

Gated Recurrent Unit (GRU)

GRU

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- Proposed in 2014

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- Simpler alternative to LSTM (fewer gates)

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Gated Recurrent Unit:

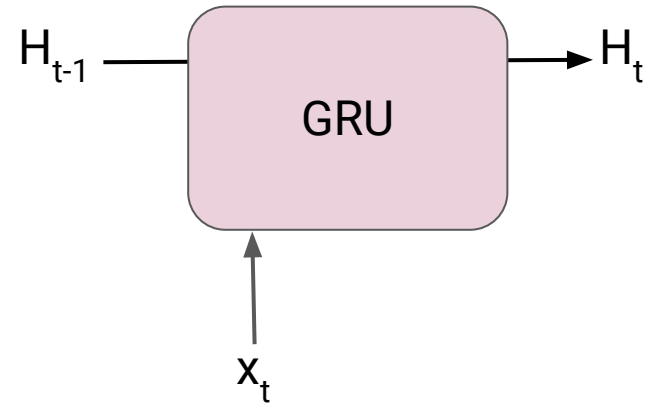
- Proposed in 2014
- Simpler alternative to LSTM (fewer gates)
- No separate cell state (C_t)

GRU

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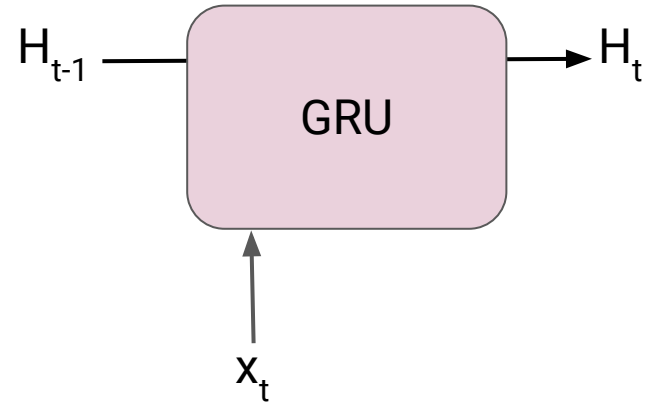
- Proposed in 2014
- Simpler alternative to LSTM (fewer gates)
- No separate cell state (C_t)
- Faster training

GRU



GRU

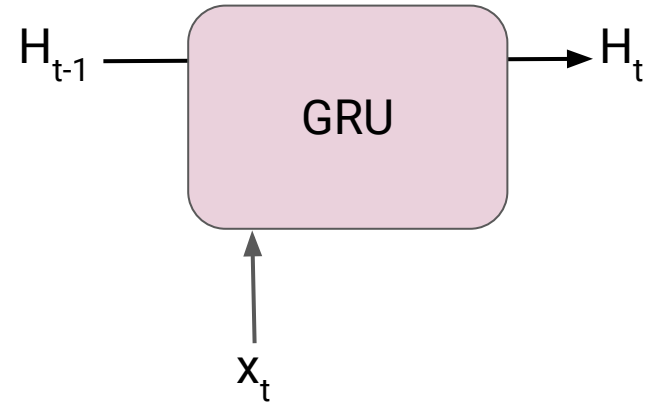
- Reset Gate (short-term memory)



GRU

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$$r_t = \sigma(x_t * U_r + H_{t-1} * W_r)$$

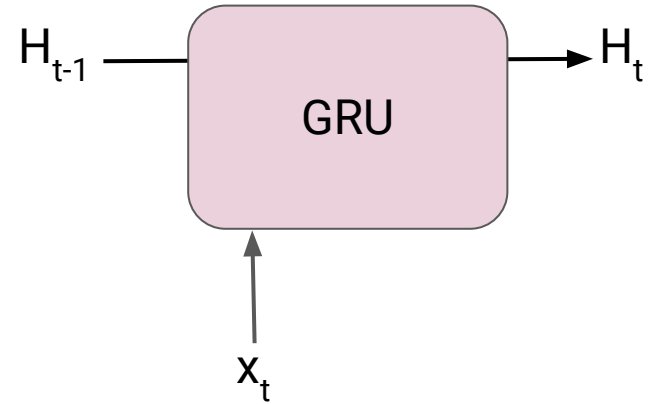


GRU

- Reset Gate (short-term memory)

$$r_t = \sigma(x_t * U_r + H_{t-1} * W_r)$$

- Update Gate (long-term memory)



