

```

01. % *****
02. %*
03. %*          S T A P M A T
04. %*
05. %*      An In-CORE SOLUTION STATIC ANALYSIS PROGRAM IN MATLAB
06. %*      Adapted from STAP90 (FORTRAN 90) for teaching purpose
07. %*
08. %*      Computational Dynamics Group, School of Aerospace Engineering
09. %*      Tsinghua University, 2019.02.20
10. %*
11. %* *****
12.
13. % Set paths of functions
14. AddPath();
15.
16. % Define Global Variables
17. global cdata;
18. global sdata;
19. cdata = ControlData;
20. sdata = SolutionData;
21.
22. % Read InPut file
23. fname = 'stap90.in';          % Specify the file name
24. ReadFile(fname);
25.
26. % Write basic data of program
27. WriteParasOut();
28.
29. % Form the stiffness matrix
30. GetStiff();
31.
32. % Triangularize stiffness matrix
33. Solve();
34.
35. % Finalize
36. Finalize();
37.
38. % ----- Functions -----
39.
40. % Functions
41. % Add paths of functions
42. function AddPath()
43. clear;
44. close all;
45. clc;
46.
47. addpath .\SRC\Initiation
48. addpath .\SRC\BasicData
49. addpath .\SRC\Mechanics
50. addpath .\SRC\Mechanics\Truss
51. addpath .\SRC\Solver
52. end
53.
54. function Finalize()
55. global cdata;
56. TIM = cdata.TIM;
57. time = zeros(5, 1, 'double');
58. time(1) = etime(TIM(2,:), TIM(1,:));
59. time(2) = etime(TIM(3,:), TIM(2,:));
60. time(3) = etime(TIM(4,:), TIM(3,:));
61. time(4) = etime(TIM(5,:), TIM(4,:));
62. time(5) = etime(TIM(5,:), TIM(1,:));
63.
64. fprintf(cdata.IOUT, ['\n\n' ...
65.     ' S O L U T I O N   T I M E   L O G   I N   S E C\n\n' ...
66.     '      TIME FOR INPUT PHASE . . . . . = %12.2f\n' ...
67.     '      TIME FOR CALCULATION OF STIFFNESS MATRIX . . . = %12.2f\n' ...
68.     '      TIME FOR FACTORIZATION OF STIFFNESS MATRIX . . = %12.2f\n' ...
69.     '      TIME FOR LOAD CASE SOLUTIONS . . . . . = %12.2f\n\n' ...
70.     '      T O T A L   S O L U T I O N   T I M E . . . . = %12.2f\n'], ...
71.     time(1), time(2), time(3), time(4), time(5));

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72.
73. fprintf(['\n' ...
74. ' S O L U T I O N   T I M E   L O G   I N   S E C\n\n' ...
75. '     TIME FOR INPUT PHASE . . . . . = %12.2f\n' ...
76. '     TIME FOR CALCULATION OF STIFFNESS MATRIX . . . . = %12.2f\n' ...
77. '     TIME FOR FACTORIZATION OF STIFFNESS MATRIX . . . = %12.2f\n' ...
78. '     TIME FOR LOAD CASE SOLUTIONS . . . . . = %12.2f\n\n' ...
79. '     T O T A L   S O L U T I O N   T I M E . . . . . = %12.2f\n'], ...
80.     time(1), time(2), time(3), time(4), time(5));
81.
82. fclose(cdata.IIN);
83. fclose(cdata.IOUT);
84. end
85.
86. %* *****
87. %* - Basic data class of STAPMAT *
88. %* *
89. %* - Purpose: *
90. %*     Storing variables which control the running of STAPMAT *
91. %* *
92. %* - Programmed by: *
93. %*     LeiYang Zhao, Yan Liu, *
94. %*     Computational Dynamics Group, School of Aerospace *
95. %*     Engineering, Tsinghua University, 2019.02.20 *
96. %* *
97. %* *****
98. classdef ControlData
99.     properties
100.         NUMNP; % Total number of nodal points
101.         % = 0 : Program stop
102.
103.         NPAR; % Element group control data
104.         % NPAR(1) - Element type
105.         % 1 : Truss element
106.         % NPAR(2) - Number of elements
107.         % NPAR(3) - Number of different sets of material
108.         % and cross-sectional constants
109.         NUMEG; % Total number of element groups, > 0
110.         NLCASE; % Number of load case (>0)
111.         LL; % Load case number
112.         NLOAD; % The number of concentrated loads applied in this load case
113.
114.         MODEX; % Solution mode: 0 - data check only; 1 - execution
115.
116.         TIM; % Timing information
117.         HED; % Master heading information for usr in labeling the output
118.
119.         IIN; % file pointer used for input
120.         IOUT; % file pointer used for output
121.     end
122. end
123.
124. %* *****
125. %* - Basic data class of STAPMAT *
126. %* *
127. %* - Purpose: *
128. %*     Storing variables used in solving process *
129. %* *
130. %* - Programmed by: *
131. %*     LeiYang Zhao, Yan Liu, *
132. %*     Computational Dynamics Group, School of Aerospace *
133. %*     Engineering, Tsinghua University, 2019.02.20 *
134. %* *
135. %* *****
136.
