

Zayaan Bhanwadia & Daniel Reyes

Vending Machine

June 16th, 2024

Mrs. Helen Strelkovska

TEJ3M-1

**Project Description:**

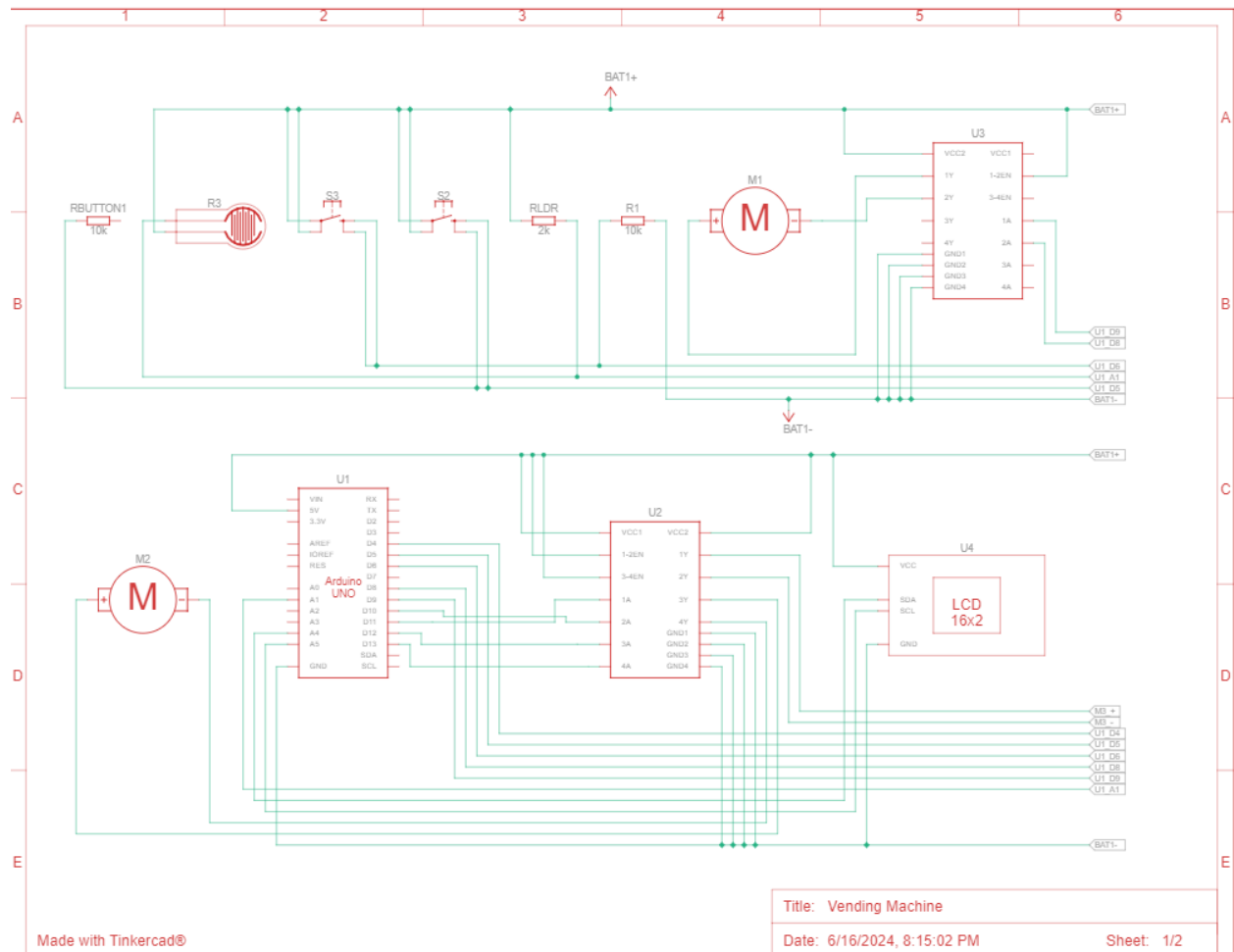
A vending machine distributes 3 types of candies, which the user can select once they insert a 25-cent coin verified by a force sensor. Users can choose candies using a movable arrow shown on a 16x2 LCD display controlled by buttons. Once a candy is selected and in stock (error message on LCD if not in stock), the candy will drop down with the help of a motor onto a ramp which will make it accessible to the user to enjoy.

