

# Part IB — Markov Chains

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## §2 Elementary Properties

### §2.1 Communicating classes

#### Definition 2.1 (Communication)

Let  $X$  be a Markov chain with transition matrix  $P$  and values in  $I$ . For  $x, y \in I$ , we say that  $x$  *leads to*  $y$ , written  $x \rightarrow y$ , if

$$\mathbb{P}_x(\exists n \geq 0, X_n = y) > 0$$

We say that  $x$  *communicates with*  $y$  and write  $x \leftrightarrow y$  if  $x \rightarrow y$  and  $y \rightarrow x$ .

#### Theorem 2.1

The following are equivalent:

1.  $x \rightarrow y$
2. There exists a sequence of states  $x = x_0, x_1, \dots, x_k = y$  such that

$$P(x_0, x_1)P(x_1, x_2) \dots P(x_{k-1}, x_k) > 0$$

3. There exists  $n \geq 0$  such that  $p_{xy}(n) > 0$ .

*Proof.* First, we show (i) and (iii) are equivalent. If  $x \rightarrow y$ , then  $\mathbb{P}_x(\exists n \geq 0, X_n = y) > 0$ . Then if  $\mathbb{P}_x(\exists n \geq 0, X_n = y) > 0$  we must have some  $n \geq 0$  such that  $\mathbb{P}_x(X_n = y) = p_{xy}(n) > 0$ . Note that we can write (i) as  $\mathbb{P}_x(\bigcup_{n=0}^{\infty} X_n = y) > 0$ . If there exists  $n \geq 0$  such that  $p_{xy}(n) > 0$ , then certainly the probability of the union is also positive.

Now we show (ii) and (iii) are equivalent. We can write

$$p_{xy}(n) = \sum_{x_1, \dots, x_{n-1}} P(x, x_1) \dots P(x_{n-1}, y)$$

which leads directly to the equivalence of (ii) with (iii).  $\square$

#### Corollary 2.1

Communication.  $\leftrightarrow$ , is an equivalence relation on  $I$ .

*Proof.* Reflexivity:  $x \leftrightarrow x$  since  $p_{xx}(0) = 1$ .

Transitivity: If  $x \rightarrow y$  and  $y \rightarrow z$  then by (ii) above,  $x \rightarrow z$ .

Symmetric by definition. □

### Definition 2.2 (Communicating Classes)

The equivalence classes induced on  $I$  by the communication equivalence relation are called **communicating classes**.

### Definition 2.3 (Closed Communicating Class)

A communicating class  $C$  is **closed** if  $x \in C, x \rightarrow y \implies y \in C$ .

### Definition 2.4 (Irreducibility)

A transition matrix  $P$  is called **irreducible** if it has a single communicating class. In other words,  $\forall x, y \in I, x \leftrightarrow y$ .

### Definition 2.5 (Absorption)

A state  $x$  is called **absorbing** if  $\{x\}$  is a closed (communicating) class. Equivalently if the markov chain started from  $x$  it stays at  $x$  forever.

## §2.2 Hitting times

### Definition 2.6 (Hitting Time)

For  $A \subseteq I$ , we define the *hitting time* of  $A$  to be a random variable  $T_A: \Omega \rightarrow \{0, 1, 2, \dots\} \cup \{\infty\}$ , defined by

$$T_A(\omega) = \inf \{n \geq 0: X_n(\omega) \in A\}$$

with the convention that  $\inf \emptyset = \infty$ .

