# Advanced Formal Tools PRISM: Probabilistic Model Checking

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# **Overview**

- 1. Background and Theory
- 2. PRISM Usage and Limitations
- 3. Case Study
- 4. Future Work
- 5. Conclusion

# **Background and theory**

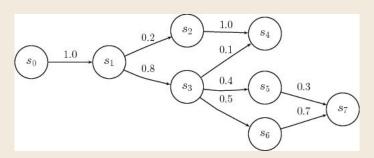
#### Probabilistic models

- Discrete Time Markov Chain
- Markov Decision Processes

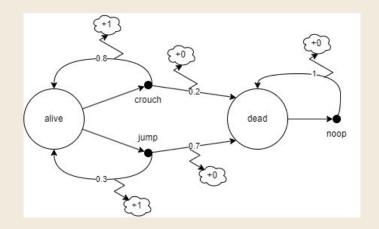
# **Discrete Time Markov Chain**

States: 
$$S = \{s_0, s_1, s_2, s_3, s_4, s_5, s_6, s_7\}$$

**Example transition:**  $\mathbf{s_0} \! \to \! \mathbf{s_1}$ , probability of 1, thus  $p(s_1|s_0) = 1$ 



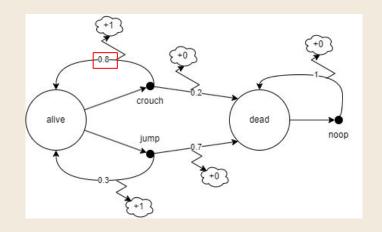
- States:
  - alive (init. state)
  - dead
- Actions:
  - crouch
  - jump



Non-deterministic, choose crouch or jump from alive?

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#### • Env. dynamics:

**Ex:** 
$$P[S_{t+1} = \text{alive}, R_{t+1} = 1 | S_t = \text{alive}, A_t = \text{crouch}] = 0.8$$

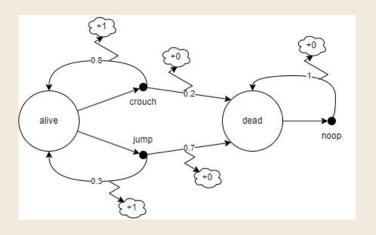
#### **Policy & objective function**

#### Policy/Strategy:

$$\pi: \mathcal{S} \times \mathcal{A} \to [0,1]$$

• Expected cumulative reward:

$$E(\pi) = \mathbb{E}_{\pi} \left[ \sum_{i=1}^{\infty} R_i \middle| S_0 = s_0 \right]$$



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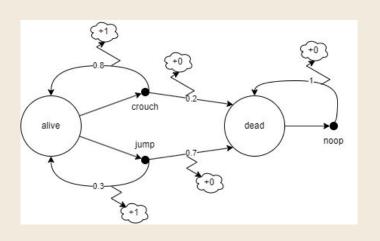
$$E(\pi) = \mathbb{E}_{\pi} \left[ \sum_{i=1}^{\infty} R_i \middle| S_0 = s_0 \right]$$
 • Best policy:

$$\pi^* = \operatorname{argmax}_{\pi} E(\pi)$$

Max. expected cumulative reward:

$$E(\pi^*)$$

Rmax=? [F"end"] in PRISM with "end": s=0 (dead)



#### **Policy & objective function**

Policy/Strategy:

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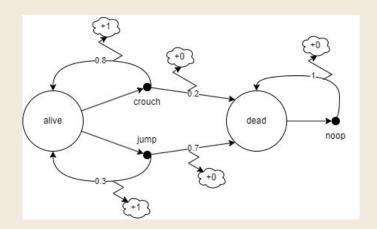
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Max. expected cumulative reward:

$$E(\pi^*)$$



What about worst policy? Min. expected cumulative reward?

Rmax=? [F"end"] in PRISM with "end": s=0 (dead)

#### **Reward structures**

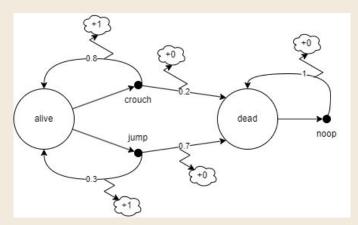
Expected cumulative reward:

$$E(\pi) = \mathbb{E}_{\pi} \left[ \sum_{i=1}^{\infty} R_i \middle| S_0 = s_0 \right]$$

• Best policy:

$$\pi^* = \operatorname{argmax}_{\pi} E(\pi)$$

• Max. expected cumulative reward:  $E(\pi^*)$ 



- Different reward distributions: reward structures
  - Enable verification of different props.
  - Implicit verification of many MDPs.
  - Ex: # of steps

