

COMP6733 IoT Design Studio

Problem Set, 2023

June 11, 2023

Instructions for candidates

- (1) **Due date and time: Friday 28 July 2023, 17:00.**
- (2) Total number of questions: Three (3). Total number of pages (including this cover page): Four (4).
- (3) Answer all questions.
- (4) In answering the questions, it is important for you to show us your intermediate steps and tell us what arguments you have made to obtain the results. You need to note that both the intermediate steps and the arguments carry marks. Please note that we are **not** just interested in whether you can get the final numerical answer right, but we are **more** interested to find out whether you understand the subject matter. We do that by looking at your intermediate steps and the arguments that you have made to obtain the answer. Thus, if you can show us the perfect intermediate steps and the in-between arguments but got the numerical values wrong for some reason, we will still award you marks for having understood the subject matter.
- (5) Answers must be submitted electronically via *give*. The only format accepted is Acrobat pdf. The recommended file name is your student number. The submission command (assuming your student number is 1234567) is:

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give cs6733 problemSet 1234567.pdf,
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or via the WebCMS web interface.

- (6) Individual work ONLY. Please check the plagiarism policy in the course outline on the webpage.

Question 1: IoT Design (4 marks)

UNSW has joined “Race to Zero”¹, which is a global campaign to rally leadership and support from businesses, cities, regions, investors for a healthy, resilient, zero carbon recovery that prevents future threats, creates decent jobs, and unlocks inclusive, sustainable growth².

As part of the “Energy and Water” strategy, you are tasked to help to achieve 1) “By 2030, substantially increase water-use efficiency across all sectors”, 2) “By 2030, double the global rate of improvement in energy efficiency.” (see Fig. 1), by monitoring/controlling energy/water usage, occupancy, temperature/humidity, HVAC and lighting in these buildings. Therefore, your proposed solution should include the sensors, the actuators, smartphones (e.g., for human inspection), and communicate the sensor data/control commands from/to an IoT cloud platform. Describe a solution to this problem: choose of hardware, protocols for different communication layers (Physical/MAC, routing, transport and application), sensing strategy, backend handling, and the cost of your solution. Also explicitly state all assumptions that you make. (page limit: 1 page)



Figure 1: Environmental Sustainability Report 2022, UNSW. (Slides 17, 18)

¹<https://www.sustainability.unsw.edu.au/unsw-joins-race-zero>, accessed on 10/06/2023

²<https://unfccc.int/climate-action/race-to-zero-campaign>, accessed on 10/06/2023

Question 2: Routing (3 marks)

Fig. 2 shows a network topology, where Node S is the source node and Node D is the destination node. A 0 to 1 number beside an arrow shows the link quality Packet Reception Rate (PRR) of an *asymmetric* wireless link; for example, the PRR from Node a to D is 0.9 (90%).

If the nodes run RPL that uses expected number of transmissions (ETX) as routing metric. What is the path between Nodes S and D ? What is the path ETX?

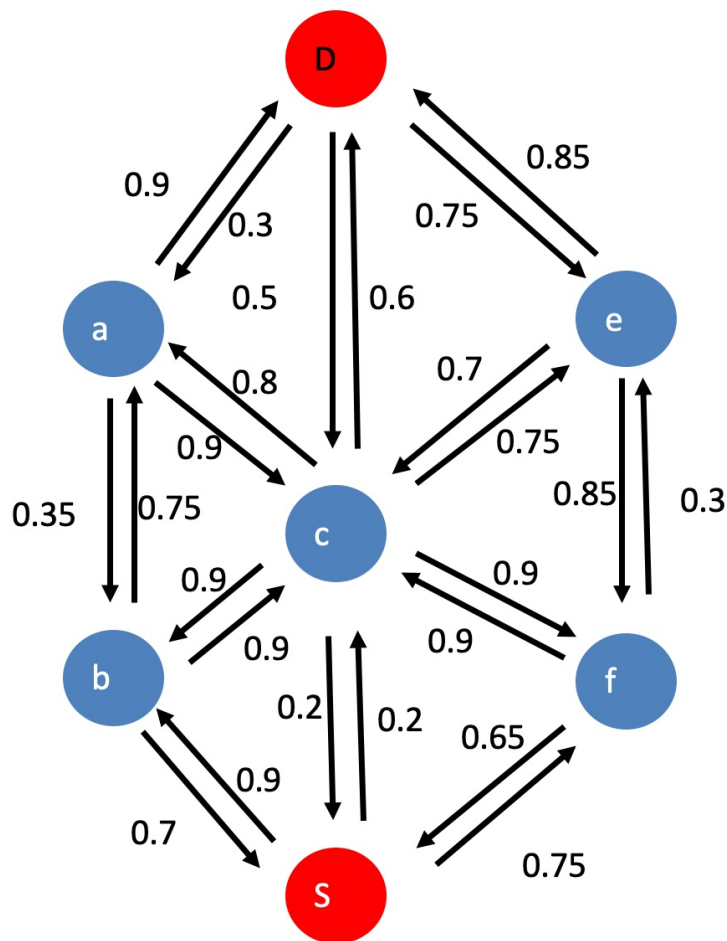


Figure 2: Figure for Question 2.

Question 3: Localisation (3 marks)

In this question, you will consider the problem of localising an IoT node (e.g., energy and water meters in Question 1 above during commissioning stage) using the time difference of arrival method.

We assume the nodes are located on the (x, y) -plane. There are three anchors (labelled as anchors 1, 2 and 3) located at $(40, 50)$, $(30, 25)$ and $(60, 30)$. (Note: co-ordinates are measured in metres.) The aim is to determine the location of the node X .

All the anchors and the IoT node X are equipped with an ultra-sonic sensor and a radio. Node X uses the ultra-sonic and radio signals to determine its distance from each anchor. The operation is as follows. The description here assumes that node X wants to measure its distance to an anchor A where $A = 1, 2$ or 3 . At a certain time $t_{A,0}$, the anchor emits an ultra-sonic pulse and send a radio packet, i.e. both the pulse and the packet leave the anchor at the same time at $t_{A,0}$. The sensor node X measures the arrival time $t_{A,u}$ of the ultra-sonic pulse at node X and the arrival time $t_{A,r}$ of the radio packet at node X . Note that node X does not know what $t_{A,0}$ is and the value of $t_{A,0}$ is not needed at all because the speed of the radio is approximately six orders of magnitude faster than the speed of sound (see below) and the radio's travel time assumed to be ignored. Table 1 summarises the arrival times (in seconds) measured by node X .

By using the data in Table 1, and the speed of radio propagation is $3 \times 10^8 \text{ ms}^{-1}$ and the speed of sound is 340 ms^{-1} , determine the location of the node X .

	$A = 1$	$A = 2$	$A = 3$
$t_{A,r}$	11.5	48.5	27.9
$t_{A,u}$	11.56	48.55	27.98

Table 1: Arrival time of the radio and ultra-sonic signals from the anchors to node X .