Chapter 1-5-Solution Sets of Linear Equations

1) Determine if the system 3) Determine if the system has a nontrivial solution

$$2x_1 - 5x_3 + 8x_3 = 0$$

 $-2x_1 - 7x_2 + x_3 = 0$
 $4x_1 + 2x_2 + 7x_3 = 0$

Augmented Matrix

$$R_{3}^{1} = R_{2} + R_{1}$$
 $R_{3}^{1} = R_{3} - 2R_{1}$

$$\begin{bmatrix} 2 - 5 & 6 & 0 \\ 0 - 12 & 9 & 0 \\ 0 & 12 - 9 & 0 \end{bmatrix}$$

$$R_{3} = R_{3} + R_{2}$$

$$\begin{bmatrix} 3 & -5 & 8 & 0 \\ 0 & +2 & 9 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Xzis afree variable.

Yes, since x3 is free, it has a nontrivial solution has a nontrivial solution

$$\begin{bmatrix} -3 & 5 & -7 & 0 \\ -6 & 7 & 1 & 0 \end{bmatrix}$$

$$R_{a}^{1} = R_{a} - \partial R_{1}$$

$$\begin{bmatrix} -3 & 5 & -7 & 0 \\ 0 & -3 & 15 & 0 \end{bmatrix}$$

X3 is free

Yes, since x3 is free, it has a nontrivial solution

5) Write the solutionset of the given homogeneous systemin parametric vector form.

$$1 + 3x_{1} + x_{3} = 0$$

$$-4x_{1} - 9x_{1} + 2x_{3} = 0$$

$$-3x_{2} - 6x_{3} = 0$$

Augmented Matrix

$$R_{a} = R_{a} + 4R_{1}$$

$$0 \quad 3 \quad 0 \quad 0$$

$$0 \quad -3 \quad -6 \quad 0$$

$$R_3' = R_3 + R_2$$
 $R_1' = R_1 - R_2$

$$\begin{bmatrix} 1 & 0 & -50 \\ 0 & 3 & 60 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_{3} = \frac{1}{3} R_{2}$$

$$\begin{bmatrix} 1 & 0 & -5 & 0 \\ 0 & 1 & 3 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$X_1 = 5x_3$$

$$X_1 = 5 \times 3$$

$$X_2 = -2 \times 3$$

$$X_3 \text{ is free}$$

$$\vec{X} = \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix} = \begin{bmatrix} 5 \times_3 \\ -2 \times_3 \\ X_3 \end{bmatrix} = \begin{bmatrix} X_3 \\ -2 \end{bmatrix}$$

Chapte 1-5- Solution Sets of Linear Equations

7) Describe the solution set

for AZ=0 in parametric

vector form for:

$$A = \begin{bmatrix} 1 & 3 & -3 & 7 \\ 0 & 1 & -4 & 5 \end{bmatrix}$$

9) Describe all Solutions in

parametric vector form

or AR=0 given

$$A = \begin{bmatrix} 3 & -9 & 6 \\ -1 & 3 & -2 \end{bmatrix}$$

Swap R, GRZ

$$R_a = R_a - 3R$$

$$\overline{Y} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3x_2 - 2x_3 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_2 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -2 \\ 0 \end{bmatrix}$$

1) Desube all solutions of A = 0 given A.'s rowequivalent to thematrix below!

$$X_1 = 4x_2 - 5x_6$$

$$X_2 \text{ is free}$$

$$\begin{cases} x_1 \\ y_2 \end{cases} \begin{cases} 4x_2 - 5y_1 \\ x_2 \end{cases}$$

Chapter 1-5- Solution Sets of Linear Equations

13) Suppose the solution set of a certain system of linear equation can be described as:

$$X_1 = 5 + 4 \times 3$$

 $X_2 = -2 - 7 \times 3$
 X_3 is free

Use vectors to describe this solution set in TR.3

$$\frac{7}{X} = \begin{bmatrix} X_{1} \\ X_{2} \\ X_{3} \end{bmatrix} = \begin{bmatrix} 5+4x_{3} \\ 2-7y_{3} \\ X_{3} \end{bmatrix} = \begin{bmatrix} 5 \\ 7 \\ 7 \end{bmatrix} = \begin{bmatrix} 5 \\ 7 \\ 7 \end{bmatrix} + \begin{bmatrix} 5 \\ 7 \\ 7 \end{bmatrix} = \begin{bmatrix} 7 7 \\ 7$$

be vector [4]

15) Give the solutionset of the system in parametric vector form and give a geometric description:

$$x_1 + 3x_2 + x_3 = 1$$

 $-4x_1 - 9x_2 + 3x_3 = 1$
 $-3x_2 - 6x_3 = -3$

Augmental Madiix

$$\begin{bmatrix} 1 & 3 & 1 & 1 \\ -4 & -9 & 2 & -1 \\ 0 & -3 & -6 & -3 \end{bmatrix}$$

$$R_{2}^{1} = R_{2} + 4R,$$

$$R_{3} = R_{3} + R_{2}$$
 $R_{1} = R_{1} - R_{2}$

$$R_2 = \frac{1}{3}R_2$$

$$\begin{bmatrix}
1 & 0 & -5 & -2 \\
0 & 1 & 2 & 1 \\
0 & 0 & 0 & 0
\end{bmatrix}$$

$$X_1 = -\lambda + 5x_3$$

$$X_2 = 1 - 2x_3$$

$$\frac{x_2 \text{ is free}}{x = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 5 \\ -2 \\ 1 \end{bmatrix}}$$