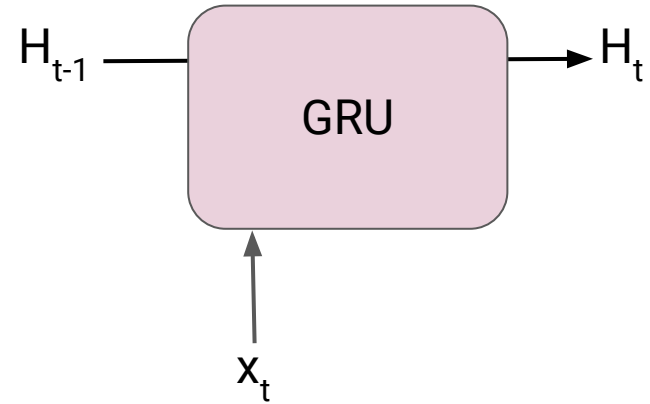
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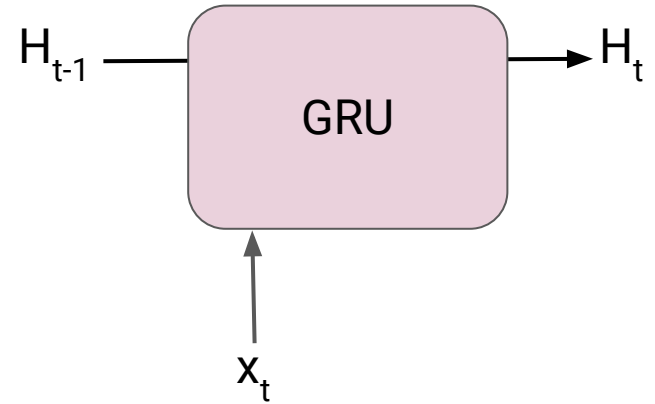
- Update Gate (long-term memory)

$$u_t = \sigma (x_t * U_u + H_{t-1} * W_u)$$



GRU

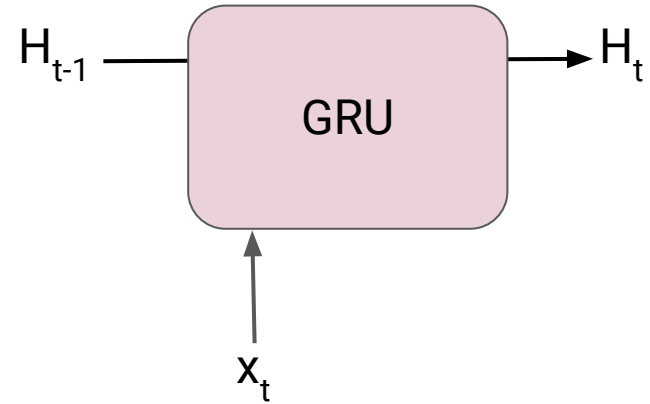
- Find candidate hidden state using new info



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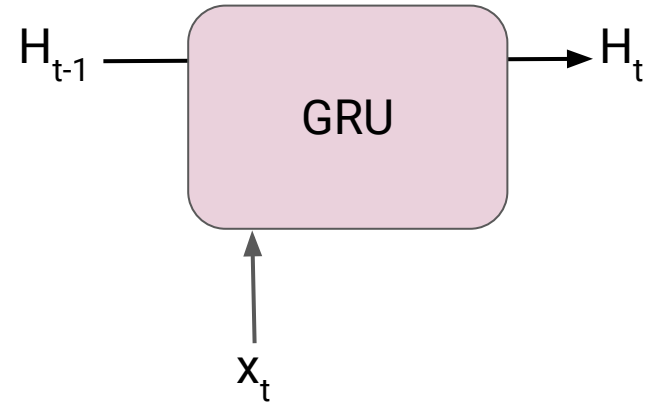
$$\hat{H}_t = \tanh(x_t * U_g + (r_t \circ H_{t-1}) * W_g)$$



