计算机原理夏季学期实验报告

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1 第六次实验

实验目的 1.1

- 1. 学习 D/A 及 A/D 转换的基本原理
- 2. 掌握转换器 DAC0832 及 ADC0809 的使用方法

1.2 任务一

用 DAC0832 实现 D/A 转换, 使产生的模拟电压波形分别为锯齿波, 三角 波和正弦波并符合题目的要求完成相关功能。汇编代码如下所示:

01 02

03 DATA SEGMENT

```
04
        SAW_WAVE DB 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13,2
05
06
            DB 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 2
            28, 29, 30, 31
07
            DB 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 2
80
09
            44, 45, 46, 47
            DB 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 2
10
            60, 61, 62, 63
11
12
            DB 64, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 2
13
            76, 77, 78, 79
14
            DB 80, 81, 82, 83, 84, 85, 86, 87, 88, 89, 90, 91, 2
15
            92, 93, 94, 95
            DB 96, 97, 98, 99, 100, 101, 102, 103, 104, 105, 106, 2
16
17
            107, 108, 109, 110, 111
18
            DB 112, 113, 114, 115, 116, 117, 118, 119, 120, 121, 2
            122, 123, 124, 125, 126, 127
19
```

```
DB 128, 129, 130, 131, 132, 133, 134, 135, 136, 137, 2
20
21
            138, 139, 140, 141, 142, 143
22
            DB 144, 145, 146, 147, 148, 149, 150, 151, 152, 153, 2
            154, 155, 156, 157, 158, 159
23
24
            DB 160, 161, 162, 163, 164, 165, 166, 167, 168, 169, 2
25
            170, 171, 172, 173, 174, 175
26
            DB 176, 177, 178, 179, 180, 181, 182, 183, 184, 185, 2
27
            186, 187, 188, 189, 190, 191
28
            DB 192, 193, 194, 195, 196, 197, 198, 199, 200, 201, 2
            202, 203, 204, 205, 206, 207
29
            DB 208, 209, 210, 211, 212, 213, 214, 215, 216, 217, 2
30
            218, 219, 220, 221, 222, 223
31
32
            DB 224, 225, 226, 227, 228, 229, 230, 231, 232, 233, 2
33
            234, 235, 236, 237, 238, 239
34
            DB 240, 241, 242, 243, 244, 245, 246, 247, 248, 249, 2
35
            250, 251, 252, 253, 254, 255
        TRIANGLE_WAVE DB 1, 3, 5, 7, 9, 11, 13, 15, 17, 19, 21, 2
36
37
        23, 25, 27, 29, 31
            DB 33, 35, 37, 39, 41, 43, 45, 47, 49, 51, 53, 55, 2
38
39
            57, 59, 61, 63
40
            DB 65, 67, 69, 71, 73, 75, 77, 79, 81, 83, 85, 87, 2
            89, 91, 93, 95
41
42
            DB 97, 99, 101, 103, 105, 107, 109, 111, 113, 115, 2
43
            117, 119, 121, 123, 125, 127
44
            DB 129, 131, 133, 135, 137, 139, 141, 143, 145, 147, 2
45
            149, 151, 153, 155, 157, 159
46
            DB 161, 163, 165, 167, 169, 171, 173, 175, 177, 179, 2
47
            181, 183, 185, 187, 189, 191
48
            DB 193, 195, 197, 199, 201, 203, 205, 207, 209, 211, 2
49
            213, 215, 217, 219, 221, 223
            DB 225, 227, 229, 231, 233, 235, 237, 239, 241, 243, 2
50
            245, 247, 249, 251, 253, 255
51
            DB 255, 253, 251, 249, 247, 245, 243, 241, 239, 237, 2
52
            235, 233, 231, 229, 227, 225
53
54
            DB 223, 221, 219, 217, 215, 213, 211, 209, 207, 205, 2
            203, 201, 199, 197, 195, 193
55
```

```
DB 191, 189, 187, 185, 183, 181, 179, 177, 175, 173, 2
56
57
            171, 169, 167, 165, 163, 161
58
            DB 159, 157, 155, 153, 151, 149, 147, 145, 143, 141, 2
            139, 137, 135, 133, 131, 129
59
60
            DB 127, 125, 123, 121, 119, 117, 115, 113, 111, 109, 2
61
            107, 105, 103, 101, 99, 97
62
            DB 95, 93, 91, 89, 87, 85, 83, 81, 79, 77, 75, 73, 2
63
            71, 69, 67, 65
64
            DB 63, 61, 59, 57, 55, 53, 51, 49, 47, 45, 43, 41, 2
65
            39, 37, 35, 33
            DB 31, 29, 27, 25, 23, 21, 19, 17, 15, 13, 11, 9, 7, 2
66
67
            5, 3, 1
68
        SINE_WAVE DB 128, 131, 134, 137, 140, 143, 146, 149, 152,
69
        155, 158, 162, 165, 167, 170, 173
70
            DB 176, 179, 182, 185, 188, 190, 193, 196, 198, 201, 2
71
            203, 206, 208, 211, 213, 215
            DB 218, 220, 222, 224, 226, 228, 230, 232, 234, 235, 2
72
73
            237, 238, 240, 241, 243, 244
74
            DB 245, 246, 248, 249, 250, 250, 251, 252, 253, 253, 2
75
            254, 254, 254, 255, 255, 255
76
            DB 255, 255, 255, 255, 254, 254, 254, 253, 253, 252, 2
77
            251, 250, 250, 249, 248, 246
            DB 245, 244, 243, 241, 240, 238, 237, 235, 234, 232, 2
78
79
            230, 228, 226, 224, 222, 220
80
            DB 218, 215, 213, 211, 208, 206, 203, 201, 198, 196, 2
81
            193, 190, 188, 185, 182, 179
82
            DB 176, 173, 170, 167, 165, 162, 158, 155, 152, 149, 2
            146, 143, 140, 137, 134, 131
83
84
            DB 128, 124, 121, 118, 115, 112, 109, 106, 103, 100, 2
85
            97, 93, 90, 88, 85, 82
            DB 79, 76, 73, 70, 67, 65, 62, 59, 57, 54, 52, 49, 2
86
87
            47, 44, 42, 40
            DB 37, 35, 33, 31, 29, 27, 25, 23, 21, 20, 18, 17, 2
88
89
            15, 14, 12, 11
90
            DB 10, 9, 7, 6, 5, 5, 4, 3, 2, 2, 1, 1, 1, 0, 0, 0
            DB 0, 0, 0, 0, 1, 1, 1, 2, 2, 3, 4, 5, 5, 6, 7, 9
91
```

```
92
           DB 10, 11, 12, 14, 15, 17, 18, 20, 21, 23, 25, 27, \nearrow
           29, 31, 33, 35
93
           DB 37, 40, 42, 44, 47, 49, 52, 54, 57, 59, 62, 65, 2
94
95
           67, 70, 73, 76
           DB 79, 82, 85, 88, 90, 93, 97, 100, 103, 106, 109, 2
96
97
           112, 115, 118, 121, 124
98
       WAVE_TYPE \mathbf{DB} 00h
99 DATA ENDS
100
101 STACKS SEGMENT STACK
102
        DB 100 dup(?)
103 STACKS ENDS
104
105 CODE SEGMENT
        ASSUME CS:CODE, DS:DATA, SS:STACKS
106
107
108
109 MAIN PROC FAR
110
111 START:
112
        MOV AX, DATA
113
        MOV DS, AX
        MOV AX, 0
114
115
        MOV DI, AX
116
117 MAIN_LOOP:
118
        MOV AH, 1
        INT 16h
119
        \mathbf{JNZ} JUDGE
120
121
122 START_CONVERSION:
123
        MOV AX, DI
        CMP AX, Offh
124
        \mathbf{JNZ} P1
125
        MOV AX, Oh
126
```

