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package net.zeevox.nearow.input

import ...

/**
 * [DataCollectionService] is a foreground service that receives sensor and location updates and
 * handles the lifecycle of the tracking process
 */
class DataCollectionService : Service(), SensorEventListener {

    /** [SensorManager] is a gateway to access device's hardware sensors */
    private lateinit var mSensorManager: SensorManager

    /**
     * [NotificationManagerCompat] is a wrapping library around [NotificationManager] Used to push
     * foreground service notifications, which are necessary to prevent the service from getting
     * killed
     */
    private lateinit var mNotificationManager: NotificationManagerCompat

    /**
     * Instance of [DataProcessor] to which we pass sensor and location updates for number-crunching
     */
    private lateinit var mDataProcessor: DataProcessor

    /** A direct reference to the [DataProcessor] currently in use by the [DataCollectionService] */
    val dataProcessor: DataProcessor
        get() = mDataProcessor

    /**
     * Whether this instance of the [DataCollectionService] is currently running as a foreground
     * service
     */
    private var inForeground: Boolean = false

    /** Contains parameters used by [FusedLocationProviderClient]. */
    private lateinit var mLocationRequest: LocationRequest

    /** Provides access to the Fused Location Provider API. */
    private lateinit var mFusedLocationClient: FusedLocationProviderClient

    /** Callback for changes in location. */
    private lateinit var mLocationCallback: LocationCallback

    companion object {
        const val NOTIFICATION_ID = 7652863

        // 20,000 us => ~50Hz sampling
        const val ACCELEROMETER_SAMPLING_DELAY = 20000

        /**
         * The desired interval for location updates. Inexact. Updates may be more or less frequent.
         */
        private const val UPDATE_INTERVAL_IN_MILLISECONDS: Long = 1000L

        /**
         * The fastest rate for active location updates. Updates will never be more frequent than
         * this value.
         */
        private const val FASTEST_UPDATE_INTERVAL_IN_MILLISECONDS: Long = 0L

        /** Logcat tag used for debugging */
        private val TAG = DataCollectionService::class.java.simpleName
    }
}

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/** https://developer.android.com/guide/components/bound-services#Binder */
private val binder = LocalBinder()

/**
 * Class used for the client Binder. Because we know this service always runs in the same
 * process as its clients, we don't need to deal with IPC.
 */
inner class LocalBinder : Binder() {
    // Return this instance of LocalService so clients can call public methods
    fun getService(): DataCollectionService = this@DataCollectionService
}

override fun onStartCommand(intent: Intent?, flags: Int, startId: Int): Int {
    return START_STICKY
}

override fun onCreate() {
    super.onCreate()

    Log.i(TAG, "Starting Nero data collection service")

    mNotificationManager = NotificationManagerCompat.from(this)

    // start the data processor before registering sensor and GPS
    // listeners so that it is ready to receive values as soon as
    // they start coming in.
    mDataProcessor =
        DataProcessor(applicationContext).also {
            // physical sensor data is not permission-protected so no need to check
            registerSensorListener()

            initGpsClient()

            // measuring GPS is neither always needed (e.g. erg) nor permitted by user
            // check that access has been granted to the user's geolocation before starting gps
            // collection
            if (isGpsPermissionGranted()) enableGps()
        }

    startService(Intent(applicationContext, DataCollectionService::class.java))
    startForeground()
}

/**
 * Called when a client comes to the foreground and binds with this service. The service should
 * cease to be a foreground service when that happens.
 */
override fun onBind(intent: Intent?): IBinder {
    Log.i(TAG, "Client bound to service")
    stopForeground()
    return binder
}

/**
 * Called when a client comes to the foreground and binds with this service. The service should
 * cease to be a foreground service when that happens.
 */
override fun onRebind(intent: Intent?) {
    Log.i(TAG, "Client rebound to service")
    stopForeground()
    super.onRebind(intent)
}

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/**
 * Called when the last client unbinds from this service. If a track is being recorded,
 * make this service a foreground service.
 */
override fun onUnbind(intent: Intent?): Boolean {
    Log.i(TAG, "Last client unbound from service")

    if (mDataProcessor.isRecording) startForeground() else stopForeground()
    return true
}

/**
 * Switch the [DataCollectionService] to a foreground service so that sensor and location
 * updates can continue to be processed even though the application UI has gone out of view
 */
private fun startForeground() {
    Log.i(TAG, "Switching to foreground service")
    startForeground(NOTIFICATION_ID, NotificationUtils.getForegroundServiceNotification(this))