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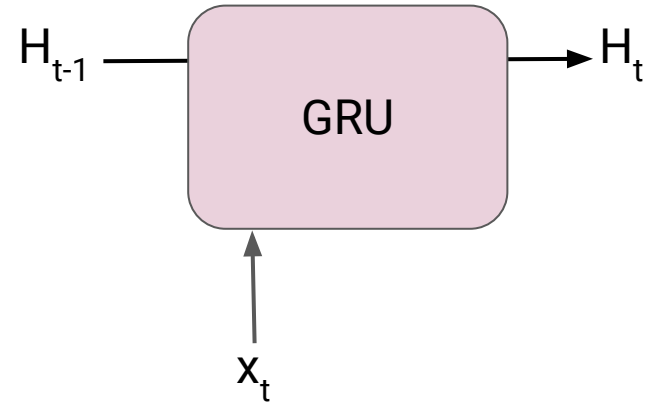


GRU

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$$\hat{H}_t = \tanh(x_t * U_g + (r_t \circ H_{t-1}) * W_g)$$

- Update the hidden state using the update gate



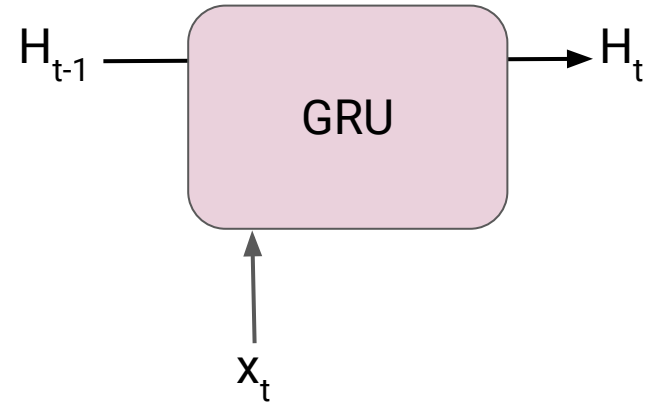
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$$H_t = u_t \circ H_{t-1} + (1-u_t) \circ \hat{H}_t$$



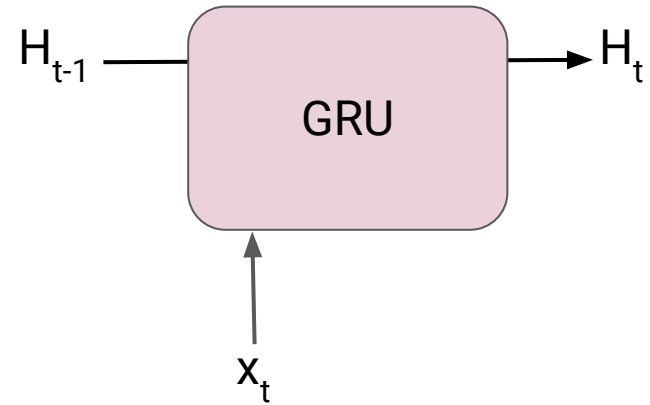
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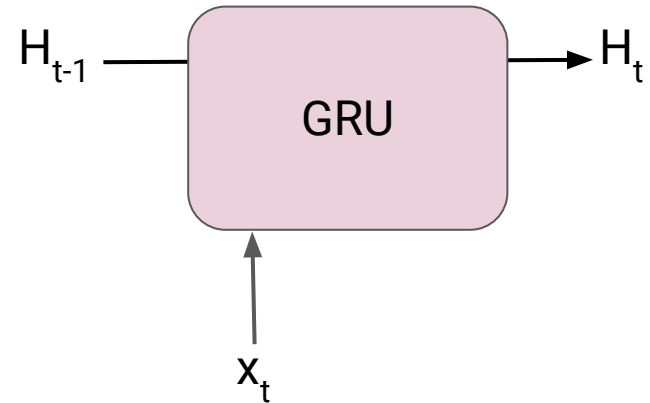
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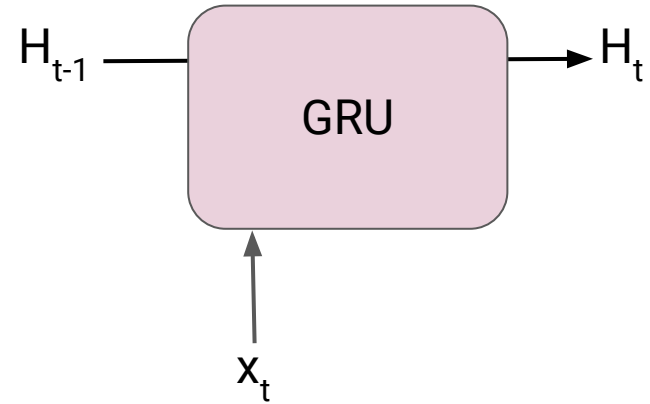
GRU