MOV DI, AX

127

```
128 P1:
129
        MOV AL, WAVE_TYPE
        \mathbf{CMP}\ \mathbf{AL},\ \mathtt{OOh}
130
131
        \mathbf{JZ} WAVE_SAW
132
        CMP AL, 01h
133
        {f JZ} WAVE_TRIANGLE
        CMP AL, 02h
134
        \mathbf{JZ} WAVE_SINE
135
136
137 FLAG:
138
        PUSH AX
139
140
        PUSH BX
141
        PUSH CX
142 DELAY:
        MOV CX, 03ffh
143
144 P2:
145
        LOOP P2
146
        POP CX
147
        POP BX
        POP AX
148
149
150
        INC DI
        JMP MAIN_LOOP
151
152
153 JUDGE:
154
        MOV AH, 1
155
        INT 21h
156
        CMP AL, 34h
157
158
        \mathbf{JZ} EXIT
159
160
        SUB AL, 31h
        \mathbf{MOV} WAVE_TYPE, \mathbf{AL}
161
        \mathbf{JMP} START_CONVERSION
162
163
```

```
164 EXIT:
165
       MOV AH, 4CH
       INT 21h
166
167
168 WAVE_SAW:
169
       MOV DX, 280h
170
       MOV AL, SAW_WAVE[DI]
       OUT DX, AL
171
       JMP FLAG
172
173
174 WAVE_TRIANGLE:
       MOV DX, 280h
175
       MOV AL, TRIANGLE_WAVE[DI]
176
177
       OUT DX, AL
       JMP FLAG
178
179
180
181 WAVE_SINE:
182
       MOV DX, 280h
       MOV AL, SINE_WAVE[DI]
183
       OUT DX, AL
184
185
       JMP FLAG
186
187 MAIN ENDP
188 CODE ENDS
189
190 END START
```

