Introduction:

After understanding how regression models and classifications models can be accomplished with neural networks, it is time to understand a different type of neural network. This new type of neural network is mostly used in image processing and it is known as Convolutional Neural Network, (CNN). These neural networks can be used to classify images, hence why this project will focus on two CNN models that will attempt to classify Pandas vs Dogs & Pandas vs Cats. The data for this project will be obtained from one of the kaggle datasets which contains 1000 images for each of the animals (Pandas, Dogs, Cats). The goal of this project is to understand how CNN's perform in image classification tasks and what is the difference in difficulty between the two CNN's.

Procedures:

In this project the first step is to set up the data by importing into google colab from kaggle and making a tensorflow dataset for each of the animals (Pandas, Dogs, Cats). Once this step has been completed then the data will not be used if it is removed from the tensorflow dataset otherwise, the model will not train as intended. Following this step, comes the creation of the CNN model and the training/evaluation of it. After the first model has been completed, an attempt to improve this model will be made by using a regularization method (dropout, L1, L2). Once the second model has been completed, a 3rd improvement will be attempted by using data augmentation. This last step marks the end of a set of CNN's models that can be used to classify Pandas vs Dogs; hence the same steps are repeated but for a set of CNN's models that can be used to classify Pandas vs Cats.

Results:

In this section the plots and final values pertaining to each model will be presented. In addition the structure of the network alongside its complete description (i.e number of layers, activation function, processing elements, etc.) will be encompassed in this section. Finally a brief description will be provided regarding the changes that were made between from one model to the next.

II.1 CNN Model 1 (pvmd1)

Model: "model"

Layer (type)	Output Shape	Param #
input_1 (InputLayer)	[(None, 180, 180, 3)]	0
rescaling (Rescaling)	(None, 180, 180, 3)	0
conv2d (Conv2D)	(None, 178, 178, 32)	896
<pre>max_pooling2d (MaxPooling2D)</pre>	(None, 89, 89, 32)	0
conv2d_1 (Conv2D)	(None, 87, 87, 64)	18496
<pre>max_pooling2d_1 (MaxPooling 2D)</pre>	(None, 43, 43, 64)	0
conv2d_2 (Conv2D)	(None, 41, 41, 128)	73856
<pre>max_pooling2d_2 (MaxPooling 2D)</pre>	(None, 20, 20, 128)	0
conv2d_3 (Conv2D)	(None, 18, 18, 256)	295168
<pre>max_pooling2d_3 (MaxPooling 2D)</pre>	(None, 9, 9, 256)	0
conv2d_4 (Conv2D)	(None, 7, 7, 256)	590080
flatten (Flatten)	(None, 12544)	0
dense (Dense)	(None, 1)	12545

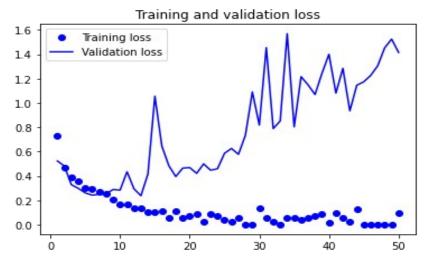


Figure 1: Preliminary Loss (Training and Validation) vs Epochs

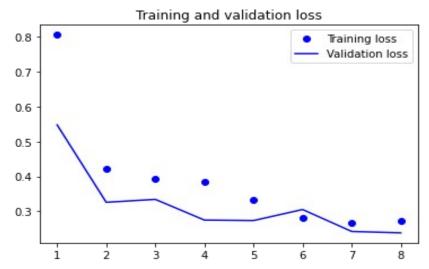


Figure 2: Final Loss (Training and Validation) vs Epochs

Final Training loss: 0.2734917998313904 Final Training Accuracy: 0.8964285850524902

Final Validation loss: 0.23817463219165802 Final Validation Accuracy: 0.8949999809265137

accuracy: 0.9050 [0.1916598081588745, 0.9049999713897705]

II.2 CNN Model 2 (pvmd2)

Model: "model_6"

