

# Advanced Formal Tools

# PRISM: Probabilistic Model Checking

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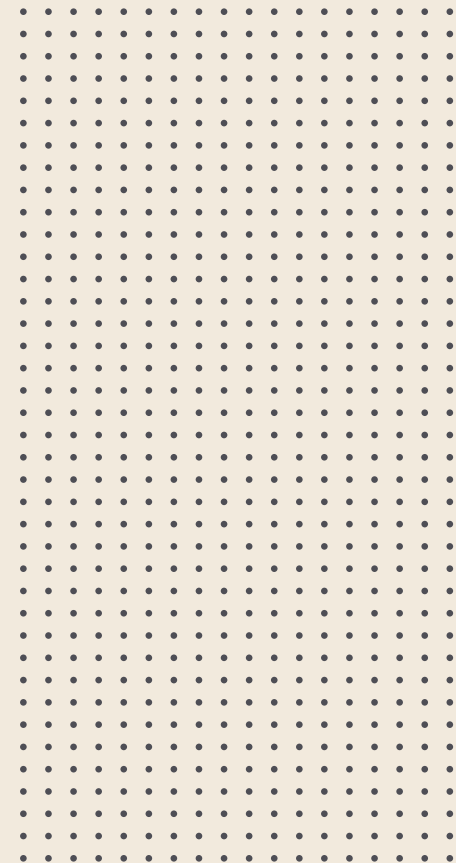
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# Overview

1. Background and Theory
2. PRISM Usage and Limitations
3. Case Study
4. Future Work
5. Conclusion

# Background and theory

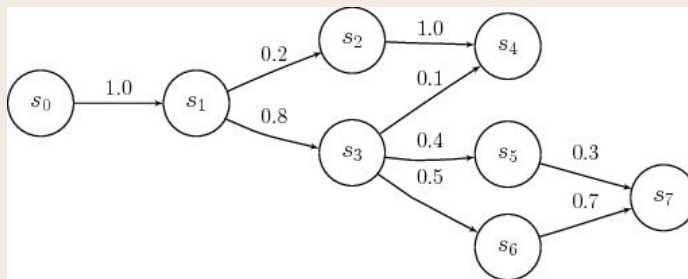
## Probabilistic models

- Discrete Time Markov Chain
- Markov Decision Processes

# Discrete Time Markov Chain

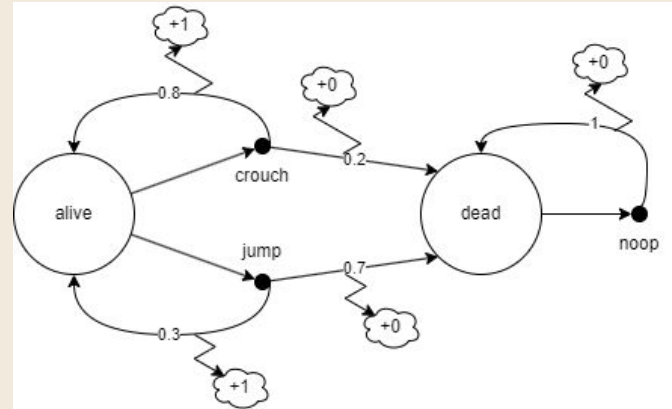
**States:**  $\mathcal{S} = \{s_0, s_1, s_2, s_3, s_4, s_5, s_6, s_7\}$

**Example transition:**  $s_0 \rightarrow s_1$ , probability of 1, thus  $p(s_1|s_0) = 1$



# Markov Decision Process Model

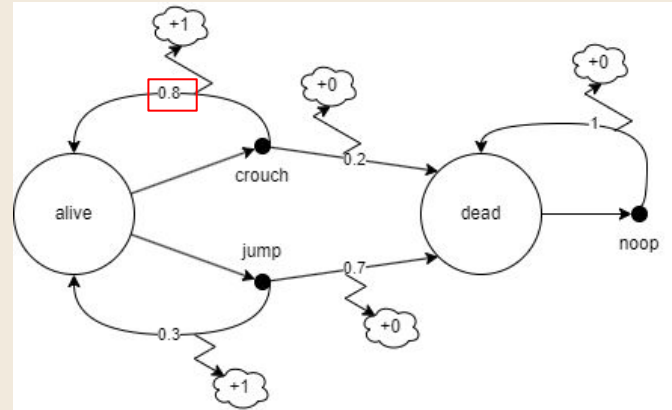
- **States:**
  - alive (init. state)
  - dead
- **Actions:**
  - crouch
  - jump



Non-deterministic, choose crouch or jump from alive ?

# Markov Decision Process Model

- **States:**
  - alive (init. state)
  - dead
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  - crouch
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Non-deterministic, choose crouch or jump from alive ?

