

Homework #1.2

1)

$$a) \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

Yes, it is in reduced echelon form.

b)

★

$$\begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

This is in reduced echelon form.

c)

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

It is in neither reduced nor standard echelon form.

d)

$$\begin{bmatrix} 1 & 1 & 0 & 1 & 1 \\ 0 & 2 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 0 & 4 \end{bmatrix}$$

Standard echelon form

3)

$$\begin{bmatrix} 1 & 2 & 3 & 4 \\ 4 & 5 & 6 & 7 \\ 6 & 7 & 8 & 9 \end{bmatrix}$$

⇓

$$\begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & -3 & -6 & -9 \\ 0 & -5 & -10 & -15 \end{bmatrix}$$

⇓

$$\begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & -1 & -2 & -3 \\ 0 & -1 & -2 & -3 \end{bmatrix}$$

⇓

$$\begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & -1 & -2 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_3' = R_3 - 6R_1 \\ R_2' = R_2 - 4R_1$$

$$R_3' = \frac{1}{5}R_3 \\ R_2' = \frac{1}{3}R_2$$

$$R_3' = R_3 - R_2$$

$$R_2' = -1 \cdot R_2$$

$$R_1' = R_1 - 2R_2$$

$$\begin{bmatrix} 1 & 0 & -1 & -2 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Pivot Columns: 1 & 2

Pivot Positions Original

$$\begin{bmatrix} \textcircled{1} & 2 & 3 & 4 \\ 4 & \textcircled{5} & 6 & 7 \\ 6 & 7 & 8 & 9 \end{bmatrix}$$

Pivot Positions RREF:

$$\begin{bmatrix} \textcircled{1} & 0 & -1 & -2 \\ 0 & \textcircled{1} & 2 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

5)

Case #1

$$\begin{bmatrix} \boxed{} & * \\ 0 & \boxed{} \end{bmatrix}$$

Case #2

$$\begin{bmatrix} \boxed{} & * \\ 0 & 0 \end{bmatrix}$$

Describe the echelon forms for a 2x2 matrix.

* - Can be zero or number

Case #3 ★

$$\begin{bmatrix} 0 & \boxed{} \\ 0 & 0 \end{bmatrix}$$

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$$7) \begin{bmatrix} 1 & 3 & 4 & 7 \\ 3 & 9 & 7 & 6 \end{bmatrix}$$

$$R_2' = R_2 - 3R_1$$

\Downarrow

$$\begin{bmatrix} 1 & 3 & 4 & 7 \\ 0 & 0 & -5 & -15 \end{bmatrix}$$

$$\Downarrow R_2' = -\frac{1}{5} \cdot R_2$$

$$\begin{bmatrix} 1 & 3 & 4 & 7 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

$$\Downarrow R_1' = R_1' - 4R_2$$

$$\begin{bmatrix} 1 & 3 & 0 & -5 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

$$x_3 = 3$$

$$x_1 = -5 - 3x_2$$

x_2 is free

$$9) \begin{bmatrix} 0 & 1 & -6 & 5 \\ 1 & -2 & 7 & -6 \end{bmatrix}$$

$R_1 \leftrightarrow R_2$ (interchange)

\Downarrow

$$\begin{bmatrix} 1 & -2 & 7 & -6 \\ 0 & 1 & -6 & 5 \end{bmatrix}$$

$$R_1' = R_1 + 2R_2$$

\Downarrow

$$\begin{bmatrix} 1 & 0 & -5 & 4 \\ 0 & 1 & -6 & 5 \end{bmatrix}$$

$$x_1 = 4 + 5x_3$$

$$x_2 = 5 + 6x_3$$

x_3 is free

$$11) \begin{bmatrix} 3 & -4 & 2 & 0 \\ -9 & 12 & -6 & 0 \\ -6 & 8 & -4 & 0 \end{bmatrix}$$

$$R_2' = R_2 + 3R_1$$

\Downarrow

$$\begin{bmatrix} 3 & -4 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ -6 & 8 & -4 & 0 \end{bmatrix}$$

$$R_3' = R_3 + 2R_1$$

\Downarrow

$$\begin{bmatrix} 3 & -4 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_1' = \frac{1}{3} R_1$$

\Downarrow

$$\begin{bmatrix} 1 & -\frac{4}{3} & \frac{2}{3} & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$x_1 = \frac{4}{3}x_2 - \frac{2}{3}x_3$$

x_2 is free

x_3 is free

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13)

$$\begin{bmatrix} 1 & -3 & 0 & -1 & 0 & -2 \\ 0 & 1 & 0 & 0 & -4 & 1 \\ 0 & 0 & 0 & 1 & 9 & 4 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_1' = R_1 + 3R_2$$