137. classdef SolutionData
138.     properties (Constant)
139.         % Gauss coord, 1D to 3D
140.         GC1 = double(0.0);
141.         GC2 = double([1/3, -1/3]);
142.         GC3 = double([sqrt(0.6), 0.0, -sqrt(0.6)]);
143.         % Gauss weight, 1D to 3D
144.         GW1 = double(2.0);

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145.         GW2 = double([1.0, 1.0]);
146.         GW3 = double([5.0/9.0, 8.0/9.0, 5.0/9.0]);
147.     end
148.     properties
149.         % Basic data
150.         ID;           % int, ID(3, NUMNP), Boundary condition codes (0=free, 1=deleted)
151.         IDorigin;     % int, backups of ID after computing of NEQ
152.         X;           % double, X(NUMNP), X coordinates
153.         Y;           % double, Y(NUMNP), Y coordinates
154.         Z;           % double, Z(NUMNP), Z coordinates
155.         R;           % double, R(NEQ), Load vector
156.         NOD;         % int, NOD(NLOAD), Node number to which this load is applied (1~NUMNP)
157.         IDIRN;       % int, IDIRN(NLOAD), Degree of freedom number for this load component
158.                     %           1 : X-direction;
159.                     %           2 : Y-direction;
160.                     %           3 : Z-direction;
161.         FLOAD;       % double, FLOAD(NLOAD), Magnitude of load
162.
163.
164.
165.         % Element data
166.         NUME;        % int, number of elements
167.         NNODE;       % int, number of nodes in an element
168.         NINIP;       % int, number of integration points in an element
169.         NDOF;        % int, the DOF of displacement
170.         NSTIFF;      % int, the number of number in element stiffness matrix
171.         XYZ;         % double, XYZ(3*NNODE, NUME), element position
172.
173.         InitCoord;   % double array, integration coordinates
174.         InitWeight;  % double array, integration weights
175.
176.         % Material data
177.         NUMMAT;      % int, the number of types of material
178.         E;           % double array, Young's Modulus
179.         nu;          % double array, poisson ratio
180.         AREA;        % double array, cross-sectional constants
181.         MATP;        % int, MATP(NUME), types of elements
182.
183.         % Solve data
184.         NEQ;         % int, Number of equations
185.         NWK;         % Number of matrix elements
186.         MK;          % Maximum half bandwidth
187.         MHT;         % int, MHT(NEQ), Vector of column heights
188.         LM;          % int, LM(6, NUME), Connectivity matrix
189.         MAXA;        % int, MAXA(NEQ)
190.         STIFF;       % double ,STIFF(NWK), store the elements of stiffness matrix
191.
192.         % Result data
193.         DIS;         % double, DIS(NEQ, NLCASE), Displacement of nodes
194.         STRAIN;      % double, STRAIN(NEQ, NLCASE), Strain
195.         STRESS;      % double, STRESS(NEQ, NLCASE), Stress
196.
197.     end
198. end
199.
200. %* *****
201. %* - Function of STAPMAT in initialization phase *
202. %* *
203. %* - Purpose: *
204. %*   Read input file of STAPMAT *
205. %* *
206. %* - Call procedures: *
207. %*   SRC/Initiation/ReadFile.m - InitBasicData() *
208. %* *
209. %* - Called by : *
210. %*   stapmat.m *
211. %* *
212. %* - Programmed by: *
213. %*   LeiYang Zhao, Yan Liu, *
214. %*   Computational Dynamics Group, School of Aerospace *
215. %*   Engineering, Tsinghua University, 2019.02.21 *
216. %* *
217. %* *****

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218.
219. function ReadFile(fname)
220. fname = strcat('.\Data\', fname);           % Deal the filename
221.
222. % Get global class
223. global cdata;
224. global sdata;
225.
226. % Open files
227. cdata.IIN = fopen(fname, 'r');
228.
229. % Begin Read input file
230. fprintf('Input phase ...\n\n');
231.
232. % the first time stamp
233. cdata.TIM = zeros(5, 6, 'double');
234. cdata.TIM(1,:) = clock;
235.
236. IIN = cdata.IIN;
237. %% Read Control data
238. cdata.HED = fgetl(IIN);
239.
240. tmp = str2num(fgetl(IIN));
241. cdata.NUMNP = int64(tmp(1));
242. cdata.NUMEG = int64(tmp(2));
243. cdata.NLCASE = int64(tmp(3));
244. cdata.MODEX = int64(tmp(4));
245.
246. if (cdata.NUMNP == 0) return; end
247.
248. %% Read nodal point data
249. InitBasicData();
250. % Define local variables to speed
251. ID = sdata.ID; X = sdata.X; Y = sdata.Y; Z = sdata.Z;
252. for i = 1:cdata.NUMNP
253.     tmp = str2num(fgetl(IIN));
254.     ID(1, i) = int64(tmp(2));
255.     ID(2, i) = int64(tmp(3));
256.     ID(3, i) = int64(tmp(4));
257.     X(i) = double(tmp(5));
258.     Y(i) = double(tmp(6));
259.     Z(i) = double(tmp(7));
260. end
261. sdata.ID = ID; sdata.X = X; sdata.Y = Y; sdata.Z = Z;
262. %% Compute the number of equations
263. sdata.IDOrigin = ID;
264. NEQ = 0;
265. for N=1:cdata.NUMNP
266.     for I=1:3
267.         if (ID(I,N) == 0)
268.             NEQ = NEQ + 1;
269.             ID(I,N) = NEQ;
270.         else
271.             ID(I,N) = 0;
272.         end
273.     end
274. end
275. sdata.ID = ID;
276. sdata.NEQ = NEQ;
277. %% Read load data
278. % Init control data
279. NLCASE = cdata.NLCASE;
280. sdata.R = zeros(NEQ, NLCASE, 'double');
281. R = sdata.R;
282. % Read data
283. for N = 1:cdata.NLCASE
284.     tmp = str2num(fgetl(IIN));
285.     cdata.LL = int64(tmp(1)); cdata.NLOAD = int64(tmp(2));
286.     NLOAD = cdata.NLOAD;
287. % Init load data
288. sdata.NOD = zeros(NLOAD, 1, 'int64');
289. sdata.IDIRN = zeros(NLOAD, 1, 'int64');
290. sdata.FLOAD = zeros(NLOAD, 1, 'double');

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291.     NOD = sdata.NOD; IDIRN = sdata.IDIRN; FLOAD = sdata.FLOAD;
292.