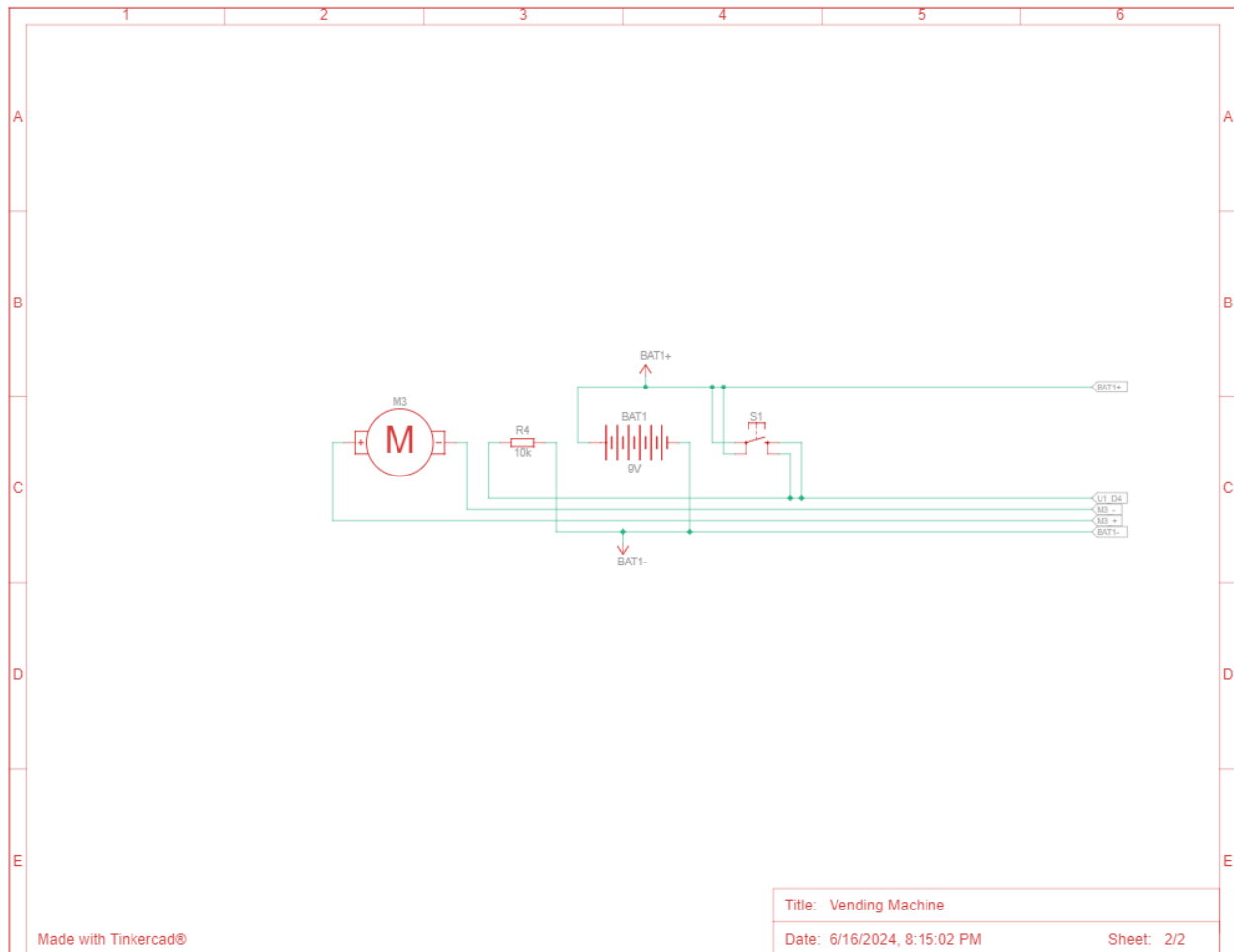
**Materials:**

- Arduino
- USB B to A wire
- 9V battery
- 9V battery clip connector
- Three buttons
- Three Vex motors
- Three vex motor shaft
- Two L293D motor drivers
- 16x2 LCD
- Force sensor
- Three breadboards
- Three 10kΩ resistors
- One 2kΩ resistor
- Wires
- Screws
- Steel Vex plate
- Shoebox
- Cardboard
- Skewers
- Electrical tape
- Hot glue