### Definition 2.7 (Hitting Probability)

The *hitting probability* of  $A$  starting at  $i \in I$  is  $h^A: I \rightarrow [0, 1]$ , defined by

$$h^A(i) = h_i^A = \mathbb{P}_i(T_A < \infty), \quad i \in I$$

### Definition 2.8 (Mean Hitting Time)

The *mean hitting time* of  $A$  starting at  $i \in I$  is  $k^A: I \rightarrow [0, \infty]$ , defined by

$$k_i^A = \mathbb{E}_i [T_A] = \sum_{n=0}^{\infty} n \mathbb{P}_i (T_A = n) + \underbrace{\infty \mathbb{P}_i (T_A = \infty)}_{0 \cdot \infty = 0}$$

### Example 2.1

Consider

$$P = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 1/2 & 0 & 1/2 & 0 \\ 0 & 1/2 & 0 & 1/2 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Consider  $A = \{4\}$ .

$$h_1^A = 0$$

$$h_2^A = \mathbb{P}_2 (T_A < \infty) = \frac{1}{2} h_1^A + \frac{1}{2} h_3^A$$

$$h_3^A = \frac{1}{2} \cdot 1 + \frac{1}{2} h_2^A$$

Hence  $h_2^A = \frac{1}{3}$ .

Now, consider  $B = \{1, 4\}$ .  $k_2^B = \mathbb{E}[T_B]$

$$k_1^B = k_4^B = 0$$

$$k_2^B = 1 + \frac{1}{2} k_1^B + \frac{1}{2} k_3^B$$

$$k_3^B = 1 + \frac{1}{2} k_4^B + \frac{1}{2} k_2^B$$

Hence  $k_2^B = 2$ .

### Theorem 2.2

Let  $A \subset I$ . Then the vector  $(h_i^A)_{i \in I}$  is the minimal non-negative solution to the

system

$$x_i = \begin{cases} 1 & i \in A \\ \sum_j P(i, j)x_j & i \notin A \end{cases}$$

Minimality here means that if  $(x_i)_{i \in I}$  is another non-negative solution, then  $\forall i, h_i^A \leq x_i$ .

*Note.* The vector  $h_i^A = 1$  always satisfies the equation, since  $P$  is stochastic, but this solution is typically not minimal.

*Proof.* First, we will show that  $(h_i^A)_{i \in I}$  solves the system of equations.

Certainly if  $i \in A$  then  $h_i^A = 1$ . Suppose  $i \notin A$ . Consider the event  $\{T_A < \infty\}$ . We can write this event as a disjoint union of the following events:

$$\{T_A < \infty\} = \bigcup_{n=0}^{\infty} \{T_A = n\} = \bigcup_{n=0}^{\infty} \{X_0 \notin A, \dots, X_{n-1} \notin A, X_n \in A\}$$

By countable additivity,

$$\begin{aligned} \mathbb{P}_i(T_A < \infty) &= \underbrace{\mathbb{P}_i(X_0 \in A)}_{=0} + \sum_{n=1}^{\infty} \mathbb{P}_i(X_0 \notin A, \dots, X_{n-1} \notin A, X_n \in A) \\ &= \mathbb{P}(X_1 \in A) + \sum_{n=2}^{\infty} \mathbb{P}_i(X_1 \notin A, \dots, X_{n-1} \notin A, X_n \in A) \\ \mathbb{P}_i(X_1 \notin A, \dots, X_{n-1} \notin A, X_n \in A) &= \sum_{j \notin A} \mathbb{P}_i(X_1 = j, X_2 \notin A, \dots, X_{n-1} \in A, X_n \in A) \\ &= \sum_{j \notin A} \mathbb{P}_i(X_2 \notin A, \dots, X_{n-1} \notin A, X_n \in A \mid X_0 = i, X_1 = j) P(i, j) \\ &= \sum_{j \notin A} P(i, j) \mathbb{P}_j(X_1 \notin A, \dots, X_{n-2} \notin A, X_{n-1} \in A) \\ h_i^A &= \mathbb{P}_i(X_1 \in A) + \sum_{n=1}^{\infty} \sum_{j \notin A} P(i, j) \mathbb{P}_j(X_1 \notin A, \dots, X_n \in A) \\ &= \sum_{j \in A} h_j^A + \sum_{j \notin A} P(i, j) h_j^A \\ &= \sum_j P(i, j) h_j^A \end{aligned}$$

So  $(h_i^A)_{i \in I}$  satisfies the equation.