293. % Read load data
294. for I = 1:NLOAD
295.     tmp = str2num(fgetl(IIN));
296.     NOD(I) = int64(tmp(1));
297.     IDIRN(I) = int64(tmp(2));
298.     FLOAD(I) = double(tmp(3));
299. end
300. if (cdata.MODEX == 0) return; end
301.
302. % Compute load vector
303. for L = 1:NLOAD
304.     II = ID(IDIRN(L), NOD(L));
305.     if (II > 0) R(II, N) = R(II, N) + FLOAD(L); end
306. end
307. sdata.NOD = NOD; sdata.IDIRN = IDIRN; sdata.FLOAD = FLOAD; sdata.R = R;
308. end
309.
310. end
311.
312. %% Functions
313. % InitBasicData
314. function InitBasicData()
315. global cdata;
316. global sdata;
317.
318. cdata.NPAR = zeros(10, 1, 'int64');
319.
320. sdata.ID = zeros(3, cdata.NUMNP, 'int64');
321. sdata.X = zeros(cdata.NUMNP, 1, 'double');
322. sdata.Y = zeros(cdata.NUMNP, 1, 'double');
323. sdata.Z = zeros(cdata.NUMNP, 1, 'double');
324. end
325.
326. %* *****
327. %* - Function of STAPMAT in initialization phase *
328. %* *
329. %* - Purpose: *
330. %*     Write parameters to output file of STAPMAT *
331. %* *
332. %* - Call procedures: None *
333. %* *
334. %* - Called by : *
335. %*     stapmat.m *
336. %* *
337. %* - Programmed by: *
338. %*     LeiYang Zhao, Yan Liu, *
339. %*     Computational Dynamics Group, School of Aerospace *
340. %*     Engineering, Tsinghua University, 2019.02.21 *
341. %* *
342. %* *****
343.
344. function WriteParasOut()
345. global cdata;
346. global sdata;
347. % Open file
348. cdata.IOUT = fopen('..\Data\STAPMAT.OUT', 'w');
349. IOUT = cdata.IOUT;
350.
351. fprintf(IOUT, ['\n %s \n\n'...
352.     ' C O N T R O L   I N F O R M A T I O N\n\n'...
353.     '     NUMBER OF NODAL POINTS . . . . . (NUMNP) = %10d \n' ...
354.     '     NUMBER OF ELEMENT GROUPS . . . . . (NUMEG) = %10d \n' ...
355.     '     NUMBER OF LOAD CASES . . . . . (NLCASE) = %10d \n' ...
356.     '     SOLUTION MODE . . . . . (MODEX) = %10d \n' ...
357.     '     EQ.0, DATA CHECK \n' ...
358.     '     EQ.1, EXECUTION'], ...
359.     cdata.HED, cdata.NUMNP, cdata.NUMEG, cdata.NLCASE, cdata.MODEX);
360.
361. % Write complete nodal data
362. ID = sdata.IDOrigin; X = sdata.X; Y = sdata.Y; Z = sdata.Z;
363. fprintf(IOUT, '\n\n N O D A L   P O I N T   D A T A \n\n');

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364. fprintf(IOUT, '          NODE          BOUNDARY          NODAL POINT\n');
365. fprintf(IOUT, '          NUMBER      CONDITION  CODES          COORDINATES\n');
366.
367. fprintf(IOUT, '          X      Y      Z          X          Y          Z\n');
368. for i = 1:cdata.NUMNP
369.     fprintf(IOUT, '%10d      %5d%5d%5d      %13.3f%13.3f%13.3f\n', ...
370.         i, ID(1,i), ID(2,i), ID(3,i), X(i), Y(i), Z(i));
371. end
372. sdata.IDOrigin = 0; % Delete old ID array
373.
374. % Write equation numbers
375. ID = sdata.ID;
376. fprintf(IOUT, '\n\n EQUATION NUMBERS\n');
377. fprintf(IOUT, '\n          NODE          DEGREES OF FREEDOM\n');
378. fprintf(IOUT, '          NUMBER\n');
379. for N=1:cdata.NUMNP
380.     fprintf(IOUT, ' %10d      %10d%10d%10d\n', ...
381.         N, ID(1,N), ID(2,N), ID(3,N));
382. end
383.
384. % Write the load vector
385. % Only the first load vector
386. fprintf(IOUT, '\n\n L O A D   C A S E   D A T A\n');
387. LL = cdata.LL; NLOAD = cdata.NLOAD;
388. NOD = sdata.NOD; IDIRN = sdata.IDIRN; FLOAD = sdata.FLOAD;
389. for I = 1:1 %cdata.NLCASE
390.     fprintf(IOUT, '\n          LOAD CASE NUMBER . . . . . = %10d\n', LL);
391.     fprintf(IOUT, '          NUMBER OF CONCENTRATED LOADS . = %10d\n', NLOAD);
392.
393.     if (LL ~= I)
394.         error(' *** ERROR *** LOAD CASES ARE NOT IN ORDER');
395.     end
396.     fprintf(IOUT, '\n\n          NODE          DIRECTION          LOAD\n');
397.     fprintf(IOUT, '          NUMBER          MAGNITUDE\n');
398.
399.     for N = 1:NLOAD(I)
400.         fprintf(IOUT, '%10d      %4d      %12.5e', ...
401.             NOD(N), IDIRN(N), FLOAD(N));
402.     end
403. end
404. end
405.