Layer (type)	Output Shape	Param #
input_7 (InputLayer)	[(None, 180, 180, 3)]	0
rescaling_6 (Rescaling)	(None, 180, 180, 3)	0
conv2d_30 (Conv2D)	(None, 178, 178, 32)	896
<pre>max_pooling2d_24 (MaxPoolin g2D)</pre>	(None, 89, 89, 32)	0
conv2d_31 (Conv2D)	(None, 87, 87, 64)	18496
<pre>max_pooling2d_25 (MaxPoolin g2D)</pre>	(None, 43, 43, 64)	0
conv2d_32 (Conv2D)	(None, 41, 41, 128)	73856
<pre>max_pooling2d_26 (MaxPoolin g2D)</pre>	(None, 20, 20, 128)	0
conv2d_33 (Conv2D)	(None, 18, 18, 256)	295168
<pre>max_pooling2d_27 (MaxPoolin g2D)</pre>	(None, 9, 9, 256)	0
conv2d_34 (Conv2D)	(None, 7, 7, 256)	590080
flatten_6 (Flatten)	(None, 12544)	0
dense_6 (Dense)	(None, 1)	12545

Training and validation loss 1.0 - Validation loss 0.8 - 0.6 - 0.4 - 0.2 - 0.2 - 0.2 - 0.8 - 0.2 - 0.2 - 0.2 - 0.8 - 0

Figure 3: Preliminary Loss (Training and Validation) vs Epochs

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10

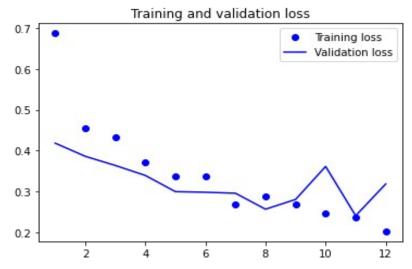


Figure 4: Final Loss (Training and Validation) vs Epochs

Final Training loss: 0.20187591016292572

Final Training Accuracy: 0.9314285516738892

Final Validation loss: 0.31808987259864807

Final Validation Accuracy: 0.8899999856948853

accuracy: 0.9200 [0.2729094624519348, 0.9200000166893005]

II.3 CNN Model 3 (pvdm3)

Model: "model_11"

Layer (type)	Output Shape	Param #
input_12 (InputLayer)	[(None, 180, 180, 3)]	0
sequential_3 (Sequential)	(None, 180, 180, 3)	0
rescaling_11 (Rescaling)	(None, 180, 180, 3)	0
conv2d_55 (Conv2D)	(None, 178, 178, 32)	896
<pre>max_pooling2d_44 (MaxPoolin g2D)</pre>	(None, 89, 89, 32)	0
dropout_3 (Dropout)	(None, 89, 89, 32)	0
conv2d_56 (Conv2D)	(None, 87, 87, 64)	18496
<pre>max_pooling2d_45 (MaxPoolin g2D)</pre>	(None, 43, 43, 64)	0
dropout_4 (Dropout)	(None, 43, 43, 64)	0
conv2d_57 (Conv2D)	(None, 41, 41, 128)	73856
<pre>max_pooling2d_46 (MaxPoolin g2D)</pre>	(None, 20, 20, 128)	0
dropout_5 (Dropout)	(None, 20, 20, 128)	0
conv2d_58 (Conv2D)	(None, 18, 18, 256)	295168
<pre>max_pooling2d_47 (MaxPoolin g2D)</pre>	(None, 9, 9, 256)	0
dropout_6 (Dropout)	(None, 9, 9, 256)	0
conv2d_59 (Conv2D)	(None, 7, 7, 256)	590080
flatten_11 (Flatten)	(None, 12544)	Θ
dropout_7 (Dropout)	(None, 12544)	0
dense_11 (Dense)	(None, 1)	12545

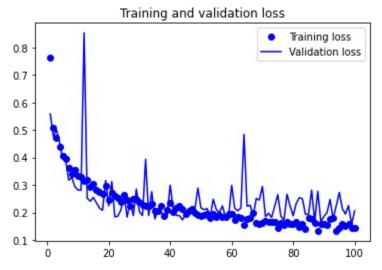


Figure 5: Preliminary Loss (Training and Validation) vs Epochs

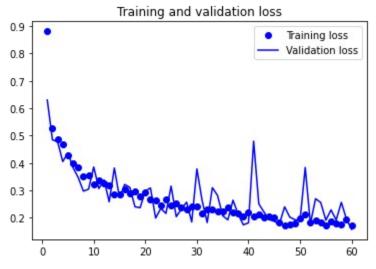


Figure 6: Final Loss (Training and Validation) vs Epochs

Final Training loss: 0.17143961787223816 Final Training Accuracy: 0.9457142949104309 Final Validation loss: 0.15801990032196045 Final Validation Accuracy: 0.9524999856948853

accuracy: 0.9600 [0.15106220543384552, 0.9599999785423279]

Discussion/Observations of Panda vs Dog model:

