

Follow the leader with Dropout perturbations

- Additive versus multiplicative noise

Manfred K. Warmuth



Simon's Institute

Nov. 17, 2016

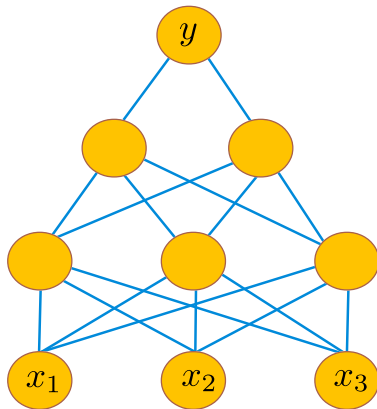
Joint work with Tim Van Erven and Wojciech Kotłowski



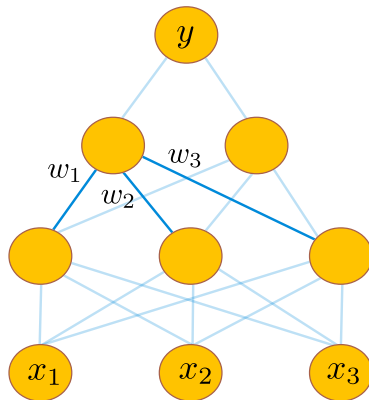
Major insights from [Devroye, Lugosi, Neu 2013]

Outline

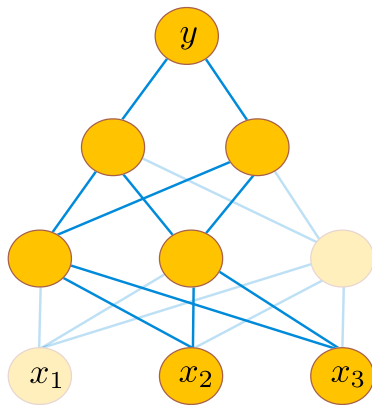
Feed forward neural net



Weights parameters - sigmoids at internal nodes



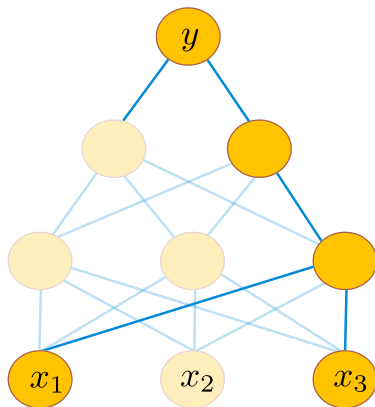
Dropout training



- Stochastic gradient descent
- Randomly remove every hidden/input node with prob. $\frac{1}{2}$ before each gradient descent update

[Hinton et al. 2012]

Dropout training



- Very successful in image recognition & speech recognition
- Why does it work?

[Wagner, Wang, Liang 2013]
[Helmbold, Long 2014]

What are we doing?

Prove bounds for dropout

- single neuron
- linear loss

Online learning with expert

	E_1	E_2	E_3	\dots	E_n	<i>prediction</i>	label	loss
day 1	0	1	0	\dots	0	0	1	1

Online learning with expert

	E_1	E_2	E_3	\dots	E_n	$prediction$	label	loss
day 1	0	1	0	\dots	0	0	1	1
day 2	1	1	0	\dots	0	1	1	0

Online learning with expert

	E_1	E_2	E_3	\dots	E_n	<i>prediction</i>	label	loss
day 1	0	1	0	\dots	0	0	1	1
day 2	1	1	0	\dots	0	1	1	0
notation	x_1	x_1	x_2	\dots	x_n	\hat{y}	y	$ \hat{y} - y $

Online learning with expert

	E_1	E_2	E_3	\dots	E_n	<i>prediction</i>	label	loss
day 1	0	1	0	\dots	0	0	1	1
day 2	1	1	0	\dots	0	1	1	0
notation	x_1	x_1	x_2	\dots	x_n	\hat{y}	y	$ \hat{y} - y $
scope	$\in [0, 1]$			\dots		$\in [0, 1]$	$\in \{0, 1\}$	$\in [0, 1]$

