

02810: INTRODUCTION TO ARTIFICIAL INTELLIGENCE

LECTURE 5: ADVERSARIAL SEARCH

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EXAMPLES OF GAMES

Every day examples of interactions:

- ▶ Driving in traffic.
- ▶ Bargain-hunting auctioning.
- ▶ Governmental elections.

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Game theory 'works' when agents behave **rationally**.

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Initially developed for competitive scenarios, later extended to cooperative ones.

Game theory is a sort of umbrella or 'unified field' theory for the rational side of social science, where 'social' is interpreted broadly, to include human as well as non-human players (computers, animals, plants).

(Aumann 1987)

A GAME

A **game** is a description of a situation of interaction of two or more agents.

It includes:

- ▶ the players;
- ▶ the actions that players can take;
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A **strategic game** is a game in which players involved make one decision each, and make it independently.

TOY GAMES: MATCHING PENNIES

- ▶ Two players: Alice and Bob.
- ▶ Both show a coin.
- ▶ Bob wins if they show different faces.
- ▶ Alice wins if they show the same.
- ▶ they each have two strategies: *heads* and *tails*.
- ▶ All possible strategy combinations give payoffs for each player.

TOY GAMES: MATCHING PENNIES (CONFLICT)

Alice	heads	tails
heads	+	-
tails	-	+

Bob	heads	tails
heads	-	+
tails	+	-

TOY GAMES: MATCHING PENNIES (CONFLICT)

Alice	heads	tails
heads	+	-
tails	-	+

Bob	heads	tails
heads	-	+
tails	+	-

Together:

	heads	tails
heads	(+, -)	(-, +)
tails	(-, +)	(+, -)

TOY GAMES: DRIVING GAME (COOPERATION)

Alice	left	right
left	+	-
right	-	+

Bob	left	right
left	+	-
right	-	+

TOY GAMES: DRIVING GAME (COOPERATION)

Alice	left	right
left	+	-
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Bob	left	right
left	+	-
right	-	+

Together:

	left	right
left	(+,+)	(-,-)
right	(-,-)	(+,+)

NUMERICAL PAYOFFS

	heads	tails
heads	(1,-1)	(-1,1)
tails	(-1,1)	(1,-1)

	left	right
left	(1,1)	(-1,-1)
right	(-1,-1)	(1,1)

TABLE: Matching Pennies and Driving Game with payoffs -1 and 1

Any numbers as long as winning > losing.

ZERO-SUM GAMES

Recall Matching Pennies game:

	heads	tails
heads	$(1,-1)$	$(-1,1)$
tails	$(-1,1)$	$(1,-1)$

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Payoffs in each cell sum up to 0.
This can be always done for games with pure conflict.

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The focus on **zero-sum**, **turn-based games**, e.g., Chess or Go.

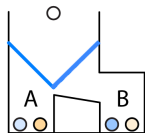
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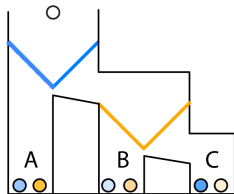
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The games of interest are often also **perfect-information** games.

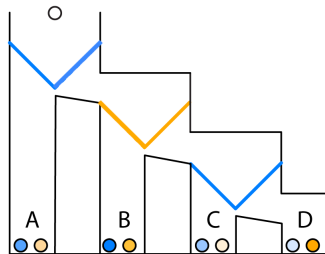
TURN-BASED GAMES: MARBLE DROP GAME



(a)



(b)

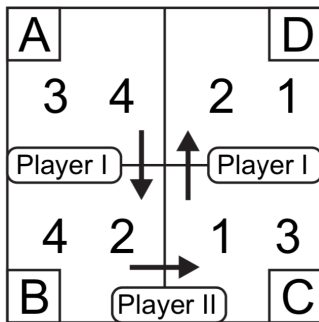


(c)

TURN-BASED GAMES: MATRIX GAME

There is one token in the game. It starts being at A. Player I can decide to *move* it to B or let it *stay* in A. If it is moved to B, player II can afterwards *move* it to C or let it *stay* in B. If it is moved to C, player I can *move* it to D or let it *stay* in C. The game ends when a player decides to *stay* or the token ends up in D.

The utility (payoff) of player I and II are the, respectively, left and right numbers in the cell that the token ends up in.



MORE MATRIX GAMES: EXERCISE

A			D
2	1	1	3
Player I	↓	↑	Player I
4	2	3	4
B	Player II		C

A			D
2	1	3	4
Player I	↓	↑	Player I
4	3	1	2
B	Player II		C

SEARCH PROBLEMS FORMALLY

So far, search problems were defined by:

- ▶ **Initial state.**
- ▶ $\text{ACTIONS}(s)$: **possible actions.**
- ▶ $\text{RESULT}(s, a)$: **transition model.**
- ▶ **Goal test.**

That induces a **state space** in which we search for a goal state.

GAME PROBLEMS FORMALLY

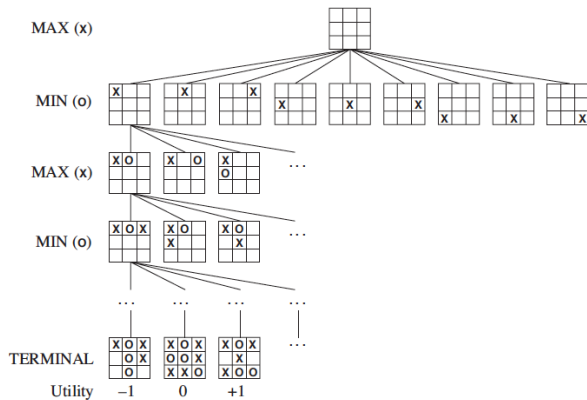
Similarly, games can be described by:

- ▶ s_0 : **initial state**.
- ▶ $\text{PLAYER}(s)$: who has the move in s .
- ▶ $\text{ACTIONS}(s)$: Legal moves in s .
- ▶ $\text{RESULT}(s, a)$: **transition model**.
- ▶ $\text{TERMINAL-TEST}(s)$: **terminal test**. Is the game over?
- ▶ $\text{UTILITY}(s, p)$: **utility function** (or **payoff function**).

Numerical value for player p in terminal state s .

Example: +1 for win and -1 for loose (zero-sum).

TIC-TAC-TOE: GAME TREE EXAMPLE



MINIMAX

- ▶ There are two players: MAX and MIN.
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- ▶ Nodes assigned values representing expected utility for MAX.

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$$\text{MINIMAX}(s) = \begin{cases} \text{UTILITY}(s, \text{MAX}) & \text{if } \text{TERMINAL-TEST}(s) \\ \max_{a \in \text{ACTIONS}(s)} \text{MINIMAX}(\text{RESULT}(s, a)) & \text{if } \text{PLAYER}(s) = \text{MAX} \\ \min_{a \in \text{ACTIONS}(s)} \text{MINIMAX}(\text{RESULT}(s, a)) & \text{if } \text{PLAYER}(s) = \text{MIN} \end{cases}$$

In a state s with $\text{PLAYER}(s) = \text{MAX}$, the following move is optimal for MAX:

$$\text{argmax}_{a \in \text{ACTIONS}(s)} \text{MINIMAX}(s).$$

That is, MAX chooses the move that maximises the minimax value.