In the first CNN model (pvdm1) the model that was built consisted of no regularization methods and data augmentation. Once the model went through the first 30 epochs (preliminary) it was decided that the best time to stop the training was in epoch 8. The final values obtained from evaluating the test dataset was (loss: 0.1917 - accuracy: 0.9050). After obtaining these values it was determined that a second model that would use regularization methods will be implemented in order to improve the accuracy of the CNN model. Hence, the second CNN model (pvdm2) was built. After trying different combinations of regularization methods it was determined that *L2*(.0001) improved the model's accuracy. Once the model went through the first 30 epochs (preliminary) it was decided that the best time to stop the training was in epoch 12. The final values obtained from evaluating the test dataset was (loss: 0.2729 - accuracy: 0.9200). Finally, it was determined that one last model would be built in an attempt to improve the accuracy of the second model. The third CNN model (pvdm3) used data augmentation, L2 regularization, and Dropout. The data augmentation used in (pvdm3) consisted of the following parameters and values: RandomFlip('horizontal'), RandomRotation(.1), and RandomZoom(.2). The Dropout layers were implemented after each MaxPool layer and after the flatten layer. The values for the Dropout layers ranged from (.15 - .5) and the L2 regularization was kept the same as in the second model. Once the model went through the first 100 epochs (preliminary) it was decided that the best time to stop the training was in epoch 60. The final values obtained from evaluating the test dataset was (loss: 0.1511 - accuracy: 0.9600)

* Further Analysis

In the midst of training the third model I attempted to use the ModelCheckpoint and callbacks functions to determine the best model. In addition, instead of saving the best model via the validation loss metric, I used the validation accuracy. Then I proceeded to train the model for 200 epochs. Once the 200 epochs were completed I used the callback function to retrieve the best model and evaluated it with the test dataset. The results obtained from this evaluation was (loss: 0.0804 - accuracy: 0.9900). Hence, an interesting question now comes into my mind, for engineers the most important parameter is the loss (specifically validation loss), because it allows us to keep track of how the model is performing from epoch to epoch. However, is it more beneficial to save the model which has the highest validation accuracy?

III.1 CNN Model 1 (pvcm1)

Model: "model_1"

Layer (type)	Output Shape	Param #
input_2 (InputLayer)	[(None, 180, 180, 3)]	0
rescaling_1 (Rescaling)	(None, 180, 180, 3)	0
conv2d_5 (Conv2D)	(None, 178, 178, 32)	896
<pre>max_pooling2d_4 (MaxPooling 2D)</pre>	(None, 89, 89, 32)	0
conv2d_6 (Conv2D)	(None, 87, 87, 64)	18496
<pre>max_pooling2d_5 (MaxPooling 2D)</pre>	(None, 43, 43, 64)	0
conv2d_7 (Conv2D)	(None, 41, 41, 128)	73856
<pre>max_pooling2d_6 (MaxPooling 2D)</pre>	(None, 20, 20, 128)	0
conv2d_8 (Conv2D)	(None, 18, 18, 256)	295168
<pre>max_pooling2d_7 (MaxPooling 2D)</pre>	(None, 9, 9, 256)	0
conv2d_9 (Conv2D)	(None, 7, 7, 256)	590080
flatten_1 (Flatten)	(None, 12544)	0
dense_1 (Dense)	(None, 1)	12545

Training and validation loss 2.0 Training loss Validation loss 1.5 1.0 0.5 0.0 5 10 15 20 25 30

Figure 7: Preliminary Loss (Training and Validation) vs Epochs

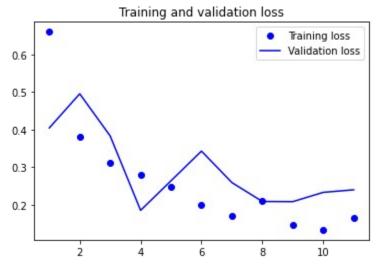


Figure 8: Final Loss (Training and Validation) vs Epochs

Final Training loss: 0.16530783474445343
Final Training Accuracy: 0.954285740852356
Final Validation loss: 0.23942400515079498
Final Validation Accuracy: 0.9125000238418579

accuracy: 0.9000 [0.30769720673561096, 0.8999999761581421]

III.2 CNN Model 2 (pvcm2)

Model: "model_9"

