frac{s}{(s^2+1)(s^2+4)}$$

$(s^2+1)(s^2+4)=0 \Rightarrow$ Poles at $s=\pm j$ and $s=\pm 2j$

\Rightarrow the system is not BIBD stable.

$$G_7(s) = \frac{s+3}{s^2+2s+17}$$

$$s^2 + 2s + 17 = 0$$

$$\Re = 1 - 17 = -16$$

\Rightarrow Poles at $s = -1 \pm 4j$

\Rightarrow the system is BIBD stable

$$G_8(s) = \frac{7}{s^3 + 5s^2 + 4s}$$

$$s^3 + 5s^2 + 4s = 0$$

$$s(s^2 + 5s + 4) = 0$$

$s(s+1)(s+4) = 0 \Rightarrow$ Poles at $s=0$, $s=-1$ and $s=-4$

\Rightarrow the system is not BIBO stable.

2.

$$G_1(s) = \frac{s-1}{s+2}$$

$$u(t) = 2 \text{ step}(t)$$

$$\lim_{t \rightarrow \infty} u(t) = 2$$

$$y_{ss}(t) = \lim_{t \rightarrow +\infty} y(t) = G_1(0) \cdot 2 = \frac{0-1}{0+2} \cdot 2 = -1$$

$$\Rightarrow y_{ss}(t) = -1 \quad \text{when } u(t) = 2 \text{ step}(t)$$

$$u(t) = 3 \sin(t)$$

$$G_1(j\omega) = \frac{j\omega - 1}{j\omega + 2}$$

For $\omega = 1 \text{ rad/s}$

$$G_1(j) = \frac{-1+j}{2+j}$$

$$|G_1(j)| = \frac{\sqrt{2}}{\sqrt{5}} = \sqrt{\frac{2}{5}}$$

$$\angle G_1(j) = \arctan(-1) + 180^\circ - \arctan\left(\frac{1}{2}\right) = 108.4^\circ$$

$$\Rightarrow y_{ss}(t) = 3 \cdot \sqrt{\frac{2}{5}} \sin(t + 108.4^\circ) \quad \text{when } u(t) = 3 \sin(t)$$

$$G_3(s) = \frac{1}{s^2 + 3s + 2}$$

$$y_{ss}(t) = G_3(0) \cdot 2 = \frac{1}{0^2 + 3 \cdot 0 + 2} \cdot 2 = 1$$

$$\Rightarrow y_{ss}(t) = 1 \quad \text{when } u(t) = 2 \text{ step}(t)$$

$$G_3(j\omega) = \frac{1}{(j\omega)^2 + 3j\omega + 2} = \frac{1}{-\omega^2 + 3j\omega + 2}$$

$$\text{For } \omega = 1 \text{ rad/s: } G_3(j) = \frac{1}{-1 + 3j + 2} = \frac{1}{1 + 3j}$$

$$|G_3(j)| = \frac{1}{\sqrt{10}}$$

$$\angle G_3(j) = 0 - \arctan(3) = -71.6^\circ$$

$$\Rightarrow y_{ss}(t) = \frac{3}{\sqrt{10}} \sin(t - 71.6^\circ) \quad \text{when } u(t) = 3 \sin(t)$$

$$G_7(s) = \frac{s+3}{s^2 + 2s + 17}$$

$$y_{ss}(t) = G_7(0) \cdot 2 = \frac{0+3}{0^2 + 2 \cdot 0 + 17} \cdot 2 = \frac{6}{17}$$

$$\Rightarrow y_{ss}(t) = \frac{6}{17} \quad \text{when } u(t) = 2 \text{step}(t)$$

$$G_7(j\omega) = \frac{j\omega + 3}{(j\omega)^2 + 2j\omega + 17} = \frac{j\omega + 3}{-\omega^2 + 2j\omega + 17}$$

$$\text{For } \omega = 1 \text{ rad/s} : G_7(j) = \frac{3+j}{-1+2j+17} = \frac{3+j}{16+2j}$$

$$|G_7(j)| = \frac{\sqrt{10}}{\sqrt{260}} = \frac{1}{\sqrt{26}}$$

$$\angle G_7(j) = \arctan\left(\frac{1}{3}\right) - \arctan\left(\frac{2}{16}\right) = 11.3^\circ$$

$$\Rightarrow y_{ss}(t) = \frac{3}{\sqrt{26}} \sin(t + 11.3^\circ) \quad \text{when } u(t) = 3 \sin(t)$$