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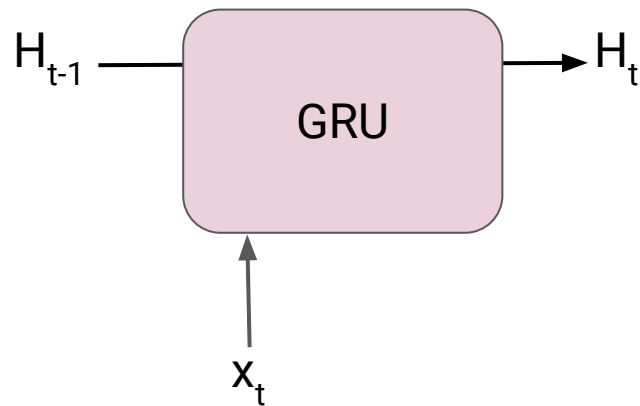
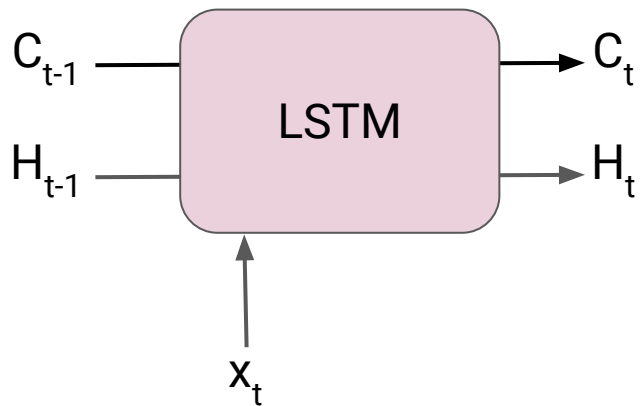
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- Update the hidden state using the update gate

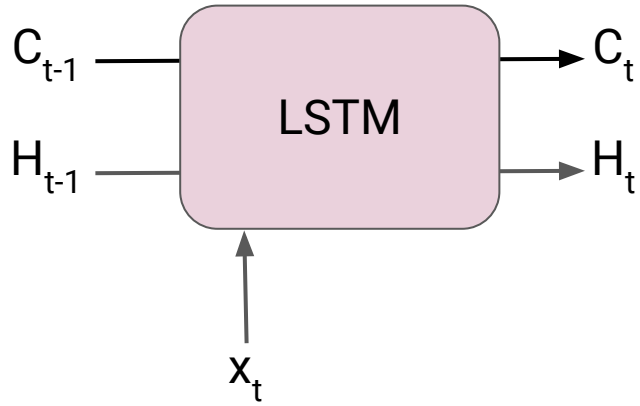
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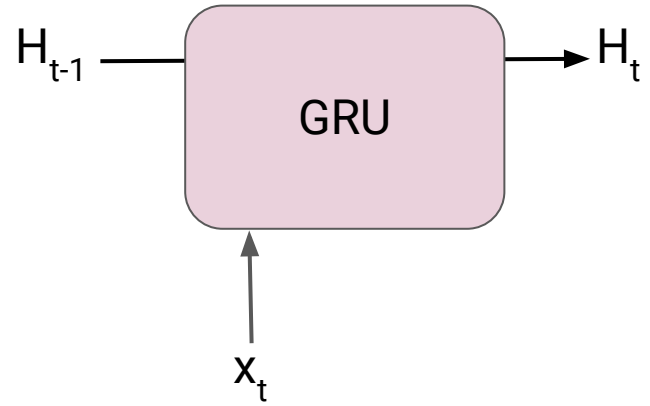
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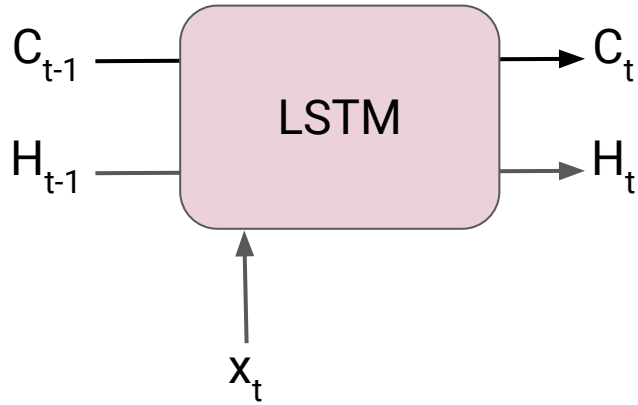


