


Last course, review of key points:

core : def of stochastic integral.

$$\sum_{i=0}^n (B_{t_{i+1}} - B_{t_i})^2 \xrightarrow{L^2(\Omega)} b-a \quad \mathbb{P} = \{ \omega : t_0 < t_1, \dots < t_n = b \}$$

simple process. $G(t, \omega) := \sum_{i=1}^{n-1} e_i(\omega) \mathbf{1}_{[t_i, t_{i+1}]} + e_n(\omega) \mathbf{1}_{[t_n, t]}$

↑ Ito isometry. → dense.

progressively measurable process $\xrightarrow{\text{contain}}$ left, right continuous

Theorem 1.20 (Ito formula)

Ito process.

$$dX_t = u(s, \omega) dt + v(s, \omega) dB_s \quad \xrightarrow{(dt)^{\frac{1}{2}}} \text{diffusion}$$

$$X_t - X_0 = \int_0^t u(s, \omega) ds + \int_0^t v(s, \omega) dB_s$$

$$Y_t = g(t, X_t)$$

$$g(t, x) \in C^2([0, \infty), \mathbb{R})$$

$\frac{dt}{ds}$

$$dY_t = \frac{\partial g}{\partial t}(t, X_t) dt + \underline{\frac{\partial g}{\partial x}(t, X_t) dX_t} + \left(\frac{1}{2} \frac{\partial^2 g}{\partial x^2}(t, X_t) (dX_t)^2 \right)$$

$$(dX_t)^2 = dX_t \cdot dX_t = \langle X_t, X_t \rangle = v^2 \cdot dt + o(dt)$$

Example 1.21. Let's us turn to $I = \int_0^t B_s dB_s$
 check well-defined. since since

$$\mathcal{L}^2(0, T) = \left\{ g(t, w) \mid E\left[\int_0^T g(s, w) ds\right] < \infty \right\}$$

$$E\left[\int_0^T B^2(s, w) ds\right] = \int_0^T E[B^2(s, w)] ds = \int_0^T s ds = \frac{T^2}{2} < \infty.$$

$$\text{choose } X_t = B_t, g(t, x) = \frac{x^2}{2}, Y_t = \frac{X_t^2}{2} = \frac{B_t^2}{2}.$$

$$\begin{aligned} dY_t &= \frac{\partial g}{\partial t} dt + \frac{\partial g}{\partial x} dB_t + \frac{1}{2} \frac{\partial^2 g}{\partial x^2} (dB_t)^2 \\ &= \cancel{\frac{\partial g}{\partial t}} dt + \frac{\partial g}{\partial x} dB_t + \frac{1}{2} \cancel{\frac{\partial^2 g}{\partial x^2}} dt = B_t dB_t + \frac{1}{2} dt. \end{aligned}$$

$$\text{hence } \frac{1}{2} B_t^2 = \int_0^t B_s dB_s + \frac{1}{2} t.$$

$$I = \frac{1}{2} B_T^2 - \frac{1}{2} t.$$

Example 1.22. choose $X_t = B_t, g(t, x) = \underline{e^{\lambda x - \frac{\lambda^2 t}{2}}}$

$$\begin{aligned} Y_t &= g(t, X_t) \quad dY_t = \frac{\partial g(t, X_t)}{\partial t} dt + \frac{\partial g(t, X_t)}{\partial x} dX_t + \frac{1}{2} \frac{\partial^2 g(t, X_t)}{\partial x^2} \langle dX_t, dX_t \rangle \\ &= -\frac{\lambda}{2} e^{\lambda B_t - \frac{\lambda^2 t}{2}} dt + \lambda e^{\lambda B_t - \frac{\lambda^2 t}{2}} \cancel{\frac{1}{2} \lambda^2 e^{\lambda B_t - \frac{\lambda^2 t}{2}}} dt \end{aligned}$$

solves

$$dY_t = \lambda Y_t dB_t.$$

$$\left| \begin{array}{l} \int_0^t dY_t = \lambda Y_t dB_t \\ Y(0) = 1 \end{array} \right. \longleftrightarrow Y_t = \underline{e^{\lambda B_t - \frac{\lambda^2 t}{2}}}$$

Example 1.23 $d(t^t B_t) = B_t dt + t dB_t \leftrightarrow \text{check.}$

Lemma 1.24. Let X and Y are Itô process, then $X+Y_t$ is a Itô process and.

$$X_t Y_t - X_0 Y_0 = \int_0^t X_s dY_s + \int_0^t Y_s dX_s + \underline{\langle X, Y \rangle_t}.$$