1.3 任务二

用 ADC0809 实现 A/D 转换,用汇编语言程序自动对一个模拟信号重复采集 20 组不同的数据,在 CRT 上将每组数据对应显示成要求的形式,代码如下所示:

```
01 DATA SEGMENT
```

- 02 HEAD **DB** 0**DH**, 0**AH**, 'D/A A/D', 0**DH**, 0**AH**, '\$'
- 03 INFO \overline{DB} 'Please input c to get the datas, e to exit:'

```
04
      LINE DB ODH, OAH, '$'
      SPACE DB '
05
06 DATA ENDS
07
08 STACKS SEGMENT
09 STACKS ENDS
10
11 CODE SEGMENT
      ASSUME CS:CODE, DS:DATA, SS:STACKS
13 MAIN PROC FAR
14
15 START:
16
      {f MOV} {f AX},DATA
17
      MOV DS,AX
18
      MOV BX, 0
19
20
21 DISPLAY:
22
23
      MOV BL,BH
      INC BH
24
25
      MOV CX, 20
      MOV AH, 9
26
      LEA DX, HEAD
27
28
      {f INT} 21H
29 ONE_LINE:
30
      MOV AL, BL
      MOV DX, 280H
31
      OUT DX, AL
32
33
34
      CALL SHOW
      CALL DELAY
35
36
      MOV AH, 9
37
      LEA DX, SPACE
38
39
      INT 21H
```

```
40
41
      MOV DX, 289H
42
       OUT DX, AL
43
44
      {f CALL} DELAY
45
      MOV DX, 289H
46
47
      IN AL, DX
48
      CALL SHOW
49
50
      MOV AH, 9
51
52
      LEA DX, LINE
53
      INT 21H
54
55
      ADD BL, OFH
56
      LOOP ONE_LINE
57
58
      MOV AH, 9
59
      LEA DX, INFO
      INT 21H
60
61
62 ENTER:
63
      MOV AH, 1
64
      {f INT} 21H
      CMP AL, 'C'
65
      {f JZ} DISPLAY
66
      CMP AL, 'c'
67
      {f JZ} DISPLAY
68
      CMP AL, 'E'
69
70
      {f JZ} EXIT
      CMP AL, 'e'
71
72
      \mathbf{JZ} EXIT
      JMP ENTER
73
74
75 EXIT:
```

```
MOV AH,4CH
76
77
      INT 21H
78
79 DELAY PROC
      PUSH AX
80
81
      PUSH BX
      PUSH CX
82
83
      MOV CX, OFFFH
84 WAIT:
      LOOP WAIT
85
86
      POP CX
87
88
      POP BX
89
      POP AX
90
      RET
91 DELAY ENDP
92
93
94 SHOW \mathbf{PROC}
95
      PUSH AX
      AND AL, OFOH
96
      SHR AL, 1
97
      SHR AL, 1
98
99
      SHR AL, 1
100
       SHR AL, 1
       CMP AL, 09H
101
       {f JBE} DIG2
102
       ADD AL, 07H
103
104 DIG2:
105
       ADD AL, 30H
106
       MOV DL, AL
       MOV AH, 2
107
       {f INT} 21H
108
       POP AX
109
110
       AND AL, OFH
111
```

- 112 **CMP AL**, 09H
- 113 **JBE** DIG1
- 114 **ADD AL**, 07H
- 115 **DIG1**:
- 116 **ADD AL**, 30H
- 117 MOV DL, AL
- 118 **MOV AH,** 2
- 119 **INT** 21H
- 120 **MOV DL, 'H'**
- 121 MOV AH, 2
- 122 **INT** 21H
- 123 **RET**
- 124 SHOW ENDP
- 125
- 126 MAIN ENDP
- 127 CODE \mathbf{ENDS}
- 128 END START

1.4 完成情况及心得体会

本次实验使用了 AD/DA 转换,通过具体代码的编写了解了计算机 IO 速度和 CPU 运算速度的差异,并提升了自己的汇编编程水平

2 第七次实验

2.1 实验目的

综合汇编语言编程及 I/O 接口的知识,提高实际应用的能力

2.2 任务一

将 TPC 实验台上的 8255 电路 A 口设置成方式 0 输入,检测 8 只开关的状态;将 C 口设置成方式 0 输出,控制 8 只 LED 灯。程序运行后不断地读入 8 只开关的状态,送往对应的 LED 灯显示,直至在计算机键盘上敲入空格键退回 DOS