- **Env. dynamics:**

$p(s', r | s, a)$

Ex:  $P[S_{t+1} = \text{alive}, R_{t+1} = 1 | S_t = \text{alive}, A_t = \text{crouch}] = 0.8$

# Markov Decision Process

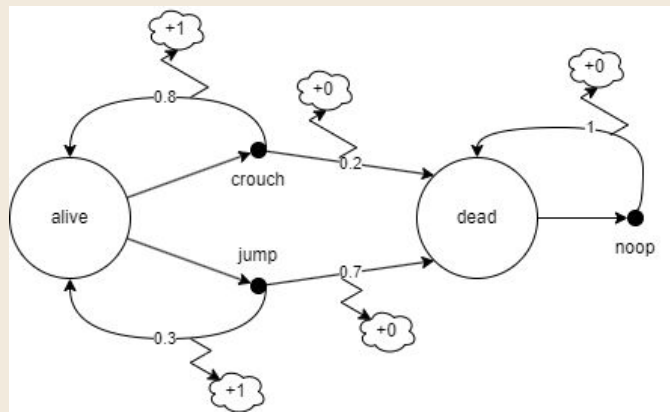
## Policy & objective function

- **Policy/Strategy:**

$$\pi : \mathcal{S} \times \mathcal{A} \rightarrow [0, 1]$$

- **Expected cumulative reward:**

$$E(\pi) = \mathbb{E}_{\pi} \left[ \sum_{i=1}^{\infty} R_i \middle| S_0 = s_0 \right]$$



# Markov Decision Process

## Policy & objective function

- Policy/Strategy:

$$\pi : \mathcal{S} \times \mathcal{A} \rightarrow [0, 1]$$

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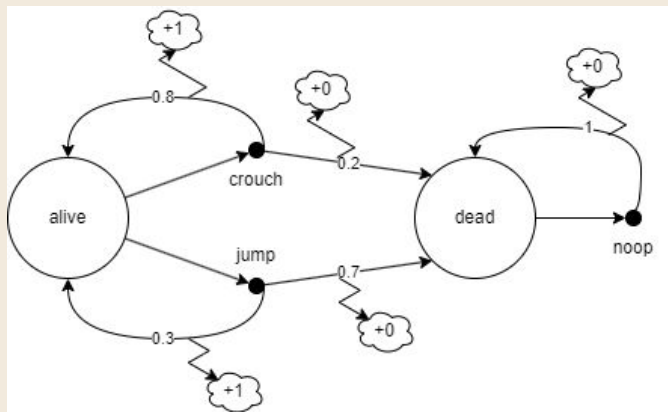
- Best policy:

$$\pi^* = \operatorname{argmax}_{\pi} E(\pi)$$

- Max. expected cumulative reward:

$$E(\pi^*)$$

Rmax=? [F "end"] in PRISM with "end" : s=0 (dead)





# Markov Decision Process

## Policy & objective function

- Policy/Strategy:

$$\pi : \mathcal{S} \times \mathcal{A} \rightarrow [0, 1]$$

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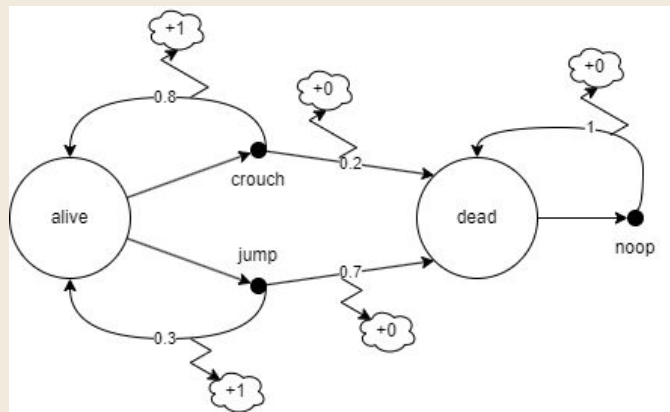
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- Max.** expected cumulative reward:

$$E(\pi^*)$$

Rmax=? [F "end"] in PRISM with "end" : s=0 (dead)



What about **worst** policy ?

**Min.** expected cumulative reward ?

# Markov Decision Process

## Reward structures

- Expected cumulative reward:

$$E(\pi) = \mathbb{E}_{\pi} \left[ \sum_{i=1}^{\infty} R_i \mid S_0 = s_0 \right]$$

- Best policy:

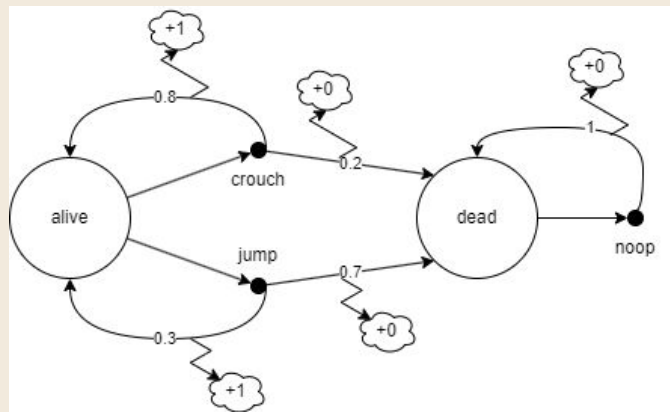
$$\pi^* = \operatorname{argmax}_{\pi} E(\pi)$$