    // Pushing notifications on main thread is warned against by StrictMode
    CoroutineScope(Dispatchers.Default).launch {
        mNotificationManager.notify(
            NOTIFICATION_ID,
            NotificationUtils.getForegroundServiceNotification(this@DataCollectionService))
    }

    inForeground = true
}

/** Stop being a foreground service if the GUI comes back into view. */
private fun stopForeground() {
    Log.i(TAG, "Cancelling foreground service")
    stopForeground(true)
    inForeground = false
}

fun setDataUpdateListener(listener: DataProcessor.DataUpdateListener) =
    mDataProcessor.setListener(listener)

private fun registerSensorListener() {
    CoroutineScope(Dispatchers.IO).launch {
        mSensorManager = getSystemService(AppCompatActivity.SENSOR_SERVICE) as SensorManager
        mSensorManager.getDefaultSensor(Sensor.TYPE_LINEAR_ACCELERATION)?.also { accelerometer
            ->
            mSensorManager.registerListener(
                this@DataCollectionService, accelerometer, ACCELEROMETER_SAMPLING_DELAY)
        }
    }
}

private fun isGpsPermissionGranted(): Boolean {
    return ActivityCompat.checkSelfPermission(this, Manifest.permission.ACCESS_FINE_LOCATION) ==
        PackageManager.PERMISSION_GRANTED &&
        ActivityCompat.checkSelfPermission(this, Manifest.permission.ACCESS_COARSE_LOCATION) ==
        PackageManager.PERMISSION_GRANTED
}

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/**
https://github.com/android/location-samples/blob/main/LocationUpdatesForegroundService/app/src/main/java/com/google/android/gms/location/sample/locationupdatesforegroundservice/LocationUpdatesService.java
*/
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```
private fun initGpsClient() {
    mFusedLocationClient = LocationServices.getFusedLocationProviderClient(this)

    mLocationCallback =
        object : LocationCallback() {
            override fun onLocationResult(locationResult: LocationResult) {
                super.onLocationResult(locationResult)
                mDataProcessor.addGpsReading(locationResult.lastLocation)
            }
        }

    createLocationRequest()
}

fun enableGps() {
    try {
        mFusedLocationClient.requestLocationUpdates(
            mLocationRequest, mLocationCallback, Looper.getMainLooper())
    } catch (unlikely: SecurityException) {
        Log.e(TAG, "Lost location permission. Could not request updates.", unlikely)
    }
}
```

```
private fun createLocationRequest() {
    mLocationRequest =
        LocationRequest.create().apply {
            interval = UPDATE_INTERVAL_IN_MILLISECONDS
            fastestInterval = FASTEST_UPDATE_INTERVAL_IN_MILLISECONDS
            priority = LocationRequest.PRIORITY_HIGH_ACCURACY
        }
}
```

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/** Stop requesting location updates */
fun disableGps() {
    Log.i(TAG, "Requesting GPS location updates to stop")
    try {
        mFusedLocationClient.removeLocationUpdates(mLocationCallback)
    } catch (unlikely: SecurityException) {
        Log.e(TAG, "Lost location permission. Could not remove updates.", unlikely)
    }
}
```

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/**
 * Called by the system to notify a Service that it is no longer used and is being removed. The
 * service should clean up any resources it holds (threads, registered receivers, etc) at this
 * point. Upon return, there will be no more calls in to this Service object and it is
 * effectively dead.
 */
override fun onDestroy() {
    disableGps()
    super.onDestroy()
}
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override fun onSensorChanged(event: SensorEvent?) {
    if (event == null) return

    when (event.sensor.type) {
        Sensor.TYPE_LINEAR_ACCELERATION -> mDataProcessor.addAccelerometerReading(event.values)
    }
}

override fun onAccuracyChanged(sensor: Sensor?, accuracy: Int) {
    // TODO accuracy handling?
    Log.w(TAG, "Unhandled ${sensor?.name} sensor accuracy change to $accuracy")
}

private class NotificationUtils private constructor() {
    companion object {
        private const val CHANNEL_ID = "tracking_channel"

        @RequiresApi(Build.VERSION_CODES.O)
        internal fun createServiceNotificationChannel(context: Context) {
            val notificationManager = NotificationManagerCompat.from(context)
            notificationManager.createNotificationChannel(
                NotificationChannel(
                    CHANNEL_ID,
                    context.getString(R.string.notification_channel_tracking_service),
                    NotificationManager.IMPORTANCE_MIN
                ).apply {
                    enableLights(false)
                    setSound(null, null)
                    enableVibration(false)
                    vibrationPattern = longArrayOf(0L)
                    setShowBadge(false)
                })
        }

        internal fun getForegroundServiceNotification(context: Context): Notification {
            val notificationBuilder =
                NotificationCompat.Builder(context, CHANNEL_ID)
                    .setAutoCancel(true)
                    .setDefaults(Notification.DEFAULT_ALL)
                    .setContentTitle(context.resources.getString(R.string.app_name))
                    .setContentText(
                        context.getString(R.string.notification_background_service_running))
                    .setWhen(System.currentTimeMillis())
                    .setOngoing(true)
                    .setVibrate(longArrayOf(0L))
                    .setSound(null)
                    .setSmallIcon(R.mipmap.ic_launcher_round)

            // Notifications channel required for Android 8.0+
            if (Build.VERSION.SDK_INT >= Build.VERSION_CODES.O) {
                createServiceNotificationChannel(context)
                notificationBuilder.setChannelId(CHANNEL_ID)
            }

            return notificationBuilder.build()
        }
    }
}

```