

02: Special Eigen-Cases

Chapter Goal: To test and strengthen our intuition about [eigenvectors](#) by examining several special 2D transformation cases, and to briefly see how the concept extends to 3D.

1. Goal: Testing Intuition

We will look at three special 2D transformation cases to ensure our understanding of eigenvectors is robust. Then, we will glance at how this concept applies in 3D.

2. Special 2D Cases

A. Uniform Scaling

- **Transformation:** Stretches or squishes space by the **same factor in all directions**. (Example: all vectors become 2x longer).
- **"Aha!" Moment:**
 - Every vector, after being uniformly scaled, will remain on its own path (span). Its direction does not change.
- **Conclusion:** For a uniform scaling, **ALL VECTORS** in the space are eigenvectors.
- **Eigenvalue:** They all share the same eigenvalue, which is the scaling factor itself.

B. 180-Degree Rotation

- **Transformation:** Rotates the entire space by 180 degrees.
- **Observation:** Every vector \vec{v} is mapped to $-\vec{v}$. The vector $-\vec{v}$ lies on the same span as \vec{v} , just in the opposite direction.
- **"Aha!" Moment:**
 - Since every vector remains on its own span, **ALL VECTORS** are also eigenvectors for a 180° rotation.
- **Eigenvalue:** Because every vector \vec{v} becomes $-1 \cdot \vec{v}$, all of these eigenvectors share the same eigenvalue: **-1**.

C. A Combination (Shear + Scaling)

- **Transformation:** A more complex transformation, combining multiple actions.
- **Observation:**
 - Horizontal vectors remain eigenvectors (just like in a pure shear).
 - Other vectors (vertical, diagonal) appear to have their directions changed.

- **"Aha!" Moment:**
 - Although it's not visually obvious, it turns out there is a **second, hidden eigenvector** in a "skewed" or diagonal direction.
 - **Key Lesson:** Eigenvectors are not always easy to find by visual inspection alone, especially for complex transformations. We will need a more powerful mathematical method to find them.
-

3. Extension to 3D: Rotation

- **Transformation:** A rotation in 3D space.
 - **Observation:** Vectors that are not on the axis of rotation will change their direction.
 - **"Aha!" Moment (Same as 3Blue1Brown):**
 - Vectors that lie exactly on the **axis of rotation** will not change their direction. They simply spin in place.
 - **Conclusion:** The eigenvector of a 3D rotation is its **axis of rotation**.
 - **Eigenvalue:** It must be **1**, because a pure rotation does not change the length of any vector.
-

4. Final Message

- These examples show that eigenvectors can be everywhere (uniform scaling), only in one direction (shear), or not exist at all in the real plane (standard 2D rotation).
 - Most importantly, they are **not always easy to see**. This motivates the need for a formal mathematical definition and a computational method to find eigenvectors and eigenvalues, which will be covered in the next video.
-

Tags: #mml-specialization #linear-algebra #eigenvectors #eigenvalues #special-cases
#rotation #scaling