2.2.1 必做任务

34

MOV AH,4CH

```
代码如下所示
01 DATA SEGMENT
02 DATA ENDS
03
04 STACKS SEGMENT
05 STACKS ENDS
06
07 CODE SEGMENT
       ASSUME CS:CODE, DS:DATA, SS:STACKS
09
10 MAIN PROC FAR
11 START:
       MOV AX,DATA
12
13
       MOV DS,AX
14
15
       MOV DX, 283H
       MOV AL, 10010000B
16
       OUT DX, AL
17
18
19 NEXT:
20
       MOV DX, 280H
       IN AL, DX
21
       MOV DX, 282H
22
       OUT DX, AL
23
       MOV AH, 1
24
25
       INT 16H
26
       \mathbf{JZ} NEXT
      MOV AH, 0
27
28
       INT 16H
       \mathbf{CMP}\ \mathbf{AL},\ \mathtt{20H}
29
       \mathbf{JZ} EXIT
30
       JMP NEXT
31
32
33 EXIT:
```

```
35
      INT 21H
36
37 MAIN ENDP
38 CODE ENDS
39
      END START
2.2.2 选做任务
A 口仍保持方式 0 输入开关状态, C 口仍以方式 0 输出 LED 灯显示, 满足
要求的条件,代码如下所示:
01 DATA SEGMENT
02 DATA ENDS
03
04 STACKS SEGMENT
05 STACKS ENDS
06
07 CODE SEGMENT
      ASSUME CS:CODE, DS:DATA, SS:STACKS
09
10 MAIN PROC FAR
11 START:
      MOV AX,DATA
12
      MOV DS,AX
13
14
15
      MOV DX, 283H
      MOV AL, 10010000B
16
      OUT DX, AL
17
18 SCAN:
      MOV DX, 280H
19
      IN AL, DX
20
21
22
      CMP AL, 11000000B
      {f JZ} TOFLASH
23
24
25
      CMP AL, 10000000B
      \mathbf{JZ} L_MOVE
26
```

```
27
       CMP AL, 01000000B
28
       \mathbf{JZ} R_MOVE
29
30
       MOV DX, 282H
31
32
       OUT DX, AL
33
       MOV AH, 1
34
       \mathbf{INT} 16H
35
       \mathbf{JZ} SCAN
36
37
       MOV AH, 0
38
39
       {f INT} 16H
40
       CMP AL, 20H
41
       {f JZ} TOEXIT
42
       \mathbf{JMP} SCAN
43
44 L_MOVE:
45
       MOV DX, 282H
       MOV BL, 10000000B
46
       MOV AL, BL
47
       OUT DX, AL
48
49 R_LEFT:
50
       ROL BL, 1
51
       MOV AL, BL
       MOV DX, 282H
52
       OUT DX, AL
53
54
       CALL DELAY
55
56
57
       MOV\ DX, 280H
58
       IN AL, DX
       CMP AL, 10000000B
59
       \mathbf{JNZ} SCAN
60
61
62
       MOV DX, 282H
```

```
OUT DX, AL
63
64
       MOV AH, 1
65
       \mathbf{INT} 16H
       \mathbf{JZ} R_LEFT
66
67
68
       MOV AH, 0
       \mathbf{INT} 16H
69
       CMP AL, 20H
70
       \mathbf{JZ} EXIT
71
72
73
       \mathbf{JMP} R_LEFT
74
75 TOFLASH:
       JMP FLASH
77 TOEXIT:
78
       JMP EXIT
79
80 R_MOVE:
81
       MOV DX, 282H
82
       MOV BL, 10000000B
       MOV AL, BL
83
       OUT DX, AL
84
85
86 R_RIGHT:
87
       ROR BL, 1
       MOV AL, BL
88
       MOV DX, 282H
89
90
       CALL DELAY
91
92
93
       MOV\ DX, 280H
94
       IN AL, DX
       \mathbf{CMP}\ \mathbf{AL},\ \mathtt{01000000B}
95
       \mathbf{JNZ} SCAN
96
97
98
       MOV DX, 282H
```

```
OUT DX, AL
99
100
        MOV AH, 1
101
        INT 16H
102
        \mathbf{JZ} R_RIGHT
        MOV AH, 0
103
104
        INT 16H
105
        CMP AL, 20H
        \mathbf{JZ} EXIT
106
107
108
        \mathbf{JMP} R_RIGHT
109
110 TOSCAN:
111
        \mathbf{JMP} SCAN
112 FLASH:
113
        MOV DX, 282H
        MOV AL, 0
114
        OUT DX, AL
115
116
117
        {f CALL} DELAY
118
        MOV DX, 282H
119
120
        MOV AL, OFFH
        OUT DX, AL
121
122
        MOV DX, 280H
123
124
        IN AL, DX
        CMP AL, 11000000B
125
        JNZ TOSCAN
126
127
        CALL DELAY
128
129
        MOV DX, 282H
130
        OUT DX, AL
131
        MOV AH, 1
132
        INT 16H
133
134
        \mathbf{JZ} FLASH
```

```
MOV AH, 0
135
       INT 16H
136
       CMP AL, 20H
137
       \mathbf{JZ} EXIT
138
139
140
       \mathbf{JMP} FLASH
141
142 EXIT:
143
       MOV AH,4CH
       INT 21H
144
145
146 DELAY PROC
147
       PUSH BX
148
       PUSH CX
       MOV \ BX, OFH
149
150 WAITB:
       MOV CX, OFFFFH
151
152 WAITC:
153
       DEC CX
       \mathbf{JNZ} WAITC
154
       DEC BX
155
156
      {f JNZ} WAITB
      POP CX
157
       POP BX
158
       RET
159
160 DELAY ENDP
161
162 MAIN ENDP
163 CODE ENDS
164
       END START
```