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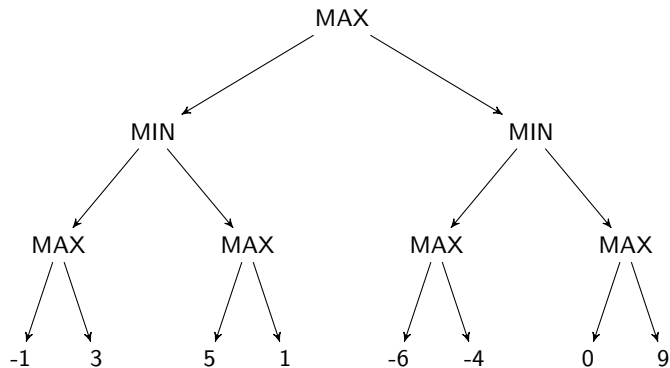
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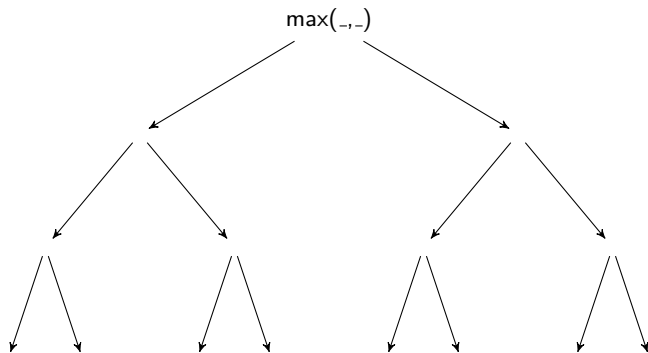
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Is MINIMAX a breadth- or a depth-first search?