406. %* *****
407. %* - Function of STAPMAT in stiffness phase *
408. %* *
409. %* - Purpose: *
410. %*   Forming the stiffness matrix *
411. %* *
412. %* - Call procedures: *
413. %*   SRC/Mechanics/Truss/TrussStiff.m - TrussStiff() *
414. %* *
415. %* - Called by : *
416. %*   stapmat.m *
417. %* *
418. %* - Programmed by: *
419. %*   LeiYang Zhao, Yan Liu, *
420. %*   Computational Dynamics Group, School of Aerospace *
421. %*   Engineering, Tsinghua University, 2019.02.21 *
422. %* *
423. %* *****
424.
425. function GetStiff()
426. % Get global variables
427. global cdata;
428.
429. % Read the type of element
430. IIN = cdata.IIN;
431. IOUT = cdata.IOUT;
432. fprintf(IOUT, '\n\n E L E M E N T   G R O U P   D A T A\n');
433.
434. for N = 1:cdata.NUMEG

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436. tmp = str2num(fgetl(IIN));
437. for I = 1:length(tmp) cdata.NPAR(I) = tmp(I); end
438.
439. fprintf(IOUT, '\n\n E L E M E N T   D E F I N I T I O N\n');
440. fprintf(IOUT, ['\n ELEMENT TYPE . . . . .\n'
441. ( NPAR(1) ) . . = %10d\n' ...
442. ' EQ.1, TRUSS ELEMENTS\n' ...
443. ' EQ.2, ELEMENTS CURRENTLY\n' ...
444. ' EQ.3, NOT AVAILABLE\n' ...
445. ' NUMBER OF ELEMENTS. . . . . ( NPAR(2) ) . . = %10d\n'], ...
446. cdata.NPAR(1), cdata.NPAR(2));
447.
448. % Different kinds of element
449. NPAR1 = cdata.NPAR(1);
450. if (NPAR1 == 1) TrussStiff()
451. else error(' *** ERROR *** No Such Element'); end
452.
453. end
454.
455. end
456.
457. %* *****
458. %* - Function of STAPMAT in stiffness phase *
459. %* *
460. %* - Purpose: *
461. %* Compute the stiffness matrix of truss *
462. %* *
463. %* - Call procedures: *
464. %* TrussStiff.m - InitTruss() *
465. %* ./ReadTruss.m - ReadTruss() *
466. %* SRC/Mechanics/Addres.m - Addres() *
467. %* *
468. %* - Called by : *
469. %* SRC/Mechanics/GetStiff.m *
470. %* *
471. %* - Programmed by: *
472. %* LeiYang Zhao, Yan Liu, *
473. %* Computational Dynamics Group, School of Aerospace *
474. %* Engineering, Tsinghua University, 2019.02.21 *
475. %* *****
476.
477. function TrussStiff()
478.
479. % Init variables of the element
480. InitTruss();
481.
482. % Read Material and Elements
483. ReadTruss();
484.
485. fprintf('Solution phase ...\n\n');
486.
487. % calculate addresses of diagonal elements
488. Addres();
489.
490. % Data check Or Solve
491. global cdata;
492. if (cdata.MODEX == 0)
493. cdata.TIM(3,:) = clock;
494. cdata.TIM(4,:) = clock;
495. cdata.TIM(5,:) = clock;
496. return;
497. end
498.
499. % Assemble structure stiffness matrix
500. Assemble();
501.
502.
503.
504.
505. end
506.
507. % ----- Functions -----

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508.
509. % Init parameters of truss element
510. function InitTruss()
511. global sdata;
512. sdata.NNODE = 2;
513. sdata.NDOF = 3;
514.
515. end
516.
517. % Assemble structure stiffness matrix
518. function Assemble()
519. global sdata;
520. global cdata;
521. S = zeros(6, 6, 'double');
522. ST = zeros(6, 1, 'double');
523. sdata.STIFF = zeros(sdata.NWK, 1, 'double');
524.
525. NUME = sdata.NUME; MATP = sdata.MATP; XYZ = sdata.XYZ;
526. E = sdata.E; AREA = sdata.AREA; LM = sdata.LM;
527. for N = 1:NUME
528.     MTYPE = MATP(N);
529.
530.     % compute the length of truss element
531.     DX = XYZ(1, N) - XYZ(4, N);
532.     DY = XYZ(2, N) - XYZ(5, N);
533.     DZ = XYZ(3, N) - XYZ(6, N);
534.     XL2 = DX*DX + DY*DY + DZ*DZ;
535.     XL = sqrt(XL2);
536.
537.     XX = E(MTYPE) * AREA(MTYPE) * XL;
538.
539.     ST(1) = DX / XL2;
540.     ST(2) = DY / XL2;
541.     ST(3) = DZ / XL2;
542.     ST(4) = -ST(1); ST(5) = -ST(2); ST(6) = -ST(3);
543.
544.     for J = 1:6
545.         YY = ST(J) * XX;
546.         for I = 1:J
547.             S(I, J) = ST(I)*YY;
548.         end
549.     end
550.
551. % SRC/Mechanics/ADDBAN.m
552. ADDBAN(S, LM(:, N));
553.
554. end
555.
556. % The third time stamp
557. cdata.TIM(3, :) = clock;
558.
559. end
560.
561. %* *****
562. %* - Function of STAPMAT in stiffness phase *
563. %* *
564. %* - Purpose: *
565. %*     Read the element information of truss *
566. %* *
567. %* - Call procedures: *
568. %*     ReadTruss.m - ReadMaterial() *
569. %*     ReadTruss.m - ReadElements() *
570. %* *
571. %* - Called by : *
572. %*     ./TrussStiff.m *
573. %* *
574. %* - Programmed by: *
575. %*     LeiYang Zhao, Yan Liu, *
576. %*     Computational Dynamics Group, School of Aerospace *
577. %*     Engineering, Tsinghua University, 2019.02.21 *
578. %* *
579. %* *****
580.

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581. function ReadTruss()
582.