2.3 任务二

实验中每按一次单脉冲按键,通过 8255 电路发一次中断请求。CRT 上显示一个 A 口的 ASCII 码字符,直到 A 口数据为 FFH 退出。

2.3.1 必做任务

34

```
代码如下所示:
01 DATA SEGMENT
02 KEEP_IP \mathbf{DW} 0
03 KEEP_CS DW 0
04 FLAG \mathbf{DB} 0
05 DATA ENDS
06
07 STACKS SEGMENT
08 STACKS ENDS
09
10 CODE SEGMENT
11
      ASSUME CS:CODE, DS:DATA, SS:STACKS
12
13 MAIN PROC FAR
14 START:
15
      MOV AX,DATA
      MOV DS,AX
16
17
18
19
      MOV DX, 283H
      MOV AL, 10110000B
20
      OUT DX, AL
21
22
23
      MOV DX, 283H
      MOV AL, 00001001B
24
25
      OUT DX, AL
26
27
28
      {f MOV} {f AH}, 35H
      MOV AL, 0BH
29
      {f INT} 21H
30
31
      MOV KEEP_IP, BX
32
      MOV KEEP_CS, ES
33
```

```
PUSH DS
35
36
      MOV DX, OFFSET INTR
37
      MOV AX, SEG INTR
      MOV DS, AX
38
      MOV AH, 25H
39
40
      MOV AL, 0BH
      INT 21H
41
      POP DS
42
43
44
      MOV AL, OF7H
45
      OUT 21H, AL
46
47 WAIT_FOR:
48
      MOV BL, FLAG
49
      CMP BL, 1
      \mathbf{JZ} ISINT
50
      {f JMP} WAIT_FOR
51
52
53 ISINT:
54
      CMP CL, OFFH
55
      \mathbf{JZ} EXIT
56
      MOV DL, CL
      MOV AH, 2
57
      \mathbf{INT} 21H
58
59
      MOV FLAG, 0
60
      {f JMP} WAIT_FOR
61
62 EXIT:
63
64
      MOV AL, OFFH
65
      OUT 21H, AL
66
67
      PUSH DS
68
      MOV DX, KEEP_IP
69
70
      MOV AX, KEEP_CS
```

- 71 **MOV DS, AX**
- 72 **MOV AH**, 25H
- 73 **MOV AL, 0BH**
- 74 **INT** 21H
- 75 **POP DS**
- 76 MOV AH,4CH
- 77 **INT** 21H

78

- 79 INTR PROC
- 80 MOV FLAG, 1
- 81 **MOV DX**, 280H
- 82 **IN AL, DX**
- 83 MOV CL, AL
- 84 **MOV AL**, 20H
- 85 **OUT** 20H, **AL**
- 86 **IRET**
- 87 INTR ENDP

88

- 89 MAIN ENDP
- 90 CODE ENDS
- 91 END START

2.3.2 选做任务一

修改主程序实现密码检测功能,连续两次从 A 口拨入数据,与计算机内部事先存放的两字节数比较,相符则在 CRT 上显示"OK",否则重新输入,代码如下所示:

- 01 DATAS SEGMENT
- 02 KEEP_IP \mathbf{DW} 0
- 03 KEEP_CS \mathbf{DW} 0
- 04 FLAG \mathbf{DB} 0
- 05 PASSWORD \mathbf{DB} OFOH, OFH
- 06 OK **DB** 'OK', O**DH**, O**AH**, '\$'
- 07 NO DB 'NO', ODH, OAH, '\$'
- 08 DATAS ENDS