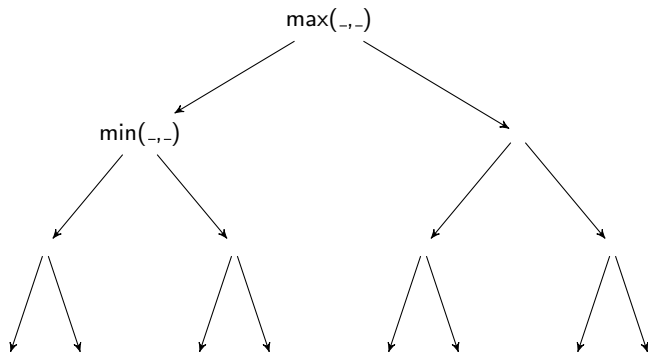
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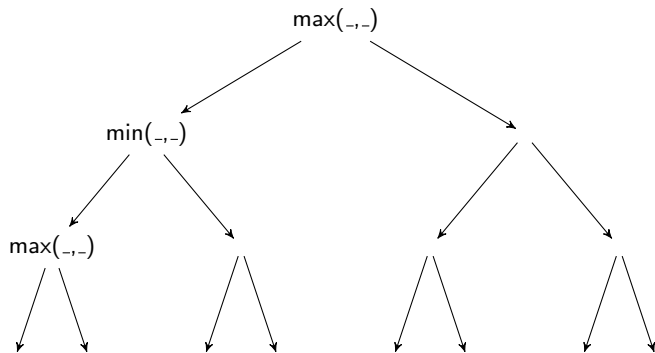
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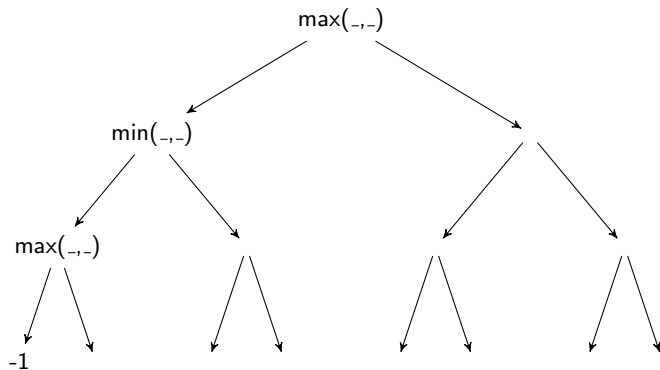
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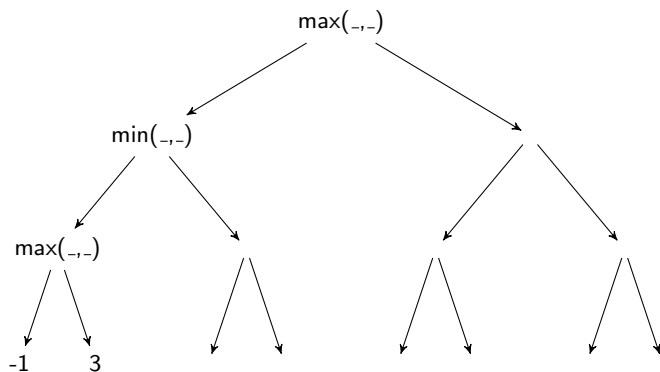
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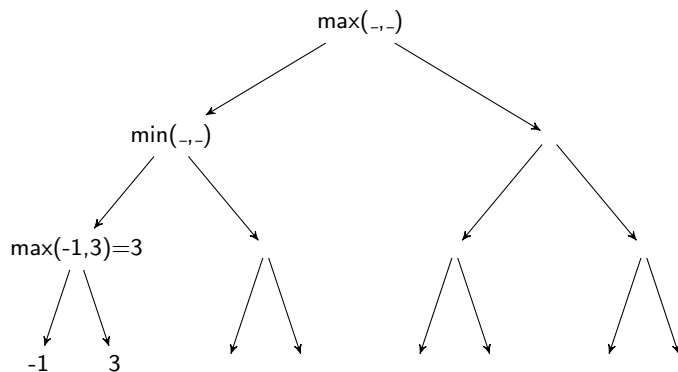
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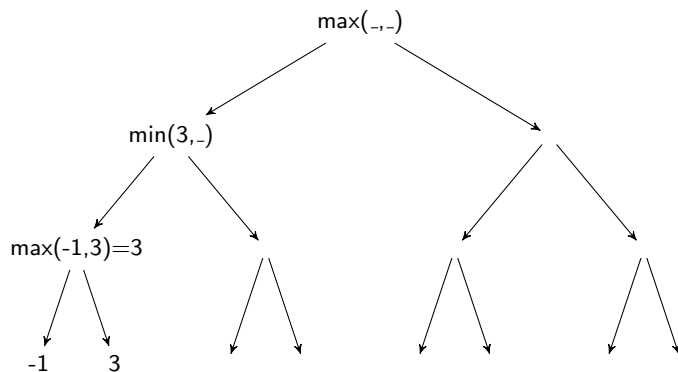
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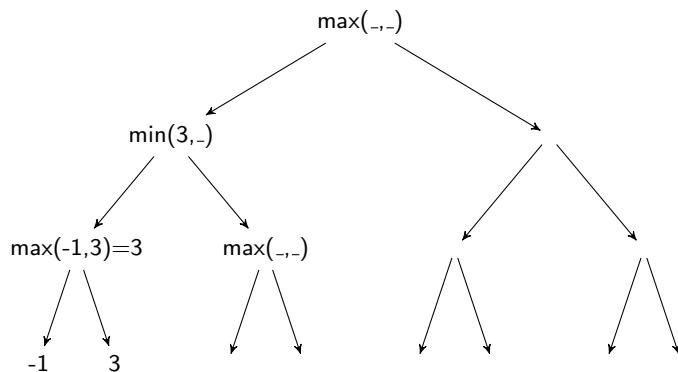
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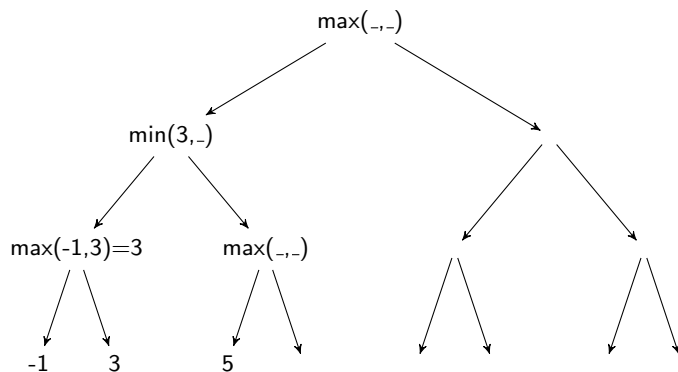
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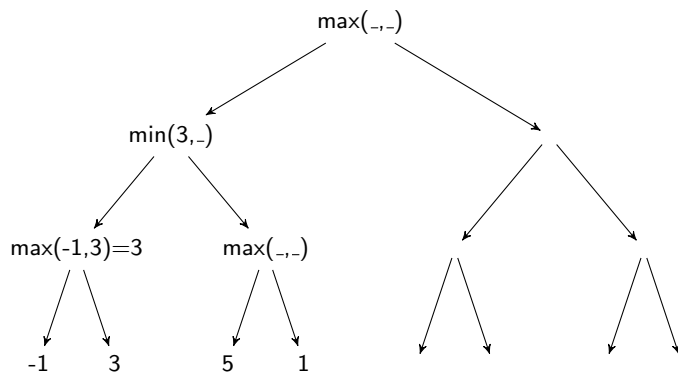
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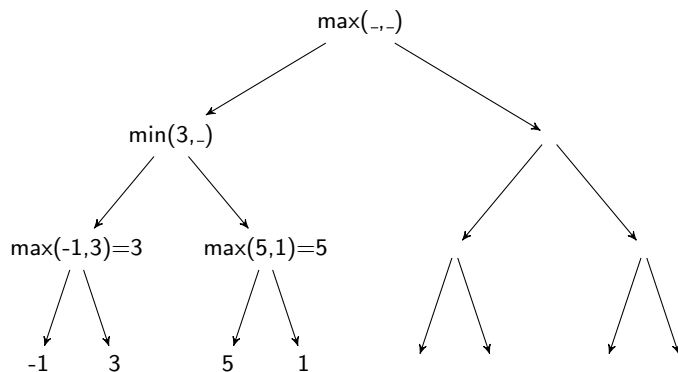
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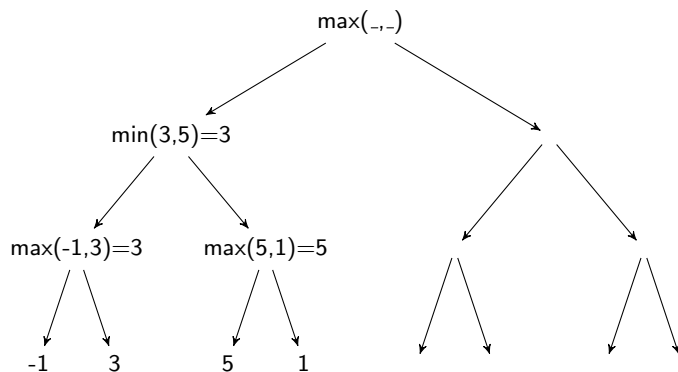
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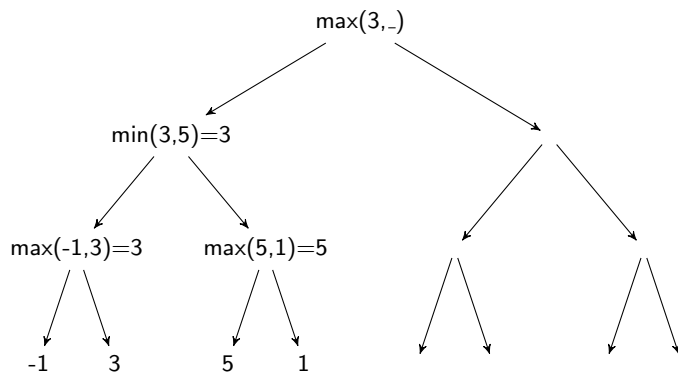
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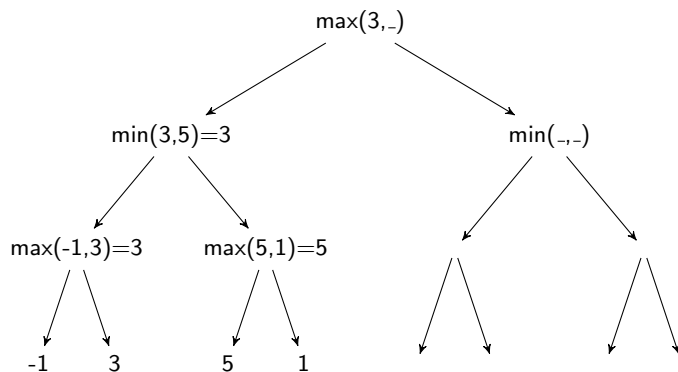
