

# Zehao Xu

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## EDUCATION

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**Zhejiang University** Current GPA: 3.93/4.00 Ranking: 2/121 Sep. 2015 – June 2019

- Major: *Automation* Major GPA: 4.00/4.00
- Minor: *Intensive Training Program of Innovation and Entrepreneurship*
- Relevant Coursework: Data Structure, Object-Oriented Programming, Computer Networks, Data Analysis and Algorithm Design, Principles of Database Systems, Software Technology, Linear Algebra, Probability and Statistics.

**University of California, Los Angeles** Summer Research Assistant July 2018 – Sep. 2018

## WORK EXPERIENCES

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**Hangzhou Hikvision Digital Technology Co., Ltd (C++)** Nov.2018 - Present

*Software Development Intern, Advanced Graphics and Vision Group*

- Designed and implemented a cloud visualization dashboard to render raw point cloud data for development.
- Built a point cloud preprocessing tool that performs denoising and amends dynamic distortion of input signal.
- Detected features by SURF and SIFT algorithms separately and compared the time cost of computing descriptors.

## RESEARCH EXPERIENCES

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**Model-based Trajectory Optimization with Nonlinear Programming (C++ & Python)** Prof. Tao Gao

*Research Assistant, Center for Vision, Cognition, Learning, and Autonomy, UCLA* July 2018 – Sep. 2018

- Researched on trajectory optimization for feeding to large-scale nonlinear optimizer IPOPT.
- Extracted the cost function from physics engine Mujoco and calculated the violation with numerical methods.
- Designed a data visualization module that can interactively render 3D trajectory animations.
- Optimized the calculation of Jacobian matrix based on profiling data to improve cache and fix memory leaks.

**VFH+ Obstacle Avoidance Algorithm and Simulation Based On EKF-SLAM (MATLAB)** Prof. Rong Xiong

*Research Assistant, Robotics Laboratory, Zhejiang University* Dec. 2017 – May 2018

- Established a robot simulation environment, including obstacle map, omnidirectional mobile robot, and a simulated ultrasonic detector to detect nearby obstacles using cutting-edge EKF-SLAM algorithms.
- Matched the nearest point of the sensor to the rigid body transform based on ICP (Iterative Closest Point).
- Implemented VFH+ algorithm in MATLAB and successfully conducted simulation tests on various conditions.
- Combined the EKF-SLAM and VFH+ algorithms and achieved superior results in various simulated environments.

**Drone Autopilot Based on Computer Vision and Machine Learning (C++ & Python)** Prof. Dongqin Feng

*Team Leader, Micro Aerial Robot Team Laboratory, Zhejiang University* Jun. 2016 – Jan. 2018

- Developed key modules of embedded flight control system, including sensors signal processing tools, cascade PID control algorithms and Pulse Width Modulation, on a self-designed flight controller.
- Built a real-time multiscale face recognition system on the four-rotor drone using Haar features, LBP features.
- Trained CNN model in TensorFlow for object detection applicable to targets not just limited to human faces.
- Migrated to a real-time compatible solution based on Single Shot Multi-Box Detector using Caffe.
- Implemented optical flow algorithm on flight controller Pixhawk, and conducted secondary development of PX4 firmware to achieve vision-based navigation.

## **Multi-layer Perceptron Classifier Development (C++)**

**Prof. Yu Pan**

*Team Leader, Course Project, OOP, Zhejiang University*

- Developed a MLP classifier from scratch in C++ based on the design principles in TensorFlow.
- Designed the system that can automatically generate the network, ingest training data, and output the optimal weighting parameters for the trained model.
- Employed OOP principles and designed the class inheritance tree, modularized project based major classes.

## **TECHNICAL SKILLS**

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- Programming Languages: C++, C, Python, MATLAB, SQL, CSS&HTML, Java, JavaScript, Assembly
- Tools and Frameworks: TensorFlow, Linux, LabView, AWS EC2, Git, GTest/GMock, OpenCV, Caffe, CMake

## **LEADERSHIP EXPERIENCES**

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Pioneering and Part work-study Instructing Center (University-wide organization)

Sep. 2016 - Sep. 2017

*Minister of Part Time Management Department*

- Managed and operated the school largest and most reliable public welfare platform for part-time tutors.
- Organized the graduation season flea market (brand activity).
- Planned and organized a brand-new activity, Wish List, and was well received by students.

## **VOLUNTEER SERVICES**

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- Led a group of volunteers and guided visitors at West Lake scenic area twice.
- Went to remote rural areas in Ningxia province and taught students there for half a month.
- Volunteered in many large events, such as Internet Conference, sports meeting, New Year Party and many more.
- Totally devoted more than 250 hours to volunteer services and won the honorary title of Outstanding Volunteer at Zhejiang University.

## **AWARDS**

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### **2018:**

- Government Scholarship for Outstanding Merits -- Oct. 2018
- First Class Scholarship for Outstanding Merits -- Oct. 2018
- First Class Scholarship for Outstanding Academic Performance -- Oct. 2018
- Merit Student in Zhejiang University -- Oct. 2018
- Outstand Volunteer at Zhejiang University -- Sep. 2018

### **2017:**

- "Ceway" Scholarship for Outstanding Students -- Oct. 2017
- First Class Scholarship for Outstanding Merits -- Oct. 2017
- First Class Scholarship for Outstanding Academic Performance -- Oct. 2017
- Merit Student in Zhejiang University -- Oct.2017
- Second Prize in "Challenge Cup" National College Student Business Plan Competition -- Sep. 2017
- Third Place in "Zhongkong Cup" Robot Race Transport Tournament -- May 2017

### **2016:**

- Second Class Scholarship for Outstanding Merits -- Oct. 2016
- Second Class Scholarship for Outstanding Academic Performance -- Oct. 2016
- Merit Student in Zhejiang University -- Oct.2016