Chapte 4-4-Coordinate Systems

$$3 = \left\{ \begin{bmatrix} 3 \\ -5 \end{bmatrix}, \begin{bmatrix} -4 \\ 6 \end{bmatrix} \right\}, \left[\hat{x} \right]_{\mathcal{B}} = \begin{bmatrix} 5 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} 3 & -4 \\ -5 & 6 \end{bmatrix} \begin{bmatrix} 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 15 - 12 \\ 25 + 18 \end{bmatrix}$$

$$\overrightarrow{X} = \begin{bmatrix} 3 \\ -7 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 5 & 4 \\ -4 & 2 & -7 \\ 3 & -2 & 0 \end{bmatrix} \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 3 + 0 - 4 \\ -12 + 0 + 7 \\ 9 + 0 + 0 \end{bmatrix}$$

$$\vec{X} = \begin{bmatrix} -1 \\ -5 \\ 9 \end{bmatrix}$$

5) Find xB where
$$\vec{b}_1 = \begin{bmatrix} 1 \\ -3 \end{bmatrix}, \vec{b}_2 = \begin{bmatrix} 2 \\ -5 \end{bmatrix}, \vec{x} = \begin{bmatrix} -3 \\ -3 \end{bmatrix}$$

$$P_{B} = \begin{bmatrix} 1 & 2 \\ -3 & -5 \end{bmatrix}, P_{B} = \begin{bmatrix} -5 & -\lambda \\ 3 & 1 \end{bmatrix}$$

$$P_{B} \left[\vec{X} \right]_{B} = \vec{X}$$

$$\left[\vec{X} \right]_{B} = P_{B} \vec{X}$$

$$\begin{bmatrix} \frac{7}{4} \\ \frac{1}{8} \end{bmatrix}_{\beta} = \begin{bmatrix} -5 - 2 \\ 3 \end{bmatrix} \begin{bmatrix} -2 \\ -5 \end{bmatrix}$$

$$\vec{b}_{i} = \begin{bmatrix} 1 \\ -1 \\ 3 \end{bmatrix}, \vec{b}_{z} = \begin{bmatrix} -3 \\ 4 \\ 9 \end{bmatrix}, \vec{b}_{3} = \begin{bmatrix} 2 \\ -2 \\ 4 \end{bmatrix}, \vec{x} = \begin{bmatrix} 8 \\ -9 \\ 6 \end{bmatrix}$$

$$\begin{array}{c} R_{2} = R_{2} + R_{1} \\ R_{3} = R_{3} + 3R_{1} \end{array} \begin{bmatrix} 1 - 32 & 100 \\ 0 & 10 & 110 \\ 0 & 16 & 301 \end{bmatrix}$$

$$R_{1} = R_{1} + 3R_{2} \begin{bmatrix} 1 & 0 & 2 & 43 & 0 \\ 0 & 1 & 0 & 11 & 0 \\ 0 & 0 & 10 & 3 & 0 \end{bmatrix}$$

$$R'=R_1-\frac{1}{5}R_3\left[\begin{array}{ccccc} 100 & \frac{17}{5} & 3-\frac{1}{5} \\ 0.10 & 1.1.0 \\ 0.010 & 3.0.1 \end{array}\right]$$

$$\begin{array}{c} C \\ R_3^{1-\frac{1}{10}}R_3 \end{array} \left[\begin{array}{cccc} 1 & 0 & 0 & \frac{17}{5} & 3 & -\frac{1}{5} \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{array} \right]$$

$$\begin{array}{cccc}
P_{B} \vec{x} &= [\vec{x}]_{B} \\
\vec{x} &= 27 - \frac{1}{5} \\
8 - 9 + 0 \\
24 + 6 \\
10
\end{array}$$

$$\begin{bmatrix} -1 \\ -1 \\ 3 \end{bmatrix} = X$$

Find the change-of-coordinates matrix

from B to R where B=
$$\{\begin{bmatrix} 2\\ -9 \end{bmatrix}, \begin{bmatrix} 1\\ 8\end{bmatrix} \}$$
 $R = \begin{bmatrix} 2\\ -9 \end{bmatrix}$