09

```
10 STACKS SEGMENT
11 STACKS ENDS
12
13 CODES SEGMENT
14
      ASSUME CS:CODES, DS:DATAS, SS:STACKS
15
16 MAIN PROC FAR
17 START:
      MOV AX, DATAS
18
      MOV DS,AX
19
20
21
22
      MOV DX, 283H
23
      MOV AL, 10110000B
      OUT DX, AL
24
25
      MOV DX, 283H
26
      MOV AL, 00001001B
27
28
      OUT DX, AL
29
30
31
      MOV AH, 35H
      MOV AL, 0BH
32
      \mathbf{INT} 21H
33
34
      \mathbf{MOV} KEEP_IP, \mathbf{BX}
35
      MOV KEEP_CS, ES
36
37
      PUSH DS
38
39
      MOV DX, OFFSET INTR
      MOV AX, SEG INTR
40
41
      MOV DS, AX
      MOV AH, 25H
42
      MOV AL, 0BH
43
      INT 21H
44
45
      POP DS
```

```
46
47
       {f MOV} {f AL}, OF7H
48
       OUT 21H, AL
49
50 WAIT_FOR1:
51
       MOV BL, FLAG
       CMP BL, 1
52
53
       {f JZ} WAIT_FOR2
       {f JMP} WAIT_FOR1
54
55
56 WAIT_FOR2:
       CMP CL, OFFH
57
58
       \mathbf{JZ} EXIT
59
       MOV DL, CL
       MOV AH, 2
60
       INT 21H
61
62
       MOV BH,
                       \mathbf{CL}
63
       MOV FLAG, 0
64
       \mathbf{JMP} WAIT2
65 WAIT2:
       MOV BL, FLAG
66
67
       CMP BL, 1
       \mathbf{JZ} CHECK
68
69
       \mathbf{JMP} WAIT2
70
71 CHECK:
72
73
       CMP CL, OFFH
74
       \mathbf{JZ} EXIT
75
       MOV DL, CL
76
       MOV AH, 2
77
       \mathbf{INT} 21H
       CMP BH, PASSWORD
78
79
       \mathbf{JNZ} ERROR
       CMP CL,PASSWORD+1
80
81
       JNZ ERROR
```

```
82
83
       MOV AH, 9
84
       LEA DX, OK
85
       \mathbf{INT} 21H
       JMP WAIT_FOR1
86
87
88 ERROR:
       MOV AH, 9
89
90
       LEA DX, NO
       \mathbf{INT} 21H
91
92
       \mathbf{JMP} \ \mathtt{WAIT\_FOR1}
93
94 EXIT:
95
96
       MOV AL, OFFH
       OUT 21H, AL
97
98
99
100
        PUSH DS
        MOV DX, KEEP_IP
101
        MOV AX, KEEP_CS
102
103
        MOV DS, AX
        MOV AH, 25H
104
        MOV AL, 0BH
105
106
        {f INT} 21H
        POP DS
107
108
        MOV AH,4CH
        INT 21H
109
110
111 INTR PROC
        \mathbf{MOV} FLAG, 1
112
        MOV DX, 280H
113
        IN AL, DX
114
        MOV CL, AL
115
        {f MOV} {f AL}, 20H
116
        OUT 20H, AL
117
```

```
118
       IRET
119 INTR ENDP
120
121 MAIN \mathbf{ENDP}
122 CODES ENDS
123
       END START
2.3.3 选做任务二
将8255 电路 A 口改成方式 1 输出(仅将PA7接一只LED示范即可),修
改前面的程序实现每次中断后,通过 A 口输出数据控制 LED 状态在 0,1 之
间翻转,代码如下所示。
01 DATA SEGMENT
02 SIG DB 0
03 KEEP_IP \mathbf{DW} 0
04 KEEP_CS \mathbf{DW} 0
05 FLAG \mathbf{DB} 0
06 DATA ENDS
07
08 STACKS SEGMENT
09 STACKS ENDS
10
11 CODE SEGMENT
12
      ASSUME CS:CODE, DS:DATA, SS:STACKS
13
14 MAIN PROC FAR
15 START:
      MOV AX,DATA
16
      MOV DS,AX
17
18
19
20
      MOV DX, 283H
      MOV AL, 10101000B
21
      OUT DX, AL
22
23
```

24

MOV DX, 283H

```
MOV AL, 11001000B
25
       OUT DX, AL
26
27
28
29
       MOV AH, 35H
30
       MOV AL, 0BH
       INT 21H
31
32
       MOV KEEP_IP, BX
       \mathbf{MOV} KEEP_CS, \mathbf{ES}
33
34
35
36
37
       PUSH DS
38
       MOV DX, OFFSET INTR
       MOV AX, SEG INTR
39
       MOV DS, AX
40
41
       MOV AH, 25H
42
       MOV AL, 0BH
43
       INT 21H
44
       POP DS
45
       MOV AL, OF7H
46
47
       OUT 21H, AL
48
49 WAIT_FOR:
50
       MOV BL, FLAG
       {
m CMP~BL},~1
51
52
       \mathbf{JZ} ISINT
53
       {f JMP} WAIT_FOR
54
55 ISINT:
56
       MOV FLAG, 0
       \mathbf{JMP} \ \mathtt{WAIT\_FOR}
57
58
59 EXIT:
60
```

```
61
      MOV AL, OFFH
      OUT 21H, AL
62
63
64
      PUSH DS
65
      MOV DX, KEEP_IP
66
67
      MOV AX, KEEP_CS
      MOV DS, AX
68
      MOV AH, 25H
69
      MOV AL, 0BH
70
71
      \mathbf{INT} 21H
      POP DS
72
73
      MOV AH,4CH
74
      INT 21H
75
76 INTR PROC
      MOV FLAG, 1
77
78
      XOR SIG, OFFH
79
      MOV AL, SIG
      MOV DX, 280H
80
      OUT DX,AL
81
82
      MOV AL, 20H
      OUT 20H, AL
83
84
      IRET
85 INTR ENDP
86
87 MAIN ENDP
88 CODE ENDS
89
      END START
```

