

# Assignment 15

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AI20MTECH11001

Download all python codes from

<https://github.com/Zeeshan-IITH/IITH-EE5609/new/master/codes>

and latex-tikz codes from

<https://github.com/Zeeshan-IITH/IITH-EE5609>

## 1 PROBLEM

Let  $f$  be a non-zero symmetric bilinear form on  $\mathbb{R}^3$ . Suppose that there exist linear transformations  $T_i : \mathbb{R}^3 \rightarrow \mathbb{R}, i = 1, 2$  such that for all  $\alpha, \beta \in \mathbb{R}^3$ ,  $f(\alpha, \beta) = T_1(\alpha) T_2(\beta)$ . Then

- 1)  $\text{rank } f = 1$
- 2)  $\dim \{\beta \in \mathbb{R}^3 : f(\alpha, \beta) = 0 \text{ for all } \alpha \in \mathbb{R}^3\} = 2$
- 3)  $f$  is positive semi-definite or negative semi-definite
- 4)  $\{\alpha : f(\alpha, \alpha) = 0\}$  is a linear subspace of dimension 2

## 2 CONSTRUCTION

Definition of bilinear form	<p>A bilinear form on a vector space <math>\mathbf{V}</math> is a function <math>f</math>, which assigns to each ordered pair of vectors <math>\alpha, \beta</math> in <math>\mathbf{V}</math> a scalar <math>f(\alpha, \beta)</math> in field <math>\mathbf{F}</math> which satisfies</p> <p>i) <math>f(c\alpha_1 + \alpha_2, \beta) = cf(\alpha_1, \beta) + f(\alpha_2, \beta)</math></p> <p>ii) <math>f(\alpha, c\beta_1 + \beta_2) = cf(\alpha, \beta_1) + f(\alpha, \beta_2)</math></p>
Symmetric bilinear form	<p>A bilinear form on the vector space <math>\mathbf{V}</math> is symmetric if</p> $f(\alpha, \beta) = f(\beta, \alpha)$ <p>for all vectors <math>\alpha, \beta \in \mathbf{V}</math></p>
Matrix of bilinear form	<p>Let <math>\alpha, \beta \in \mathbb{R}^3</math> be two vectors, which are represented in standard basis as <math>\alpha = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3</math> and <math>\beta = \beta_1 \mathbf{e}_1 + \beta_2 \mathbf{e}_2 + \beta_3 \mathbf{e}_3</math>, therefore <math>f(\alpha, \beta)</math> can be represented in matrix form as</p> $f(\alpha, \beta) = f(\alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3, \beta_1 \mathbf{e}_1 + \beta_2 \mathbf{e}_2 + \beta_3 \mathbf{e}_3)$ $= \begin{pmatrix} \alpha_1 & \alpha_2 & \alpha_3 \end{pmatrix} \begin{pmatrix} f(\mathbf{e}_1, \mathbf{e}_1) & f(\mathbf{e}_1, \mathbf{e}_2) & f(\mathbf{e}_1, \mathbf{e}_3) \\ f(\mathbf{e}_2, \mathbf{e}_1) & f(\mathbf{e}_2, \mathbf{e}_2) & f(\mathbf{e}_2, \mathbf{e}_3) \\ f(\mathbf{e}_3, \mathbf{e}_1) & f(\mathbf{e}_3, \mathbf{e}_2) & f(\mathbf{e}_3, \mathbf{e}_3) \end{pmatrix} \begin{pmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \end{pmatrix}$

Given	<p>Given a non-zero symmetric bilinear form <math>f</math> such that <math>f(\alpha, \beta) = T_1(\alpha) T_2(\beta)</math> where <math>\alpha, \beta \in \mathbb{R}^3</math>. So the symmetric bilinear form can be represented on matrix form as</p> $f(\alpha, \beta) = \begin{pmatrix} \alpha_1 & \alpha_2 & \alpha_3 \end{pmatrix} \begin{pmatrix} f(\mathbf{e}_1, \mathbf{e}_1) & f(\mathbf{e}_1, \mathbf{e}_2) & f(\mathbf{e}_1, \mathbf{e}_3) \\ f(\mathbf{e}_2, \mathbf{e}_1) & f(\mathbf{e}_2, \mathbf{e}_2) & f(\mathbf{e}_2, \mathbf{e}_3) \\ f(\mathbf{e}_3, \mathbf{e}_1) & f(\mathbf{e}_3, \mathbf{e}_2) & f(\mathbf{e}_3, \mathbf{e}_3) \end{pmatrix} \begin{pmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \end{pmatrix}$ $f(\alpha, \beta) = \begin{pmatrix} \alpha_1 & \alpha_2 & \alpha_3 \end{pmatrix} \begin{pmatrix} T_1(\mathbf{e}_1)T_2(\mathbf{e}_1) & T_1(\mathbf{e}_1)T_2(\mathbf{e}_2) & T_1(\mathbf{e}_1)T_2(\mathbf{e}_3) \\ T_1(\mathbf{e}_2)T_2(\mathbf{e}_1) & T_1(\mathbf{e}_2)T_2(\mathbf{e}_2) & T_1(\mathbf{e}_2)T_2(\mathbf{e}_3) \\ T_1(\mathbf{e}_3)T_2(\mathbf{e}_1) & T_1(\mathbf{e}_3)T_2(\mathbf{e}_2) & T_1(\mathbf{e}_3)T_2(\mathbf{e}_3) \end{pmatrix} \begin{pmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \end{pmatrix}$ $f(\alpha, \beta) = \begin{pmatrix} \alpha_1 & \alpha_2 & \alpha_3 \end{pmatrix} \begin{pmatrix} T_1(\mathbf{e}_1) \\ T_1(\mathbf{e}_2) \\ T_1(\mathbf{e}_3) \end{pmatrix} \begin{pmatrix} T_2(\mathbf{e}_1) & T_2(\mathbf{e}_2) & T_2(\mathbf{e}_3) \end{pmatrix} \begin{pmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \end{pmatrix} = \alpha^T \mathbf{T}_1 \mathbf{T}_2^T \beta$ <p>where <math>\mathbf{T}_1 = \begin{pmatrix} T_1(\mathbf{e}_1) \\ T_1(\mathbf{e}_2) \\ T_1(\mathbf{e}_3) \end{pmatrix}</math> and <math>\mathbf{T}_2 = \begin{pmatrix} T_2(\mathbf{e}_1) \\ T_2(\mathbf{e}_2) \\ T_2(\mathbf{e}_3) \end{pmatrix}</math> are the matrix representation of the linear transformations <math>T_1, T_2</math>. So, the matrix representation of <math>f</math> is <math>\mathbf{T}_1 \mathbf{T}_2^T</math> or <math>\mathbf{T}_2 \mathbf{T}_1^T</math> since <math>f</math> is symmetric.</p> <p><i>note</i> : Since <math>f</math> is non-zero symmetric bilinear form <math>rank(\mathbf{T}_1) = rank(\mathbf{T}_2) = 1</math></p>
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TABLE 1: Construction