Online learning with expert

	E_1	E_2	E_3	\dots	E_n	$prediction$	label	loss
day 1	0	1	0	\dots	0	0	1	1
day 2	1	1	0	\dots	0	1	1	0
notation	x_1	x_1	x_2	\dots	x_n	\hat{y}	y	$ \hat{y} - y $
scope	$\in [0, 1]$			\dots		$\in [0, 1]$	$\in \{0, 1\}$	$\in [0, 1]$

- Algorithm maintains probability vector w :
 - prediction $\hat{y} = w \cdot x$

Online learning with expert

	E_1	E_2	E_3	\dots	E_n	$prediction$	label	loss
day 1	0	1	0	\dots	0	0	1	1
day 2	1	1	0	\dots	0	1	1	0
notation	x_1	x_1	x_2	\dots	x_n	\hat{y}	y	$ \hat{y} - y $
scope	$\in [0, 1]$			\dots		$\in [0, 1]$	$\in \{0, 1\}$	$\in [0, 1]$

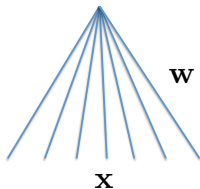
- Algorithm maintains probability vector w :
- prediction $\hat{y} = w \cdot x$

- Loss linear because label $y \in \{0, 1\}$

- $$\underbrace{|\overbrace{w \cdot x}^{\hat{y}} - y|}_{\text{loss of alg.}} = \sum_i w_i \underbrace{|x_i - y|}_{\text{loss of expert } i}$$

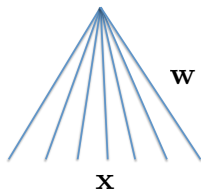
Predicting with expert advice

$$\hat{y} = \mathbf{w} \cdot \mathbf{x} \quad \text{loss } |\hat{y} - y|$$



Predicting with expert advice

$$\hat{y} = \mathbf{w} \cdot \mathbf{x} \quad \text{loss } |\hat{y} - y|$$

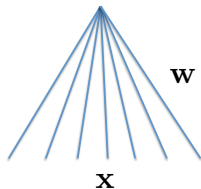


trial t

- get advice vector \mathbf{x}_t
- predict $\hat{y}_t = \mathbf{w}_t \cdot \mathbf{x}_t$
- get label y_t
- exp. losses $|x_{t,i} - y_t|$
- alg. loss $|\hat{y}_t - y_t|$
- update $\mathbf{w}_t \rightarrow \mathbf{w}_{t+1}$

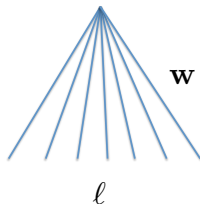
Predicting with expert advice

$$\hat{y} = \mathbf{w} \cdot \mathbf{x} \quad \text{loss } |\hat{y} - y|$$



Hedge setting

$$\text{loss } \mathbf{w} \cdot \ell$$

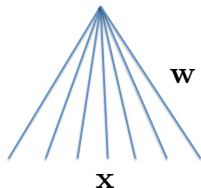


trial t

- get advice vector \mathbf{x}_t
- predict $\hat{y}_t = \mathbf{w}_t \cdot \mathbf{x}_t$
- get label y_t
- exp. losses $|x_{t,i} - y_t|$
- alg. loss $|\hat{y}_t - y_t|$
- update $\mathbf{w}_t \rightarrow \mathbf{w}_{t+1}$

Predicting with expert advice

$$\hat{y} = \mathbf{w} \cdot \mathbf{x} \quad \text{loss } |\hat{y} - y|$$

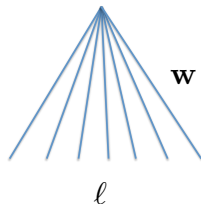


trial t

- get advice vector \mathbf{x}_t
- predict $\hat{y}_t = \mathbf{w}_t \cdot \mathbf{x}_t$
- get label y_t
- exp. losses $|x_{t,i} - y_t|$
- alg. loss $|\hat{y}_t - y_t|$
- update $\mathbf{w}_t \rightarrow \mathbf{w}_{t+1}$