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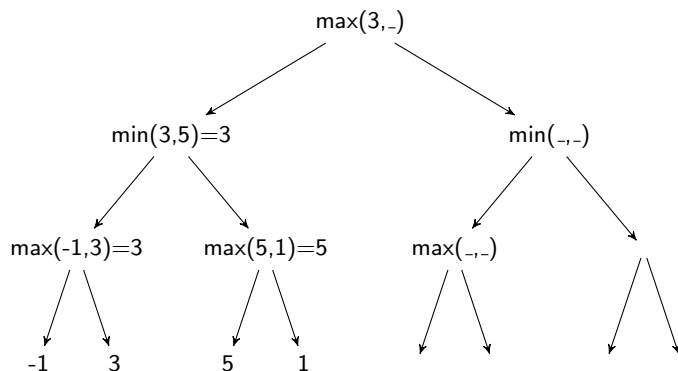
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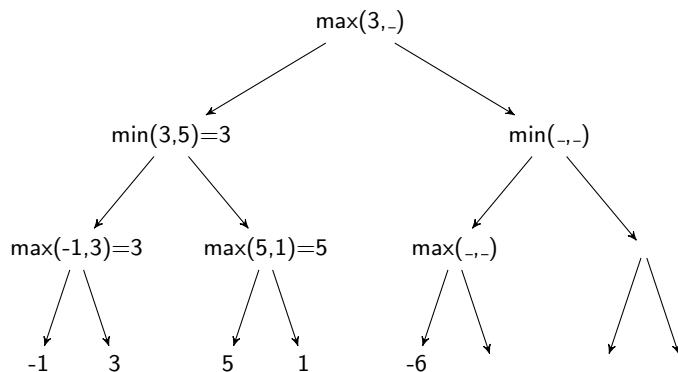
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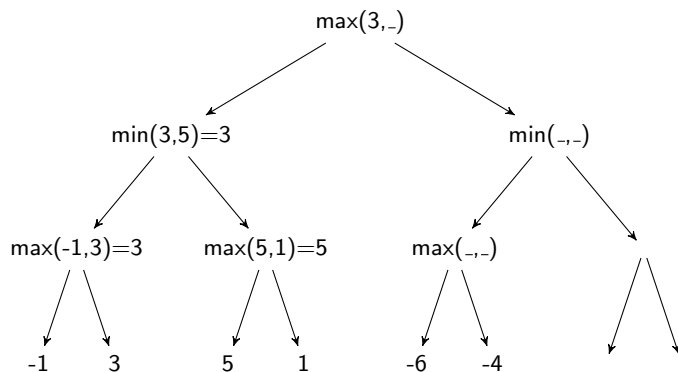
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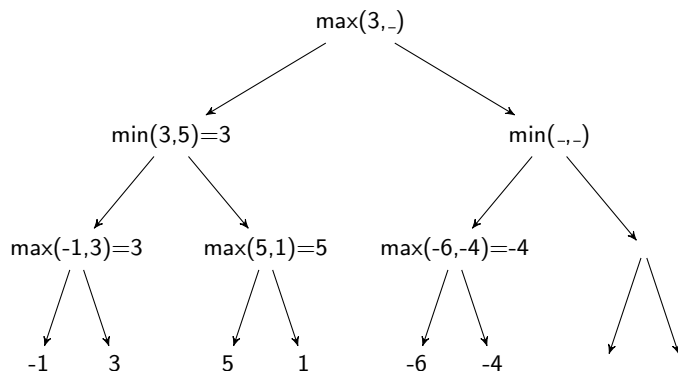
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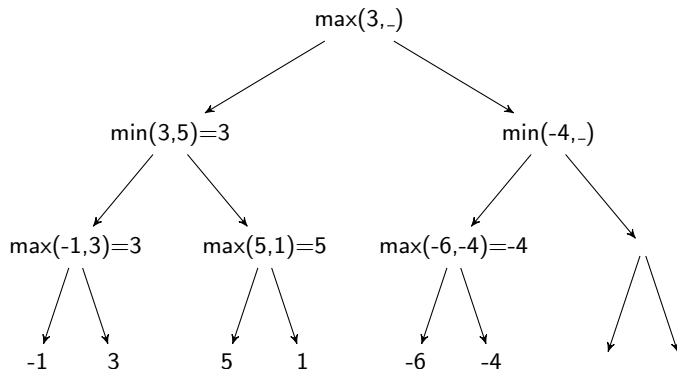
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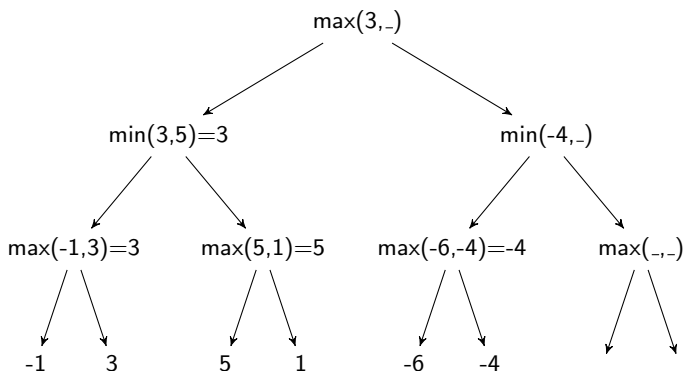
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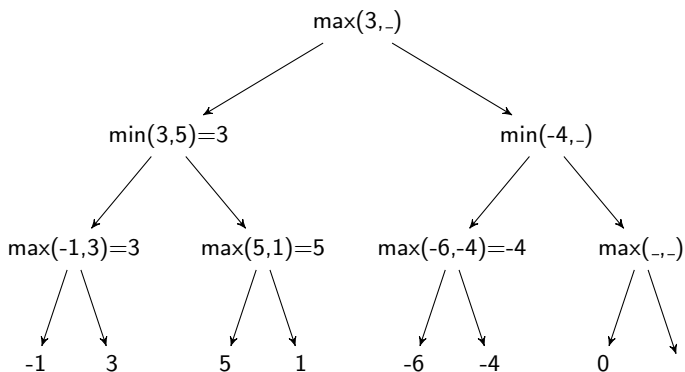
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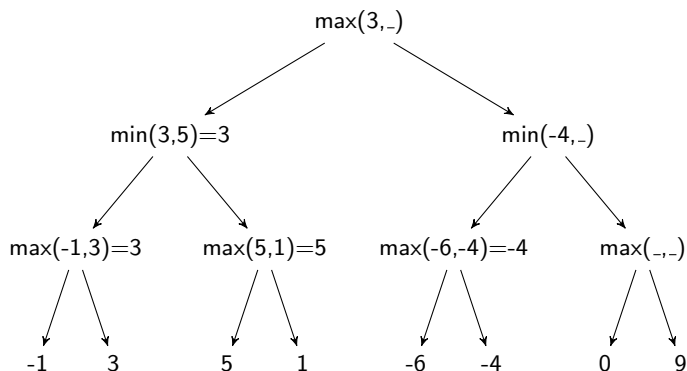
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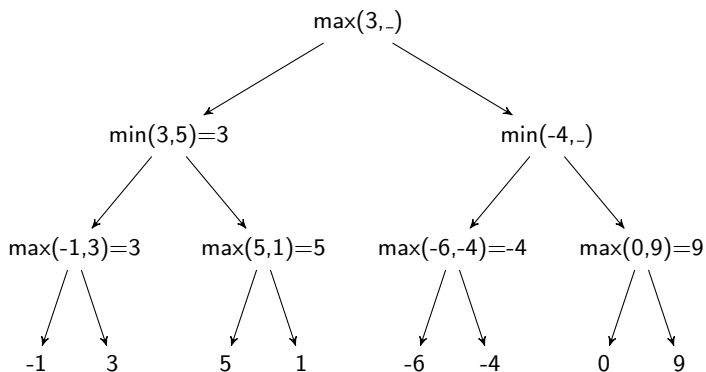
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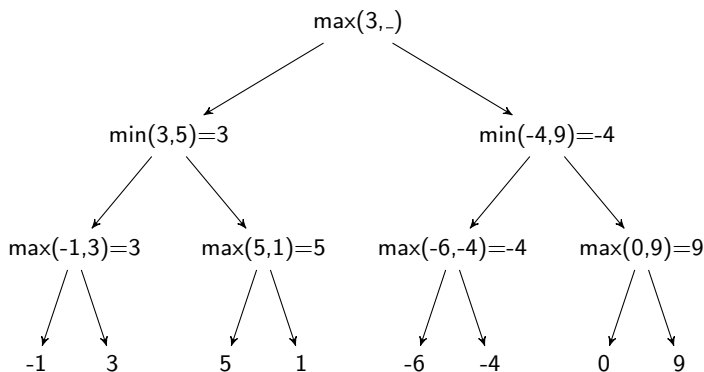
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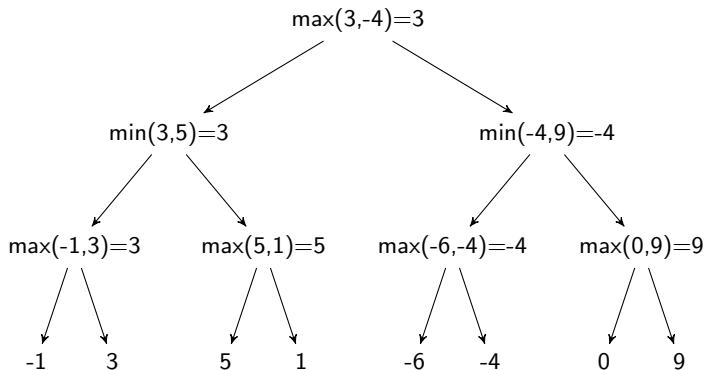
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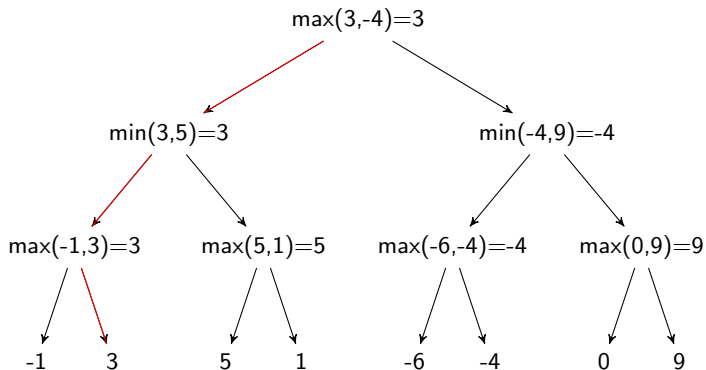
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ALPHA-BETA PRUNING