- Max. expected cumulative reward:

$$E(\pi^*)$$

- Different reward distributions: reward structures**

- Enable verification of different props.
- Implicit verification of many MDPs.
- Ex: # of steps



# Prism Usage and Limitations

## Usage

- Coding
- Analysis

## Limitations

# PRISM Representation

mdp

module mdp\_example

s : [0..1] init 1; // Alive initially

// non-deterministic choice from s =1

// jump vs crouch

[jump] (s=1)  $\rightarrow$  0.3: (s'=1) + 0.7: (s'=0);

[crouch] (s=1)  $\rightarrow$  0.8: (s'=1) + 0.2: (s'=0);

[noop] (s=0)  $\rightarrow$  (s'=0); // absorbing state

endmodule

rewards

(s=1) : 1; // reward for staying alive

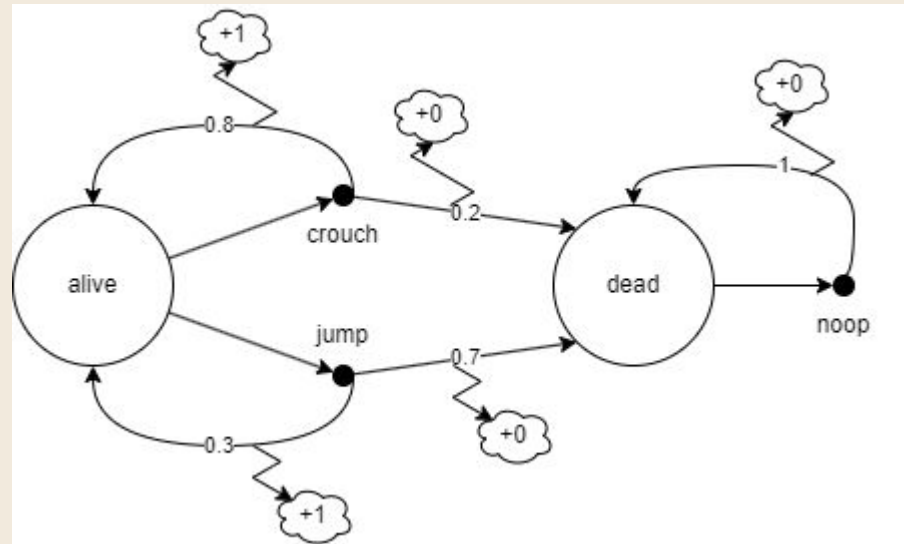
(s=0) : 0; // died

endrewards

rewards "steps"

true : 1;

endrewards



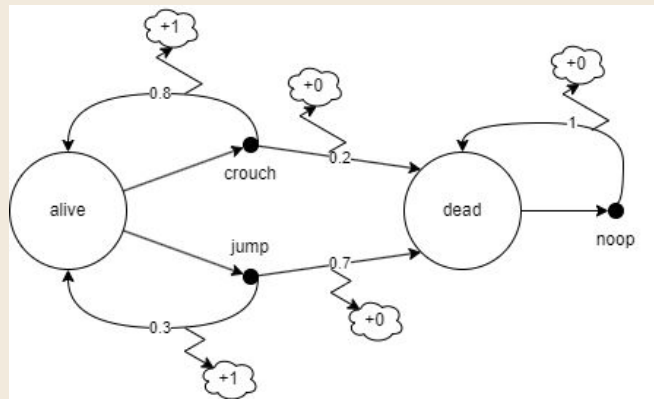
# PRISM Model Analysis

## Simulator

- Sample/simulate paths from probabilities
- Manually choose transitions

## Properties

- PRISM's logics subsumes PCTL and others:
  - Extension with rewards
  - Extension with quantitative prop.



- Example of CTL vs PCTL for a given strategy:

CTL  $E [G s=1]$

Exist path where always alive

PCTL  $P>0 [G \leq 10 s=1]$

Exist a path where alive for at least 10 steps

PRISM  $P=? [G \leq 10 s=1]$

PRISM can get the value (quant. prop.)



