

## Problem 1

Set there are 1,2,3 three doors

Set C as the door which the car was hidden behind

Set M as the door which I firstly chose by myself

Set H as the door which the host opened

Suppose I firstly chose the door 1, the host opened the door 3

I need to calculate conditional probability of two situation: switch or do not switch

And from the given information, we can get that C event and M event are independent, so

$$P(C=1|M=1) = P(C=1) = \frac{1}{3} = P(C=2|M=1) = P(C=3|M=1)$$

According Bayesian Rule:

$$\begin{aligned} P(C=1|M=1, H=3) &= \frac{P(H=3|M=1, C=1)P(C=1|M=1)}{P(H=3|M=1, C=1)P(C=1|M=1) + P(H=3|M=1, C=2)P(C=2|M=1) + P(H=3|M=1, C=3)P(C=3|M=1)} \\ &= \frac{\frac{1}{2} \times \frac{1}{3}}{\frac{1}{2} \times \frac{1}{3} + 1 \times \frac{1}{3} + 0 \times \frac{1}{3}} \\ &= \frac{1}{3} \end{aligned}$$

$$P(C=2|M=1, H=3) = 1 - P(C=1|M=1, H=3) = 1 - \frac{1}{3} = \frac{2}{3}$$

$$\therefore \frac{1}{3} = P(C=1|M=1, H=3) < P(C=2|M=1, H=3) = \frac{2}{3}$$

$\therefore$  I will be more likely to get the car if I switch my choice to door 2

## Problem 2

From the image given, we can get that

$x_1$  has no root of arrow,  $x_2$  has 1 root of arrow  $x_1$ ,  $x_3$  has no root of arrow,

$x_4$  has 2 roots of arrow  $x_1$  and  $x_3$ ,  $x_5$  has 2 roots of arrow  $x_2$  and  $x_4$ .

According to the fomula  $p(x_1, \dots, x_n) = \prod_{i=1}^n p(x_i | pa_i)$ ,

where  $pa_i$  represents the parents of child i = root of arrow

So the factorization of the probability distribution is

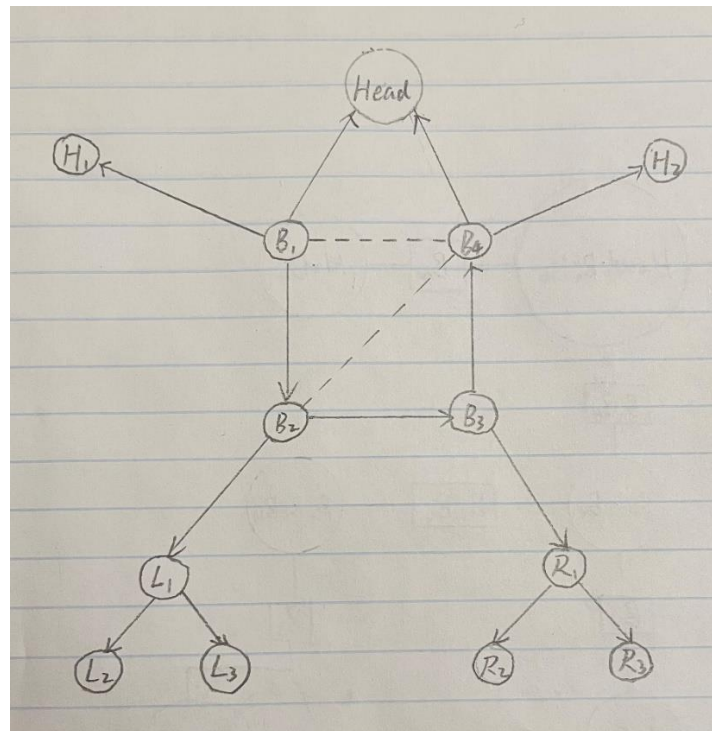
$$p(x_1, \dots, x_5) = \prod_{i=1}^5 p(x_i | pa_i) = p(x_1)p(x_2 | x_1)p(x_3)p(x_4 | x_1, x_3)p(x_5 | x_2, x_4)$$

Use the Bayes ball algorithm

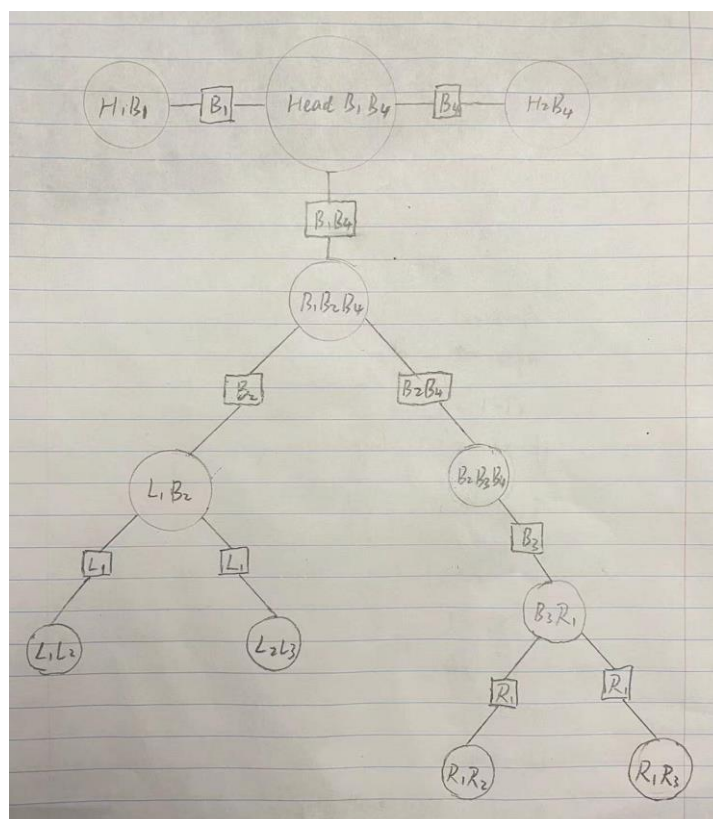
1. False      None is given, ball can go through  $x_2, x_1, x_4$
2. False       $x_5$  is given, ball can go through  $x_2, x_5, x_4$
3. True       $x_5$  is not given,  $x_1$  is given, ball can not arrive  $x_4$  from  $x_2$
4. True      According to Markov Chain condition, ball can not reach  $x_5$  from  $x_3$
5. True       $x_4$  is given,  $x_3$  and  $x_5$  can not reach each other
6. True       $x_4$  is not given, ball from  $x_3$  can not reach anywhere and ball can not reach  $x_3$  through  $x_4$
7. True       $x_4$  is not given, ball from  $x_3$  can not reach anywhere and ball can not reach  $x_3$  through  $x_4$
8. True       $x_2$  can reach  $x_4$  but not  $x_3$
9. False       $x_3 \rightarrow x_4 \rightarrow x_5 \rightarrow x_2$
10. False       $x_3 \rightarrow x_4 \rightarrow x_1 \rightarrow x_2$