$$3. \quad G_2(s) = \frac{1}{s^2 + 2s}$$

Step input of any amplitude makes the output unbounded, for example, $u(t) = \text{step}(t)$

$$(U(s) = \frac{1}{s})$$

$$G_4(s) = \frac{1}{s}$$

Step input of any amplitude makes the output unbounded, for example, $u(t) = \text{step}(t)$

$$(U(s) = \frac{1}{s})$$

$$G_5(s) = \frac{s+2}{s^2 - 1}$$

Any input signal whose Laplace transform has no zeros at $s=1$ makes the output unbounded, for example, $u(t) = e^{-t}$ ($U(s) = \frac{1}{s+1}$)

$$G_6(s) = \frac{s}{(s^2 + 1)(s^2 + 4)}$$

Sinusoidal input with frequency $\omega = 1 \text{ rad/s}$ or $\omega = 2 \text{ rad/s}$ and any amplitude makes the output unbounded, for example, $u(t) = \sin(2t)$

$$(U(s) = \frac{2}{s^2 + 4})$$

$$G_8(s) = \frac{7}{s^3 + 5s^2 + 4s}$$

Step input of any amplitude makes the output unbounded, for example, $u(t) = \text{step}(t)$

$$(U(s)) = \frac{1}{s})$$

4.

$$G_1(s) = \frac{200}{s^4 + 6s^3 + 11s^2 + 6s + 200}$$

$$\begin{array}{c|ccc} s^4 & 1 & 11 & 200 \\ s^3 & 61 & 61 & 0 \\ s^2 & 10 & 200 \\ s^1 & -19 & -1 \\ s^0 & 20 \end{array}$$

$$\beta_1 = -\frac{\begin{vmatrix} 1 & 11 \\ 1 & 1 \end{vmatrix}}{1} = 10$$

$$\beta_2 = -\frac{\begin{vmatrix} 1 & 200 \\ 1 & 0 \end{vmatrix}}{1} = 200$$

$$c_1 = - \frac{\begin{vmatrix} 1 & 1 \\ 1 & 20 \end{vmatrix}}{1} = -19$$

$$d_1 = - \frac{\begin{vmatrix} 1 & 20 \\ -1 & 0 \end{vmatrix}}{-1} = 20$$

The order of the characteristic polynomial is 4,
and there are 2 sign changes

$\Rightarrow g_1(s)$ has 2 poles in the RHP and 2 poles in the LHP

\Rightarrow the system is not BIBO stable.

$$g_2(s) = \frac{10}{s^5 + 2s^4 + 3s^3 + 6s^2 + 5s + 3}$$

s^5	1	3	5
s^4	2	6	3
s^3	$\cancel{0\epsilon}$	$\frac{7}{2}$	
s^2	$\frac{6\epsilon-7}{\epsilon}$	3	
s^1	1		
s^0	3		

$$b_1 = - \frac{\begin{vmatrix} 1 & 3 \\ 2 & 6 \end{vmatrix}}{2} = 0$$

$$b_2 = - \frac{\begin{vmatrix} 1 & 5 \\ 2 & 3 \end{vmatrix}}{2} = \frac{7}{2}$$

$$c_1 = - \frac{\begin{vmatrix} 2 & 6 \\ \varepsilon & 7/2 \end{vmatrix}}{\varepsilon} = \frac{6\varepsilon - 7}{\varepsilon} \quad (\text{negative})$$

$$c_2 = - \frac{\begin{vmatrix} 2 & 3 \\ \varepsilon & 0 \end{vmatrix}}{\varepsilon} = \frac{3\varepsilon}{\varepsilon} = 3$$

$$d_1 = - \frac{\begin{vmatrix} \varepsilon & 7/2 \\ \frac{6\varepsilon - 7}{\varepsilon} & 3 \end{vmatrix}}{\frac{6\varepsilon - 7}{\varepsilon}} = - \frac{3\varepsilon^2 - 21\varepsilon + 24.5}{6\varepsilon - 7} \quad (\text{positive})$$

$$e_1 = - \frac{\begin{vmatrix} \frac{6\varepsilon - 7}{\varepsilon} & 3 \\ 1 & 0 \end{vmatrix}}{1} = 3$$

The order of the characteristic polynomial is 5, and there are 2 sign changes.