583. % Read Material information
584. ReadMaterial()
585.
586. % Read Element information
587. ReadElements()
588.
589. % the second time stamp
590. global cdata;
591. cdata.TIM(2,:) = clock;
592.
593. end
594.
595. % ----- Functions -----
596. % Read Material information
597. function ReadMaterial()
598.
599. global cdata;
600. global sdata;
601. % Get file pointers
602. IIN = cdata.IIN;
603. IOUT = cdata.IOUT;
604.
605. if (cdata.NPAR(3) == 0) cdata.NPAR(3) = 1; end
606. fprintf(IOUT, '\n M A T E R I A L   D E F I N I T I O N\n');
607. fprintf(IOUT, '\n NUMBER OF DIFFERENT SETS OF MATERIAL\n');
608. fprintf(IOUT, ' AND CROSS-SECTIONAL   CONSTANTS   . . . .( NPAR(3) ) . . = %10d\n', ...
609.     cdata.NPAR(3));
610. fprintf(IOUT, '   SET           YOUNG''S           CROSS-SECTIONAL\n');
611. fprintf(IOUT, ' NUMBER           MODULUS           AREA\n');
612. fprintf(IOUT, '           E           A\n');
613.
614.
615. % Read material datas
616. sdata.NUME = cdata.NPAR(2);
617. sdata.NUMMAT = cdata.NPAR(3);
618. NUMMAT = cdata.NPAR(3);
619. sdata.E = zeros(NUMMAT, 1, 'double');
620. sdata.AREA = zeros(NUMMAT, 1, 'double');
621. for I = 1:cdata.NPAR(3)
622.     tmp = str2num(fgetl(IIN));
623.     N = round(tmp(1));
624.     sdata.E(N) = tmp(2);
625.     sdata.AREA(N) = tmp(3);
626.     fprintf(IOUT, '%5d   %12.5e   %14.6e\n', N, tmp(2), tmp(3));
627. end
628.
629. end
630.
631. % Read elements information
632. function ReadElements()
633.
634. global cdata;
635. global sdata;
636.
637. % Get file pointer
638. IIN = cdata.IIN;
639. IOUT = cdata.IOUT;
640.
641. fprintf(IOUT, '\n\n E L E M E N T   I N F O R M A T I O N\n');
642. fprintf(IOUT, '\n           ELEMENT           NODE           NODE           MATERIAL\n');
643. fprintf(IOUT, '           NUMBER-N           I           J           SET NUMBER\n');
644.
645. % Get Position data
646. NUME = cdata.NPAR(2);
647. sdata.XYZ = zeros(6, NUME, 'double');
648. sdata.MATP = zeros(NUME, 1, 'int64');
649. sdata.LM = zeros(6, NUME, 'double');
650. sdata.MHT = zeros(sdata.NEQ, 1, 'int64');
651. X = sdata.X; Y = sdata.Y; Z = sdata.Z; ID = sdata.ID;
652. XYZ = sdata.XYZ; MATP = sdata.MATP; LM = sdata.LM;
653.

```

```

654. for N = 1:NUME
655.     tmp = str2num(fgetl(IIN));
656.     I = round(tmp(2));
657.     J = round(tmp(3));
658.     MTYPE = round(tmp(4));
659.
660. % Save element information
661.     XYZ(1, N) = X(I);
662.     XYZ(2, N) = Y(I);
663.     XYZ(3, N) = Z(I);
664.     XYZ(4, N) = X(J);
665.     XYZ(5, N) = Y(J);
666.     XYZ(6, N) = Z(J);
667.     MATP(N) = MTYPE;
668.
669.     fprintf(IOUT, '%10d      %10d      %10d      %5d\n', N, I, J, MTYPE);
670.
671. % Compute connectivity matrix
672.     LM(1, N) = ID(1, I);
673.     LM(4, N) = ID(1, J);
674.     LM(2, N) = ID(2, I);
675.     LM(5, N) = ID(2, J);
676.     LM(3, N) = ID(3, I);
677.     LM(6, N) = ID(3, J);
678.
679. % Udata column heights and bandwidth
680.     ColHt(LM(:, N))
681. end
682. sdata.XYZ = XYZ; sdata.MATP = MATP; sdata.LM = LM;
683.
684. % Clear the memory of X, Y, Z
685. sdata.X = double(0);
686. sdata.Y = double(0);
687. sdata.Z = double(0);
688.
689. end
690.
691. %* *****
692. %* - Function of STAPMAT in solver phase *
693. %* *
694. %* - Purpose: *
695. %*   To calculate stresses *
696. %* *
697. %* - Call procedures: None *
698. %* *
699. %* - Called by : *
700. %*   SRC/Solver/GetStress.m *
701. %* *
702. %* - Programmed by: *
703. %*   LeiYang Zhao, Yan Liu, *
704. %*   Computational Dynamics Group, School of Aerospace *
705. %*   Engineering, Tsinghua University, 2019.02.22 *
706. %* *
707. %* *****
708.
709. function TrussStress(NUM, NG)
710.
711. % Get global data
712. global cdata;
713. global sdata;
714.
715. IOUT = cdata.IOUT;
716. NUME = sdata.NUME; MATP = sdata.MATP; XYZ = sdata.XYZ;
717. E = sdata.E; AREA = sdata.AREA; LM = sdata.LM;
718. U = sdata.DIS(:, NUM);
719.
720. fprintf(IOUT, ['\n\n S T R E S S   C A L C U L A T I O N S   F O R   ' ...
721.     'E L E M E N T   G R O U P %4d\n\n' ...
722.     '           ELEMENT          FORCE          STRESS\n' ...
723.     '           NUMBER\n'], NG);
724.
725. for N = 1:NUME
726.     MTYPE = MATP(N);

```

```

727.
