

ZENGYI QIN

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RESEARCH INTEREST

Safe Autonomous Systems; Robotics; Machine Learning; Control Theory

EDUCATION

Massachusetts Institute of Technology

M.S. / Ph.D. in Aeronautics and Astronautics

Sep. 2020 - present

Advisor: Prof. [Chuchu Fan](#)

Tsinghua University

B.E. in Electronic Engineering (with honor)

Aug. 2016 - June 2020

Advisor: Prof. [Jiansheng Chen](#)

Stanford University

Visiting Scholar in Computer Science

July 2019 - Sep. 2019

Advisor: Prof. [Fei-Fei Li](#) and Prof. [Silvio Savarese](#)

HONORS AND AWARDS

Fellowship of Stanford Undergraduate Visiting and Research (UGVR) Program (2019)

Scholarship of Technological Innovation at Tsinghua University (2019 - 2020)

Scholarship of Comprehensive Excellence at Tsinghua University (2019)

The Highest Award of Challenge Cup Technological Innovation Competition at Tsinghua University (2019)

The Highest Award of Beijing Challenge Cup Technological Innovation Competition (2019)

The First Prize of Microsoft Imagine Cup Global Student Technological Competition, China Finals (2018)

PUBLICATIONS

8. [ICLR 21] [Zengyi Qin](#), Kaiqing Zhang, Yuxiao Chen, Jingkai Chen, Chuchu Fan. “Learning Safe Multi-Agent Control with Decentralized Neural Barrier Certificates.” *The International Conference on Learning Representations*, 2021. [\[PDF\]](#)
7. [TAC 21] Chuchu Fan, [Zengyi Qin](#), Umang Mathur, Qiang Ning, Sayan Mitra, Mahesh Viswanathan. “Controller Synthesis for Linear System with Reach-avoid Specifications.” *The IEEE Transactions on Automatic Control*, 2021.
6. [SR 21] [Zengyi Qin](#), Jiansheng Chen, Zhenyu Jiang, Xumin Yu, Chunhua Hu, Yu Ma, Suhua Miao, Rongsong Zhou. “Learning Fine-Grained Estimation of Physiological States from Coarse-Grained Labels by Distribution Restoration.” *Scientific Reports*, 2021. [\[PDF\]](#)
5. [ACM MM 20] [Zengyi Qin](#), Jinglu Wang, Yan Lu. “Weakly Supervised 3D Object Detection from Point Clouds.” *ACM Multimedia*, 2020. [\[PDF\]](#) [\[Code\]](#)
4. [ICRA 20] [Zengyi Qin](#), Kuan Fang, Yuke Zhu, Li Fei-Fei, Silvio Savarese. “KETO: Learning Keypoint Representations for Tool Manipulation.” *The International Conference on Robotics and Automation*, 2020. [\[PDF\]](#) [\[Website\]](#) [\[Video\]](#)
3. [AAAI 19] [Zengyi Qin](#), Jinglu Wang, Yan Lu. “MonoGRNet: A Geometric Reasoning Network for Monocular 3D Object Localization.” *The Thirty-Third AAAI Conference on Artificial Intelligence*, 2019. **Oral Presentation** (< 8%) [\[PDF\]](#) [\[Website\]](#) [\[Code\]](#)

2. [CVPR 19] Zengyi Qin, Jinglu Wang, Yan Lu. “Triangulation Learning Network: from Monocular to Stereo 3D Object Detection.” *The International Conference on Computer Vision and Pattern Recognition*, 2019. [\[PDF\]](#) [\[Website\]](#) [\[Code\]](#)
1. [SPL 19] Zengyi Qin*, Zhenyu Jiang*, Jiansheng Chen, Chunhua Hu, Yu Ma. “sEMG based Tremor Severity Evaluation for Parkinson’s Disease using a Light-weight CNN.” *IEEE Signal Processing Letters*, 2019. [\[PDF\]](#) [\[Website\]](#)

RESEARCH EXPERIENCES

Reliable Autonomous Systems Lab at MIT

Graduate Student Researcher

Sep. 2020 - present

Advisor: Prof. [Chuchu Fan](#)

- Project: Advancing the safety of autonomous systems via certifiable algorithms

Stanford Vision and Learning Lab

Visiting Scholar

July 2019 - Sep. 2019

Advisor: Prof. [Fei-Fei Li](#) and Prof. [Silvio Savarese](#)

- Project: Robotic dexterous manipulation via self-supervised keypoint representations

Microsoft Research Asia, Media Computing Group

Research Intern

June 2018 - July 2019

Advisor: Dr. [Jinglu Wang](#)

- Project: 3D scene understanding for autonomous driving

Tsinghua University, High-speed Image Processing Lab

Undergraduate Student Researcher

Sep. 2017 - June 2018

Advisor: Prof. [Jiansheng Chen](#)

- Project: Early diagnosis of Parkinson’s Disease via surface electromyography

PATENTS

1. ”Surface Electromyography-based Parkinson’s Disease Diagnosis”, CN210697629U, granted July 2020.

INVITED TALKS

2. “Learning Keypoint Representations for Tool Manipulation”, *Stanford University*, Stanford, CA, 2019.
1. “A Geometric Reasoning Network for Monocular 3D Object Localization”, *The AAAI Conference on Artificial Intelligence*, Honolulu, Hawaii, 2019.

LEADERSHIP AND ACTIVITIES

- Member of the execution team of MIT Chinese Entrepreneurs Organization
- Co-founder and Chief of Student Association of Data Science and Machine Learning at Tsinghua University