Where B= {[3], [4]},
$$\vec{x} = [-3]$$

$$det P_{B} = (3)(6) - (-4)(-5) = 18 - 20 = -2$$

$$P_{B}^{-1} = \begin{bmatrix} -3 & -4 \\ -5 & -\frac{3}{2} \end{bmatrix}$$

$$\begin{bmatrix} \vec{x} \\ \vec{y} \end{bmatrix}_{\mathcal{B}} = P_{\mathcal{B}} \times \vec{x} = \begin{bmatrix} -6 + 12 \\ -5 + 9 \end{bmatrix} = \begin{bmatrix} 6 \\ 4 \end{bmatrix}$$

$$R_{3} = R_{3} - R_{2} \begin{bmatrix} 101 & 106 \\ 010 & -101 \\ 002 & 11-1 \end{bmatrix} R_{3}^{1} = \frac{1}{2} R_{3} \begin{bmatrix} 101 & 100 \\ 010 & -101 \\ 001 & \frac{1}{2} \frac{1}{2} - \frac{1}{2} \end{bmatrix}$$

$$R_{1}^{1}=R_{1}-R_{3}\begin{bmatrix}100&\frac{1}{2}&\frac{1}{2}\\010&-1&0\\001&\frac{1}{2}&\frac{1}{2}&2\end{bmatrix}$$

$$P_{B}^{-1}=\begin{bmatrix}\frac{1}{2}&\frac{1}{2}\\\frac{1}{2}&2\\-1&0\\\frac{1}{2}&2&2\end{bmatrix}$$

Chapter 4-4 - Coordinate Systems

a) True - The number of vectors in B defines the number of dimensions for [7]B

b) False - The change of coordinates matrixis definedes: PB[X]B=X

2) True - The standard pasismops TR Ponto itself,

passerthrough the origin.

1) Vectors v.= [-3], v.= [-8], v.= [-3] spansik butisnot abosi) Find at least two ways to expres [!]as

$$\vec{X} = \begin{bmatrix} 5 \\ -2 \\ 0 \end{bmatrix} + X_3 \begin{bmatrix} 5 \\ -1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} C_1 \\ C_2 \\ C_3 \end{bmatrix} = \begin{bmatrix} 5 \\ -2 \\ 0 \end{bmatrix} \text{ or } \begin{bmatrix} C_1 \\ C_2 \\ C_3 \end{bmatrix} = \begin{bmatrix} 10 \\ -3 \\ 1 \end{bmatrix}$$

21) Let B= {[4][9]} Find a matrix A such that AZ=[x]B

$$P_{\mathcal{B}}^{-1} = A = \begin{bmatrix} q & 2 \\ 4 & 1 \end{bmatrix}$$

27) Determine if the vectors are independent: 1+2t3, 2+t-3+3, -1+2+2-t3 Mapto TR4

$$\begin{bmatrix}
(1 & 0 & -1 \\
0 & 1 & 0 \\
0 & -3 & 0 \\
0 & 0 & -1
\end{bmatrix}$$

$$R_{4} = R_{4} - \lambda R_{1} \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & 0 \\ 0 & -3 & 2 \\ 0 & -4 & 1 \end{bmatrix}$$

$$\begin{array}{c} R_{3} = R_{3} + 3R_{2} \\ R_{4} = R_{4} + 4R_{2} \end{array} \begin{array}{c} \left(\begin{array}{c} 1 & 2 - 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{array} \right) \end{array}$$

Linearly independent as pivotin every column

29) Determine if the polynomial, are lines 4 independent where 1-2+++2, t-2++23, 1-3++3+2-+3

$$\begin{bmatrix} 1 & 0 & 1 \\ -2 & 1 & -3 \\ 1 & -2 & 3 \\ 0 & 1 & -1 \end{bmatrix} = \begin{bmatrix} \overline{q}_1 & \overline{a}_2 & \overline{q}_3 \end{bmatrix}$$

$$\vec{q}_3 = \vec{q}_1 - \vec{q}_2$$

Linear combinations o linearly dependent

Chapter 4-4 - Coordinate Systems

31) Use coordinatevectors to determine Ithe polynomials spen P.

$$\begin{array}{c} & & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & \\ & & \\$$

No -Thereis not a pivotine very row.

les - Last two rows are not scalar multiple, meaning there will be a pivotin every row.