Layer (type)	Output Shape	Param #
input_10 (InputLayer)	[(None, 180, 180, 3)]	
rescaling_9 (Rescaling)	(None, 180, 180, 3)	0
conv2d_45 (Conv2D)	(None, 178, 178, 32)	896
<pre>max_pooling2d_36 (MaxPoolin g2D)</pre>	(None, 89, 89, 32)	0
dropout_10 (Dropout)	(None, 89, 89, 32)	Θ
conv2d_46 (Conv2D)	(None, 87, 87, 64)	18496
<pre>max_pooling2d_37 (MaxPoolin g2D)</pre>	(None, 43, 43, 64)	0
dropout_11 (Dropout)	(None, 43, 43, 64)	0
conv2d_47 (Conv2D)	(None, 41, 41, 128)	73856
<pre>max_pooling2d_38 (MaxPoolin g2D)</pre>	(None, 20, 20, 128)	0
dropout_12 (Dropout)	(None, 20, 20, 128)	0
conv2d_48 (Conv2D)	(None, 18, 18, 256)	295168
<pre>max_pooling2d_39 (MaxPoolin g2D)</pre>	(None, 9, 9, 256)	0
dropout_13 (Dropout)	(None, 9, 9, 256)	0
conv2d_49 (Conv2D)	(None, 7, 7, 256)	590080
flatten_9 (Flatten)	(None, 12544)	0
dropout_14 (Dropout)	(None, 12544)	0
dense_9 (Dense)	(None, 1)	12545

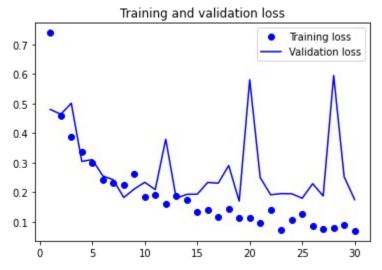


Figure 9: Preliminary Loss (Training and Validation) vs Epochs

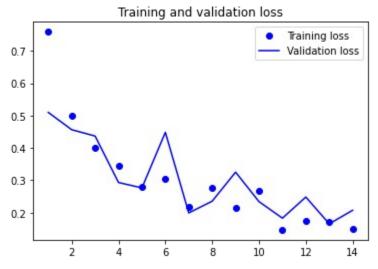


Figure 10: Final Loss (Training and Validation) vs Epochs

Final Training loss: 0.14952512085437775

Final Training Accuracy: 0.9557142853736877

Final Validation loss: 0.20736859738826752

Final Validation Accuracy: 0.9325000047683716

accuracy: 0.9300 [0.23292145133018494, 0.9300000071525574]

III.3 CNN Model 3 (pvcm3)

Model: "model_6"

	Layer (type)	Output Shape	Param #
-	input_7 (InputLayer)	[(None, 180, 180, 3)]	0
	sequential (Sequential)	(None, 180, 180, 3)	0
	rescaling_6 (Rescaling)	(None, 180, 180, 3)	0
	conv2d_30 (Conv2D)	(None, 178, 178, 32)	896
	<pre>max_pooling2d_24 (MaxPoolin g2D)</pre>	(None, 89, 89, 32)	0
	dropout (Dropout)	(None, 89, 89, 32)	0
	conv2d_31 (Conv2D)	(None, 87, 87, 64)	18496
	<pre>max_pooling2d_25 (MaxPoolin g2D)</pre>	(None, 43, 43, 64)	0
	dropout_1 (Dropout)	(None, 43, 43, 64)	0
	conv2d_32 (Conv2D)	(None, 41, 41, 128)	73856
	<pre>max_pooling2d_26 (MaxPoolin g2D)</pre>	(None, 20, 20, 128)	Θ
	dropout_2 (Dropout)	(None, 20, 20, 128)	0
	conv2d_33 (Conv2D)	(None, 18, 18, 256)	295168
	<pre>max_pooling2d_27 (MaxPoolin g2D)</pre>	(None, 9, 9, 256)	Θ
	dropout_3 (Dropout)	(None, 9, 9, 256)	0
	conv2d_34 (Conv2D)	(None, 7, 7, 256)	590080
	flatten_6 (Flatten)	(None, 12544)	0
	dropout_4 (Dropout)	(None, 12544)	0
	dense_6 (Dense)	(None, 1)	12545

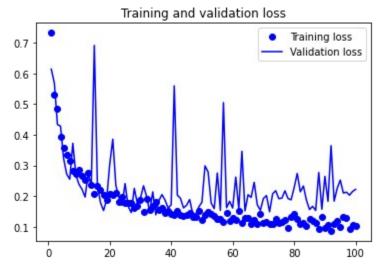


Figure 11: Preliminary Loss (Training and Validation) vs Epochs

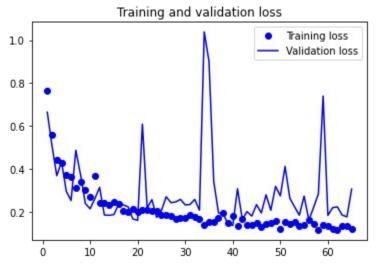


Figure 12: Final Loss (Training and Validation) vs Epochs

Final Training loss: 0.12229102849960327
Final Training Accuracy: 0.9628571271896362
Final Validation loss: 0.30623793601989746
Final Validation Accuracy: 0.9424999952316284

