

# 04: Changing to the Eigenbasis & Diagonalization

**Chapter Goal:** To understand the practical **utility** of the [Eigenbasis](#) concept by using it to solve the difficult problem of raising a matrix to a high power. This is the Coursera version of 3Blue1Brown's Chapter 14 finale.

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## 1. A Practical Problem: Raising a Matrix to a Power

- **Context:** Imagine we have a transformation  $T$  that represents the change in a system over one time step (e.g.,  $\vec{v}_1 = T\vec{v}_0$ ).
  - **The Problem:** How do we calculate the state of the system after  $n$  time steps? ( $\vec{v}_n = T^n\vec{v}_0$ ). This requires us to calculate  $T^n$  (matrix  $T$  multiplied by itself  $n$  times).
  - **The Difficulty:** Calculating  $T^n$  for a large  $n$  (e.g., a million) is a computational nightmare if  $T$  is a standard, non-diagonal matrix.
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## 2. The "Dream Shortcut": Diagonal Matrices

- **Special Case:** If our matrix is a **diagonal matrix**, raising it to a power is incredibly easy.

$$D = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} \implies D^n = \begin{bmatrix} a^n & 0 \\ 0 & b^n \end{bmatrix}$$

We only need to raise each diagonal element to the power  $n$ .

- **Connection to Eigenvectors:** A matrix is diagonal if and only if its standard basis vectors are eigenvectors, and the diagonal entries are the corresponding eigenvalues.
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## 3. Core Idea: Work in the "Perfect World" (The Eigenbasis)

- **Problem:** Our matrix  $T$  is not diagonal in our standard world.
- **Strategy:** Instead of working hard in our world, let's temporarily move to a "perfect world" where the transformation looks simple.
- **What is the "Perfect World"?** It is the world where the basis vectors **are the eigenvectors** of  $T$ . This world is called the [Eigenbasis](#).
- **The Steps:**
  1. **Build the "Translator Dictionary":**
    - Find the eigenvectors of  $T$  (e.g.,  $\vec{v}_1, \vec{v}_2, \vec{v}_3$ ).

- Create the change of basis matrix  $C$ , where the **columns are these eigenvectors**.

$$C = \begin{bmatrix} | & | & | \\ \vec{v}_1 & \vec{v}_2 & \vec{v}_3 \\ | & | & | \end{bmatrix}$$

## 2. The Transformation in the Eigenbasis World:

- In this world, the action of  $T$  is very simple: it just stretches each of its basis vectors by the corresponding eigenvalue.
- Therefore, in the eigenbasis world, the transformation  $T$  is represented by a **diagonal matrix**  $D$ , where the diagonal entries are the eigenvalues  $\lambda_1, \lambda_2, \lambda_3$ .

$$D = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}$$


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## 4. "Aha!" Moment: The Relationship $T = CDC^{-1}$

We now know how to "translate" our transformation  $T$  into the eigenbasis world. This uses the [change of basis formula](#) we've already learned ( $A^{-1}MA$ ).

$$D = C^{-1}TC$$

- $D$  : The diagonal matrix (transformation  $T$  in the eigenbasis world).
- $C$  : The translator from the eigenbasis world to our world.
- $C^{-1}$  : The translator from our world to the eigenbasis world.
- $T$  : The transformation  $T$  in our world.

With a little algebra, we can rewrite this as:

$$T = C D C^{-1}$$

- **Intuitive Meaning:** Performing the complex transformation  $T$  in our world is the same as taking a 3-step journey:
    1.  $C^{-1}$  : Translate into the eigenbasis world.
    2.  $D$  : Perform the simple stretch there.
    3.  $C$  : Translate back to our world.
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## 5. The Solution to the Powering Problem

Now we can calculate  $T^n$  easily. Let's look at  $T^2$ :

$$T^2 = T \cdot T = (CDC^{-1}) \cdot (CDC^{-1})$$

The middle part,  $C^{-1}C$ , is the identity matrix  $I$  (they cancel each other out).

$$T^2 = C \cdot D \cdot I \cdot D \cdot C^{-1} = C \cdot D \cdot D \cdot C^{-1} = CD^2C^{-1}$$

- **General Pattern (The Final Result):**

$$T^n = C D^n C^{-1}$$

- **Why is this so efficient?**

Instead of performing  $n$  complex matrix multiplications, we now only need to:

1. Find  $C$  and  $C^{-1}$  (one time cost).
2. Calculate  $D^n$  (this is super easy, just power the diagonal numbers).
3. Perform two final matrix multiplications ( $C * D^n$ , then the result  $* C^{-1}$ ).

This process, called **Diagonalization**, turns a nearly impossible problem into a few quick computational steps.

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**Tags:** #mml-specialization #linear-algebra #eigenbasis #diagonalization #change-of-basis