Alpha-beta pruning can make the game tree smaller while still guaranteeing optimal strategies.

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Alpha-beta pruning can make the game tree smaller while still guaranteeing optimal strategies.

The recursive MINIMAX algorithm **passes down** an α and β value to each node:

- ▶ α : **lower bound** on what MAX can achieve when playing through the choice points leading to the current node.
- ▶ β : **upper bound** on what MIN can achieve when playing through the choice points leading to the current node.

The root node has $\alpha = -\infty$ and $\beta = \infty$.

ALPHA-BETA PRUNING

Additionally, the algorithm iteratively updates the value v of each node.
Initially $v = -\infty$ for MAX nodes and $v = \infty$ for MIN nodes.

- ▶ **Alpha-cut:** If $v \leq \alpha$ in a MIN node, we can prune further search below that node: MAX has a better choice at a previous choice point.
- ▶ **Beta-cut:** If $v \geq \beta$ in a MAX node, we can prune further search below that node: MIN has a better choice at a previous choice point.

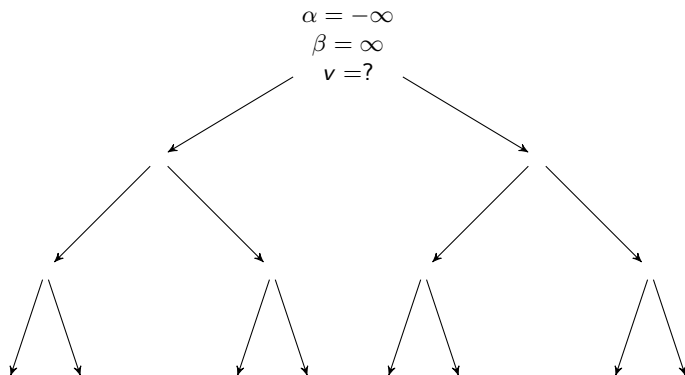
ALPHA-BETA PRUNING

α -values concern the choice of MAX, β -values concern the choice of MIN.

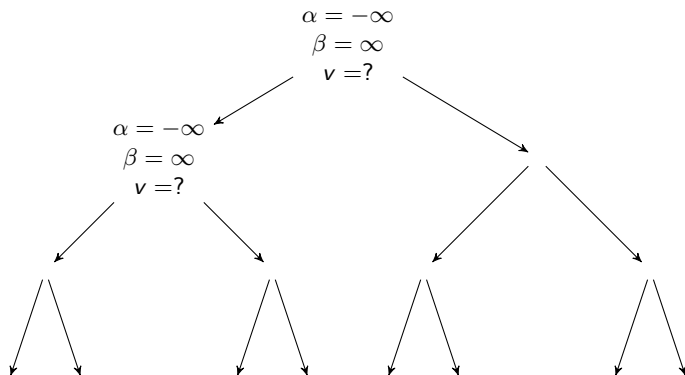
ALPHA-BETA-SEARCH algorithm (see pseudocode in R&N):

- ▶ MAX nodes passes α values down:
the max of the α - and v -values of the parent.
- ▶ MIN nodes passes β values down:
the min of the β and v -values of the parent.

