

# Zehao Xu

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## EDUCATION

<b>University of California, San Diego</b>	<i>M.S. in Computer Science</i>	Sep. 2019 – Dec. 2020
<b>Zhejiang University</b>	<i>B.E. in Automation</i>	Sep. 2015 – June 2019
<ul style="list-style-type: none"><li>• Overall GPA: 3.9/4.0 • Ranking: 3/121 • Major GPA: 4.0/4.0</li><li>• Relevant Coursework: Data Structure, Object-Oriented Programming Technology, Data Analysis and Algorithm Design, Computer Networks, Principles of Database Systems, Software Technology, Linux Application.</li></ul>		

## TECHNICAL SKILLS

- **Languages:** Java, Python, C/C++, JavaScript, HTML/CSS
- **Tools/Frameworks:** React.js, Redux, Node.js, Express, Spring, Bootstrap, Sass, Git, GTest/GMock, TensorFlow
- **Databases:** MongoDB, MySQL

## WORK EXPERIENCES

<b>Hangzhou Hikvision Digit Technology Co., Ltd</b> (C++ & React.js & Express & Node.js)	Hangzhou, China
<i>Software Engineer Intern, Mobile Robot Department, Point Cloud Team</i>	Oct. 2018 - Jan. 2019
<ul style="list-style-type: none"><li>• Developed a point cloud visualization dashboard web application based on MVC for rendering point cloud images and parameters to provide data-driven references for upper management, which was used by <b>10+</b> teams.</li><li>• Created the front-end interface using <b>D3.js</b> and <b>React.js</b> with Context API for comprehensive data visualization.</li><li>• Built backend service using <b>Node.js</b>, <b>Express</b> framework, with <b>MongoDB</b>, and built authentication API with <b>JWT</b>.</li><li>• Designed a point cloud preprocessing tools that performs denoising of input signals using C++ and PCL.</li><li>• Implemented SURF and SIFT feature detection algorithms and compared the time cost of computing descriptors.</li></ul>	

## PROJECT EXPERIENCES

<b>Project Management Web Application</b> (React.js & Redux)	July 2019 - Aug. 2019
<ul style="list-style-type: none"><li>• Designed responsive layout structure with Flexbox and beautified UI with <b>React Bootstrap</b> components.</li><li>• Maintained the large stylesheets using Sass and CSS Modules and customized the default search bar style.</li><li>• Built the front-end interface using <b>React.js</b> and managed the whole states of the application using <b>Redux</b>.</li><li>• Created a mock back-end using Json-Server to get fake REST APIs and server responses for front-end developing.</li></ul>	
<b>Model-based Trajectory Optimization with Nonlinear Programming</b> (C++ & Python)	Prof. Tao Gao
<i>Research Assistant, University of California, Los Angeles</i>	July 2018 – Sep. 2018
<ul style="list-style-type: none"><li>• Researched on data-driven trajectory optimization method for feeding large-scale nonlinear optimizer IPOPT.</li><li>• Extracted the constrain function from physics engine Mujoco and calculated the violation with numerical methods.</li><li>• Designed a data visualization module that can interactively render 3D trajectory animations using OpenGL.</li><li>• Optimized the calculation of Jacobian matrix based on profiling data and improve cache performance by <b>40%</b>.</li><li>• Wrote unit test using <b>GTest/GMock</b> framework in C++ with rigorous practice to maintain test coverage above <b>90%</b>.</li></ul>	
<b>Diseases Diagnosis with YOLOv3 Model on Chest X-Ray Images</b> (Python)	Prof. Jiangang Lu
<i>Graduation Project</i>	Mar. 2019 - June 2019
<ul style="list-style-type: none"><li>• Adjusted YOLOv3 model to medical images and implemented K-means cluster algorithm to get better anchors.</li><li>• Implemented adaptive learning rate scheduler based on real-time loss to reduce learning rate on plateau.</li><li>• Designed 3-level training strategy based on the network structure and finally improved the recall rate of Cardiomegaly to <b>92%</b> and meanwhile maintained a relatively high precision rate.</li></ul>	
<b>Self-designed Drone Autopilot Based on Computer Vision</b> (C++ & Python)	Prof. Dongqin Feng
<i>Team Leader, Micro Aerial Robot Team Laboratory, Zhejiang University</i>	Jun. 2016 – Jan. 2018
<ul style="list-style-type: none"><li>• Developed key modules of embedded flight control system on a self-designed flight controller.</li><li>• Trained CNN model in TensorFlow and migrated to a real-time compatible solution based on YOLOv3 model.</li><li>• Conducted secondary development on open source flight controller Pixhawk to achieve vision-based navigation.</li></ul>	