(Rmk 1. example 1.23 is a special case of Lemma 1.24)
 $\langle t, B_t \rangle = 0$, $\langle B_t, B_t \rangle = t$.

$$d(X_t Y_t) = X_t dY_t + Y_t dX_t + \underline{d\langle X, Y \rangle_t}.$$

Rmk 2. For independent B.M., B^2 and B^3

$$\langle B^2, B^3 \rangle = 0 \quad \text{and} \quad \langle B^2, B^2 \rangle = t.$$

Theorem 1.25 (Itô). Let $X = (X_1, \dots, X_d)$ where X_t^i ($1 \leq i \leq d$) are Itô process and $f \in C^2(\mathbb{R}^d)$. Then

$$\begin{aligned} f(X_t) - f(X_0) &= \sum_{i=1}^d \int_0^t \frac{\partial f}{\partial x_i}(X_s) dX_s^i \quad f(x, y) = x \cdot y \\ &\quad + \frac{1}{2} \sum_{i,j=1}^d \int_0^t \frac{\partial^2 f}{\partial x_i \partial x_j}(X_s) d\langle X^i, X^j \rangle_s \end{aligned}$$

Rmk 3. For $f \in C^2(\mathbb{R}^d)$, $\frac{\partial f}{\partial x_i x_j} = \frac{\partial^2 f}{\partial x_j \partial x_i}$.

Proof: we only consider $d=1$.

Step 1. consider $f(x) = x^n$.

Induction with Lemma 1.24

Step 2. $\forall f \in C^2(\mathbb{R})$, $|x| \leq a$, can be approximated

by polynomial sequence $\{f_n\}$. s.t. f_n, f'_n, f''_n

uniformly converge to f, f', f'' on $[-a, a]$.

Step 3. Localization skill.

§2. Stochastic Differential Equation

§2.1 Linear SDEs

In this section we study the following linear SDEs

$$X_t = \eta + \int_0^t [b_s X_s + b_s^\circ] ds + \int_0^t [\sigma_s X_s + \sigma_s^\circ] dB_s, \quad 0 \leq t \leq T.$$

$(\int_0^t f(s) dg(s)) \hookrightarrow g \in B.V. \quad B.M. \in B.V. \quad X_0 = \eta$

introduce the adjoint process

$$\Gamma_0 = 1$$

$$\begin{aligned} \Gamma_t &= \exp(\int_0^t \beta_s dB_s + \int_0^t [\alpha_s - \frac{1}{2} |\beta_s|^2] ds) \rightarrow \text{known}, \\ \frac{d\Gamma_t}{\Gamma_t} &= [\alpha_t - \frac{1}{2} |\beta_t|^2] dt + \beta_t dB_t + \frac{1}{2} \cancel{\beta_t \beta_t^*} dt. \end{aligned}$$

$$= \alpha_t dt + \beta_t dB_t.$$

$$\Rightarrow d\Gamma_t = \Gamma_t [\alpha_t dt + \beta_t dB_t]. \quad \Gamma_0 = 0 \quad (*)$$

$$\underline{d(\Gamma_t X_t)} \stackrel{It\ddot{o}}{=} \Gamma_t dX_t + X_t d\Gamma_t + d<\Gamma_t, X_t>$$

$$= \Gamma_t [\cancel{b_t X_t} + \cancel{b_t^\circ} + \cancel{\alpha_t X_t} + \cancel{\beta_t [\sigma_t X_t + \sigma_t^\circ]}] dt$$

$$+ \Gamma_t [\cancel{\sigma_t X_t} + \cancel{\sigma_t^\circ} + \cancel{\beta_t X_t}] dB_t$$

$$\text{set } \beta = -\sigma^\top \quad \alpha = -b^\top + (\sigma^\top)^2$$

$$\Rightarrow d(\Gamma_t X_t) = \Gamma_t [-b_t^\circ - \sigma_t^\top \sigma_t^\top] dt + \Gamma_t \sigma_t^\circ dB_t.$$

$$\Gamma_t X_t - \Gamma_0 \eta = \int_0^t (*) ds + \int_0^t \square dB_s$$

$$X_t = \Gamma_t^{-1} [\eta + \int_0^t \Gamma_s [b_s^\circ - \sigma_s^\top \sigma_s^\top] ds + \int_0^t \Gamma_s \cdot \sigma_s^\circ dB_s]. \quad \square$$

§ 2.2. An Existence and uniqueness Result.