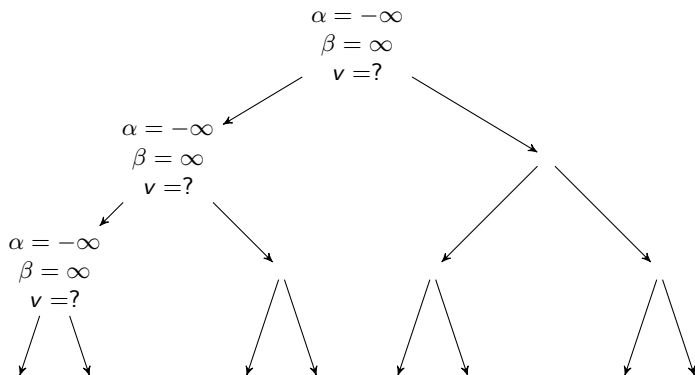
ALPHA-BETA PRUNING: AN EXAMPLE



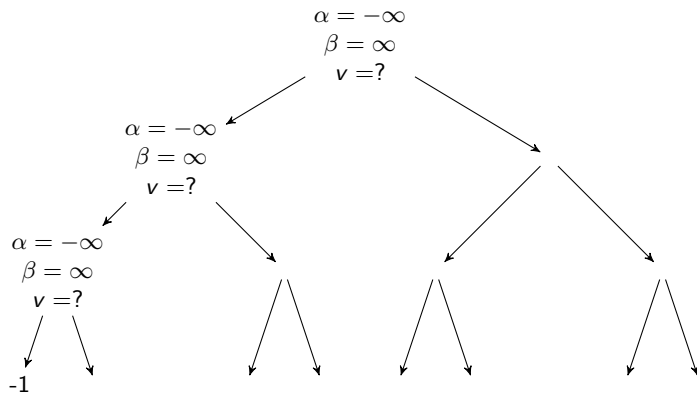
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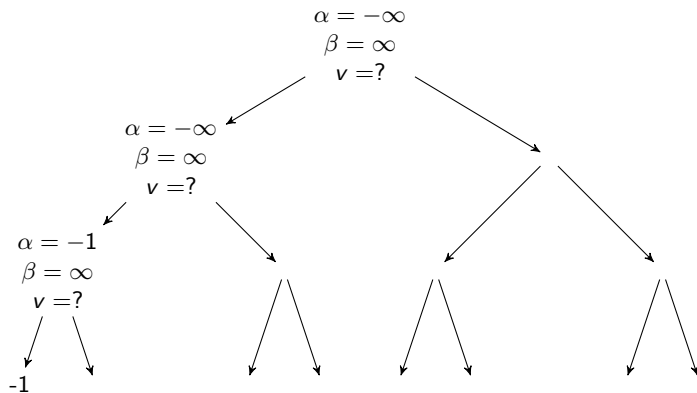
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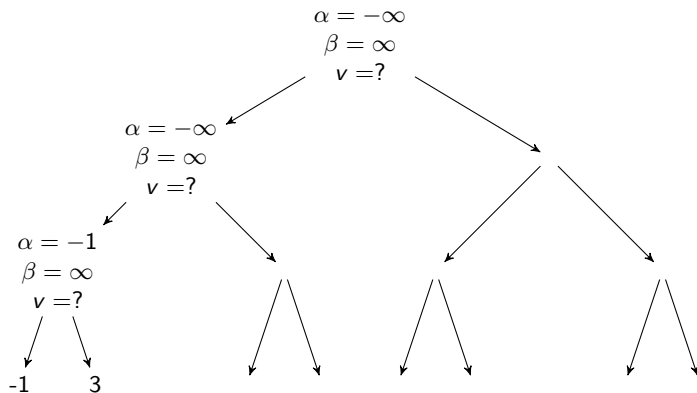
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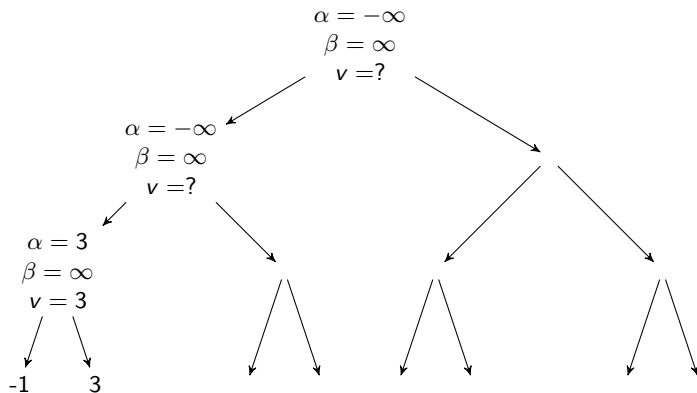
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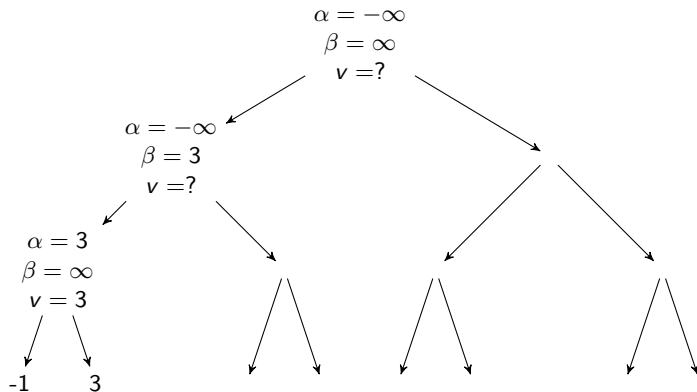
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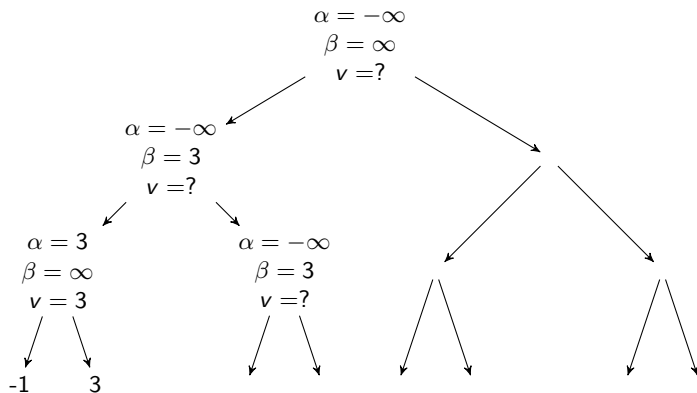
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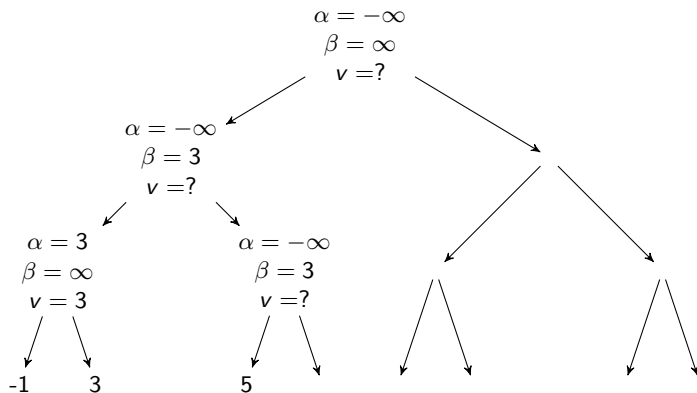
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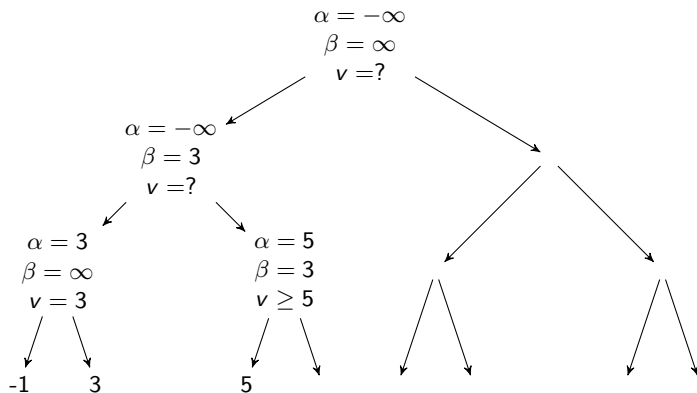
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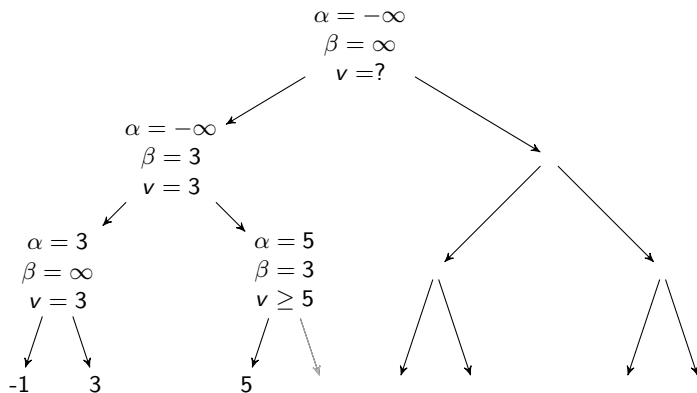