728. % compute the length of truss element
729. DX = XYZ(1, N) - XYZ(4, N);
730. DY = XYZ(2, N) - XYZ(5, N);
731. DZ = XYZ(3, N) - XYZ(6, N);
732. XL2 = DX*DX + DY*DY + DZ*DZ;
733.
734. ST(1) = DX / XL2 * E(MTYPE);
735. ST(2) = DY / XL2 * E(MTYPE);
736. ST(3) = DZ / XL2 * E(MTYPE);
737. ST(4) = -ST(1); ST(5) = -ST(2); ST(6) = -ST(3);
738.
739. STR = 0.0;
740.
741. if (LM(1, N) > 0) STR = STR + ST(1)*U(LM(1, N)); end
742. if (LM(2, N) > 0) STR = STR + ST(2)*U(LM(2, N)); end
743. if (LM(3, N) > 0) STR = STR + ST(3)*U(LM(3, N)); end
744. if (LM(4, N) > 0) STR = STR + ST(4)*U(LM(4, N)); end
745. if (LM(5, N) > 0) STR = STR + ST(5)*U(LM(5, N)); end
746. if (LM(6, N) > 0) STR = STR + ST(6)*U(LM(6, N)); end
747.
748. P = STR*AREA(MTYPE);
749.
750. fprintf(IOUT, ' %10d          %13.6e    %13.6e\n', N, P, STR);
751. end
752.
753. end
754.
755. %* *****
756. %* - Function of STAPMAT in stiffness phase *
757. %* *
758. %* - Purpose: *
759. %*   To calculate addresses of diagonal elements in banded *
760. %*   matrix whose column heights are known *
761. %* *
762. %* - Call procedures: None *
763. %* *
764. %* - Called by : *
765. %*   ./Truss/TrussStiff.m *
766. %* *
767. %* - Programmed in Fortran 90 by Xiong Zhang *
768. %* *
769. %* - Adapted to Matlab by: *
770. %*   LeiYang Zhao, Yan Liu, Computational Dynamics Group, *
771. %*   School of Aerospace Engineering, Tsinghua University, *
772. %*   2019.02.22 *
773. %* *
774. %* *****
775.
776. function Addres()
777.
778. % Get global data
779. global sdata;
780. global cdata;
781.
782. NEQ = sdata.NEQ; MHT = sdata.MHT;
783. sdata.MAXA = zeros(NEQ+1, 1, 'int64');
784. MAXA = sdata.MAXA;
785.
786. MAXA(1) = 1;
787. MAXA(2) = 2;
788. MK = 0;
789.
790. if (NEQ > 1)
791.     for I = 2:NEQ
792.         if (MHT(I) > MK) MK = MHT(I); end
793.         MAXA(I+1) = MAXA(I) + MHT(I) + 1;
794.     end
795. end
796.
797. sdata.MK = MK + 1;
798. sdata.NWK = MAXA(NEQ+1) - MAXA(1);
799. sdata.MAXA = MAXA;

```

```

800.
801. % Write total system data
802. MM = round(sdata.NWK / NEQ);
803. fprintf(cdata.IOUT, ['\n\n TOTAL SYSTEM DATA\n\n' ...
804.     '    NUMBER OF EQUATIONS . . . . .(NEQ) = %10d\n' ...
805.     '    NUMBER OF MATRIX ELEMENTS . . . . .(NWK) = %10d\n' ...
806.     '    MAXIMUM HALF BANDWIDTH . . . . .(MK ) = %10d\n' ...
807.     '    MEAN HALF BANDWIDTH . . . . .(MM ) = %10d\n'], ...
808.     NEQ, sdata.NWK, sdata.MK, MM);
809.
810. end
811.
812. %* *****
813. %* - Function of STAPMAT in stiffness phase *
814. %* *
815. %* - Purpose: *
816. %*   To calculate column heights *
817. %* *
818. %* - Call procedures: None *
819. %* *
820. %* - Called by : *
821. %*   ./Truss/ReadTruss.m *
822. %* *
823. %* - Programmed in Fortran 90 by Xiong Zhang *
824. %* *
825. %* - Adapted to Matlab by: *
826. %*   LeiYang Zhao, Yan Liu, Computational Dynamics Group, *
827. %*   School of Aerospace Engineering, Tsinghua University, *
828. %*   2019.02.22 *
829. %* *
830. %* *****
831.
832. function ColHt(LM)
833.
834. % Get global data
835. global sdata;
836. MHT = sdata.MHT;
837. LS = min(LM(LM ~= 0));
838. ND = sdata.NDOF * sdata.NNODE;
839. for I = 1:ND
840.     II = LM(I);
841.     if (II ~= 0)
842.         ME = II - LS;
843.         if (ME > MHT(II)) MHT(II) = ME; end
844.     end
845. end
846.
847. sdata.MHT = MHT;
848.
849. end
850.
851. %* *****
852. %* - Function of STAPMAT in stiffness phase *
853. %* *
854. %* - Purpose: *
855. %*   To assemble element stiffness into global stiffness *
856. %* *
857. %* - Call procedures: None *
858. %* *
859. %* - Called by : *
860. %*   ./Truss/ReadTruss.m - Assemble() *
861. %* *
862. %* - Programmed in Fortran 90 by Xiong Zhang *
863. %* *
864. %* - Adapted to Matlab by: *
865. %*   LeiYang Zhao, Yan Liu, Computational Dynamics Group, *
866. %*   School of Aerospace Engineering, Tsinghua University, *
867. %*   2019.02.22 *
868. %* *
869. %* *****
870.
871. function ADDBAN(S, LM)
872.