7/7 [=================] - 0s 13ms/step - loss: 0.2660 -

accuracy: 0.9500 [0.26600533723831177, 0.949999988079071]

Discussion/Observations of Panda vs Cat models:

In the first CNN model (pvcm1) the model that was built consisted of no regularization methods and data augmentation. Once the model went through the first 30 epochs (preliminary) it was decided that the best time to stop the training was in epoch 11. The final values obtained from evaluating the test dataset was (loss: 0.3077 - accuracy: 0.9000). After obtaining these values it was determined that a second model that would use regularization methods will be implemented in order to improve the accuracy of the CNN model. Hence, the second CNN model (pvcm2) was built. After trying different combinations of regularization methods it was determined that L2(.0001) and Dropout layers with values of (.25) improved the model's accuracy. Once the model went through the first 30 epochs (preliminary) it was decided that the best time to stop the training was in epoch 12. The final values obtained from evaluating the test dataset was (loss: 0.2329 - accuracy: 0.9300). Finally, it was determined that one last model would be built in an attempt to improve the accuracy of the second model. The third CNN model (pvdm3) used data augmentation, L2 regularization, and Dropout. The data augmentation used in (pvdm3) consisted of the following parameters and values: RandomFlip('horizontal'), RandomRotation(.1), and RandomZoom(.2). The Dropout layers were implemented after each MaxPool layer and after the flatten layer. The values for the Dropout layers ranged from (.15 - .5) and the L2 regularization was kept the same as in the second model. Once the model went through the first 100 epochs (preliminary) it was decided that the best time to stop the training was in epoch 65. The final values obtained from evaluating the test dataset was (loss: 0.2660 - accuracy: 0.9500).

Conclusion:

In this project the biggest thing I learned was the impacts of regularization methods and data augmentation on the performance of CNN models, specifically data augmentation seems to always improve the model no matter what. In this project I expected the models to be able to classify images with an accuracy of 90%. However, what I definitely was not expecting was that the first CNN model would automatically be around this range. Even more unexpected was that the model can be improved to 95-96% just by using some basic techniques such as regularization and data augmentation. I believe that one way to improve these models is by increasing the dataset to have more images to classify. In addition, a preprocessing stage can be set up to select random images to have in the training, validation and test split. This will eliminate possible selecting images that are harder to train. I believe that Panda vs Cats seems to be a harder classification task because for the second model I had to use much more techniques to improve the second model, but the last model was lower than the one for the Panda vs Dogs final model.

Appendix

Importing Libraries import matplotlib.pyplot as plt import seaborn as sns import numpy as np import pandas as pd from io import StringIO from sklearn.preprocessing import LabelEncoder import sklearn from sklearn.model selection import train test split from numpy import array from numpy import argmax from sklearn.preprocessing import LabelEncoder from sklearn.preprocessing import OneHotEncoder import copy from keras.engine.input layer import Input import tensorflow as tf from tensorflow import keras from tensorflow.keras import layers from sklearn.neighbors import KNeighborsClassifier from sklearn.naive bayes import GaussianNB from sklearn.neural network import MLPClassifier from google.colab import files import os, shutil, pathlib from tensorflow.keras.preprocessing import image dataset from directory from keras import regularizers from sklearn.utils import validation # Uploading Kaggle JSon File files.upload() # Removing/Creating Directory for Kaggle

```
!rm -r ~/.kaggle/
!mkdir ~/.kaggle
!cp kaggle.json ~/.kaggle/
!chmod 600 ~/.kaggle/kaggle.json
```