# PRISM Limitations



## DevOps

- No CTRL+F
- Missing standard graph tools, need to export data
- No for-loops

## Modeling

- No negative rewards
- Can't assign probability distribution over rewards
- Simulation uses a uniform strategy to resolve non-determinism

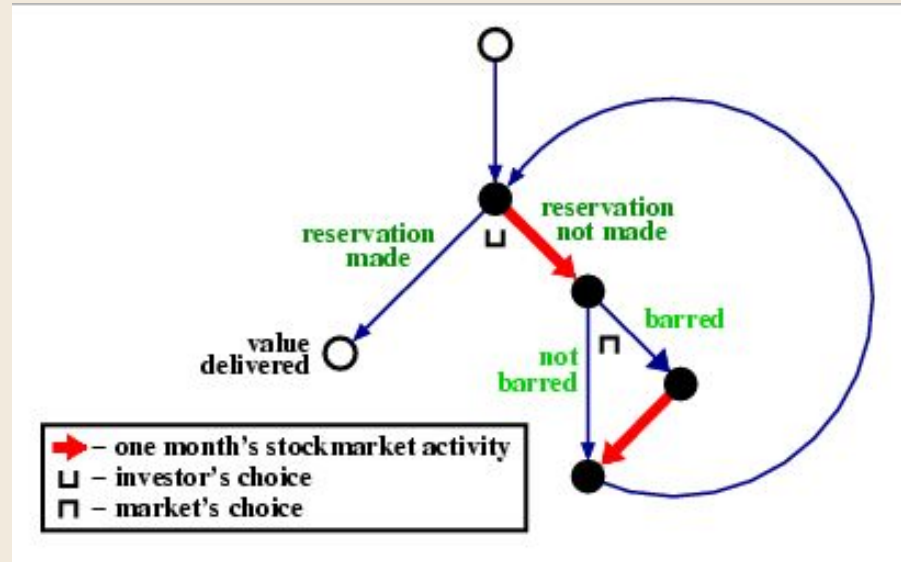
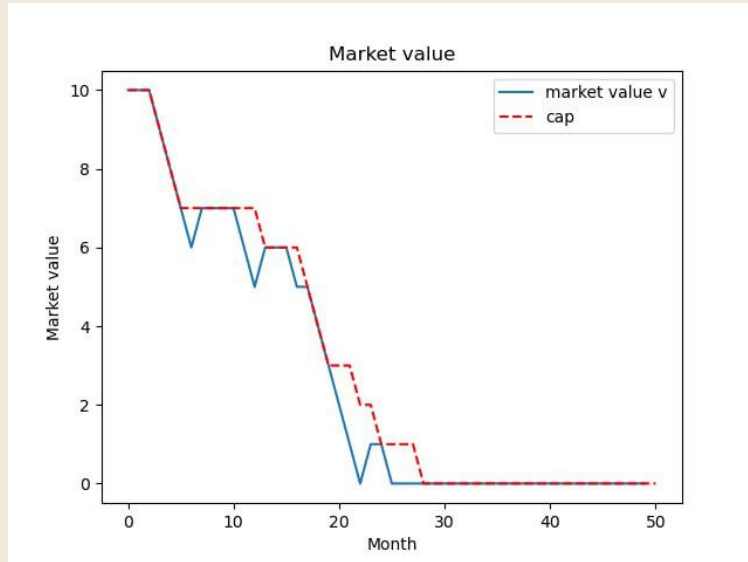
# Case study: Market Bidding Investor

## Description

- Motivations
- Visual representation
- State transition

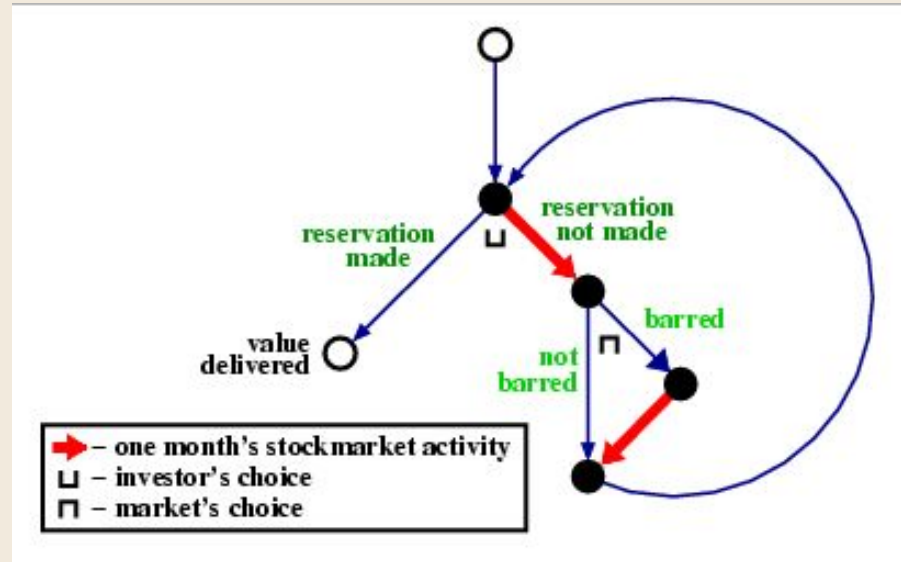
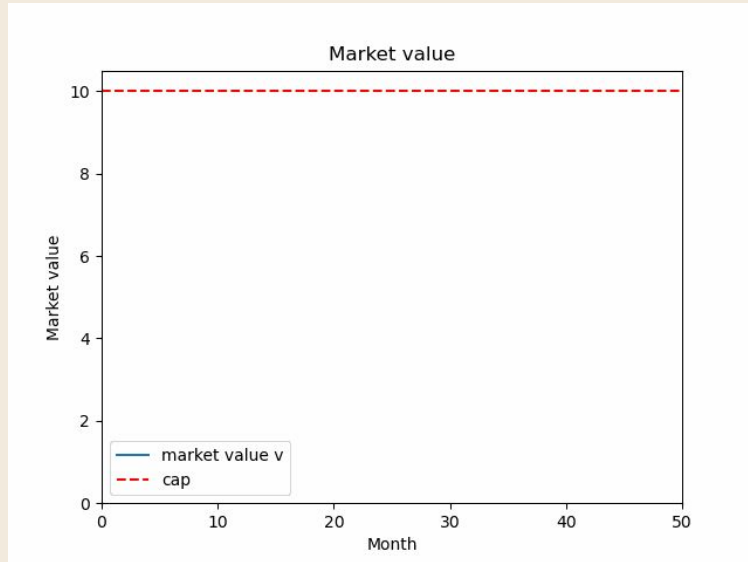
## Analysis and Results