## 3 ANSWER

Option 1	<p>By using the property of rank of product of two matrices, we get</p> $rank(f) = rank(\mathbf{T}_1 \mathbf{T}_2^T) \leq \min(rank(\mathbf{T}_1), rank(\mathbf{T}_2)) \leq 1.$ <p>Since <math>f</math> is non-zero the <math>rank(f) \neq 0</math>. Hence the <math>rank(f) = 1</math></p>
Option 2	<p><math>\beta \in \mathbb{R}^3 : f(\alpha, \beta) = 0</math> for all <math>\alpha \in \mathbb{R}^3 \implies \beta \in \mathbb{R}^3 : T_2(\beta) = 0</math> for all <math>\alpha \in \mathbb{R}^3</math> because <math>T_1(\alpha) \neq 0</math> for all <math>\alpha \in \mathbb{R}^3</math>. By using rank nullity theorem</p>

	$rank\{T_2\} + dim\{Nullspace(T_2)\} = 3 \implies dim\{Nullspace(T_2)\} = 2$ . Similarly for $T_1$ , we get $dim\{Nullspace(T_1)\} = 2$ . Therefore $dim\{\beta \in \mathbb{R}^3 : f(\alpha, \beta) = 0 \text{ for all } \alpha \in \mathbb{R}^3\} = dim\{Nullspace(T_1)\} = dim\{Nullspace(T_2)\} = 2$
Option 3	<p>By using rank nullity theorem we get <math>rank(f) + dim\{nullspace(f)\} = 3</math>. We know that <math>rank(f) = 1 \implies dim\{nullspace(f)\} = 2</math>. Therefore two eigen values of <math>f</math> will be 0.</p> <p>Since the matrix is a symmetric matrix the eigen values are real. So, the third eigen value can be either positive or negative. So, the matrix will be either positive semi-definite or negative semi-definite accordingly. This option is correct.</p>
Option 4	<p><math>\{\alpha : f(\alpha, \alpha) = 0\}</math> is a linear subspace of dimension 2. Since the <math>dim\{nullspace(f)\} = 2</math>, and <math>f</math> is diagonalizable, since it is a symmetric, the two eigen vectors corresponding to 0 eigen values form a subspace of dimension 2.</p>

TABLE 2: Answer

## 4 EXAMPLE

Construction	<p>Consider the non-zero symmetric bilinear form <math>f(\alpha, \beta) = T_1(\alpha) T_2(\beta)</math> on <math>\mathbb{R}^3</math> where</p> <p>Where the matrix of linear transformations are <math>T_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}</math> and <math>T_2 = \begin{pmatrix} 2 \\ 0 \\ 2 \end{pmatrix}</math>.</p> <p>The matrix of symmetric bilinear form is <math>f = \begin{pmatrix} 2 &amp; 0 &amp; 2 \\ 0 &amp; 0 &amp; 0 \\ 2 &amp; 0 &amp; 2 \end{pmatrix}</math>. The <math>rank(f) = 1</math>.</p> <p><math>f(\alpha, \beta) = \alpha^T \begin{pmatrix} 2 &amp; 0 &amp; 2 \\ 0 &amp; 0 &amp; 0 \\ 2 &amp; 0 &amp; 2 \end{pmatrix} \beta</math></p> <p>The characteristic equation is <math> \mathbf{f} - \lambda \mathbf{I}  = \lambda^2(\lambda - 4)</math>. So the eigen values are 0, 0, 4</p>
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	<p>Therefore <math>f</math> is positive semi-definite.</p> <p><math>f(\alpha, \beta) = 0</math> for all <math>\alpha \in \mathbb{R}^3</math>, then <math>\beta = xe_1 + ye_2</math> where <math>e_1 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}</math> and <math>e_2 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}</math>. Therefore</p> <p><math>\dim \{\beta \in \mathbb{R}^3 : f(\alpha, \beta) = 0 \text{ for all } \alpha \in \mathbb{R}^3\} = 2</math></p> <p><math>\alpha : f(\alpha, \alpha) = 0</math> also has a dimension of 2 which forms the nullspace of <math>f</math>, where nullspace of <math>f</math> is the <math>\text{span}\{e_1, e_2\}</math></p>
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TABLE 3: Example