Now we must show minimality. If  $(x_i)$  is another non-negative solution, we must

show that  $h_i^A \leq x_i \forall i$ . We have for  $i \notin A$

$$x_i = \sum_j P(i, j)x_j = \sum_{j \in A} P(i, j) + \sum_{j \notin A} P(i, j)x_j$$

Substituting again,

$$x_i = \sum_{j \in A} P(i, j)x_j + \sum_{j \notin A} P(i, j) \left( \sum_{k \in A} P(j, k) + \sum_{k \notin A} P(j, k)x_k \right)$$

$$x_i = \mathbb{P}_i(X_1 \in A) + \mathbb{P}(X_1 \notin A, X_2 \in A) + \sum_{j \notin A} \sum_{k \notin A} P(i, j)P(j, k)x_k$$

$$x_i \geq \mathbb{P}_i(X_1 \in A) + \mathbb{P}_i(X_1 \notin A, X_2 \in A) + \dots + \mathbb{P}_i(X_1 \notin A, \dots, X_{n-1} \notin A, X_n \in A) \text{ as } x_k \geq 0.$$

$$x_i \geq \mathbb{P}_i(T_A \leq n) \forall n \in \mathbb{N}$$

Now, note  $\{T_A \leq n\}$  are a set of increasing functions of  $n$ , so by continuity of the probability measure, the probability increases to that of the union,  $\{T_A < \infty\} = h_i^A$ .  $\square$

### Example 2.2

Consider the Markov chain previously explored:

$$P = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 1/2 & 0 & 1/2 & 0 \\ 0 & 1/2 & 0 & 1/2 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Let  $A = \{4\}$ . Then  $h_1^A = 0$  since there is no route from 1 to 4. From the theorem above, the system of linear equations is

$$h_2 = \frac{1}{2}h_1 + \frac{1}{2}h_3$$

$$h_3 = \frac{1}{2}h_4 + \frac{1}{2}h_2$$

$$h_4 = 1$$

Hence,

$$h_2 = \frac{2}{3}h_1 + \frac{1}{3}$$

$$h_3 = \frac{1}{3}h_1 + \frac{2}{3}$$

So the minimal solution arises at  $h_1 = 0$ .

### Example 2.3

Consider  $I = \mathbb{N}$ , and

$$P(i, i+1) = p \in (0, 1); \quad P(i, i-1) = 1 - p = q$$

Then  $h_i = \mathbb{P}_i(T_0 < \infty)$  hence  $h_0 = 1$ . The linear equations are

$$p \neq q \implies h_i = ph_{i+1} + qh_{i-1}$$

$$p(h_{i+1} - h_i) = q(h_i - h_{i-1})$$

Let  $u_i = h_i - h_{i-1}$ . Then,

$$\frac{q}{p}u_i = \dots = \left(\frac{q}{p}\right)^i u_1$$

Hence

$$h_i = \sum_{j=1}^i (h_j - h_{j-1}) + 1 = 1 - (1 - h_1) \sum_{j=1}^i \left(\frac{q}{p}\right)^j$$

The general solution is therefore

$$h_i = a + b\left(\frac{q}{p}\right)^i$$

If  $q > p$ , then minimality of  $h_i$  implies  $b = 0$ ,  $a = 1$ . Hence,

$$h_i = 1$$

Otherwise, if  $p > q$ , minimality of  $h_i$  implies  $a = 0$ ,  $b = 1$ . Hence,

$$h_i = \left(\frac{q}{p}\right)^i$$

If  $p = q = \frac{1}{2}$ , then

$$h_i = \frac{1}{2}h_{i+1} + \frac{1}{2}h_{i-1}$$

Hence,  $h_i = a + bi$ . Minimality implies  $a = 1$  and  $b = 0$ .