Hedge setting

$$\text{loss } \mathbf{w} \cdot \ell$$



trial t

-
- predict \mathbf{w}_t
- get loss vector ℓ_t
- exp. losses $\ell_{t,i}$
- alg. loss $\mathbf{w}_t \cdot \ell_t$
- update $\mathbf{w}_t \rightarrow \mathbf{w}_{t+1}$

Predicting with a random expert

trial t

- predict w_t

or predict with random expert \hat{i}_t

Predicting with a random expert

trial t

- predict w_t
- get loss vector ℓ_t
- alg. loss $w_t \cdot \ell_t$

or predict with random expert \hat{i}_t

or alg. expected loss $\mathbb{E} \left[e_{\hat{i}_t} \cdot \ell_t \right] = \underbrace{\mathbb{E} \left[e_{\hat{i}_t} \right]}_{w_t} \cdot \ell_t$

Predicting with a random expert

trial t

- predict w_t
- get loss vector ℓ_t
- alg. loss $w_t \cdot \ell_t$

or predict with random expert \hat{i}_t

or alg. expected loss $\mathbb{E} \left[e_{\hat{i}_t} \cdot \ell_t \right] = \underbrace{\mathbb{E} \left[e_{\hat{i}_t} \right]}_{w_t} \cdot \ell_t$

- update $w_t \rightarrow w_{t+1}$

Predicting with a random expert

trial t

- predict w_t
- get loss vector ℓ_t
- alg. loss $w_t \cdot \ell_t$

or predict with random expert \hat{i}_t

or alg. expected loss $\mathbb{E} \left[e_{\hat{i}_t} \cdot \ell_t \right] = \underbrace{\mathbb{E} \left[e_{\hat{i}_t} \right]}_{w_t} \cdot \ell_t$

- update $w_t \rightarrow w_{t+1}$

weights are implicit

Only works for linear loss

How do we measure performance

Worst-case **regret**

$$\underbrace{\sum_{t=1}^T w_t \cdot \ell_t}_{\text{total expected loss of alg}} - \underbrace{\inf_i \ell_{\leq T, i}}_{\text{loss } \ell^* \text{ of best expert}}$$

Should be logarithmic in # of experts n

Main algorithms

	E_1	E_2	E_3	E_4	E_5
	0	1	0	0	1
	1	1	0	1	1
day $t - 1$	0	0	1	1	1
<hr/>					
	$\ell_{\leq t-1,i}$				

Main algorithms

	E_1	E_2	E_3	E_4	E_5
	0	1	0	0	1
	1	1	0	1	1
day $t - 1$	0	0	1	1	1
$\ell_{\leq t-1,i}$	1	2	1	2	3

Main algorithms

	E_1	E_2	E_3	E_4	E_5
	0	1	0	0	1
	1	1	0	1	1
day $t - 1$	0	0	1	1	1
$\ell_{\leq t-1,i}$	1	2	1	2	3

FL

$$\hat{i}_t = \operatorname{argmin}_i \ell_{\leq t-1,i}$$

ties broken uniformly

Main algorithms

	E_1	E_2	E_3	E_4	E_5
	0	1	0	0	1
	1	1	0	1	1
day $t - 1$	0	0	1	1	1
$\ell_{\leq t-1,i}$	1	2	1	2	3

FL	$\hat{i}_t = \operatorname{argmin}_i \ell_{\leq t-1,i}$	ties broken uniformly
FPL(η)	$\hat{i}_t = \operatorname{argmin}_i \ell_{\leq t-1,i} + \frac{1}{\eta} \xi_{t,i}$	indep. <u>additive</u> noise

Main algorithms

	E_1	E_2	E_3	E_4	E_5
	0	1	0	0	1
	1	1	0	1	1
day $t - 1$	0	0	1	1	1
$\ell_{\leq t-1,i}$	1	2	1	2	3

FL $\hat{i}_t = \operatorname{argmin}_i \ell_{\leq t-1,i}$ ties broken uniformly

FPL(η) $\hat{i}_t = \operatorname{argmin}_i \ell_{\leq t-1,i} + \frac{1}{\eta} \xi_{t,i}$ indep. additive noise