```

```

873. % Get global data
874. global sdata;
875. MAXA = sdata.MAXA;
876. STIFF = sdata.STIFF;
877. ND = sdata.NDOF * sdata.NNODE;
878. for J = 1:ND
879.     JJ = LM(J);
880.     if (JJ > 0)
881.         for I = 1:J
882.             II = LM(I);
883.             if (II > 0)
884.                 if (JJ > II) KK = MAXA(JJ) + JJ - II;
885.                 else KK = MAXA(II) + II - JJ; end
886.                 STIFF(KK) = STIFF(KK) + S(I, J);
887.             end
888.         end
889.     end
890. end
891.
892. sdata.STIFF = STIFF;
893.
894. end
895.
896. %* *****
897. %* - Function of STAPMAT in Solver phase *
898. %* *
899. %* - Purpose: *
900. %*   To solve finite element static equilibrium equations *
901. %* *
902. %* - Call procedures: *
903. %*   ./LDLTFactor.m           - LDLTFactor() *
904. %*   Solve.m                 - Stiff2Sparse() *
905. %*   ./ColSol.m              - ColSol() *
906. %*   Solve.m                 - WriteDis() *
907. %*   SRC/Mechanics/GetStress.m - GetStress() *
908. %* *
909. %* - Called by : *
910. %*   stapmat.m *
911. %* *
912. %* - Programmed by: *
913. %*   LeiYang Zhao, Yan Liu, *
914. %*   Computational Dynamics Group, School of Aerospace *
915. %*   Engineering, Tsinghua University, 2019.02.22 *
916. %* *
917. %* *****
918.
919. function Solve()
920.
921. global cdata;
922. global sdata;
923.
924. NEQ = sdata.NEQ;
925. NLCASE = cdata.NLCASE;
926. MODEX = cdata.MODEX;
927. sdata.DIS = zeros(NEQ, NLCASE, 'double');
928. sdata.STRAIN = zeros(NEQ, NLCASE, 'double');
929. sdata.STRESS = zeros(NEQ, NLCASE, 'double');
930.
931. % The pre-process of Solution
932. % MODEX = 1, LDLTFactor() - ColSol()
933. % MODEX = 2, Stiff2Sparse() - sdata.SPSTIFF \ Sdata.R(:, L)
934. if (MODEX == 1) LDLTFactor();
935. else SPSTIFF = Stiff2Sparse(); end
936.
937. cdata.TIM(4,:) = clock;
938.
939. % Solve
940. for L = 1:NLCASE
941.
942. %   Solve the equilibrium equations to calculate the displacements
943. if (MODEX == 1) ColSol(L);
944. else sdata.DIS(:,L) = SPSTIFF \ sdata.R(:,L); end
945.

```

```

946. % Print displacements
947. WriteDis(L);
948.
949. % Calculation of stresses
950. GetStress(L);
951.
952. end
953.
954. cdata.TIM(5, :) = clock;
955.
956. end
957.
958. % ----- Functions -----
959.
960. % Convert the stiff vector to a sparse stiff matrix
961. function SPSTIFF = Stiff2Sparse()
962.
963. global sdata;
964. A = sdata.STIFF; MAXA = sdata.MAXA; NEQ = sdata.NEQ; NWK = sdata.NWK;
965. IIndex = zeros(NWK*2-NEQ, 1);
966. JIndex = IIndex;
967. STIFF = IIndex;
968.
969. NUM = 1;
970. NUMC = 0;
971. for N = 1:NEQ
972.     KU = MAXA(N + 1) - MAXA(N);
973.     for L = 1:KU
974.         IIndex(NUM) = N;
975.         JIndex(NUM) = N - L + 1;
976.         STIFF(NUM) = A(NUM);
977.         NUM = NUM + 1;
978.         if (L == 1) NUMC = NUMC + 1; continue; end
979.         SYMN = NUM-1 - NUMC + NWK;
980.         IIndex(SYMN) = N - L + 1;
981.         JIndex(SYMN) = N;
982.         STIFF(SYMN) = A(NUM-1);
983.     end
984. end
985.
986. SPSTIFF = sparse(IIndex, JIndex, STIFF, NEQ, NEQ);
987. end
988.
989. % Print Displacements
990. function WriteDis(NUM)
991.
992. % Get global data
993. global cdata;
994. global sdata;
995. IOUT = cdata.IOUT;
996. NUMNP = cdata.NUMNP;
997. DIS = sdata.DIS(:, NUM); ID = sdata.ID;
998.
999. fprintf(IOUT, '\n\n LOAD CASE %3d', NUM);
1000. fprintf(IOUT, ['\n\n D I S P L A C E M E N T S\n' ...
1001.     '\n      NODE          X-DISPLACEMENT      Y-DISPLACEMENT      Z-DISPLACEMENT\n']);
1002.
1003. D = zeros(3, 1, 'double');
1004. for II = 1:NUMNP
1005.     D(:) = 0;
1006.     if (ID(1, II) ~= 0) D(1) = DIS(ID(1, II)); end
1007.     if (ID(2, II) ~= 0) D(2) = DIS(ID(2, II)); end
1008.     if (ID(3, II) ~= 0) D(3) = DIS(ID(3, II)); end
1009.
1010.     fprintf(IOUT, ' %10d      %18.6e%18.6e%18.6e\n', II, D(1), D(2), D(3));
1011. end
1012.
1013. end
1014.
1015. %* *****
1016. %* - Function of STAPMAT in Solver phase *
1017. %* *
1018. %* - Purpose: *

```

```

1019.  %*      Perform L*D*L(T) factorization of stiffness matrix      *
1020.  %*                                                              *
1021.  %* - Call procedures: None                                     *
1022.  %*                                                              *
1023.  %* - Called by :                                             *
1024.  %*      ./Solve.m                                           *
1025.  %*                                                              *
1026.  %* - Programmed in Fortran 90 by Xiong Zhang                 *
1027.  %*                                                              *
1028.  %* - Adapted to Matlab by:                                   *
1029.  %*      Yan Liu, Computational Dynamics Group, School of Aerospace *
1030.  %*      Engineering, Tsinghua University, 2019.02.22         *
1031.  %*                                                              *
1032.  %* *****
1033.