# **Prism Usage and Limitations**

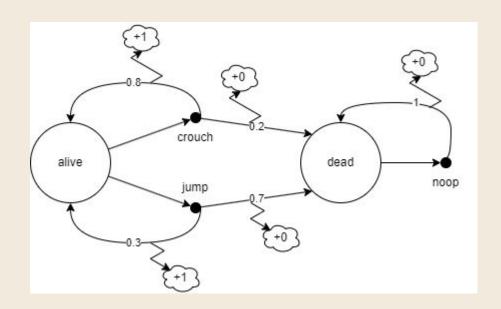
#### <u>Usage</u>

- Coding
- Analysis

#### **Limitations**

# **PRISM Representation**

```
mdp
module mdp example
s: [0..1] init 1; // Alive initially
// non-deterministic choice from s =1
// jump vs crouch
[jump] (s=1) \rightarrow 0.3: (s'=1) + 0.7: (s'=0);
[crouch] (s=1) \rightarrow 0.8: (s'=1) + 0.2: (s'0);
[noop] (s=0) \rightarrow (s'=0); // absorbing state
endmodule
rewards
  (s=1): 1; // reward for staying alive
  (s=0):0; // died
endrewards
rewards "steps"
  true: 1;
endrewards
```



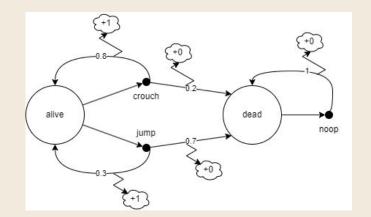
# **PRISM Model Analysis**

#### **Simulator**

- Sample/simulate paths from probabilities
- Manually choose transitions

#### **Properties**

- PRISM's logics subsumes PCTL and others:
  - Extension with rewards
  - Extension with quantitative prop.



Example of CTL vs PCTL for a given strategy:

CTL EG s=1 Exist path where always alive

PCTL P>0[G<=10 s=1] Exist a path where alive for at least 10 steps

PRISM P=?[G<=10 s=1] PRISM can get the value (quant. prop.)

### **PRISM Limitations**

#### Dev0ps

- No CTRL+F
- Missing standard graph tools, need to export data
- No for-loops

#### **Modeling**

- No negative rewards
- Can't assign probability distribution over rewards
- Simulation uses a uniform strategy to resolve non-determinism