Hedge(η) $w_i = \frac{e^{-\eta \ell_{\leq t-1,i}}}{Z}$ Weighted Majority algorithm
for pred. with Expert Advice
Soft min

Dropout

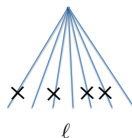
	E_1	E_2	E_3	E_4	E_5
	0	$\cancel{1}$	0	0	$\cancel{1}$
	1	1	0	1	1
day $t - 1$	0	0	$\cancel{1}$	$\cancel{1}$	1

$\hat{\ell}_{\leq t-1, i}$

Dropout

	E_1	E_2	E_3	E_4	E_5
	0	$\cancel{1}$	0	0	$\cancel{1}$
	1	1	0	1	1
day $t - 1$	0	0	$\cancel{1}$	$\cancel{1}$	1
$\hat{\ell}_{\leq t-1,i}$	1	1	0	1	2

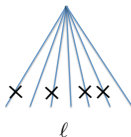
$$\hat{\ell}_{t,i} = \beta_{t,i} \ell_{t,i}, \quad \text{where } \beta_{t,i} \text{ iid Bernoulli}$$



Dropout

	E_1	E_2	E_3	E_4	E_5
	0	$\cancel{1}$	0	0	$\cancel{1}$
	1	1	0	1	1
day $t - 1$	0	0	$\cancel{1}$	$\cancel{1}$	1
$\hat{\ell}_{\leq t-1,i}$	1	1	0	1	2

$$\hat{\ell}_{t,i} = \beta_{t,i} \ell_{t,i}, \quad \text{where } \beta_{t,i} \text{ iid Bernoulli}$$



FL on dropout

$$\hat{i}_t = \operatorname{argmin}_i \hat{\ell}_{\leq t-1,i}$$

How good?

Optimal worst case regret: $\sqrt{L^* \ln n} + \ln n$

How good?

Optimal worst case regret: $\sqrt{L^* \ln n} + \ln n$

- FL is bad
- $\text{FPL}(\eta)$ and $\text{Hedge}(\eta)$ achieve optimal regret with tuning
 - fancy tunings: AdaHedge and Flipflop

How good?

Optimal worst case regret: $\sqrt{L^* \ln n} + \ln n$

- FL is bad
- $\text{FPL}(\eta)$ and $\text{Hedge}(\eta)$ achieve optimal regret with tuning
 - fancy tunings: AdaHedge and Flipflop
- FL on dropout requires no tuning

How good?

Optimal worst case regret: $\sqrt{L^* \ln n} + \ln n$

- FL is bad
- $\text{FPL}(\eta)$ and $\text{Hedge}(\eta)$ achieve optimal regret with tuning
 - fancy tunings: AdaHedge and Flipflop
- FL on dropout requires no tuning
 - dropout better noise for achieving optimal worst case regret
 - additive noise needs tuning - multiplicative noise does not
 - in iid case when gap between 1st and 2nd: $\log n$ regret

How good?

Optimal worst case regret: $\sqrt{L^* \ln n} + \ln n$

- FL is bad
- $\text{FPL}(\eta)$ and $\text{Hedge}(\eta)$ achieve optimal regret with tuning
 - fancy tunings: AdaHedge and Flipflop
- FL on dropout requires no tuning
 - dropout better noise for achieving optimal worst case regret
 - additive noise needs tuning - multiplicative noise does not
 - in iid case when gap between 1st and 2nd: $\log n$ regret
- In the meantime
 - new fancy algorithms by Haipeng Luo, Rob Schapire & Tim van Erven, Wouter Koolen

How good?

Optimal worst case regret: $\sqrt{L^* \ln n} + \ln n$

- FL is bad
- $\text{FPL}(\eta)$ and $\text{Hedge}(\eta)$ achieve optimal regret with tuning
 - fancy tunings: AdaHedge and Flipflop
- FL on dropout requires no tuning
 - dropout better noise for achieving optimal worst case regret
 - additive noise needs tuning - multiplicative noise does not
 - in iid case when gap between 1st and 2nd: $\log n$ regret
- In the meantime
 - new fancy algorithms by Haipeng Luo, Rob Schapire & Tim van Erven, Wouter Koolen
 - also no tuning, many other advantages