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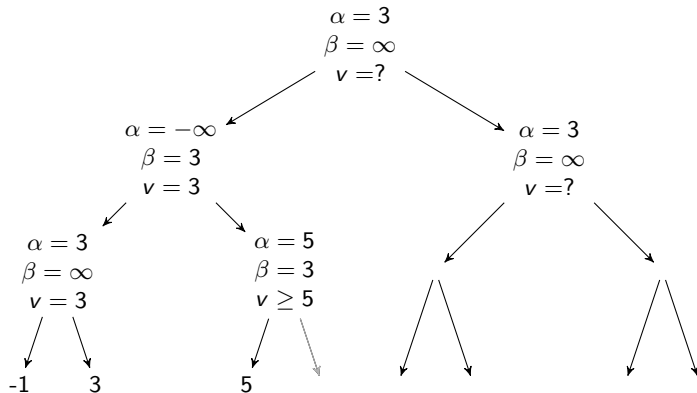
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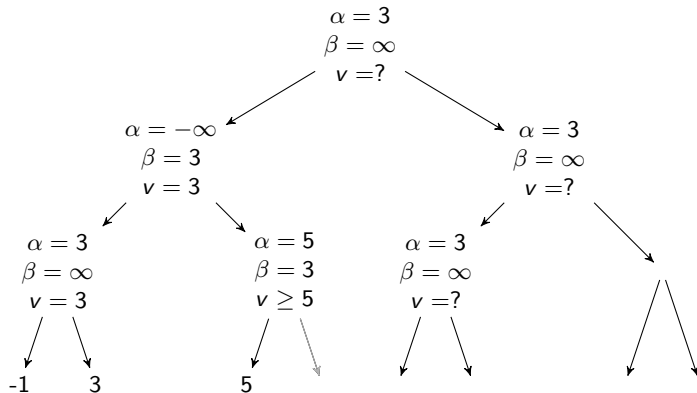
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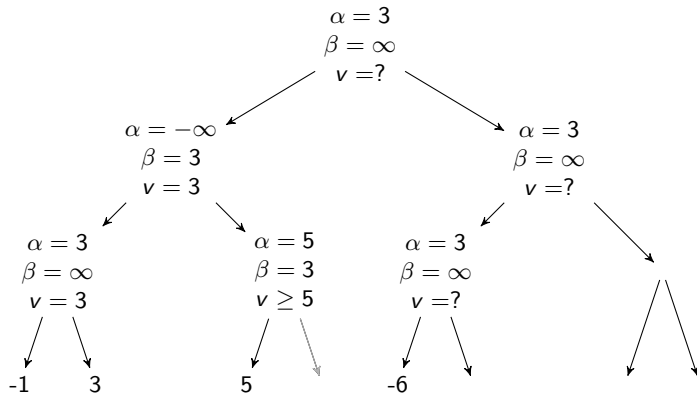
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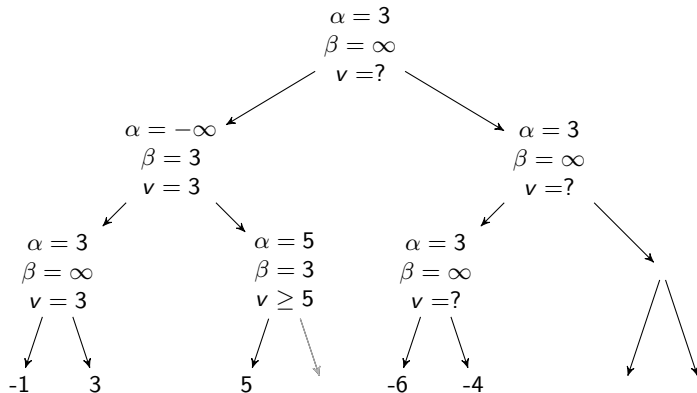
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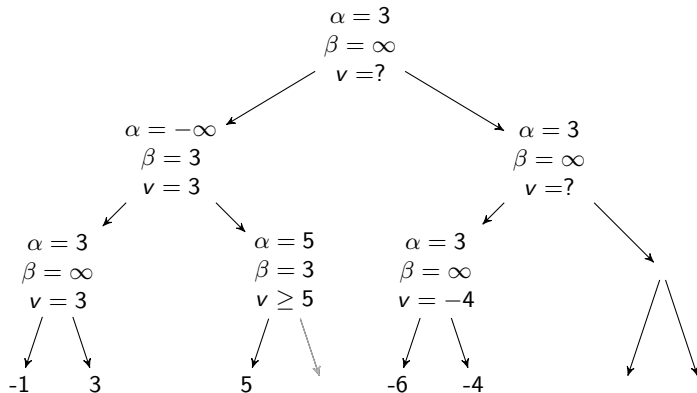
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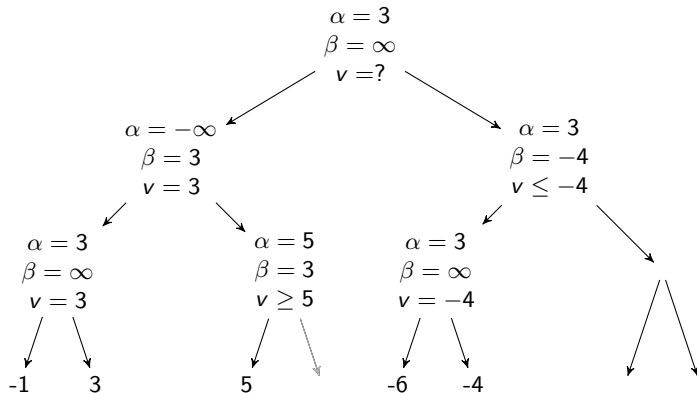
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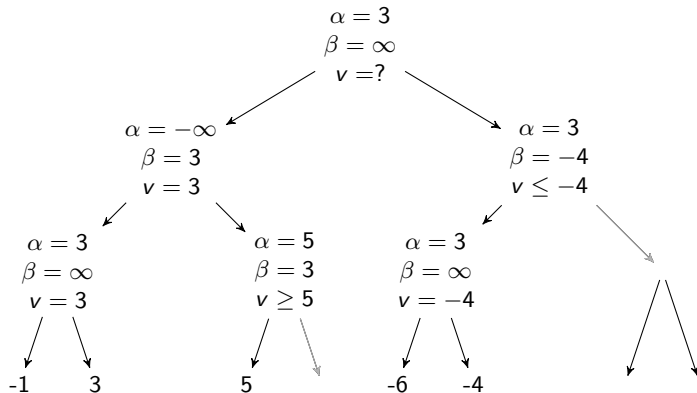
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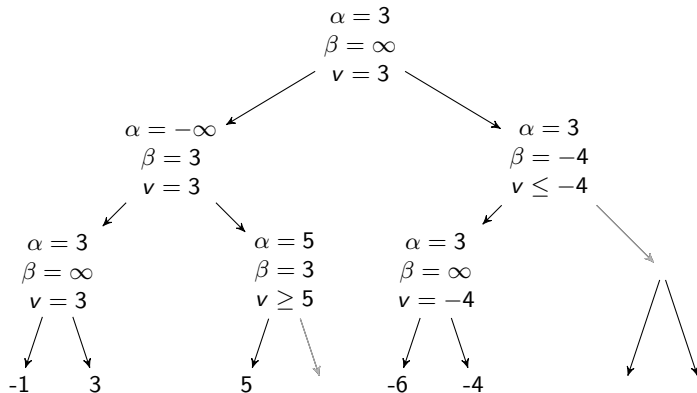
ALPHA-BETA PRUNING: AN EXAMPLE