# Original Case Study

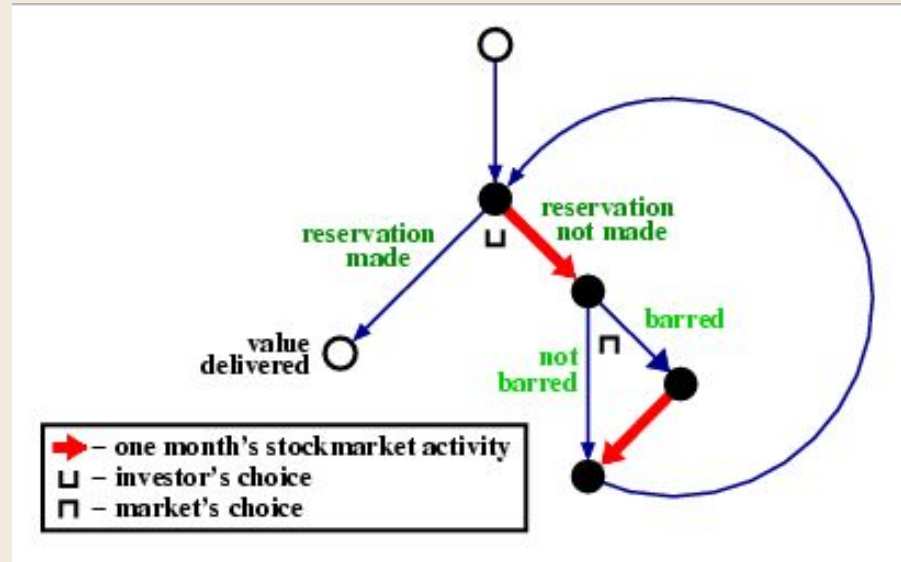
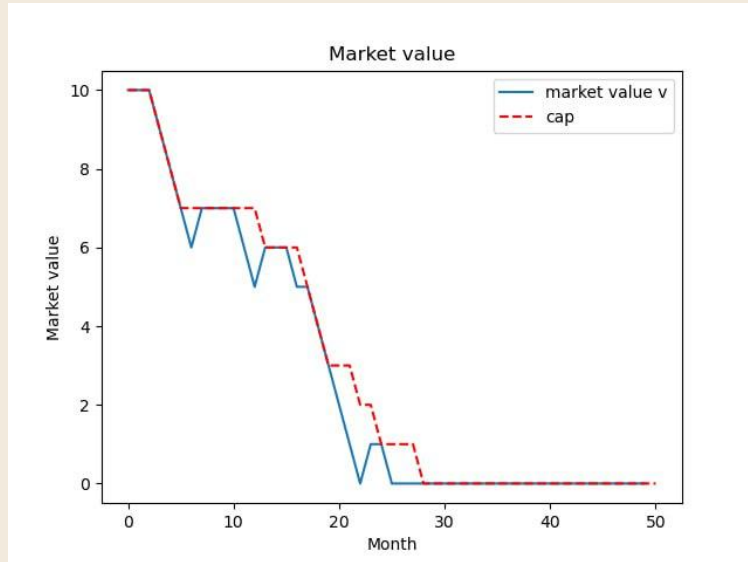