Our path to dropout

- Loss vectors $\ell_t \longrightarrow$ loss matrices L_t
- Prob. vectors $w_t \longrightarrow$ density matrices W_t
- Hedge $w_{t,i} = \frac{e^{-\eta \ell_{\leq t-1,i}}}{Z} \longrightarrow$ Matrix Hedge

$$W_t = \frac{\exp(-\eta L_{\leq t-1})}{Z'}$$

- Matrix Hedge $O(n^3)$ per update

Our path to dropout

- Loss vectors $\ell_t \longrightarrow$ loss matrices L_t
- Prob. vectors $w_t \longrightarrow$ density matrices W_t
- Hedge $w_{t,i} = \frac{e^{-\eta \ell_{\leq t-1,i}}}{Z} \longrightarrow$ Matrix Hedge

$$W_t = \frac{\exp(-\eta L_{\leq t-1})}{Z'}$$

- Matrix Hedge $O(n^3)$ per update
- FL minimum eigenvector calculation of $L_{\leq t-1}$: $O(n^2)$

Our path to dropout

- Loss vectors $\ell_t \longrightarrow$ loss matrices L_t
- Prob. vectors $w_t \longrightarrow$ density matrices W_t
- Hedge $w_{t,i} = \frac{e^{-\eta \ell_{\leq t-1,i}}}{Z} \longrightarrow$ Matrix Hedge

$$W_t = \frac{\exp(-\eta L_{\leq t-1})}{Z'}$$

- Matrix Hedge $O(n^3)$ per update
- FL minimum eigenvector calculation of $L_{\leq t-1}$: $O(n^2)$
- Is there $O(n^2)$ perturbation with optimal regret bound?

Our path to dropout

- Loss vectors $\ell_t \longrightarrow$ loss matrices L_t
- Prob. vectors $w_t \longrightarrow$ density matrices W_t
- Hedge $w_{t,i} = \frac{e^{-\eta \ell_{\leq t-1,i}}}{Z} \longrightarrow$ Matrix Hedge

$$W_t = \frac{\exp(-\eta L_{\leq t-1})}{Z'}$$

- Matrix Hedge $O(n^3)$ per update
- FL minimum eigenvector calculation of $L_{\leq t-1}$: $O(n^2)$
- Is there $O(n^2)$ perturbation with optimal regret bound?
- Follow the skipping leader:
Drop entire loss L_t with probability $\frac{1}{2}$
= Online Bagging

Our path to dropout

- Loss vectors $\ell_t \longrightarrow$ loss matrices L_t
- Prob. vectors $w_t \longrightarrow$ density matrices W_t
- Hedge $w_{t,i} = \frac{e^{-\eta \ell_{\leq t-1,i}}}{Z} \longrightarrow$ Matrix Hedge

$$W_t = \frac{\exp(-\eta L_{\leq t-1})}{Z'}$$

- Matrix Hedge $O(n^3)$ per update
- FL minimum eigenvector calculation of $L_{\leq t-1}$: $O(n^2)$
- Is there $O(n^2)$ perturbation with optimal regret bound?
- Follow the skipping leader:
 - Drop entire loss L_t with probability $\frac{1}{2}$
 - = Online Bagging
- Proof techniques break down
 - settled for vector case and independent multiplicative noise
 - = dropout

Our path to dropout

- Loss vectors $\ell_t \longrightarrow$ loss matrices L_t
- Prob. vectors $w_t \longrightarrow$ density matrices W_t
- Hedge $w_{t,i} = \frac{e^{-\eta \ell_{\leq t-1,i}}}{Z} \longrightarrow$ Matrix Hedge

$$W_t = \frac{\exp(-\eta L_{\leq t-1})}{Z'}$$

- Matrix Hedge $O(n^3)$ per update
- FL minimum eigenvector calculation of $L_{\leq t-1}$: $O(n^2)$
- Is there $O(n^2)$ perturbation with optimal regret bound?
- Follow the skipping leader:
 - Drop entire loss L_t with probability $\frac{1}{2}$
 - = Online Bagging
- Proof techniques break down
 - settled for vector case and independent multiplicative noise
 - = dropout
- ~~Follow the skipping leader~~ has linear regret [Lugosi, Neu2014]

What regularization?