Importing Dataset

!kaggle datasets download -d ashishsaxena2209/animal-image-datasetdog-cat-and-panda

```
# Unzipping Dataset
!unzip -qq animal-image-datasetdog-cat-and-panda.zip
# New Directory Structure
original_dir = pathlib.Path('animals')
new base dir = pathlib.Path('newanim')
def make subset(subset name, start index, end index):
  for category in ('cats','dogs','panda'):
    dir = new_base_dir / subset_name / category
    dirsrc = original_dir / category
    os.makedirs(dir)
    fnames = ['{} {:05d}.jpg'.format(category,i) for i in range
(start index, end index)]
    for fname in fnames:
      shutil.copyfile(src=dirsrc / fname , dst = dir / fname)
make subset('train', start index=1, end index=701)
make subset('validation', start index=701, end index=901)
make subset('test', start index=901,end index=1001)
# Remove the Cat Directories
!rm -r ./newanim/train/cats/
!rm -r ./newanim/validation/cats/
!rm -r ./newanim/test/cats/
# Creating TensorFlow Dataset
train_dataset = image_dataset_from_directory(
    new base dir / 'train',
    image size = (180, 180),
    batch size = 32)
valdiation dataset = image dataset from directory(
    new_base_dir / 'validation',
    image size = (180, 180),
    batch size = 32)
test dataset = image dataset from directory(
    new_base_dir / 'test',
    image_size = (180, 180),
    batch size = 32)
# Displaying shape of Dataset
```

```
for data batch, labels batch in train dataset:
  print("data batch shape:", data batch.shape)
  print("labels batch shape:", labels_batch.shape)
  break
# CNN Model Panda vs Dog (pvdm1)
inputs = keras.Input(shape=(180, 180, 3))
x = layers.Rescaling(1./255)(inputs)
x = layers.Conv2D(filters=32, kernel size=3,activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=64, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=128, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.Flatten()(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
pvdm1 = keras.Model(inputs=inputs, outputs=outputs)
pvdm1.summary()
## Configure Model for Training
pvdm1.compile(loss = "binary crossentropy", optimizer="rmsprop",
metrics=["accuracy"])
## Fitting the Model using a Dataset
callbacks = [
    keras.callbacks.ModelCheckpoint(
        filepath="pvdm1.h5",
        save best only = True,
        monitor = "val loss")
]
history1 = pvdm1.fit(
    train dataset,
    epochs = 8,
    validation data = valdiation dataset,
    callbacks = callbacks
)
## Displaying Curves of Loss and Accuracy during Training
```

```
accuracy = history1.history["accuracy"]
val accuracy = history1.history["val accuracy"]
loss = history1.history["loss"]
val loss = history1.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, "bo", label="Training accuracy")
plt.plot(epochs, val_accuracy, "b", label="Validation accuracy")
plt.title("Training and validation accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, "bo", label="Training loss")
plt.plot(epochs, val loss, "b", label="Validation loss")
plt.title("Training and validation loss")
plt.legend()
plt.show()
# Final Values
print("Final Training loss: ",history1.history['loss'][-1],"\nFinal Training
Accuracy: ", history1.history['accuracy'][-1])
print("Final Validation loss: ",history1.history['val_loss'][-1],"\nFinal
Validation Accuracy: ", history1.history['val accuracy'][-1])
## Evaluate Model
pvdm1.evaluate(test_dataset)
# CNN Model 2 Panda vs Dog (w/L2) (pvdm2)
inputs = keras.Input(shape=(180, 180, 3))
x = layers.Rescaling(1./255)(inputs)
x = layers.Conv2D(filters=32, kernel size=3,
kernel_regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=64, kernel_size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=128, kernel size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.Flatten()(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