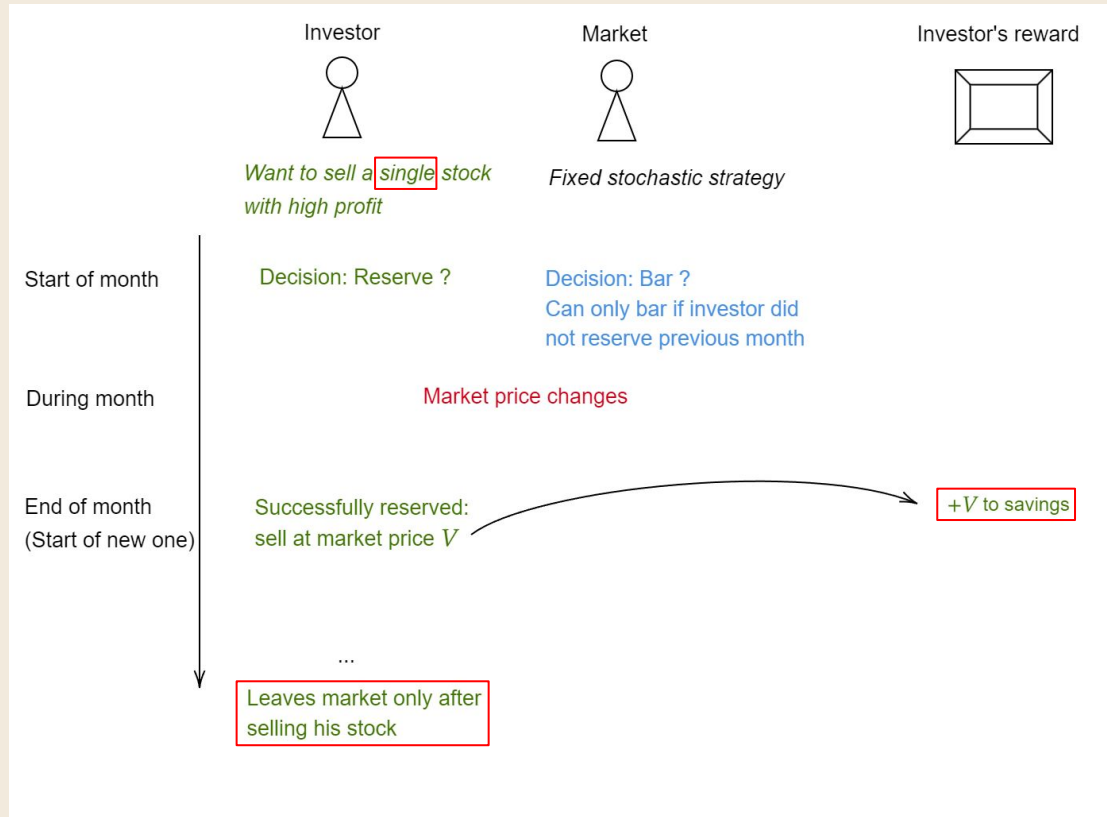
# Original Case Study



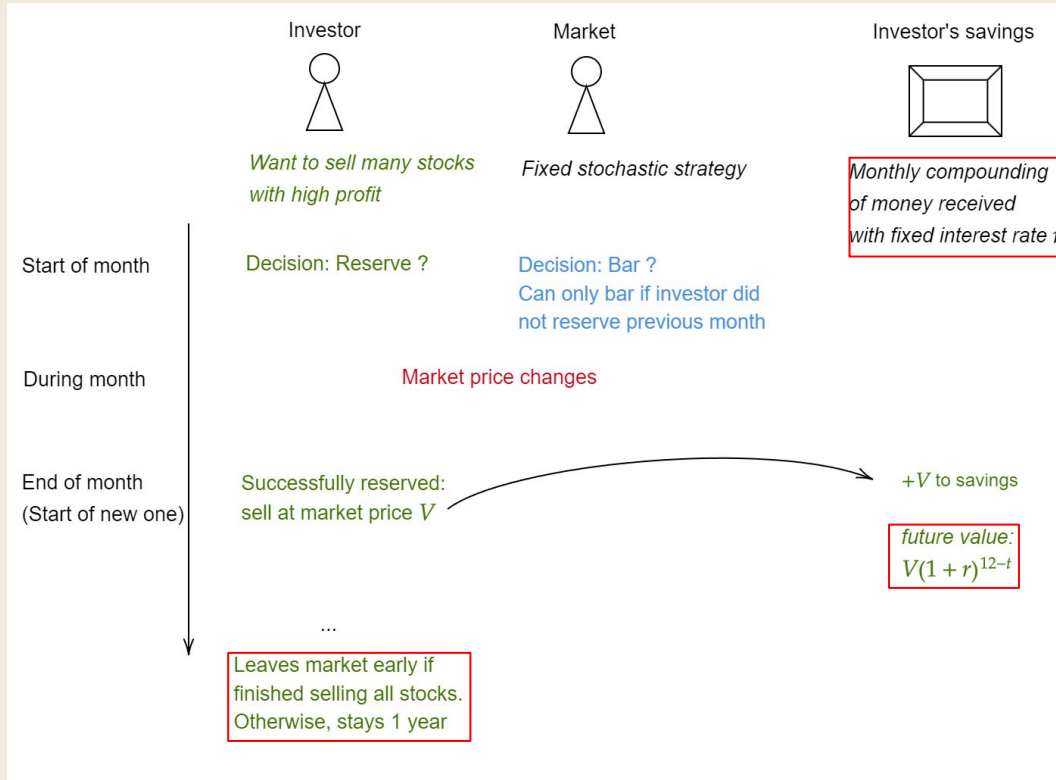
# Original Case Study



# Visual Representation

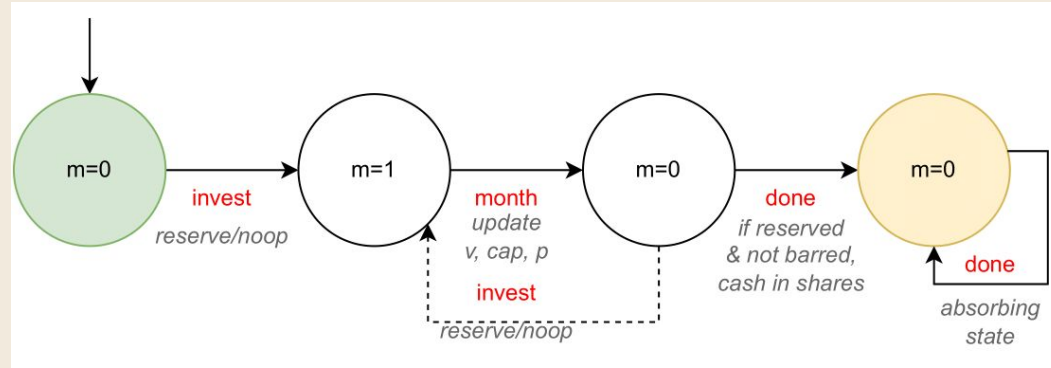