Hedge(η)

relative entropy

What regularization?

Hedge(η)

relative entropy

FPL(η)

additive $\frac{1}{\eta} \log$ exponential noise = Hedge(η)

What regularization?

Hedge(η) relative entropy
FPL(η) additive $\frac{1}{\eta}$ log exponential noise = Hedge(η)

FL on dropout tricky

Feed forward NN [Wagner, Wang, Liang 2013]
Logistic regression [Helmbold, Long 2014]
Linear loss case [ALST 2014]

Simple algorithms

Any deterministic alg. (such as FL) has huge regret

- For T trials: give algorithm's expert a unit of loss
- Loss of alg.: T loss of best: $\leq \frac{T}{n}$

Simple algorithms

Any deterministic alg. (such as FL) has huge regret

- For T trials: give algorithm's expert a unit of loss
- Loss of alg.: T loss of best: $\leq \frac{T}{n}$

$$\text{regret: } \geq \underbrace{T}_{nL^*} - \underbrace{\frac{T}{n}}_{L^*} = (n-1)L^*$$

Simple algorithms

Any deterministic alg. (such as FL) has huge regret

- For T trials: give algorithm's expert a unit of loss
- Loss of alg.: T loss of best: $\leq \frac{T}{n}$

$$\text{regret: } \geq \underbrace{T}_{nL^*} - \underbrace{\frac{T}{n}}_{L^*} = (n-1)L^*$$

Recall optimum regret: $\sqrt{L^* \ln n} + \ln n$

FL with random ties

Simple algorithms

Any deterministic alg. (such as FL) has huge regret

- For T trials: give algorithm's expert a unit of loss

- Loss of alg.: T loss of best: $\leq \frac{T}{n}$

$$\text{regret: } \geq \underbrace{T}_{nL^*} - \underbrace{\frac{T}{n}}_{L^*} = (n-1)L^*$$

Recall optimum regret: $\sqrt{L^* \ln n} + \ln n$

FL with random ties

- Give every expert one unit of loss

- iterate $L^* + 1$ times

- Loss per sweep $\frac{1}{n} + \frac{1}{n-1} + \dots + \frac{1}{2} + 1 \approx \ln n$

- Loss of alg.: $(L^* + 1) \ln n$ loss of best: L^*

regret: $L^* \ln n$

Our analysis of dropout

Unit rule

- Adversary forces more regret by splitting loss vectors into units

$$\begin{pmatrix} \textcolor{red}{1} \\ 0 \\ \textcolor{blue}{1} \\ \textcolor{green}{1} \end{pmatrix} \longrightarrow \begin{pmatrix} \textcolor{red}{1} \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ \textcolor{blue}{1} \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ 0 \\ \textcolor{green}{1} \end{pmatrix}$$

Our analysis of dropout

Unit rule

- Adversary forces more regret by splitting loss vectors into units

$$\begin{pmatrix} \textcolor{red}{1} \\ 0 \\ \textcolor{blue}{1} \\ \textcolor{green}{1} \end{pmatrix} \longrightarrow \begin{pmatrix} \textcolor{red}{1} \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ \textcolor{blue}{1} \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ 0 \\ \textcolor{green}{1} \end{pmatrix}$$

Swapping rule

		$\ell_{\leq T, i}$								
E_1	1	1	1	1	1	1	$\textcolor{blue}{1}$	1	1	9
E_2	1	1	1	1	1	1	1	1		8
E_3	1	1	1	$\textcolor{red}{1}$	1	1	1	1	1	10
E_4	1	1	1	1	1	1				6

Our analysis of dropout

Unit rule

- Adversary forces more regret by splitting loss vectors into units

$$\begin{pmatrix} \textcolor{red}{1} \\ 0 \\ \textcolor{blue}{1} \\ \textcolor{green}{1} \end{pmatrix} \longrightarrow \begin{pmatrix} \textcolor{red}{1} \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ \textcolor{blue}{1} \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ 0 \\ \textcolor{green}{1} \end{pmatrix}$$

