

# 05: The Gram-Schmidt Process

**Chapter Goal:** To learn a practical and important algorithm, the **Gram-Schmidt Process**. This is the answer to the question, "What if our basis isn't 'nice'? Can we make it 'nice'?"

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## 1. The Problem: A "Messy" Basis

- **Situation:** We are given a set of linearly independent basis vectors  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3, \dots\}$  that can define a space.
  - **The Problem:** These vectors are "messy".
    - They are **not mutually orthogonal** (not perpendicular).
    - They are **not unit vectors** (their lengths are not 1).
  - **Goal:** To create a new **orthonormal basis**  $\{\vec{e}_1, \vec{e}_2, \vec{e}_3, \dots\}$  from the messy  $\vec{v}$  basis. This new basis must span the exact same space.
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## 2. The Core Idea: "Cleaning" Vectors One by One

The Gram-Schmidt process works by building the new orthonormal basis **iteratively**, one vector at a time. The idea is: "take the next messy vector, subtract the parts we don't like, and then clean up what's left."

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## 3. The Step-by-Step Process (The Gram-Schmidt Recipe)

### Step 1: Create $\vec{e}_1$ (The First Orthonormal Basis Vector)

1. **Choose:** Take the first vector from the messy set,  $\vec{v}_1$ , as our starting point.
2. **Direction:** Its direction is fine. We will make this our first fundamental direction.
3. **Clean Up the Length:** The only problem with  $\vec{v}_1$  is its length might not be 1. So, we **normalize** it.

$$\vec{e}_1 = \frac{\vec{v}_1}{|\vec{v}_1|}$$

We now have  $\vec{e}_1$ , our first orthonormal basis vector.

### Step 2: Create $\vec{e}_2$ (The Second Orthonormal Basis Vector)

1. **Choose:** Take the next messy vector,  $\vec{v}_2$ .

2. **Analyze  $\vec{v}_2$ :** We can imagine  $\vec{v}_2$  as having two components:

- A part that is **parallel** to  $\vec{e}_1$  (this is the "shadow" of  $\vec{v}_2$  on  $\vec{e}_1$ ). This is the "dirty" or "unwanted" part because it's not orthogonal to  $\vec{e}_1$ .
- A part that is **perpendicular** to  $\vec{e}_1$ . This is the "clean" and "original" part of  $\vec{v}_2$  that we want to keep.

3. **Subtract the "Dirty" Part:**

- The "dirty" part (parallel to  $\vec{e}_1$ ) is the [vector projection](#) of  $\vec{v}_2$  onto  $\vec{e}_1$ .
- Projection Formula (since  $\vec{e}_1$  is a unit vector):  $\text{proj}_{\vec{e}_1}(\vec{v}_2) = (\vec{v}_2 \cdot \vec{e}_1)\vec{e}_1$ .
- Now, we "clean"  $\vec{v}_2$  by subtracting this dirty part from it:

$$\vec{u}_2 = \vec{v}_2 - (\vec{v}_2 \cdot \vec{e}_1)\vec{e}_1$$

- The resulting vector,  $\vec{u}_2$ , is now **guaranteed to be orthogonal** to  $\vec{e}_1$ .

4. **Clean Up the Length:**  $\vec{u}_2$  has the correct direction, but its length is probably not 1. So, we normalize it.

$$\vec{e}_2 = \frac{\vec{u}_2}{|\vec{u}_2|}$$

We now have  $\vec{e}_2$ , which has a length of 1 and is perpendicular to  $\vec{e}_1$ .

### Step 3: Create $\vec{e}_3$ (and so on...)

1. **Choose:** Take  $\vec{v}_3$ .

2. **Subtract the "Dirty" Parts:**  $\vec{v}_3$  has a component parallel to  $\vec{e}_1$  AND a component parallel to  $\vec{e}_2$ . We must subtract both.

- Subtract the shadow on  $\vec{e}_1$ :  $(\vec{v}_3 \cdot \vec{e}_1)\vec{e}_1$ .
- Subtract the shadow on  $\vec{e}_2$ :  $(\vec{v}_3 \cdot \vec{e}_2)\vec{e}_2$ .

$$\vec{u}_3 = \vec{v}_3 - (\vec{v}_3 \cdot \vec{e}_1)\vec{e}_1 - (\vec{v}_3 \cdot \vec{e}_2)\vec{e}_2$$

- $\vec{u}_3$  is now guaranteed to be orthogonal to both  $\vec{e}_1$  and  $\vec{e}_2$ .

3. **Clean Up the Length:**

$$\vec{e}_3 = \frac{\vec{u}_3}{|\vec{u}_3|}$$

Repeat this process for all remaining  $\vec{v}$  vectors.

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## 4. Conclusion

- The Gram-Schmidt process is a **constructive algorithm** that transforms any set of basis vectors into a "nice" orthonormal basis.

- This is extremely useful because orthonormal bases make many calculations (inverses, projections, change of basis) significantly easier.
  - It is a fundamental tool in many areas of applied mathematics and machine learning.
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## 5. Worked Example: Orthonormalizing a Basis

### Problem:

We are given a "messy" basis  $B$  in  $\mathbb{R}^2$ :

- $\vec{v}_1 = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$
- $\vec{v}_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

These vectors are linearly independent (not co-linear), so they form a valid basis. However, they are not orthogonal ( $\vec{v}_1 \cdot \vec{v}_2 = 3$ ) and  $\vec{v}_1$  is not a unit vector.