$$h_i = 1$$

## §2.3 Birth and death chain

Consider a Markov chain on  $\mathbb{N}$  with

$$P(i, i+1) = p_i; \quad P(i, i-1) = q_i; \quad \forall i, \quad p_i + q_i = 1$$

Now, consider  $h_i = \mathbb{P}_i(T_0 < \infty)$ .  $h_0 = 1$ , and  $h_i = p_i h_{i+1} + q_i h_{i-1}$ .

$$p_i(h_{i+1} - h_i) = q_i(h_i - h_{i-1})$$

Let  $u_i = h_i - h_{i-1}$  to give

$$u_{i+1} = \frac{q_i}{p_i} u_i = \underbrace{\prod_{j=i}^{\infty} \frac{q_j}{p_j}}_{\gamma_i} u_i$$

Then

$$h_i = 1 - (1 - h_1)(\gamma_0 + \gamma_1 + \cdots + \gamma_{i-1})$$

where we let  $\gamma_0 = 1$ . Since  $h_i$  is the minimal non-negative solution,

$$h_i \geq 0 \implies 1 - h_1 \leq \frac{1}{\sum_{j=0}^{i-1} \gamma_j} \leq \frac{1}{\sum_{j=0}^{\infty} \gamma_j}$$

By minimality, we must have exactly this bound. If  $\sum_{j=0}^{\infty} \gamma_j = \infty$  then  $1 - h_1 = 0 \implies h_i = 1$  for all  $i$ . If  $\sum_{j=0}^{\infty} \gamma_j < \infty$  then

$$h_i = \frac{\sum_{j=i}^{\infty} \gamma_j}{\sum_{j=0}^{\infty} \gamma_j}$$

## §2.4 Mean hitting times

Recall that

$$k_i^A = \mathbb{E}_i[T_A] = \sum_n n \mathbb{P}_i(T_A = n) + \infty \mathbb{P}_i(T_A = \infty)$$



### Theorem 2.3

The vector  $(k_i^A)_{i \in I}$  is the minimal non-negative solution to the system of equations

$$\begin{cases} 0 & \text{if } i \in A \\ 1 + \sum_{j \notin A} P(i, j) k_j^A & \text{if } i \notin A \end{cases}$$

*Proof.* Suppose  $i \in A$ . Then  $k_i = 0$ . Now suppose  $i \notin A$ . Further, we may assume that  $\mathbb{P}_i(T_A = \infty) = 0$ , since if that probability is positive then the claim is trivial. Indeed, if  $\mathbb{P}_i(T_A = \infty) > 0$ , then there must exist  $j$  such that  $P(i, j) > 0$  and  $\mathbb{P}_j(T_A = \infty) > 0$  since

$$\mathbb{P}_i(T_A < \infty) = \sum_j P(i, j) h_j^A \implies 1 - \mathbb{P}_i(T_A = \infty) = \sum_j P(i, j) (1 - \mathbb{P}_j(T_A = \infty))$$

Because  $P$  is stochastic,

$$\mathbb{P}_i(T_A = \infty) = \sum_j P(i, j) \mathbb{P}_j(T_A = \infty)$$

so since the left hand side is positive, there must exist  $j$  with  $P(i, j) > 0$  and  $\mathbb{P}_j(T_A = \infty > 0)$ . For this  $j$ , we also have  $k_j^A = \infty$ . Now we only need to compute  $\sum_n n \mathbb{P}_i(T_A = n)$ .

$$\mathbb{P}_i(T_A = n) = \mathbb{P}_i(X_0 \notin A, \dots, X_{n-1} \notin A, X_n \in A)$$

Then, using the same method as the previous theorem,

$$k_i^A = \sum_n n \mathbb{P}_i(T_A = n) = 1 + \sum_{j \notin A} P(i, j) k_j^A$$

It now suffices to prove minimality. Suppose  $(x_i)$  is another solution to this system of equations. We need to show that  $x_i \geq k_i^A$  for all  $i$ . Suppose  $i \notin A$ . Then

$$x_i = 1 + \sum_{j \notin A} P(i, j) x_j = 1 + \sum_{j \notin A} P(i, j) \left( 1 + \sum_{k \notin A} P(j, k) x_k \right)$$