Swapping rule

		$\ell_{\leq T, i}$								
E_1	1	1	1	1	1	1	$\textcolor{blue}{1}$	1	1	9
E_2	1	1	1	1	1	1	1	1		8
E_3	1	1	1	$\textcolor{red}{1}$	1	1	1	1	1	10
E_4	1	1	1	1	1	1				6

- 1's occur in some order
- Worst case: $\textcolor{red}{1}$ before $\textcolor{blue}{1}$
- Otherwise adversary benefits from swapping

Worst-case pattern

1	1	1	1	1				
1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1

Cost per sweep

Assume we have s leaders

Cost per sweep

Assume we have s leaders

s leader get unit
ignore non-leaders

$$\left\{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{array} \right.$$

Cost per sweep

Assume we have s leaders

s leader get unit
ignore non-leaders

$$\left\{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{array} \right.$$

FL

$$\frac{1}{s} + \frac{1}{s-1} + \frac{1}{s-2} + \frac{1}{s-3} + \dots + \frac{1}{\underbrace{s-s-2}_2} + \frac{1}{\underbrace{s-s-1}_1}$$

$$\approx \ln s$$

Cost per sweep

Assume we have s leaders

s leader get unit
ignore non-leaders

$$\left\{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{array} \right.$$

FL

$$\frac{1}{s} + \frac{1}{s-1} + \frac{1}{s-2} + \frac{1}{s-3} + \dots + \underbrace{\frac{1}{s-s-2}}_2 + \underbrace{\frac{1}{s-s-1}}_1$$

$$\approx \ln s$$

Dropout

$$\frac{1}{s} + \frac{1}{s-1/2} + \frac{1}{s-2/2} + \frac{1}{s-3/2} + \dots + \frac{1}{s-(s-2)/2} + \frac{1}{s-(s-1)/2}$$

Cost per sweep

Assume we have s leaders

s leader get unit
ignore non-leaders

$$\left\{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{array} \right.$$

FL

$$\frac{1}{s} + \frac{1}{s-1} + \frac{1}{s-2} + \frac{1}{s-3} + \dots + \underbrace{\frac{1}{s-s-2}}_2 + \underbrace{\frac{1}{s-s-1}}_1$$

$$\approx \ln s$$

Dropout

$$\frac{2}{2s} + \frac{2}{2s-1} + \frac{2}{2s-2} + \frac{2}{s-3} + \dots + \frac{2}{2s-(s-2)} + \frac{2}{2s-(s-1)}$$

$$\approx 2(\ln 2s - \ln s) = 2 \ln 2$$

Cost per sweep

Assume we have s leaders

$$\left. \begin{array}{l} s \text{ leader get unit} \\ \text{ignore non-leaders} \end{array} \right\} \begin{array}{c} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{array}$$

FL

$$\frac{1}{s} + \frac{1}{s-1} + \frac{1}{s-2} + \frac{1}{s-3} + \dots + \underbrace{\frac{1}{s-s-2}}_2 + \underbrace{\frac{1}{s-s-1}}_1$$

$$\approx \ln s$$

Dropout

$$\frac{2}{2s} + \frac{2}{2s-1} + \frac{2}{2s-2} + \frac{2}{s-3} + \dots + \frac{2}{2s-(s-2)} + \frac{2}{2s-(s-1)}$$

$$\approx 2(\ln 2s - \ln s) = 2 \ln 2$$

$L^* = 0$ - one expert incurs no loss

FL

- One sweep

$$\frac{1}{n} + \frac{1}{n-1} + \dots + \frac{1}{2} \cancel{+ 1} \approx (\ln n) \cancel{- 1}$$

- Optimal

$L^* = 0$ - one expert incurs no loss

FL

- One sweep

$$\frac{1}{n} + \frac{1}{n-1} + \dots + \frac{1}{2} \cancel{+ 1} \approx (\ln n) - 1$$