2.4 任务三

8255 电路 A 口以方式 0 输出, C 口也初始化成方式 0 输出且仅用其最低两位: PC1 接数码管位码输入端 S1, PC0 接位码输入端 S0。程序实现当 A 口输出字形"0"的段码时, C 口输出 01H, 第一个数码管显示"0", 当 A 口输出字形"1"的段码时, C 口输出 02H, 于是第二个数码管显示"1"。

每一位显示之后调用一段延时程序,选择恰当的延时程序,使"01"几乎同时显示在两位数码管上。

2.4.1 必做任务

```
代码如下所示:
01 DATAS SEGMENT
02 DATAS ENDS
03
04 STACKS SEGMENT
05 STACKS ENDS
06
07 CODES SEGMENT
80
      ASSUME CS:CODES, DS:DATAS, SS:STACKS
09
10 MAIN PROC FAR
11 START:
12
      MOV AX, DATAS
13
      MOV DS,AX
14
15
      MOV DX, 283H
      MOV AL, 10000000B
16
      OUT DX, AL
17
18
19 NEXT:
20
      MOV DX, 282H
21
      MOV AL, 01H
      OUT DX, AL
22
      MOV DX, 280H
23
24
      MOV AL, 3FH
25
      OUT DX, AL
26
27
      CALL DELAY
28
      MOV DX, 280H
29
      MOV AL, 06H
30
```

OUT DX, AL

31

```
32
      MOV DX, 282H
33
      MOV AL, 02H
       OUT DX, AL
34
35
      CALL DELAY
36
37
      MOV AH, 1
38
      INT 16H
39
      \mathbf{JZ} NEXT
40
      CMP AL, 20H
41
42
      \mathbf{JZ} EXIT
      JMP NEXT
43
44
45 EXIT:
46
      MOV AH,4CH
      INT 21H
47
48
49 DELAY PROC
50
      MOV CX, OFFH
51 D WAIT:
                LOOP D_WAIT
52
      RET
53 DELAY ENDP
54
55 MAIN \mathbf{ENDP}
56 CODES ENDS
57
      END START
```

2.4.2 选做任务一

当程序运行后,从计算机键盘上输入两位十进制数,分别在两个数码管上显示。若继续输入数字则更新显示。若发现输入了非数字键则退回 DOS,代码如下所示。

- 01 DATAS SEGMENT
- 02 NUM **DB** 3FH,06H,5**BH**,4FH,66H,6**DH**,7**DH**,07H,7FH,6FH
- 03 DATAS ENDS

04

```
05 STACKS SEGMENT
     DB 100 DUP(?)
07 STACKS ENDS
08
09 CODES SEGMENT
      ASSUME CS:CODES, DS:DATAS, SS:STACKS
11 START:
12
      MOV AX,DATAS
      MOV DS,AX
13
14
15
      MOV DX,283H
16
      MOV AL,10000000B
17
      OUT DX,AL
18
19
      MOV BX,0
      MOV CX,0
20
21 MAIN:
22
      MOV AH,0BH
23
      \mathbf{INT} 21H
24
      INC AL
25
      JNE NEXT
26
      MOV AH,1
27
      INT 21H
28
29
      CMP AL,'0'
30
      \mathbf{JS} EXIT
      CMP AL,'9'+1
31
32
      JNS EXIT
      SUB AL,30H
33
      MOV BL,AL
34
35
36
      MOV AH,1
      \mathbf{INT} 21H
37
      CMP AL,'0'
38
39
      \mathbf{JS} EXIT
40
      CMP AL, '9'+1
```

```
41
      JNS EXIT
42
      SUB AL,30H
43
      MOV CL,AL
44
45 CALL DELAY
46 CALL DELAY
47 CALL DELAY
49 NEXT:
50
51
52
      MOV DX,280H
53
      PUSH BX
54
      MOV BX,CX
      MOV AL,[NUM+BX]
55
      OUT DX,AL
56
57
      MOV DX,282H
58
      MOV AL,01H
59
      OUT DX,AL
60
      POP BX
61
62
      CALL DELAY
63
64
65
      MOV DX,282H
66
      MOV AL,00H
      OUT DX,AL
67
68
      MOV DX,280H
69
      MOV AL,[NUM+BX]
70
71
      OUT DX,AL
      MOV DX,282H
72
73
      MOV AL,02H
74
      OUT DX,AL
75
76
      CALL DELAY
```

```
77
78
79
        MOV DX,282H
80
        MOV AL,00H
        OUT DX,AL
81
82
        \mathbf{JMP} MAIN
83
84 EXIT:
85
        MOV AH, 4CH
        INT 21H
86
87
88
89 DELAY PROC
            PUSH
                         \mathbf{C}\mathbf{X}
90
            PUSH
                         \mathbf{A}\mathbf{X}
91
92
            MOV
                        AX,000FH
                        \mathbf{CX},OFFFH
93 X1:
             MOV
94 X2:
             \mathbf{DEC}
                       \mathbf{C}\mathbf{X}
            JNE
95
                      Х2
96
            DEC
                       \mathbf{A}\mathbf{X}
97
            JNE
                      X1
            POP
                       \mathbf{A}\mathbf{X}
98
                       \mathbf{C}\mathbf{X}
99
            POP
100
             RET
101 DELAY ENDP
102
103
104 CODES ENDS
          END START
105
106
107
108
109
```