Expanding inductively,

$$\begin{aligned} x_i &= 1 + \sum_{j_1 \notin A} P(i, j_1) + \sum_{j_1 \notin A, j_2 \notin A} P(i, j_1) P(j_1, j_2) + \dots \\ &+ \sum_{j_1 \notin A, \dots, j_n \notin A} P(i, j_1) \dots P(j_{n-1}, j_n) + \sum_{j_1 \notin A, \dots, j_{n+1} \notin A} P(i, j) \dots P(j_n, j_{n+1}) x_{j_{n+1}} \end{aligned}$$

Since  $x$  is non-negative, we can remove the last term and reach an inequality.

$$x_i \geq 1 + \sum_{j_1 \notin A} P(i, j_1) + \sum_{j_1 \notin A, j_2 \notin A} P(i, j_1)P(j_1, j_2) + \cdots + \sum_{j_1 \notin A, \dots, j_n \notin A} P(i, j_1) \cdots P(j_{n-1}, j_n)$$

Hence

$$\begin{aligned} x_i &\geq 1 + \mathbb{P}_i(T_A > 1) + \mathbb{P}_i(T_A > 2) + \cdots + \mathbb{P}_i(T_A > n) \\ &= \mathbb{P}_i(T_A > 0) + \mathbb{P}_i(T_A > 1) + \mathbb{P}_i(T_A > 2) + \cdots + \mathbb{P}_i(T_A > n) \\ &= \sum_{k=0}^n \mathbb{P}_i(T_A > k) \end{aligned}$$

for all  $n$ . Hence, the limit of this sum is

$$x_i \geq \sum_{k=0}^{\infty} \mathbb{P}_i(T_A > k) = \mathbb{E}_i[T_A]$$

which gives minimality as required.  $\square$

## §2.5 Strong Markov property

The simple Markov property shows that, if  $X_m = i$ ,

$$X_{m+n} \sim \text{Markov}(\delta_i, P)$$

and this is independent of  $X_0, \dots, X_m$ . The strong Markov property will show that the same property holds when we replace  $m$  with a finite random ‘time’ variable. It is not the case that *any* random variable will work; indeed, an  $m$  very dependent on the Markov chain itself might not satisfy this property.

### Definition 2.9

A random time  $T: \Omega \rightarrow \{0, 1, \dots\} \cup \{\infty\}$  is called a *stopping time* if, for all  $n \in \mathbb{N}$ ,  $\{T = n\}$  depends only on  $X_0, \dots, X_n$ .

### Example 2.4

The hitting time  $T_A = \inf \{n \geq 0: X_n \in A\}$  is a stopping time. This is because we can write

$$\{T_A = n\} = \{X_0 \notin A, \dots, X_{n-1} \notin A, X_n \in A\}$$

### Example 2.5

The time  $L_A = \sup \{n \geq 0: X_n \in A\}$  is not a stopping time. This is because we need to know information about the future behaviour of  $X_n$  in order to guarantee that we are at the supremum of such events.

### Theorem 2.4 (Strong Markov Property)

Let  $X \sim \text{Markov}(\lambda, P)$  and  $T$  be a stopping time. Conditional on  $T < \infty$  and  $X_T = i$ ,

$$(X_{n+T})_{n \geq 0} \sim \text{Markov}(\delta_i, P)$$

and this distribution is independent of  $X_0, \dots, X_T$ .