### Problem 3

After Moralization and Triangulation, the graph is like

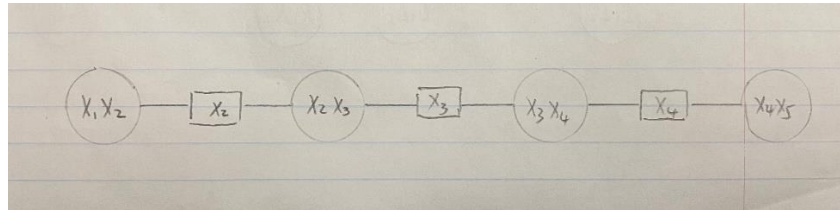


The constructed junction tree is like



## Problem 4

The constructed junction tree is like



We picked clique  $x_{n-1}, x_n$  as root. In this problem, it is  $x_4, x_5$

First send message from 1 to  $n-1$ , and then  $n-1$  to 1

Our separator values ends up being equal to those marginals as expected

The Matlab code is

```
n = 5;
psis = cell(n-1, 1);
for i = 1:(n-1)
    psis{i} = rand(2,2);
end
[ ma ] = JCT4MarkovChain( psis );
ptest = cell(4,1);
ptest{1} = [0.1, 0.7; 0.8, 0.3];
ptest{2} = [0.5, 0.1; 0.1, 0.5];
ptest{3} = [0.1, 0.5; 0.5, 0.1];
ptest{4} = [0.9, 0.3; 0.1, 0.3];
[ mtest ] = JCT4MarkovChain(ptest);
function[ ma ] = JCT4MarkovChain( po )
ma = po;
n = size(ma,1);
se = ones(n-1,2);
for i = 1:n-1
    se(i,:) = sum(ma{i});
    ma{i+1} = ma{i+1}.*(se(i,:)'*[1,1]);
end
for i = 1:n-1
    sold = se(n-i,:);
    se(n-i,:) = sum(ma{n-i+1},2)';
    ma{n-i} = ma{n-i}.*([1;1]*(se(n-i,:)./sold));
end
for i = 1:n
    ma{i} = ma{i}/sum(sum(ma{i}));
end
end
```

Where po = potentials = cell of potentials

ma = marginals = output marginals

se = separators

$p(x_1, x_2)$	$x_2 = 0$	$x_2 = 1$	$p(x_1)$
$x_1 = 0$	0.0405	0.4451	0.4856
$x_1 = 1$	0.3237	0.1908	0.5145
$p(x_2)$	0.3642	0.6358	

$p(x_1, x_2)$	$x_3 = 0$	$x_3 = 1$	$p(x_2)$
$x_2 = 0$	0.2601	0.1040	0.3642
$x_2 = 1$	0.0578	0.5780	0.6358
$p(x_3)$	0.3179	0.6821	

$p(x_1, x_2)$	$x_4 = 0$	$x_4 = 1$	$p(x_3)$
$x_3 = 0$	0.1192	0.1987	0.3179
$x_3 = 1$	0.6395	0.0426	0.6821
$p(x_4)$	0.7587	0.2413	

$p(x_1, x_2)$	$x_5 = 0$	$x_5 = 1$	$p(x_4)$
$x_4 = 0$	0.5690	0.1897	0.7587
$x_4 = 1$	0.0603	0.1810	0.2413
$p(x_5)$	0.6293	0.3707	

## Problem 5

The Matlab code is

```
function[ H ] = argMaxInfer( T, E, O, I )
t = size(T, 1);
n = size(O, 2);
psi = zeros(t, t, n);
phi = zeros(t, n);
phi(:, 1) = I;
for i = 2 : n
k = O(1, i);
psi(:, :, i) = diag(phi(:, i - 1)) *T *diag(E(:,k));
phi(:, i) = max(psi(:, :, i));
end
for i = n - 1 : -1 : 1
phinew = max(psi(:, :, i + 1), [], 2);
psi(:, :, i) = psi(:, :, i) *diag(phinew ./ phi(:, i));
phi(:, i) = phinew;
end
[neg,H] = max(phi);
end
```

Where the input T = transition probabilities

E = emission probabilities

O = observed states

I = initial probabilities

the output H = the most likely hidden states

And the most likely sequence of Mario's emotional states for the first five days is

Day1	Day2	Day3	Day4	Day5
Happy	Angry	Angry	Angry	Angry