Geometrically, it is the line through [3] parallel to [3] which is a vector 17) Describe and Compone the Solution Sets of:

First Solution Set

$$X_1 = -9x_2 + 4x_3$$

$$\overrightarrow{X} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} q_{x_2} + q_{x_3} \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} q_{x_2} + q_{x_3} \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} q_{x_2} + q_{x_3} \\ x_3 \\ x_3 \end{bmatrix} =$$

X

奴

X

Second Solution Set:

$$\vec{X} = \begin{bmatrix} -2 \\ 0 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} -9 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 4 \\ 0 \\ 1 \end{bmatrix}$$

Both solution sets are planes with the first solution set is through the origin and vectors

[-9] and [9] (i.e. spans { [-9], [4]3)

The second solutionset is parallel to the first (i.e. homogeneous) Solution Set and through [-2]

Chapte 1-5-Solution Sets of Linear Systems

19) Find the parametric equation of the line through \vec{a} and parallel to \vec{b} $\vec{a} = \begin{bmatrix} -2 \\ 0 \end{bmatrix}, \vec{b} = \begin{bmatrix} -5 \\ 3 \end{bmatrix}$

$$\vec{X} = \vec{a} + \vec{b}$$

$$\vec{X} = \begin{bmatrix} -2 \\ 0 \end{bmatrix} + \vec{x} \begin{bmatrix} -5 \\ 3 \end{bmatrix}$$

P= $\begin{bmatrix} 3 \\ -5 \end{bmatrix}$ $9 = \begin{bmatrix} -3 \\ 1 \end{bmatrix}$

$$\vec{q} - \vec{p} = \begin{bmatrix} 3 \\ 1 \end{bmatrix} - \begin{bmatrix} 3 \\ -5 \end{bmatrix}$$

$$\vec{q} - \vec{p} = \begin{bmatrix} -5 \\ 6 \end{bmatrix}$$

$$\vec{X} = \vec{p} + x(\vec{q} - \vec{p})$$

$$\vec{X} = \begin{bmatrix} -5 \\ 6 \end{bmatrix} + x \begin{bmatrix} -5 \\ 6 \end{bmatrix}$$

23)

a) True - It is not possible to get arow in the augmental matrix of a homogeneous systeminthe form

[0 0... 0 b] where b\(\)

b) Fake - The equation

AZ = B gives on implicit

description of the solutionset.

C) False - A homogeneous System always has a Erivial Solution

d) False - The quation $\vec{x} = \vec{p} + t\vec{v}$ describes a line through \vec{p} and parallel to \vec{v} .

e) False - This statement to is true if and only if $A\vec{x} = \vec{b}$ is consistent which may not be the case,

27) Suppose Ais the 3x3

Zeno matrix. Describe the solution set of Ax=0.

Inthis case all variables are free. This make, the Solution Set:

$$\overrightarrow{X} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = X_1 \begin{bmatrix} 0 \\ 0 \end{bmatrix} + X_2 \begin{bmatrix} 0 \\ 0 \end{bmatrix} + X_3 \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

This mean the Solutionse tis all vectors in TR3

a) Does AZ=0 have a
nontrivial solution?
b) Does the equation AZ=b
have at least one solution
for all b

Ais 3x3 matrix with 3 plant postum

a) No - Since it has no free
variables, it has only the
trivial solution.

b) Yes - Since thereis a pivot in each row, it is not possible to have a row in the augmented metrix with the form

[0000 c] (where c \$0)

Chapter 1-5-Solution Sets of Linear Systems

31) For the given matrix A:

A is a 3x2 matrix with 2 pivotposition

a) Does the equation AR = Oh are a non-trivial solution?

No - This equation hasno free variable, so it cannot have anon-trivial solution.

b) Does the equation $A\vec{x} = \vec{b}$ have at least one solution for all \vec{b} ?

No-By the Theoren 4in Section 1.4, if a matrix does not have apivotin every row, then a solution does not exist for all b 35) Construct a non-zero motive of size 3x3 such that the vector [i] is a solution to $A\vec{x}=\vec{o}$.

$$A = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

This example holds since the dot product for each now with [i] must be

Chapter 1-5- Solution Sets of Linear Systems

Do the following planes interest? If so, describe their interestion?

$$x_1 + 4x_2 - 5x_3 = 0$$

 $2x_1 - x_2 + 8x_3 = 9$

Augmented Matrix

$$\begin{bmatrix} 1 & 4 & -5 & 0 \\ a & -1 & 8 & 9 \end{bmatrix}$$

$$R_{a} = R_{a} - 2R_{a}$$

$$R_a = -\frac{1}{9}R_a$$

$$\begin{bmatrix} 1 & 4 & -5 & 0 \\ 0 & 1 & -2 & -1 \end{bmatrix}$$

$$\begin{bmatrix}
 1 & 0 & 3 & 4 \\
 0 & 1 & -2 & -1
 \end{bmatrix}$$

$$\begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix} = \begin{bmatrix} 4 - 3x_3 \\ -1 + 2x_3 \\ X_3 \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -3 \\ 2 \\ 1 \end{bmatrix}$$