pvdm2 = keras.Model(inputs=inputs, outputs=outputs)
```

```
pvdm2.summary()
## Configure Model for Training
pvdm2.compile(loss = "binary crossentropy", optimizer="rmsprop",
metrics=["accuracy"])
## Fitting the Model using a Dataset
callbacks = [
    keras.callbacks.ModelCheckpoint(
        filepath="pvdm2.h5",
        save best only = True,
        monitor = "val loss")
1
history2 = pvdm2.fit(
    train dataset,
    epochs = 10,
    validation data = valdiation dataset,
    callbacks = callbacks
)
## Displaying Curves of Loss and Accuracy during Training
accuracy = history2.history["accuracy"]
val_accuracy = history2.history["val_accuracy"]
loss = history2.history["loss"]
val loss = history2.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, "bo", label="Training accuracy")
plt.plot(epochs, val_accuracy, "b", label="Validation accuracy")
plt.title("Training and validation accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, "bo", label="Training loss")
plt.plot(epochs, val_loss, "b", label="Validation loss")
plt.title("Training and validation loss")
plt.legend()
plt.show()
# Final Values
print("Final Training loss: ",history2.history['loss'][-1],"\nFinal Training
Accuracy: ", history2.history['accuracy'][-1])
print("Final Validation loss: ",history2.history['val loss'][-1],"\nFinal
Validation Accuracy: ", history2.history['val accuracy'][-1])
```

```
## Evaluate Model
pvdm2.evaluate(test_dataset)
# CNN Model 3 Panda vs Dog (w/Data Augmentation) (pvdm3)
data augmentation = keras.Sequential(
      layers.RandomFlip("horizontal"),
      layers.RandomRotation(.1),
      layers.RandomZoom(.2)
    ]
)
inputs = keras.Input(shape=(180, 180, 3))
x = data augmentation(inputs)
x = layers.Rescaling(1./255)(x)
x = layers.Conv2D(filters=32, kernel size=3,
kernel_regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Dropout(.15)(x)
x = layers.Conv2D(filters=64, kernel size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Dropout(.25)(x)
x = layers.Conv2D(filters=128, kernel size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Dropout(.5)(x)
x = layers.Conv2D(filters=256, kernel size=3,
kernel_regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Dropout(.25)(x)
x = layers.Conv2D(filters=256, kernel size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.Flatten()(x)
x = layers.Dropout(.25)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
pvdm3 = keras.Model(inputs=inputs, outputs=outputs)
pvdm3.summary()
## Configure Model for Training
pvdm3.compile(loss = "binary_crossentropy", optimizer="rmsprop",
metrics=["accuracy"])
```

```
## Fitting the Model using a Dataset
callbacks = [
    keras.callbacks.ModelCheckpoint(
        filepath="pvdm3.h5",
        save best only = True,
        monitor = "val loss")
]
history3 = pvdm3.fit(
    train dataset,
    epochs = 150,
    validation data = valdiation dataset,
    callbacks = callbacks
)
## Displaying Curves of Loss and Accuracy during Training
accuracy = history3.history["accuracy"]
val accuracy = history3.history["val accuracy"]
loss = history3.history["loss"]
val loss = history3.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, "bo", label="Training accuracy")
plt.plot(epochs, val_accuracy, "b", label="Validation accuracy")
plt.title("Training and validation accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, "bo", label="Training loss")
plt.plot(epochs, val loss, "b", label="Validation loss")
plt.title("Training and validation loss")
plt.legend()
plt.show()
# Final Values
print("Final Training loss: ",history3.history['loss'][-1],"\nFinal Training
Accuracy: ", history3.history['accuracy'][-1])
print("Final Validation loss: ",history3.history['val_loss'][-1],"\nFinal
Validation Accuracy: ", history3.history['val accuracy'][-1])
## Evaluate Model
pvdm3.evaluate(test_dataset)
```