1034.  function LDLTFactor()
1035.
1036.  % Get global data
1037.  global sdata;
1038.
1039.  A = sdata.STIFF;
1040.  MAXA = sdata.MAXA; NEQ = sdata.NEQ;
1041.
1042.  for N = 1:NEQ
1043.      KN = MAXA(N);
1044.      KL = KN + 1;
1045.      KU = MAXA(N + 1) - 1;
1046.      KH = KU - KL;
1047.
1048.      if (KH > 0)
1049.          K = N - KH;
1050.          IC = 0;
1051.          KLT = KU;
1052.          for J = 1:KH
1053.              IC = IC + 1;
1054.              KLT = KLT - 1;
1055.              KI = MAXA(K);
1056.              ND = MAXA(K+1) - KI - 1;
1057.              if (ND > 0)
1058.                  KK = min(IC, ND);
1059.                  C = 0.0;
1060.                  for L = 1:KK C = C+A(KI+L)*A(KLT+L); end
1061.                  A(KLT) = A(KLT) - C;
1062.              end
1063.              K = K + 1;
1064.          end
1065.      end
1066.
1067.      if (KH >= 0)
1068.          K = N;
1069.          B = 0.0;
1070.          for KK = KL:KU
1071.              K = K - 1;
1072.              KI = MAXA(K);
1073.              C = A(KK) / A(KI);
1074.              B = B + C*A(KK);
1075.              A(KK) = C;
1076.          end
1077.          A(KN) = A(KN) - B;
1078.      end
1079.
1080.      if (A(KN) <= 0)
1081.          error(['STOP - Stiffness matrix is not positive definite\n' ...
1082.              'Nonpositive number for equation %8d is %20.12e\n'], N, A(KN));
1083.      end
1084.  end
1085.
1086.  sdata.STIFF = A;
1087.
1088.  end
1089.
1090.  %* *****
1091.  %* - Function of STAPMAT in Solver phase                        *

```

```

1092.  %*
1093.  %* - Purpose:
1094.  %*    To solve finite element static equilibrium equations
1095.  %*
1096.  %* - Call procedures: None
1097.  %*
1098.  %* - Called by :
1099.  %*    ./Solve.m
1100.  %*
1101.  %* - Programmed in Fortran 90 by Xiong Zhang
1102.  %*
1103.  %* - Adapted to Matlab by:
1104.  %*    Yan Liu, Computational Dynamics Group, School of Aerospace
1105.  %*    Engineering, Tsinghua University, 2019.02.22
1106.  %*
1107.  %* *****
1108.
1109.  function ColSol(NUM)
1110.
1111.  % Get global data
1112.  global sdata;
1113.  A = sdata.STIFF; MAXA = sdata.MAXA; R = sdata.R(:,NUM);
1114.  NEQ = sdata.NEQ; NWK = sdata.NWK;
1115.  NNM = NEQ + 1;
1116.
1117.  % Reduce right-hand-side load vector
1118.  for N = 1:NEQ
1119.      KL = MAXA(N) + 1;
1120.      KU = MAXA(N+1) - 1;
1121.      if (KU-KL >= 0)
1122.          K = N;
1123.          C = 0.0;
1124.          for KK = KL:KU
1125.              K = K - 1;
1126.              C = C + A(KK) * R(K);
1127.          end
1128.          R(N) = R(N) - C;
1129.      end
1130.  end
1131.
1132.  % Back-Substitute
1133.  for N = 1:NEQ
1134.      K = MAXA(N);
1135.      R(N) = R(N) / A(K);
1136.  end
1137.
1138.  if (NEQ == 1) return; end;
1139.
1140.  N = NEQ;
1141.  for L = 2:NEQ
1142.      KL = MAXA(N) + 1;
1143.      KU = MAXA(N+1) - 1;
1144.      if (KU-KL >= 0)
1145.          K = N;
1146.          for KK = KL:KU
1147.              K = K - 1;
1148.              R(K) = R(K) - A(KK)*R(N);
1149.          end
1150.      end
1151.      N = N - 1;
1152.  end
1153.
1154.  sdata.DIS(:, NUM) = R(:);
1155.
1156.  end
1157.
1158.  %* *****
1159.  %* - Function of STAPMAT in Solver phase
1160.  %*
1161.  %* - Purpose:
1162.  %*    Calculation of strain and stress
1163.  %*
1164.  %* - Call procedures:

```



```

1165.  %*      SRC/Mechanics/Truss/TrussStress.m    - TrussStress()      *
1166.  %*                                           *
1167.  %* - Called by :                                           *
1168.  %*      ./Solver.m                                           *
1169.  %*                                           *
1170.  %* - Programmed by:                                           *
1171.  %*      LeiYang Zhao, Yan Liu,                               *
1172.  %*      Computational Dynamics Group, School of Aerospace    *
1173.  %*      Engineering, Tsinghua University, 2019.02.22         *
1174.  %*                                           *
1175.  %* *****
1176.
1177.  function GetStress(NUM)
1178.
1179.  % Different type of element
1180.  global cdata;
1181.  NUMEG = cdata.NUMEG;
1182.  IOOUT = cdata.IOOUT;
1183.
1184.  for N = 1:NUMEG
1185.      NPAR1 = cdata.NPAR(1);
1186.      if (NPAR1 == 1) TrussStress(NUM, N)
1187.      else error(' *** ERROR *** No Such Element'); end
1188.  end
1189.
1190.  end

```