# Extended Version

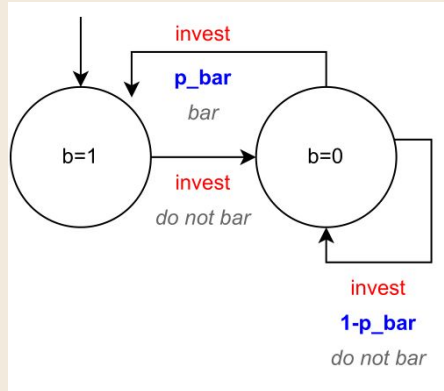


# State transition Representation

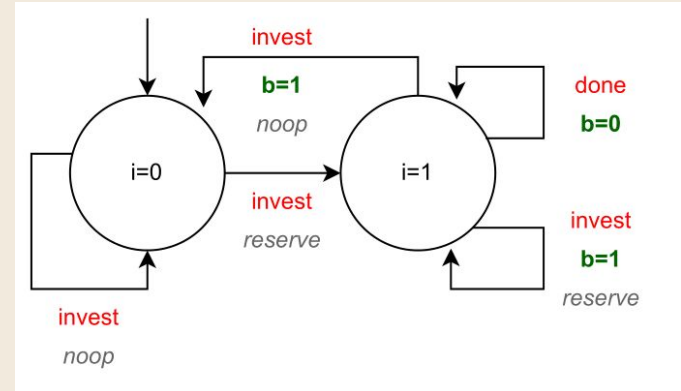
Month Module:



Market Module:

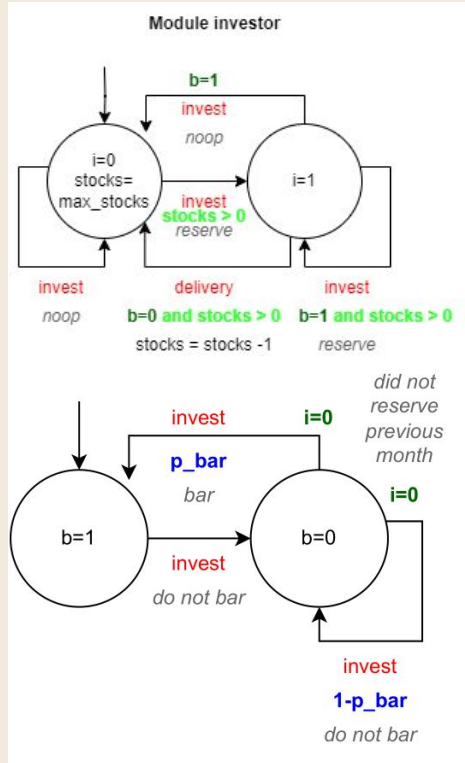


Investor Module:



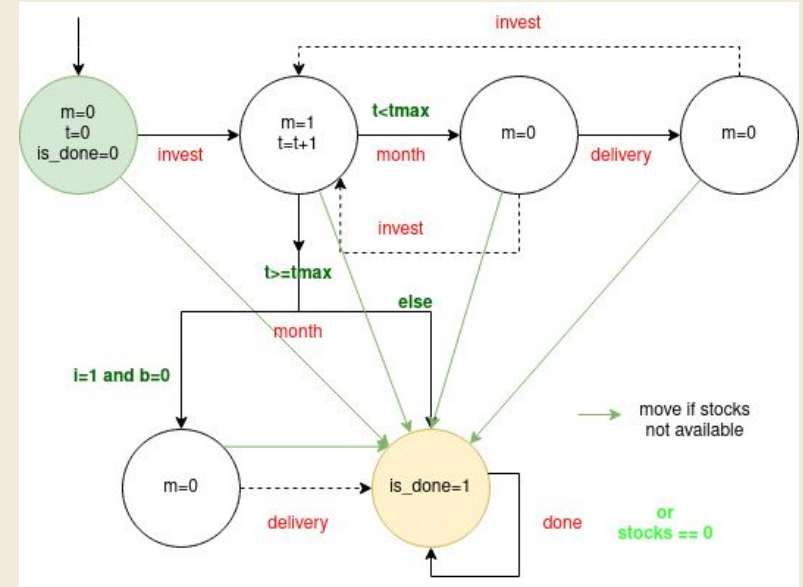
# Representation with Changes

Investor Module:



Market Module:

Month Module:

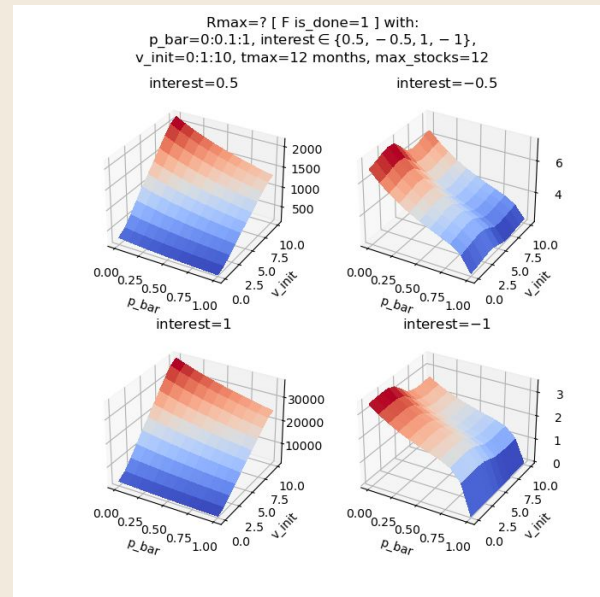
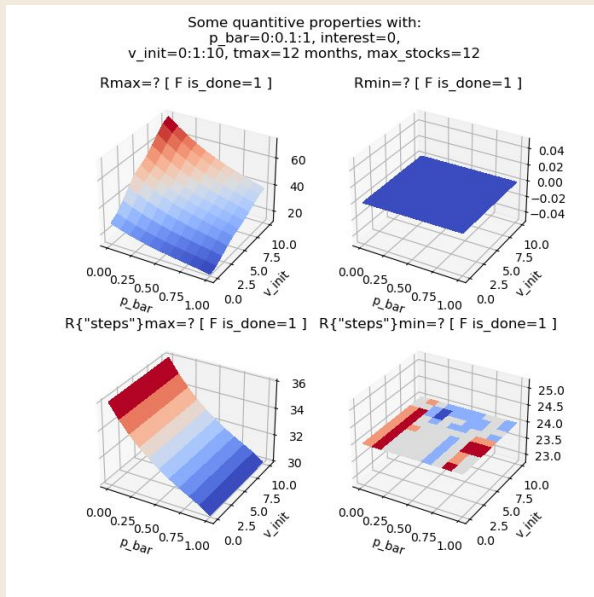
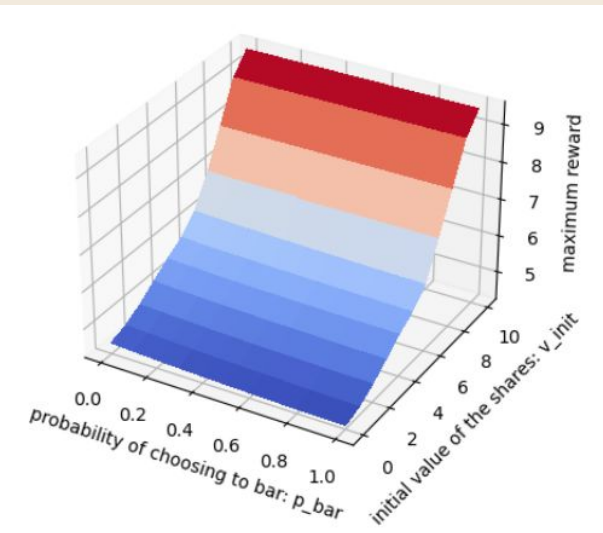




# Results

## Zero interest rate

## Non-zero interest rate



Original case study's results

Our case study's results



# Future Work

- Analyze effect of max\_stocks on expected reward
- Analyze effect of interest together with max\_stocks on number of steps

## PRISM-Games extension

- Analyze the case where market has no predefined strategy (stochastic multiplayer game)
- Introduce another investor, they take turns buying/selling to each other
- Implement a stock Future (both actors settle on a price now, for later)





# Conclusion