$\Rightarrow g_2(s)$ has 2 poles in the RHP and 3 poles in the LHP

\Rightarrow the system is not BIBO stable.

$$g_3(s) = \frac{1}{2s^5 + 3s^4 + 2s^3 + 3s^2 + 2s + 1}$$

s^5	λ^1	λ^1	λ^1
s^4	3	3	1
s^3	$\partial \epsilon$	$\frac{2}{3}$	
s^2	$\frac{3\epsilon - 2}{\epsilon}$	1	
s^1	1		
s^0	1		

$$b_1 = - \frac{\begin{vmatrix} 1 & 1 \\ 3 & 3 \end{vmatrix}}{3} = 0$$

$$b_2 = - \frac{\begin{vmatrix} 1 & 1 \\ 3 & 1 \end{vmatrix}}{3} = \frac{2}{3}$$

$$c_1 = - \frac{\begin{vmatrix} 3 & 3 \\ \epsilon & 2/3 \end{vmatrix}}{\epsilon} = \frac{3\epsilon - 2}{\epsilon} \quad (\text{negative})$$

$$c_2 = - \frac{\begin{vmatrix} 3 & 1 \\ \epsilon & 0 \end{vmatrix}}{\epsilon} = \frac{\epsilon}{\epsilon} = 1$$

$$d_1 = - \frac{\begin{vmatrix} \epsilon & \frac{2}{3} \\ \frac{3\epsilon - 2}{\epsilon} & 1 \end{vmatrix}}{\frac{3\epsilon - 2}{\epsilon}} = - \frac{\epsilon^2 - 2\epsilon + \frac{4}{3}}{3\epsilon - 2} \quad (\text{positive})$$

$$e_1 = - \frac{\begin{vmatrix} \frac{3\epsilon - 2}{\epsilon} & 1 \\ 1 & 0 \end{vmatrix}}{1} = 1$$

The order of the characteristic polynomial is 5, and there are 2 sign changes

$\Rightarrow g_3(s)$ has 2 poles in the RHP and 3 poles in the LHP

\Rightarrow the system is not BIBD stable

$$g_4(s) = \frac{10}{s^5 + 7s^4 + 6s^3 + 42s^2 + 8s + 56}$$

s^5	1	6	8
s^4	7	1	42^6
s^3	0	41	$0 1/2 3$
s^2	3	8	
s^1	$1/2$	1	
s^0	8		

$$\beta_1 = - \frac{\begin{vmatrix} 1 & 6 \\ 1 & 6 \end{vmatrix}}{1} = 0 \quad \beta_2 = - \frac{\begin{vmatrix} 1 & 8 \\ 1 & 8 \end{vmatrix}}{1} = 0$$

$$p(s) = s^4 + 6s^2 + 8$$

$$\frac{d p(s)}{ds} = 4s^3 + 12s$$

$$c_1 = - \frac{\begin{vmatrix} 1 & 6 \\ 1 & 3 \end{vmatrix}}{1} = -3$$

$$c_2 = - \frac{\begin{vmatrix} 1 & 8 \\ 1 & 0 \end{vmatrix}}{1} = -8$$

$$d_1 = - \frac{\begin{vmatrix} 1 & 3 \\ 3 & 8 \end{vmatrix}}{3} = \frac{1}{3}$$

$$e_1 = - \frac{\begin{vmatrix} 3 & 8 \\ 1 & 0 \end{vmatrix}}{1} = -8$$

$$p(s) = s^4 + 6s^2 + 8 = 0$$

$$(s^2 + 4)(s^2 + 2) = 0$$

$$s = \pm 2j \quad s = \pm \sqrt{2} j$$

The order of the characteristic polynomial is 5, and there are no sign changes

$\Rightarrow G_4(s)$ has 4 poles on the imaginary axis and 1 pole in the LHP

\Rightarrow the system is not BIBO stable.

$$G_5(s) = \frac{128}{s^8 + 3s^7 + 10s^6 + 24s^5 + 48s^4 + 96s^3 + 128s^2 + 192s + 128}$$

s^8	1	10	48	128	128
s^7	31	248	9/632	19/264	0
s^6	21	168	64/32	12/864	
s^5	0/63	0/3/216	0/6/32		
s^4	8/31	64/38	64/24		
s^3	-8-1	-40-5			
s^2	31	248			
s^1	31				
s^0	8				