2.4.3 选做任务二

3132

使用 TPC 实验台上的 8253 定时计数电路来代替前面的软件延时。8253 定时器自动重复工作,每工作一个周期发出一次中断请求信号,在中断服务程序里同步更换段码和位码,实现扫描显示,代码如下所示。

```
01 DATA SEGMENT
02 KEEPIP \mathbf{DW} 0
03 KEEPCS DW 0
04 DATA ENDS
05
06 STACK SEGMENT
      DB 100 DUP(?)
08 STACK ENDS
09
10 CODE SEGMENT
      ASSUME CS:CODE, DS:DATA, ES:DATA, SS:STACK
12 START:
13
14
      MOV AX,DATA
15
      MOV DS,AX
      MOV ES,AX
16
17
18
      MOV DX,293H
      MOV AL,00110111B
19
      OUT DX,AL
20
21
      MOV DX,290H
22
23
      XOR AL, AL
      OUT DX,AL
24
      MOV AL,50
25
      OUT DX,AL
26
27
      MOV DX,283H
28
      MOV AL,10000000B
29
      OUT DX,AL
30
```

```
MOV AH,35H
33
34
      MOV AL,0BH
35
      INT 21H
      MOV KEEPIP,BX
36
      MOV KEEPCS,ES
37
38
      PUSH DS
39
40
      MOV DX, OFFSET INTR
      MOV AX,SEG INTR
41
42
      MOV DS,AX
43
      MOV AH,25H
44
      MOV AL,0BH
45
      INT 21H
      POP DS
46
47
48
49
      IN AL,21H
      AND AL,011110111B
50
51
      OUT 21H,AL
52
53
      MOV BL,0
54 MAIN:
55
      HLT
56
      MOV AH,1
57
      INT 16H
58
      JNZ EXIT
      \mathbf{JMP} MAIN
59
60
61 EXIT:
62
63
      IN AL,21H
      OR AL,00001000B
64
      OUT 21H,AL
65
66
67
68
      PUSH DS
```

```
69
      MOV DX, KEEPIP
70
      MOV AX, KEEPCS
71
      MOV DS,AX
72
      MOV AH,25H
73
      MOV AL,0BH
74
      INT 21H
      POP DS
75
76
77
      MOV AH,4CH
      \mathbf{INT} 21H
78
79
80
81
82 INTR PROC
83
84
85
      MOV DX,282H
      MOV AL,00H
86
87
      OUT DX,AL
88
89
      CMP BL,0
      JNZ OUT1
90
91 OUT0:
92
      MOV DX,280H
93
      MOV AL, 3FH
      OUT DX,AL
94
95
      MOV DX,282H
      MOV AL,01H
96
97
      OUT DX,AL
      MOV BL,1
98
99
      \mathbf{JMP} \; \mathtt{END\_INTR}
100 OUT1:
101
102
       MOV DX,280H
103
       MOV AL,06H
104
       OUT DX,AL
```

```
MOV DX,282H
105
       MOV AL,02H
106
107
       OUT DX,AL
       MOV BL,0
108
109
       \mathbf{JMP} \mathtt{END\_INTR}
110
111 END_INTR:
112
       MOV AL,20H
       OUT OAOH, AL
113
       OUT 20H,AL
114
115 IRET
116 INTR ENDP
117
118
119 CODE ENDS
120 END START
121
122
123
124
125
126
127
128
```

2.5 完成情况及心得体会

本次实验使用了并口等元件完成了 CPU 对外设的控制,提升了汇编语言学习能力。