↓

$$\begin{bmatrix} 1 & 0 & 0 & -1 & -12 & 1 \\ 0 & 1 & 0 & 0 & -4 & 1 \\ 0 & 0 & 0 & 1 & 9 & 4 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_1' = R_1 + R_3$$

↓

$$\begin{bmatrix} 1 & 0 & 0 & 0 & -3 & 5 \\ 0 & 1 & 0 & 0 & -4 & 1 \\ 0 & 0 & 0 & 1 & 9 & 4 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$x_1 = 5 + 3x_5$$

$$x_2 = 1 + 4x_5$$

x_3 is free

$$x_4 = 4 - 9x_5$$

x_5 is free

15) ★

a)

$$\begin{bmatrix} \boxed{1} & * & * & * \\ 0 & \boxed{1} & * & * \\ 0 & 0 & \boxed{1} & 0 \end{bmatrix}$$

Consistent and unique since each variable has a pivot

b)

$$\begin{bmatrix} 0 & \boxed{1} & * & * & * \\ 0 & 0 & \boxed{1} & * & * \\ 0 & 0 & 0 & 0 & \boxed{1} \end{bmatrix}$$

Inconsistent since last row has a contradiction as $0 \neq \boxed{1}$

17)

$$\begin{bmatrix} 2 & 3 & h \\ 4 & 6 & 7 \end{bmatrix}$$

$$R_2' = R_2 - 2R_1$$

↓

$$\begin{bmatrix} 2 & 3 & h \\ 0 & 0 & 7-2h \end{bmatrix}$$

$$0 = 7 - 2h$$

$$2h = 7$$

$$\boxed{h = \frac{7}{2}}$$

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19) **A**

$$x_1 + h x_2 = 2$$

$$4x_1 + 8x_2 = k$$

$$\begin{bmatrix} 1 & h & 2 \\ 4 & 8 & k \end{bmatrix}$$

$$R_2' = R_2 - 4R_1$$

\Downarrow

$$\begin{bmatrix} 1 & h & 2 \\ 0 & 8-4h & k-8 \end{bmatrix}$$

$$R_2' = \frac{1}{8-4h} \cdot R_2$$

\Downarrow

$$\begin{bmatrix} 1 & h & 2 \\ 0 & 1 & \frac{k-8}{8-4h} \end{bmatrix}$$

$$R_1' = R_1 - h R_2$$

\Downarrow

$$\begin{bmatrix} 1 & 0 & 2 - h \left(\frac{k-8}{8-4h} \right) \\ 0 & 1 & \frac{k-8}{8-4h} \end{bmatrix}$$

a) **No Solution**

$$8-4h=0$$

$$h=2$$

if $k \neq 8$, then no solution if $h=2$

b) **Unique Solution**

This is the set of all cases not infinite and not inconsistent.

$$h \neq 2$$

c) **Infinite Solution**

$k=8$, $h=2$ since last row becomes all zeros

21) Mark each selection as **A** true or false

a) **False** - The reduced echelon matrix is unique

b) **False** - The row reduction algorithm applies to all matrices not just augmented ones.

c) **True** - Basic variables corresponds to pivot columns in the coefficient and augmented matrix

d) **True** - Solving a system amounts to finding a parametric description of the solution set

e) **False** - This is not enough information to determine if the system is consistent as the row $[0 \ 0 \ 0 \ 50]$ is not a contradiction.

23)

Yes it is consistent, since with three rows and three pivot columns, there cannot be a row in the form:

$$\begin{bmatrix} 0 & 0 & 0 & 0 & h \end{bmatrix}$$

where $h \neq 0$ in the augmented matrix

25)

If a linear system has a pivot position in every row, it means there are no rows in the augmented matrix that can have a contradiction in the form

$$[0 \ 0 \ 0 \ \dots \ 0 \ h]$$

where $h \neq 0$

Hence, **there is no room for a pivot in the augmented column.**

27) ★

If a linear system is consistent, then the solution is unique if and only if **each column in the coefficient matrix is a pivot column.**

29) An **undetermined system** always has more variables than equations. **There cannot be more basic variables than there are equations.** As such, there must be at least one free variable. Such a variable **may be assigned infinitely many values.** If a system is consistent, each different value of a free variable will produce a different solution.