We now turn to general case.

$$X_t = X_0 + \int_0^t b(s, X_s) ds + \int_0^t \sigma(s, X_s) dB_s \in \mathbb{R}^n$$

or

$$\int dX_t = b(t, X_t) dt + \underline{\sigma(t, X_t) dB_t}$$

$$| X_t |_{t=0} = X_0$$

Theorem 2.1. Let $T > 0$ and $b(\cdot, \cdot) : [0, T] \times \mathbb{R}^n \rightarrow \mathbb{R}^n$

$\sigma(\cdot, \cdot) : [0, T] \times \mathbb{R}^n \rightarrow \mathbb{R}^{n \times n}$ be measurable satisfying.

$$|b(t, x)| + |\sigma(t, x)| \leq C(1+|x|), \quad x \in \mathbb{R}^n, t \in [0, T]. \quad \textcircled{1}$$

$$\text{and } |b(t, x) - b(t, y)| + |\sigma(t, x) - \sigma(t, y)| \leq D|x-y| \quad \textcircled{2}$$

$$\textcircled{2} + |b(t, 0) + \sigma(t, 0)| < c \Rightarrow \textcircled{1}$$

Let $Z \in L^2(\Omega)$, the the SDEs

$$\begin{cases} dX_t = b(t, X_t) dt + \sigma(t, X_t) dB_t \\ X_0 = Z \end{cases}$$

has a unique continuous solution $X_t(\omega)$. s.t.

$$\mathbb{E} \left[\int_0^T |X_t|^2 dt \right] < \infty, \quad X_t \in \mathcal{F}_t = \sigma(B_s : s \leq t)$$

Rmk: a) if $\sigma = 0$. $dX_t = b(t, X_t) dt$, $X_0 = x_0 \rightarrow \text{r.v.}$
 $dX_{t(w)} = b(t, X_{t(w)}) dt$.
 $X_0(w) = x_0 \downarrow$
 $dX_t = A X_t dt \Rightarrow X_t = x_0 \cdot e^{At} \in \mathcal{F}_0 \subset \mathcal{F}_t$.

b) The equation

$$\begin{cases} \frac{dX_t}{dt} = X_t^2 \\ X_0 = 1 \end{cases}$$
 corresponding to $b(x) = x^2$ has the solution $X_t = \frac{1}{1-t}$, $0 \leq t < 1$.
thus it's impossible to find a global solution.

c) The equation

$$\begin{cases} \frac{dX_t}{dt} = 3X_t^{\frac{2}{3}} \\ X_0 = 0 \end{cases}$$
 has more than one solution.
In fact. $b = 3X_t^{\frac{2}{3}}$
 $X_t = \begin{cases} 0 & t \leq a \\ (t-a)^3 & t > a \end{cases}$

Proof of Thm 2.1.

Uniqueness. Consider the following two SDEs

$$\begin{cases} dX_t = b(t, X_t) dt + \sigma(t, X_t) dB_t \\ X_0 = z \end{cases}$$

$$\begin{cases} d\hat{X}_t = b(t, \hat{X}_t) dt + \sigma(t, \hat{X}_t) dB_t \\ \hat{X}_0 = \hat{z}, \quad (\hat{z} = z) \end{cases}$$

$$\text{Put } a(s, w) = b(s, X_s) - b(s, \hat{X}_s), \quad |a(s, w)| \leq D |X_s - \hat{X}_s|$$

$$r(s, w) = \sigma(s, X_s) - \sigma(s, \hat{X}_s). \quad |r(s, w)| \leq D |X_s - \hat{X}_s|$$

$$X_t - \hat{X}_t = z - \hat{z} + \int_0^t a(s, w) ds + \int_0^t r(s, w) dB_s.$$

$$\underline{\mathbb{E}[|X_t - \hat{X}_t|^2]} = \mathbb{E}[|z - \hat{z} + \int_0^t a(s, w) ds + \int_0^t r(s, w) dB_s|^2]$$

$$\leq 3 \underline{\mathbb{E}[|z - \hat{z}|^2]} + 3 \mathbb{E}[(\int_0^t a(s, w) ds)^2] + 3 \mathbb{E}[(\int_0^t r(s, w) dB_s)^2]$$

$$\leq 3 \mathbb{E}[|z - \hat{z}|^2] + 3 \mathbb{E}[\int_0^t |a(s, w)|^2 ds]. \quad \uparrow \text{Itô}$$