- 3 Gates

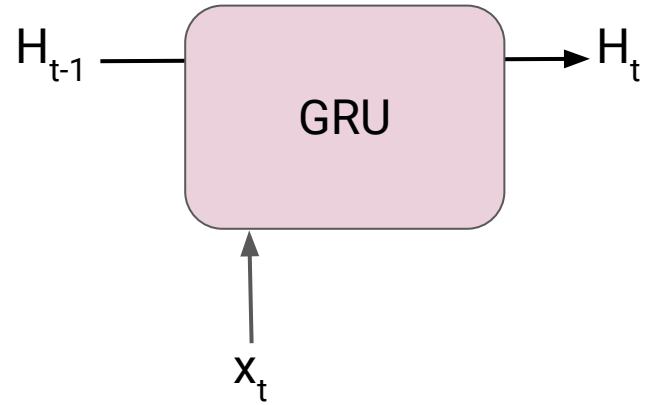


- 2 Gates

GRU

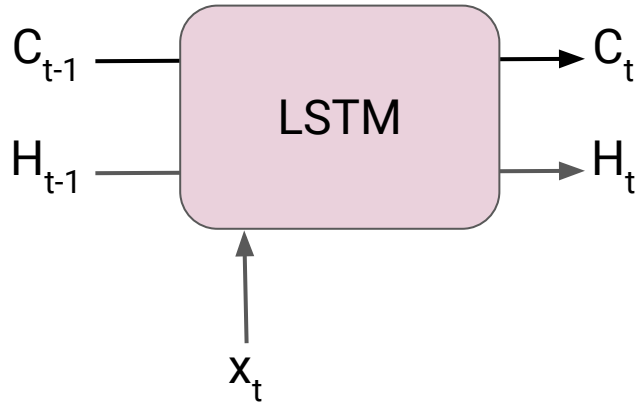


- 3 Gates
- Input, Output, and Forget

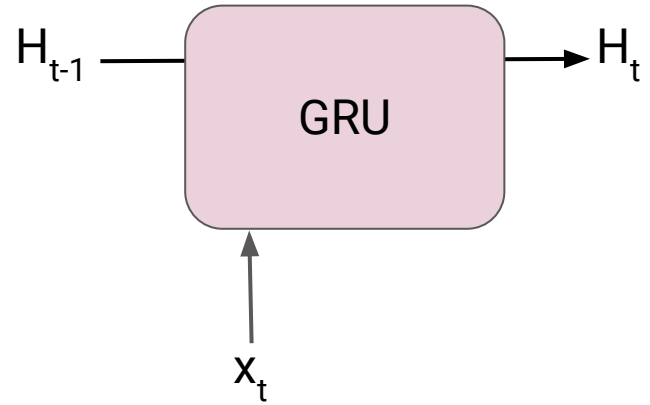


- 2 Gates
- Update and Reset

GRU



- 3 Gates
- Input, Output, and Forget
- Separate cell state C_t and Hidden state H_t



- 2 Gates
- Update and Reset
- Single Hidden state H_t

Thank You