### Goal:

Use the Gram-Schmidt Process to transform basis  $B$  into an orthonormal basis  $E = \{\vec{e}_1, \vec{e}_2\}$ .

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### Step 1: Create $\vec{e}_1$ (The First Orthonormal Basis Vector)

- **Recipe:** Take  $\vec{v}_1$  and normalize it (make its length 1).

$$\vec{e}_1 = \frac{\vec{v}_1}{|\vec{v}_1|}$$

1. **Take  $\vec{v}_1$ :**

$$\vec{v}_1 = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$$

2. **Calculate its length,  $|\vec{v}_1|$ :**

$$|\vec{v}_1| = \sqrt{3^2 + 0^2} = \sqrt{9} = 3$$

3. **Divide  $\vec{v}_1$  by its length:**

$$\vec{e}_1 = \frac{1}{3} \begin{bmatrix} 3 \\ 0 \end{bmatrix} = \begin{bmatrix} 3/3 \\ 0/3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

- **Result of Step 1:**

We have found our first orthonormal basis vector:

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

(In this case, it happens to be the standard  $\hat{i}$ , because  $\vec{v}_1$  was already on the x-axis).

**Jawaban:**

**Panjang vektor  $\vec{a} = |\vec{a}| = \sqrt{a_1^2 + a_2^2}$**

**Vektor satuan  $\vec{a} = \frac{\vec{a}}{|\vec{a}|} = \frac{1}{\sqrt{a_1^2 + a_2^2}} (a_1, a_2)$**

**Pembahasan:**

Vektor merupakan besaran yang punya nilai dan arah. Untuk menentukan panjang vektor kita menggunakan rumus:

$$\text{Panjang vektor } \vec{a} = |\vec{a}| = \sqrt{a_1^2 + a_2^2}$$

Sedangkan vektor satuan adalah suatu vektor yang panjangnya satu satuan. Untuk menentukan vektor satuan kita menggunakan rumus:

$$\text{Vektor satuan } \vec{a} = \frac{\vec{a}}{|\vec{a}|} = \frac{1}{\sqrt{a_1^2 + a_2^2}} (a_1, a_2)$$

Jadi, cara menentukan panjang vektor adalah **Panjang vektor  $\vec{a} = |\vec{a}| = \sqrt{a_1^2 + a_2^2}$** . Sedangkan untuk menentukan vektor satuan adalah **Vektor satuan  $\vec{a} = \frac{\vec{a}}{|\vec{a}|} = \frac{1}{\sqrt{a_1^2 + a_2^2}} (a_1, a_2)$** .

## Step 2: Create $\vec{e}_2$ (The Second Orthonormal Basis Vector)

- **Recipe:**

1. Take  $\vec{v}_2$ .
2. "Clean"  $\vec{v}_2$  by subtracting its "shadow" on  $\vec{e}_1$  to get  $\vec{u}_2$ .

$$\vec{u}_2 = \vec{v}_2 - \text{proj}_{\vec{e}_1}(\vec{v}_2) = \vec{v}_2 - (\vec{v}_2 \cdot \vec{e}_1) \vec{e}_1$$

3. Normalize  $\vec{u}_2$  to get  $\vec{e}_2$ .

$$\vec{e}_2 = \frac{\vec{u}_2}{|\vec{u}_2|}$$

Let's do the work.

1. **Take  $\vec{v}_2$ :**

$$\vec{v}_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

2. **Calculate the "dirty" part (the projection of  $\vec{v}_2$  onto  $\vec{e}_1$ ):**

- First, calculate the dot product  $\vec{v}_2 \cdot \vec{e}_1$ :

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix} = (1 \cdot 1) + (2 \cdot 0) = 1$$

- The projection vector is  $(\vec{v}_2 \cdot \vec{e}_1) \vec{e}_1$ :

$$1 \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

3. **"Clean"  $\vec{v}_2$  to get  $\vec{u}_2$ :**

$$\vec{u}_2 = \vec{v}_2 - (\text{projection vector})$$

$$\vec{u}_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1-1 \\ 2-0 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$$

The vector  $\vec{u}_2 = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$  is now guaranteed to be orthogonal to  $\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ . (Check it:  $[1, 0] \cdot [0, 2] = 0$ . It works!).

4. **Normalize  $\vec{u}_2$  to get  $\vec{e}_2$ :**

- Calculate the length of  $\vec{u}_2$ :  
 $|\vec{u}_2| = \sqrt{0^2 + 2^2} = \sqrt{4} = 2$ .
- Divide  $\vec{u}_2$  by its length:

$$\vec{e}_2 = \frac{1}{2} \begin{bmatrix} 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 0/2 \\ 2/2 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

• **Result of Step 2:**

We have found our second orthonormal basis vector:

$$\vec{e}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

## Final Solution

The new orthonormal basis we constructed from  $\{[3, 0], [1, 2]\}$  is:

$$E = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$

In this simple example, the Gram-Schmidt process transformed a "skewed" basis back into the familiar standard basis. For more complex initial bases, the result would be a set of unit vectors that are mutually orthogonal but may not align with the x and y axes.

**Tags:** [#mml-specialization](#) [#linear-algebra](#) [#gram-schmidt](#) [#orthonormal-basis](#) [#orthogonalization](#)