- Hot glue gun

## Circuit Diagram:





### Code:

/\*

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\* Vending Machine

\*/

#include <Wire.h>

#include <LiquidCrystal\_I2C.h>

LiquidCrystal\_I2C lcd(0x27,16,2);

// Coin checking variables

```
int coinLight = 0;
int coinPin = A1;
boolean coinCheck = false;

// Button checking variables
int button1 = 4;
int button2 = 5;
int button3 = 6;
int read1 = 0;
int read2 = 0;
int read3 = 0;

// Motor pins
int motor1 = 9;
int motor2 = 10;
int motor3 = 12;

// Motor reverse
int motorR1 = 8;
int motorR2 = 11;
int motorR3 = 13;

// snack counters
int snackLeft = 1;
int snackCentre = 1;
int snackRight = 1;
boolean snackDropped = false;

// LCD text variables
String coin1 = "Insert quarter";
String coin2 = "  $0.25";

String bye1 = "Enjoy your snack";
String bye2 = "Come back later!";

String lowStock1 = "Out of Stock";
```

```
String lowStock2 = "Please try again";
```

```
String loading = " Please wait...";
```

```
// Custom arrow code
```

```
int arrowPos = 0;
```

```
boolean select = false;
```

```
byte topL[] = {
```

```
    B00001,
```

```
    B00001,
```

```
    B00011,
```

```
    B00011,
```

```
    B00111,
```

```
    B00111,
```

```
    B01111,
```

```
    B11111
```

```
};
```

```
byte topR[] = {
```

```
    B10000,
```

```
    B10000,
```

```
    B11000,
```

```
    B11000,
```

```
    B11100,
```

```
    B11100,
```

```
    B11110,
```

```
    B11111
```

```
};
```

```
byte bottomL[] = {
```

```
    B00011,
```

```
    B00011,
```

```
    B00011,
```

```
    B00011,
```

```
    B00011,
```

```
B00011,  
B00011,  
B00011  
};
```

```
byte bottomR[] = {  
  B11000,  
  B11000,  
  B11000,  
  B11000,  
  B11000,  
  B11000,  
  B11000,  
  B11000  
};
```

```
void setup(){  
  Serial.begin(9600);  
  lcd.init(); //initialize the lcd  
  lcd.backlight(); //open the backlight  
  lcd.clear();  
  
  // input pins  
  pinMode(button1, INPUT);  
  pinMode(button2, INPUT);  
  pinMode(button3, INPUT);  
  
  // motor pins  
  pinMode(motor1, OUTPUT);  
  pinMode(motor2, OUTPUT);  
  pinMode(motor3, OUTPUT);  
  
  // motor reverse pins  
  pinMode(motorR1, OUTPUT);  
  pinMode(motorR2, OUTPUT);
```

```

pinMode(motorR3, OUTPUT);

// arrow character
lcd.createChar(0, topL);
lcd.createChar(1, topR);
lcd.createChar(2, bottomL);
lcd.createChar(3, bottomR);
}

void loop(){

if (!coinCheck){
  // print line 1
  lcd.setCursor(0,0);
  lcd.print(coin1);

  // print line 2
  lcd.setCursor(0,1);
  lcd.print(coin2);

  // read ldr for coin
  coinLight = analogRead(coinPin);

  //coin detected
  if (coinLight > 100){
    coinCheck = true;
    lcd.clear();
  }
}

// user selection
else {

  // get user button input value