Remove the Dog DIrectories

```
!rm -r ./newanim/train/dogs/
!rm -r ./newanim/validation/dogs/
!rm -r ./newanim/test/dogs/
# CNN Model Panda vs Cat (pvcm1)
inputs = keras.Input(shape=(180, 180, 3))
x = layers.Rescaling(1./255)(inputs)
x = layers.Conv2D(filters=32, kernel size=3,activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=64, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=128, kernel_size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Conv2D(filters=256, kernel size=3, activation="relu")(x)
x = layers.Flatten()(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
pvcm1 = keras.Model(inputs=inputs, outputs=outputs)
pvcm1.summary()
## Configure Model for Training
pvcml.compile(loss = "binary crossentropy", optimizer="rmsprop",
metrics=["accuracy"])
## Fitting the Model using a Dataset
callbacks = [
    keras.callbacks.ModelCheckpoint(
        filepath="pvcm1.h5",
        save best only = True,
        monitor = "val loss")
]
history1 = pvcm1.fit(
    train dataset,
    epochs = 11,
    validation data = valdiation_dataset,
    callbacks = callbacks
)
## Displaying Curves of Loss and Accuracy during Training
```

```
accuracy = history1.history["accuracy"]
val accuracy = history1.history["val accuracy"]
loss = history1.history["loss"]
val loss = history1.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, "bo", label="Training accuracy")
plt.plot(epochs, val_accuracy, "b", label="Validation accuracy")
plt.title("Training and validation accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, "bo", label="Training loss")
plt.plot(epochs, val loss, "b", label="Validation loss")
plt.title("Training and validation loss")
plt.legend()
plt.show()
# Final Values
print("Final Training loss: ",history1.history['loss'][-1],"\nFinal Training
Accuracy: ", history1.history['accuracy'][-1])
print("Final Validation loss: ",history1.history['val_loss'][-1],"\nFinal
Validation Accuracy: ", history1.history['val accuracy'][-1])
## Evaluate Model
pvcm1.evaluate(test_dataset)
# CNN Model 2 Panda vs Cat (w/L2) (pvcm2)
inputs = keras.Input(shape=(180, 180, 3))
x = layers.Rescaling(1./255)(inputs)
x = layers.Conv2D(filters=32, kernel size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Dropout(.25)(x)
x = layers.Conv2D(filters=64, kernel size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Dropout(.25)(x)
x = layers.Conv2D(filters=128, kernel_size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Dropout(.25)(x)
x = layers.Conv2D(filters=256, kernel size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Dropout(.25)(x)
x = layers.Conv2D(filters=256, kernel size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
```

```
x = layers.Flatten()(x)
x = layers.Dropout(.25)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
pvcm2 = keras.Model(inputs=inputs, outputs=outputs)
pvcm2.summary()
## Configure Model for Training
pvcm2.compile(loss = "binary_crossentropy", optimizer="rmsprop",
metrics=["accuracy"])
## Fitting the Model using a Dataset
callbacks = [
    keras.callbacks.ModelCheckpoint(
        filepath="pvcm2.h5",
        save best only = True,
        monitor = "val loss")
1
history2 = pvcm2.fit(
    train dataset,
    epochs = 14,
    validation data = valdiation dataset,
    callbacks = callbacks
)
## Displaying Curves of Loss and Accuracy during Training
accuracy = history2.history["accuracy"]
val_accuracy = history2.history["val_accuracy"]
loss = history2.history["loss"]
val loss = history2.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, "bo", label="Training accuracy")
plt.plot(epochs, val_accuracy, "b", label="Validation accuracy")
plt.title("Training and validation accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, "bo", label="Training loss")
plt.plot(epochs, val_loss, "b", label="Validation loss")
plt.title("Training and validation loss")
plt.legend()
plt.show()
# Final Values
```

```
print("Final Training loss: ",history2.history['loss'][-1],"\nFinal Training
Accuracy: ", history2.history['accuracy'][-1])
print("Final Validation loss: ",history2.history['val_loss'][-1],"\nFinal
Validation Accuracy: ", history2.history['val accuracy'][-1])
## Evaluate Model
pvcm2.evaluate(test_dataset)
# CNN Model 3 Panda vs Cat (w/Data Augmentation) (pvcm3)
data augmentation = keras.Sequential(
      layers.RandomFlip("horizontal"),
      layers.RandomRotation(.1),
      layers.RandomZoom(.2)
    ]
)
inputs = keras.Input(shape=(180, 180, 3))
x = data augmentation(inputs)
x = layers.Rescaling(1./255)(x)
x = layers.Conv2D(filters=32, kernel size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Dropout(.15)(x)
x = layers.Conv2D(filters=64, kernel size=3,
kernel_regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Dropout(.25)(x)
x = layers.Conv2D(filters=128, kernel size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool_size=2)(x)
x = layers.Dropout(.5)(x)
x = layers.Conv2D(filters=256, kernel size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Dropout(.25)(x)
x = layers.Conv2D(filters=256, kernel size=3,
kernel regularizer=regularizers.l2(.0001),activation="relu")(x)
x = layers.Flatten()(x)
x = layers.Dropout(.25)(x)
outputs = layers.Dense(1, activation="sigmoid")(x)
pvcm3 = keras.Model(inputs=inputs, outputs=outputs)
pvcm3.summary()
## Configure Model for Training
```

```
pvcm3.compile(loss = "binary crossentropy", optimizer="rmsprop",
metrics=["accuracy"])
## Fitting the Model using a Dataset
callbacks = [
    keras.callbacks.ModelCheckpoint(
        filepath="pvcm3.h5",
        save best only = True,
        monitor = "val loss")
]
history3 = pvcm3.fit(
    train dataset,
    epochs = 65,
    validation data = valdiation dataset,
    callbacks = callbacks
)
## Displaying Curves of Loss and Accuracy during Training
accuracy = history3.history["accuracy"]
val accuracy = history3.history["val accuracy"]
loss = history3.history["loss"]
val loss = history3.history["val loss"]
epochs = range(1, len(accuracy) + 1)
plt.plot(epochs, accuracy, "bo", label="Training accuracy")
plt.plot(epochs, val_accuracy, "b", label="Validation accuracy")
plt.title("Training and validation accuracy")
plt.legend()
plt.figure()
plt.plot(epochs, loss, "bo", label="Training loss")
plt.plot(epochs, val loss, "b", label="Validation loss")
plt.title("Training and validation loss")
plt.legend()
plt.show()
# Final Values
print("Final Training loss: ",history3.history['loss'][-1],"\nFinal Training
Accuracy: ", history3.history['accuracy'][-1])
print("Final Validation loss: ",history3.history['val loss'][-1],"\nFinal
Validation Accuracy: ", history3.history['val accuracy'][-1])
## Evaluate Model
pvcm3.evaluate(test dataset)
```