- Optimal

Dropout

- # of leaders reduced by half in each sweep
- $\approx \log_2 n$ sweeps times $\leq 2 \ln 2 = 1.386$

$$\begin{array}{c} \text{=====} \\ 2 \ln n \end{array}$$

Overview of proof for noisy case

- Focus on first L sweeps
- Only occurs constant regret if number of leaders > 1

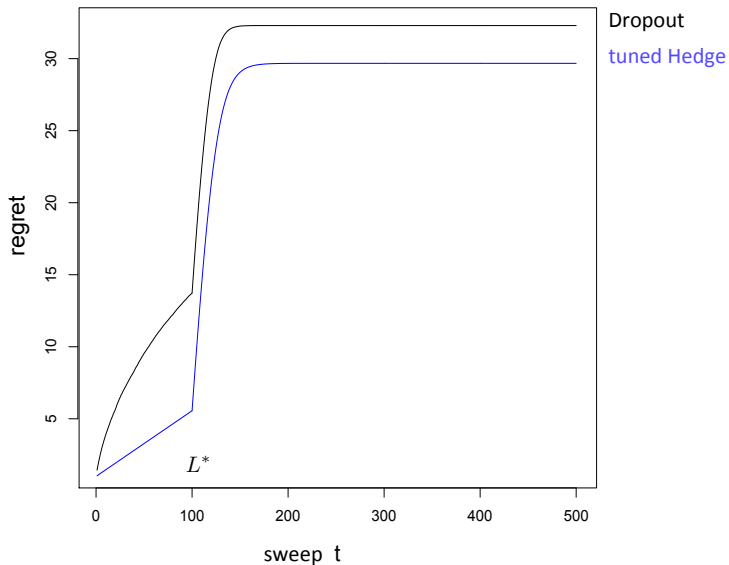
Overview of proof for noisy case

- Focus on first L sweeps
- Only occurs constant regret if number of leaders > 1
- Prob. that number of leaders > 1 is at most $\sqrt{\frac{\ln n}{q+1}}$ for sweep q

Overview of proof for noisy case

- Focus on first L sweeps
- Only occurs constant regret if number of leaders > 1
- Prob. that number of leaders > 1 is at most $\sqrt{\frac{\ln n}{q+1}}$ for sweep q
- For $\text{Hedge}(\eta)$ and $\text{FPL}(\eta)$ cost per sweep constant and dependent on η

Dropout versus Hedge



- Combinatorial experts
- Matrix case
- Where else can dropout perturbations be used?
- Dropout for convex losses
- Dropout for neural nets

- Combinatorial experts
- Matrix case
- Where else can dropout perturbations be used?
- Dropout for convex losses
- Dropout for neural nets
- Privacy

[Lugosi, Neu 2014] dense counter example

0	1*
1	0
1	0
1	0
1	0
1	0
1	0
$\frac{n-1}{n}$	$\frac{1}{2}$

Iterate this pattern n times:

$$\sum_{i=1}^n \left(\frac{n-i}{n-i+1} + \frac{1}{2} \right) \\ \approx n - \ln n + \frac{n}{2}$$

$L^* = n$: Follow the Skipping Leader has **linear regret**

How does dropout avoid this example?

0	1
1	0
1	0
1	0
1	0
1	0
$\frac{n-1}{n}$	$\frac{1}{\frac{n-1}{2}}$

How does dropout avoid this example?

0	1
1	0
1	0
1	0
1	0
1	0
$\frac{n-1}{n}$	$\frac{1}{\frac{n-1}{2}}$

It leaves the adversary clueless as to who the leader is
i.e. privacy against adversary

sparse counter example

0	1*
$\frac{1}{n-1}$	0
$\frac{1}{n-1}$	0
$\frac{1}{n-1}$	0
$\frac{1}{n-1}$	0
$\frac{1}{n-1}$	0
$\frac{1}{n-1}$	0
$\frac{n-1}{n^2}$	$\frac{1}{2}$

Iterate this pattern n times:

$$\begin{aligned} & \sum_{i=1}^n \left(\frac{n-i}{(n-i+1)^2} + \frac{1}{2} \right) \\ &= \sum_{i=1}^n \left(\frac{1}{n-i+1} - \frac{1}{(n-i+1)^2} + \frac{1}{2} \right) \\ &\approx \ln n - O(1) + \frac{n}{2} \end{aligned}$$

$L^* = \ln n$: Follow the Skipping Leader has **linear regret**