$$b_1 = - \frac{\begin{vmatrix} 1 & 10 \\ 1 & 8 \end{vmatrix}}{1} = 2$$

$$b_2 = - \frac{\begin{vmatrix} 1 & 48 \\ 1 & 32 \end{vmatrix}}{1} = 16$$

$$b_3 = - \frac{\begin{vmatrix} 1 & 128 \\ 1 & 64 \end{vmatrix}}{1} = 64$$

$$b_4 = - \frac{\begin{vmatrix} 1 & 128 \\ 1 & 0 \end{vmatrix}}{1} = 128$$

$$c_1 = c_2 = c_3 = 0$$

$$P(s) = s^6 + 8s^4 + 32s^2 + 64$$

$$\frac{dP(s)}{ds} = 6s^5 + 32s^3 + 64s$$

$$d_1 = - \frac{\begin{vmatrix} 1 & 8 \\ 3 & 16 \end{vmatrix}}{3} = \frac{8}{3}$$

$$d_2 = - \frac{\begin{vmatrix} 1 & 32 \\ 3 & 32 \end{vmatrix}}{3} = \frac{64}{3}$$

$$d_3 = - \frac{\begin{vmatrix} 1 & 64 \\ 3 & 0 \end{vmatrix}}{3} = \frac{192}{3} = 64$$

$$e_1 = - \frac{\begin{vmatrix} 3 & 16 \\ 1 & 8 \end{vmatrix}}{1} = -8$$

$$e_2 = - \frac{\begin{vmatrix} 3 & 32 \\ 1 & 24 \end{vmatrix}}{1} = -40$$

$$f_1 = - \frac{\begin{vmatrix} 1 & 8 \\ -1 & -5 \end{vmatrix}}{-1} = 3$$

$$f_2 = - \frac{\begin{vmatrix} 1 & 24 \\ -1 & 0 \end{vmatrix}}{-1} = 24$$

$$g_1 = - \frac{\begin{vmatrix} -1 & -5 \\ 1 & 8 \end{vmatrix}}{1} = 3$$

$$h_1 = - \frac{\begin{vmatrix} 1 & 8 \\ 1 & 0 \end{vmatrix}}{1} = 8$$

The order of the characteristic polynomial is 8

Before $P(s)$: no sign changes

Then: 2 sign changes

$\Rightarrow P(s)$ has 2 roots in the RHP, 2 roots in the LHP,
and 2 roots on the imaginary axis

$\Rightarrow G_5(s)$ has 2 poles in the RHP, 4 poles in the LHP,
and 2 poles on the imaginary axis

\Rightarrow the system is not BIBD stable.

5.

$$G_1(s) = \frac{1}{s^4 + 2s^3 + (4+k)s^2 + 9s + 25}$$

s^4	1	$4+K$	25
s^3	2	9	0
s^2	$K - \frac{1}{2}$	25	
s^1	$\frac{g K - 54.5}{K - 0.5}$		
s^0	25		

$$b_1 = - \frac{\begin{vmatrix} 1 & 4+K \\ 2 & g \end{vmatrix}}{2} = \frac{2K - 1}{2} = K - \frac{1}{2}$$

$$b_2 = - \frac{\begin{vmatrix} 1 & 25 \\ 2 & 0 \end{vmatrix}}{2} = 25$$

$$c_1 = - \frac{\begin{vmatrix} 2 & g \\ K - \frac{1}{2} & 25 \end{vmatrix}}{K - \frac{1}{2}} = \frac{gK - 54.5}{K - 0.5}$$

$$d_1 = - \frac{\begin{vmatrix} K - \frac{1}{2} & 25 \\ \frac{9K-54.5}{K-0.5} & 0 \end{vmatrix}}{K-0.5} = 25$$

For the system to be BIBO stable:

$$K - \frac{1}{2} > 0 \quad \text{and} \quad \frac{9K-54.5}{K-0.5} > 0$$

$$K > \frac{1}{2} \quad K > \frac{109}{18}, \quad K \neq \frac{1}{2}$$

$$\Rightarrow \text{For BIBO stability : } K > \frac{109}{18}$$

$$G_2(s) = \frac{K}{s^3 + 18s^2 + 77s + K}$$

s^3	1	77	
s^2	18	K	
s^1	$\frac{1386 - K}{18}$		
s^0	K		

$$\beta_1 = - \frac{\begin{vmatrix} 1 & 77 \\ 18 & K \end{vmatrix}}{18} = \frac{1386 - K}{18}$$

$$C_1 = - \frac{\begin{vmatrix} 18 & K \\ \frac{1386 - K}{18} & 0 \end{vmatrix}}{\frac{1386 - K}{18}} = K$$

For the system to be BIBD stable:

$$\frac{1386 - K}{18} > 0 \quad K > 0$$

$$K < 1386$$

\Rightarrow For BIBD stability: $0 < K < 1386$