```

```
read1 = digitalRead(button1);
read2 = digitalRead(button2);
read3 = digitalRead(button3);

// button checking
if (read1 == 1 && arrowPos != -1){
    arrowPos--;
    lcd.clear();
    delay(200);
}
if (read3 == 1 && arrowPos != 1){
    arrowPos++;
    lcd.clear();
    delay(200);
}
if (read2 == 1){
    select = true;
    lcd.clear();
    delay(200);
}

//arrow middle
if (arrowPos == 0){

    lcd.setCursor(7,0);
    lcd.write(0);
    //lcd.home();

    lcd.setCursor(8,0);
    lcd.write(1);
    //lcd.home();

    lcd.setCursor(7,1);
    lcd.write(2);
    //lcd.home();
```



```
    lcd.setCursor(8,1);  
    lcd.write(3);  
  
}  
  
// arrow left  
else if (arrowPos == -1){  
  
    lcd.setCursor(1,0);  
    lcd.write(0);  
  
    lcd.setCursor(2,0);  
    lcd.write(1);  
  
    lcd.setCursor(1,1);  
    lcd.write(2);  
  
    lcd.setCursor(2,1);  
    lcd.write(3);  
}  
  
// arrow right  
else if (arrowPos == 1){  
  
    lcd.setCursor(13,0);  
    lcd.write(0);  
  
    lcd.setCursor(14,0);  
    lcd.write(1);  
  
    lcd.setCursor(13,1);  
    lcd.write(2);  
  
    lcd.setCursor(14,1);  
    lcd.write(3);  
}
```

```

// drop candy and display ending message
if (select == true){
    lcd.clear();
    lcd.setCursor(0,1);
    lcd.print(loading);

    // run right motor
    if (arrowPos == 1){

        // ensuring snack is stocked
        if (snackRight > 0) {
            digitalWrite(motor3, HIGH);
            delay(1000);
            digitalWrite(motor3, LOW);
            delay(2000);
            digitalWrite(motorR3, HIGH);
            delay(1000);
            digitalWrite(motorR3 , LOW);

            snackDropped = true;
            snackRight--;
        }
        else {
            // print low stock line 1
            lcd.clear();
            lcd.setCursor(0,0);
            lcd.print(lowStock1);

            // print low stock line 2
            lcd.setCursor(0,1);
            lcd.print(lowStock2);
            delay(3000);
        }
    }
}

```

```

// run centre motor
if (arrowPos == 0) {

    if (snackCentre > 0) {
        digitalWrite(motor2, HIGH);
        delay(700);
        digitalWrite(motor2, LOW);
        delay(2000);
        digitalWrite(motorR2, HIGH);
        delay(3000);
        digitalWrite(motorR2, LOW);

        snackDropped = true;
        snackCentre--;
    }
    else {
        // print low stock line 1
        lcd.clear();
        lcd.setCursor(0,0);
        lcd.print(lowStock1);

        // print low stock line 2
        lcd.setCursor(0,1);
        lcd.print(lowStock2);
        delay(3000);
    }
}

// run left motor
if (arrowPos == -1) {

    if (snackLeft > 0) {
        digitalWrite(motor1, HIGH);
        delay(500);
        digitalWrite(motor1, LOW);
    }
}

```

```

    delay(1000);
    digitalWrite(motorR1, HIGH);
    delay(1000);
    digitalWrite(motorR1, LOW);

    snackDropped = true;
    snackLeft--;
}
else {
    // print low stock line 1
    lcd.clear();
    lcd.setCursor(0,0);
    lcd.print(lowStock1);

    // print low stock line 2
    lcd.setCursor(0,1);
    lcd.print(lowStock2);
    delay(3000);
}
}

// only reset if snack was dropped
if (snackDropped == true) {
    lcd.clear();
    // print exit line 1
    lcd.setCursor(0,0);
    lcd.print(bye1);

    // print exit line 2
    lcd.setCursor(0,1);
    lcd.print(bye2);
    coinCheck = false;
}

// reset variables to reset vending machine
select = false;

```

```
arrowPos = 0;  
snackDropped = false;
```

```
// wait before resetting  
delay(5000);  
lcd.clear();
```

```
}
```

```
}
```

```
}
```