*Proof.* We need to show that, for all  $x_0, \dots, x_n$  and for all vectors  $w$  of any length,

$$\begin{aligned} \mathbb{P}(X_T = x_0, \dots, X_{T+n} = x_n, (X_0, \dots, X_T) = w \mid T < \infty, X_T = i) \\ = \delta_{ix_0} P(x_0, x_1) \dots P(x_{n-1}, x_n) \mathbb{P}((X_0, \dots, X_T) = w: T < \infty, X_T = i) \end{aligned}$$

Suppose that  $w$  is of the form  $w = (w_0, \dots, w_k)$ . Then,

$$\begin{aligned} \mathbb{P}(X_T = x_0, \dots, X_{T+n} = x_n, (X_0, \dots, X_T) = w \mid T < \infty, X_T = i) \\ = \frac{\mathbb{P}(X_k = x_0, \dots, X_{k+n} = x_n, (X_0, \dots, X_k) = w, T = k, X_k = i)}{\mathbb{P}(T < \infty, X_T = i)} \end{aligned}$$

Now, since  $\{T = k\}$  depends only on  $X_0, \dots, X_k$ , by the simple Markov property we have

$$\begin{aligned} \mathbb{P}(X_k = x_0, \dots, X_{k+n} = x_n \mid (X_0, \dots, X_k) = w, T = k, X_k = i) \\ = \mathbb{P}(X_k = x_0, \dots, X_{k+n} = x_n \mid X_k = i) = \delta_{ix_0} P(x_0, x_1) \dots P(x_{n-1}, x_n) \end{aligned}$$

Now,

$$\begin{aligned} \mathbb{P}(X_T = x_0, \dots, X_{T+n} = x_n, (X_0, \dots, X_T) = w \mid T < \infty, X_T = i) \\ = \frac{\delta_{ix_0} P(x_0, x_1) \dots P(x_{n-1}, x_n) \mathbb{P}((X_0, \dots, X_k) = w: T = k, X_k = i)}{\mathbb{P}(T < \infty, X_T = i)} \\ = \delta_{ix_0} P(x_0, x_1) \dots P(x_{n-1}, x_n) \mathbb{P}((X_0, \dots, X_T) = w: T < \infty, X_T = i) \end{aligned}$$

as required.  $\square$

### Example 2.6

Consider a simple random walk on  $I = \mathbb{N}$ , where  $P(x, x \pm 1) = \frac{1}{2}$  for  $x \neq 0$ , and  $P(0, 1) = 1$ . Now, let  $h_i = \mathbb{P}_i(T_0 < \infty)$ . We want to calculate  $h_1$ . We can write

$$h_1 = \frac{1}{2} + \frac{1}{2}h_2$$

but the system of recursion relations this generates is difficult to solve. Instead, we will write

$$h_2 = \mathbb{P}_2(T_0 < \infty)$$

Note that in order to hit 0, we must first hit 1. So conditioning on the first hitting time of 1 being finite, after this time the process starts again from 1. We can write  $T_0 = T_1 + \tilde{T}_0$ , where  $\tilde{T}_0$  is independent of  $T_1$ , with the same distribution as  $T_0$  under  $\mathbb{P}_1$ . Now,

$$h_2 = \mathbb{P}_2(T_0 < \infty, T_1 < \infty) = \mathbb{P}_2(T_0 < \infty \mid T_1 < \infty) \mathbb{P}_2(T_1 < \infty)$$

Note that

$$\mathbb{P}_2(T_0 < \infty \mid T_1 < \infty) = \mathbb{P}_2(T_1 + \tilde{T}_0 < \infty \mid T_1 < \infty) = \mathbb{P}_2(\tilde{T}_0 < \infty \mid T_1 < \infty) = \mathbb{P}_1(T_0 < \infty)$$

But  $\mathbb{P}_2(T_1 < \infty) = \mathbb{P}_1(T_0 < \infty)$ , so

$$h_2 = \mathbb{P}_2(T_1 < \infty) \mathbb{P}_1(T_0 < \infty)$$

By translation invariance,

$$h_2 = h_1^2$$

In general, therefore, for any  $n \in \mathbb{N}$ ,

$$h_n = h_1^n$$