$$+ 3 \mathbb{E}[\int_0^t r(s, w)^2 ds]$$

$$\leq 3 \mathbb{E}[|z - \hat{z}|^2] + 3 t D^2 \mathbb{E}[\int_0^t |X_s - \hat{X}_s|^2 ds]$$

$$+ 3 D^2 \mathbb{E}[\int_0^t |X_s - \hat{X}_s|^2 ds]$$

$$= 3 \mathbb{E}[|z - \hat{z}|^2] + 3(t+1)D^2 \int_0^t \underline{\mathbb{E}[|X_s - \hat{X}_s|^2]} ds.$$

$$\text{set } V(t) = \mathbb{E}[\cdot | X_t - \hat{X}_t|^2] \quad 0 \leq t \leq T$$

$$V(t) \leq E + A \int_0^t V(s) ds$$

By the Gronwall ineq. if $\exists = \hat{\Sigma}$ a.e. $\Rightarrow X_t = \hat{X}_t$ a.e.

Existence.

we define $\bar{Y}_t^\circ = X_0$ where

$$Y_t^{(k+1)} = X_0 + \int_0^t b(s, Y_s^{(k)}) ds + \int_0^t \sigma(s, Y_s^{(k)}) dB_s \quad (\ast)$$

similarly

$$\mathbb{E}[|Y_t^{(k+1)} - Y_t^{(k)}|^2] \leq C(1+T)D^2 \int_0^T \mathbb{E}[|Y_s^{(k)} - Y_s^{(k-1)}|^2] ds$$

and $\mathbb{E}[|Y_t^{(1)} - Y_t^\circ|^2] \leq At$.

by induction

$$\mathbb{E}[|Y_t^{(k+1)} - Y_t^{(k)}|^2] \leq \frac{A^{k+1} t^{k+1}}{(k+1)!} \quad 0 \leq t \leq T$$

therefore. $\{Y_t^{(n)}\}$ is a Cauchy sequence in $L^2([0, T])$.

For (\ast) . let $k \rightarrow \infty$, we conclude.

$$X_t = X_0 + \int_0^t b(s, X_s) ds + \int_0^t \sigma(s, X_s) dB_s \quad \text{a.s.}$$

Thm 2.2. For any $\vec{\gamma} \in L^2(\mathbb{R}, \mathbb{R}^n)$, we have.

$$\mathbb{E} \left[\max_{0 \leq s \leq T} |X_s|^2 \right] \leq K_T (1 + \mathbb{E} |\vec{\gamma}|^2) \quad 0 \leq t \leq T$$

$$\text{and } \mathbb{E} |X(t) - X(s)|^t \leq K_T (1 + \mathbb{E} |\vec{\gamma}|^t) |t-s|^{\frac{t}{2}} \quad (t \geq 1).$$

Moreover if $\vec{\gamma} \in L^2_{\text{loc}}(\mathbb{R}, \mathbb{R}^n)$ $|t-s|^{\frac{t}{2}} \gg |t-s|^t$

$\hat{X}(t)$ is the corresponding solution, we have.

$$\mathbb{E} \max_{0 \leq s \leq t} |X(s) - \hat{X}(s)|^2 \leq K_T |\vec{\gamma} - \hat{\vec{\gamma}}|^2.$$

Example 2.3 (Langevin equation)

$$dX_t = \alpha dB_t - \beta \underline{X_t dt}$$

$$d(e^{\beta t} X_t) = e^{\beta t} dX_t + \beta e^{\beta t} X_t dt = \alpha e^{\beta t} dB_t.$$

$$e^{\beta t} X_t - X_0 = \alpha \int_0^t e^{\beta s} dB_s$$

$$X_t = e^{-\beta t} X_0 + \alpha e^{-\beta t} \int_0^t e^{\beta s} dB_s$$

Example 2.4. (Geometric B.M.).

Black-Scholes-Merton
1997 Nobel prize.

Consider Black-Scholes equation.

$$dX_t = bX_t dt + \sigma X_t dB_t$$

where b, σ are constant.

$$d(\ln X_t) = \frac{dX_t}{X_t} - \frac{1}{2X_t^2} d\langle X_t, X_t \rangle$$

$$= b dt + \sigma dB_t - \frac{\sigma^2 X_t^2}{2X_t^2} dt.$$

$$= (b - \frac{\sigma^2}{2}) dt + \sigma dB_t.$$

$$\ln X_t - \ln X_0 = (b - \frac{\sigma^2}{2}) t + \sigma B_t$$

$$X_t = X_0 e^{[(b - \frac{\sigma^2}{2}) t + \sigma B_t]}$$