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WHEN SEARCHING TO THE END IS NOT POSSIBLE

- ▶ Use CUTOFF-TEST(s) instead of TERMINAL-TEST(s). E.g. limit by depth (search only to depth 5).
- ▶ Use EVAL(s, p) instead of UTILITY(s, p). This is called an **evaluation function**.

EVAL(s, p): How desirable is state s for player p ?

E.g. an estimate of the chance of winning or the expected utility.

Expected utility. If 20% chance of getting utility 5 and 80% chance of getting utility 2, expected utility is $0.2 * 5 + 0.8 * 2 = 2.6$.

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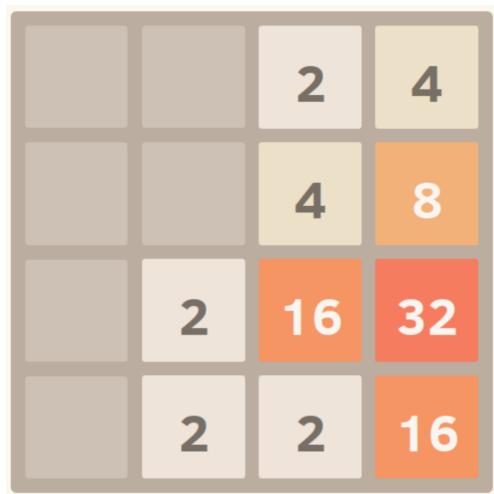
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Evaluation functions in adversarial search play approximately the same role as heuristic functions in classical search: an estimate of “how good” the state is that can be used to guide the search/decisions.

H-MINIMAX(s, d) =

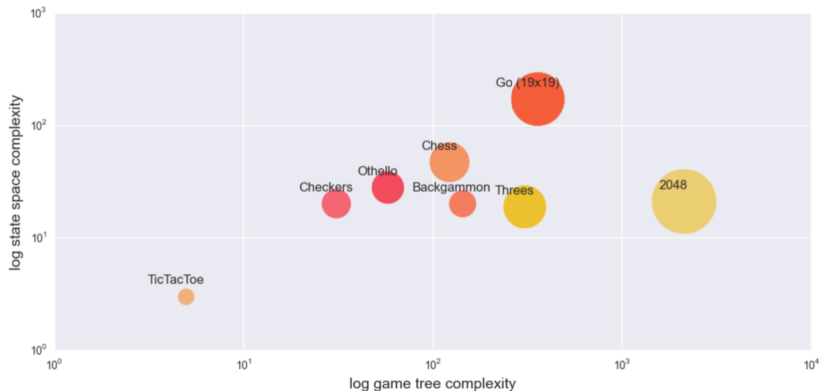
$$\begin{cases} \text{EVAL}(s) & \text{if CUTOFF-TEST}(s, d) \\ \max_{a \in \text{ACTIONS}(s)} \text{MINIMAX}(\text{RESULT}(s, a), d + 1) & \text{if PLAYER}(s) = \text{MAX} \\ \min_{a \in \text{ACTIONS}(s)} \text{MINIMAX}(\text{RESULT}(s, a), d + 1) & \text{if PLAYER}(s) = \text{MIN} \end{cases}$$

EXAMPLE: AI FOR 2048



GAMES AND THEIR COMBINATORIAL COMPLEXITY

- ▶ State space complexity: number of possible states of the game.
- ▶ Game tree complexity: number of possible games.



10^n on these axes mean that the complexity/size is $10^{(10^n)}$.

STOCHASTIC GAMES: EXPECTIMAX

In 2048, the opponent is nature (the game engine), that makes probabilistic decisions, not maximising decisions. We call this player `CHANCE`. The best suited algorithm is `EXPECTIMAX` rather than `MINIMAX`.

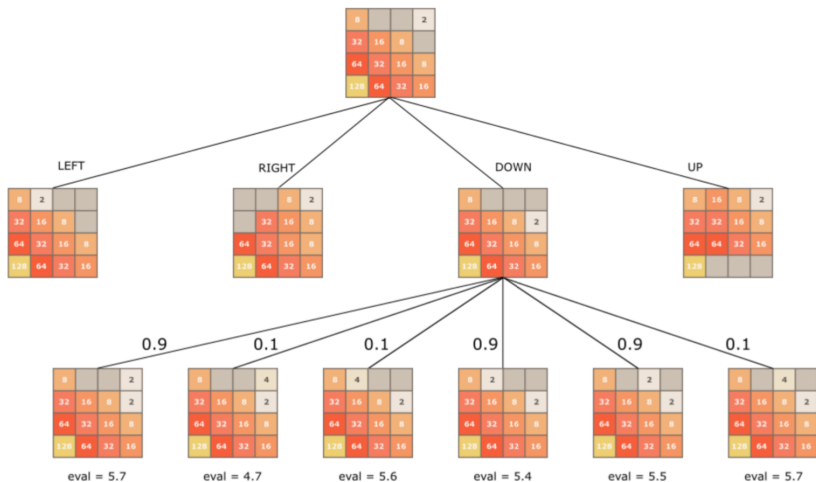
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EXPECTIMAX(s) =

$$\begin{cases} \text{UTILITY}(s, \text{MAX}) & \text{if } \text{TERMINAL-TEST}(s) \\ \max_{a \in \text{ACTIONS}(s)} \text{EXPECTIMAX}(\text{RESULT}(s, a)) & \text{if } \text{PLAYER}(s) = \text{MAX} \\ \sum_{a \in \text{ACTIONS}(s)} P(a, s) \cdot \text{EXPECTIMAX}(\text{RESULT}(s, a)) & \text{if } \text{PLAYER}(s) = \text{CHANCE} \end{cases}$$

Here $P(a, s)$ is the probability of CHANCE choosing action a in s .



Expectimax value of going down from root state:

$$\frac{0.9 \cdot (5.7 + 5.4 + 5.5) + 0.1 \cdot (4.7 + 5.6 + 5.7)}{3} = 5.512.$$

DEMO OF EXPECTIMAX ON 2048

Expectimax for 2048 (by a previous student Kristine Strandby):

<http://kstrandby.github.io/2048-Helper/>

THE END OF LECTURE 5