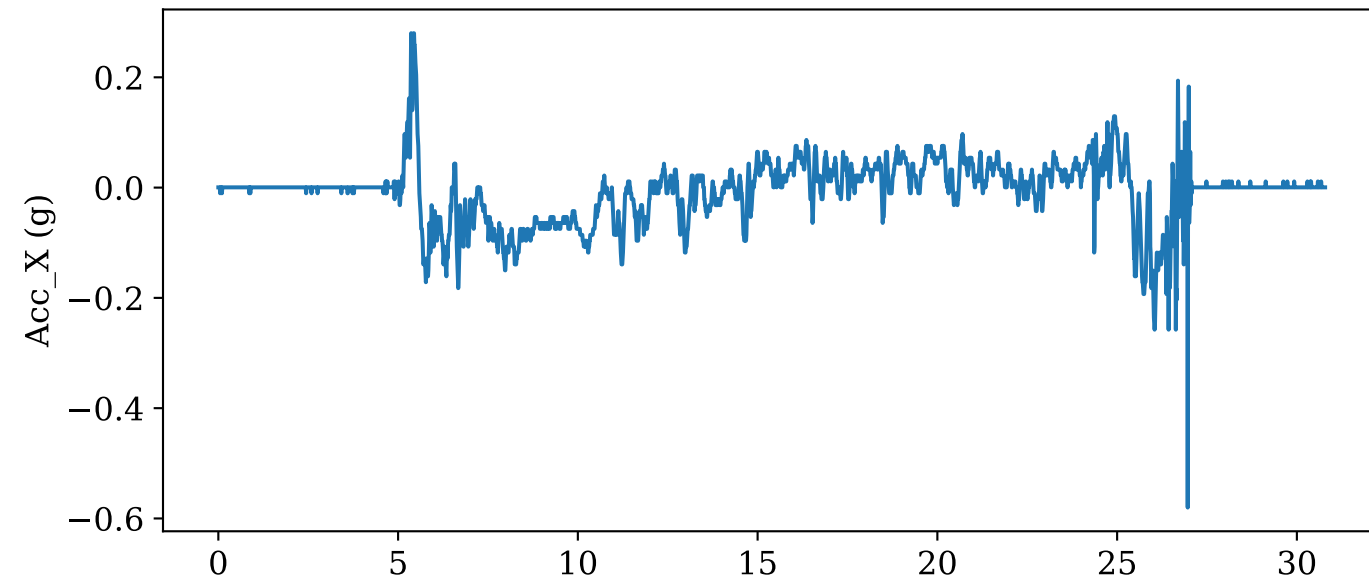


# Processed IMU data

## Accelerometer



## Gyroscope