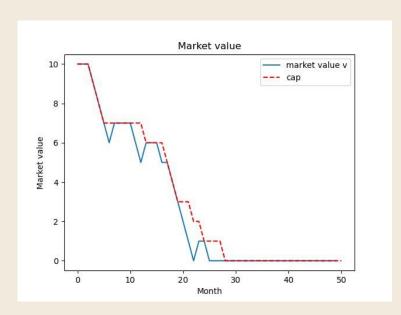
# Case study: Market Bidding Investor

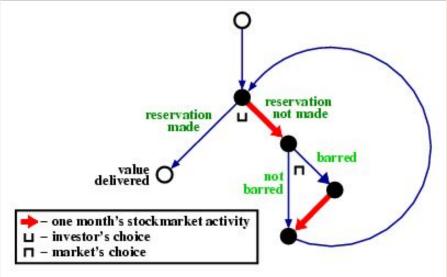
#### **Description**

- Motivations
- Visual representation
- State transition

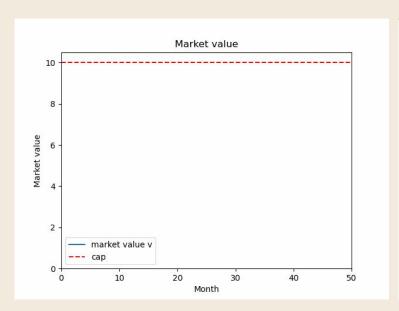
#### **Analysis and Results**

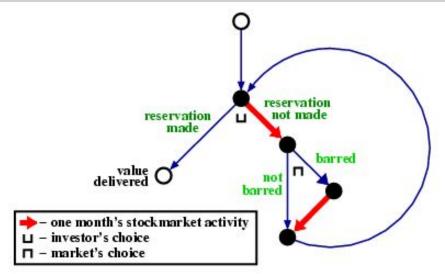
# **Original Case Study**



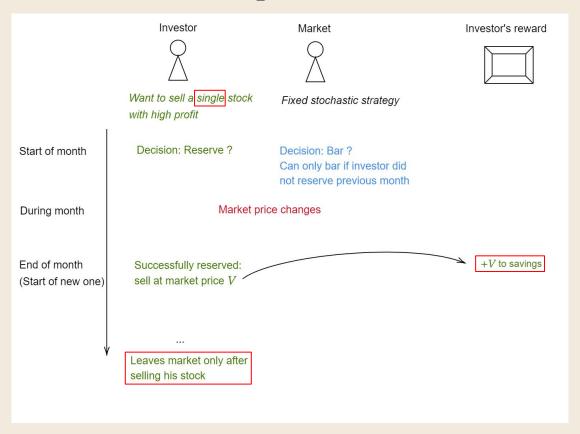


# **Original Case Study**

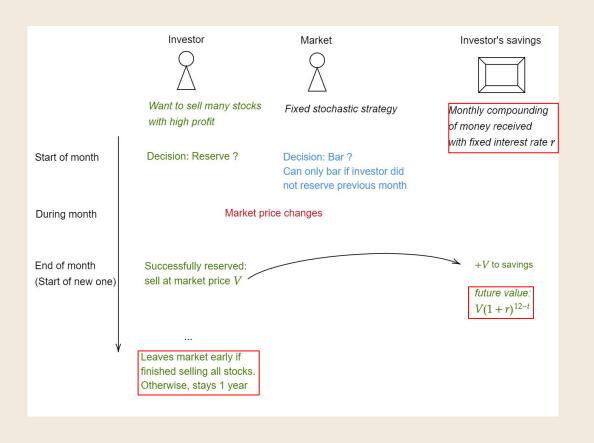




# **Visual Representation**

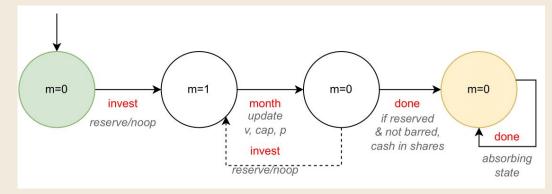


### **Extended Version**

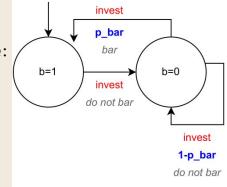


# **State transition Representation**

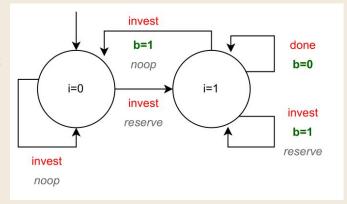
Month Module:



Market Module:



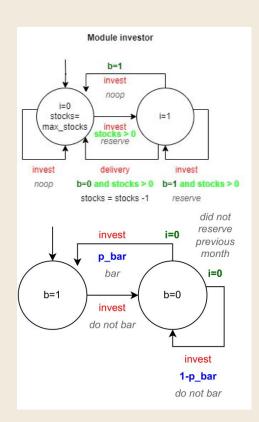
Investor Module:



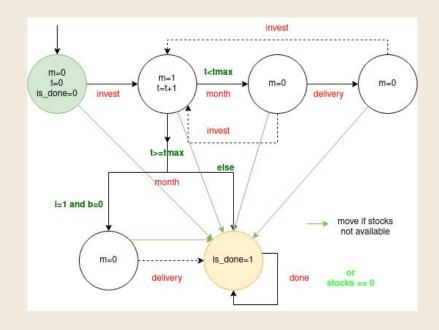
# Representation with Changes

Investor Module:

Market Module:



#### Month Module:



# Results

#### Zero interest rate

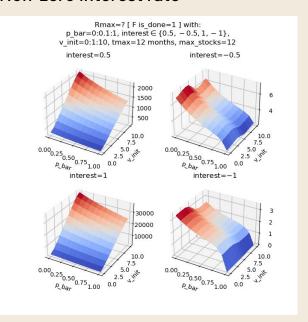
reward

maximum

inita value of the states, vinit

#### Some quantitive properties with: p\_bar=0:0.1:1, interest=0, v init=0:1:10, tmax=12 months Rmax=? [Fis done=1] Rmin=? [ F is done=1 ] 0.04 0.02 0.00 -0.02 -0.0410.0 10.0 7.5 7.5 0.00<sub>0.25</sub> 0.50<sub>0.75</sub> 1.00 0.0 0.0000.2500.7500.75 5.0 Jink 5.0 Juit R{"steps"}max=?[Fis\_done=1] R{"steps"}min=?[Fis\_done=1] 25.0 24.5 24.0 23.5 23.0 10.0 10.0 7.5 7.5 0.00<sub>0.25</sub><sub>0.50</sup><sub>0.75</sub><sub>1.00</sub></sub> 0.00 0.25 0.50 0.75 1.00 0.0 5.0 Jink 5.0

#### Non-zero interest rate



probability of choosing to bar: p bar

### **Future Work**

- Analyze effect of interest together with max\_stocks on number of steps
- Analyze effect of max\_stocks on expected reward

#### PRISM-Games extension

- Analyze the case where market has no predefined strategy (stochastic multiplayer game)
- Introduce another investor, they take turns buying/selling to each other
- Implement a stock Future (both actors settle on a price now, for later)

# Conclusion

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