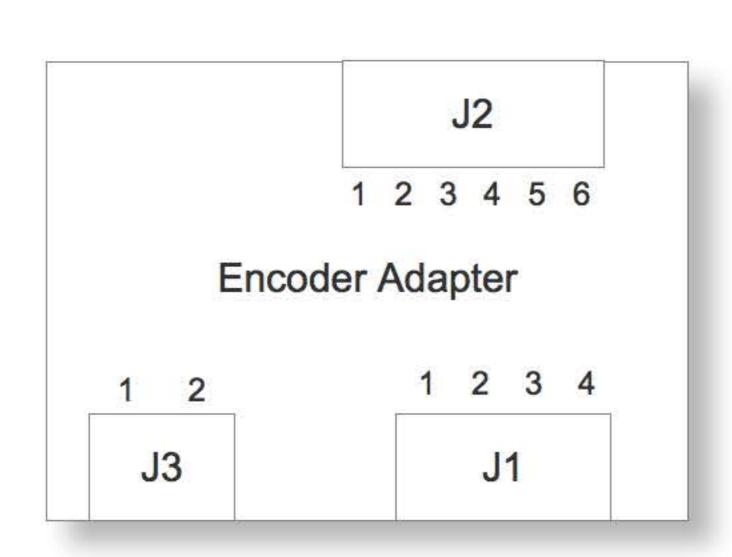


Motor:

1	Motor-	Black
2	Motor+	Red
3	Hall Vcc	Yellow
4	Hall GND	Green
5	Hall A	Blue
6	Hall B	Orange





Adapter J1:

- 1 GND
- 2 Vcc_in(+5V)
- 3 Hall A
- 4 Hall B

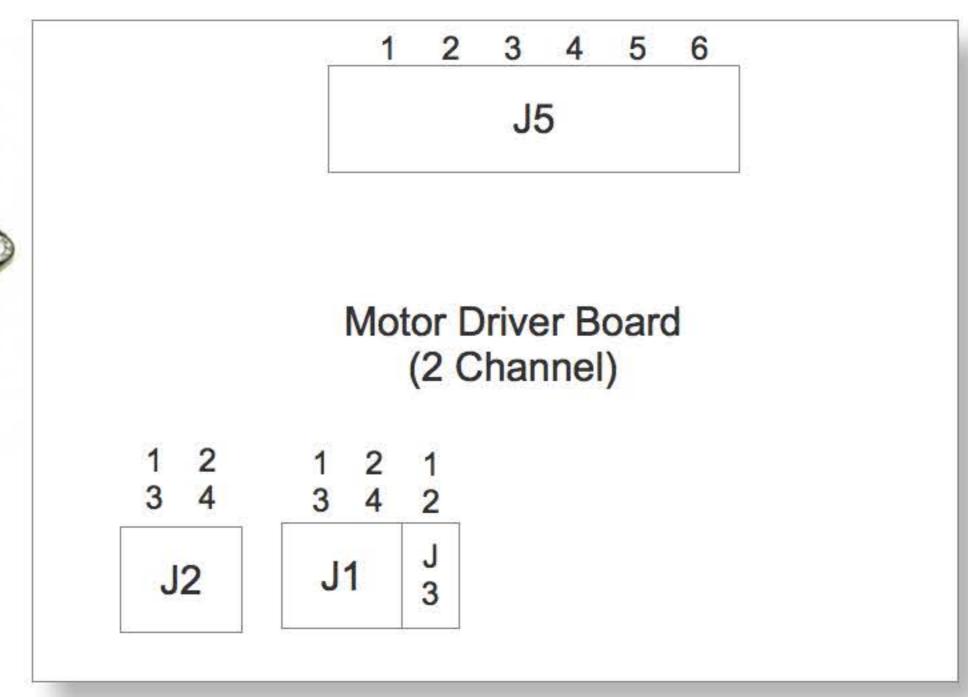
Adapter J3:

- 1 Motor-
- Motor+

Adapter J2:

- 1 Motor-
- 2 Motor+
- 3 Vcc_out(+5V)
- 4 GND
- 5 Hall A
- 6 Hall B





Driver J5:

- 1 Motor_1-
- 2 Motor_1+
- 3 Vcc(+14.8V)
- GND(+14.8V)
- Motor_2-
- 6 Motor_2+

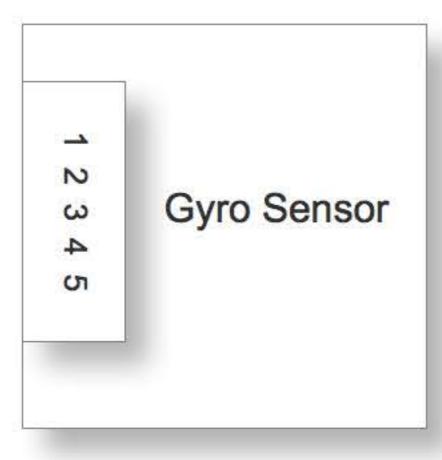
Driver J1: (3.3/5V)

- B_27 A_27 B_11 A_11 1 Motor_2 PWM 2 Motor_1 PWM
- 3 Motor_2 Direction
- 4 Motor_1 Direction

Driver J3:

1 Vcc_in(+5V) 2 GND A_1 A_8/12/16/24/30





Gyro Sensor:

St1

6

1	VCC(+5V)	B 1
	GND	B 6
3	RateOut(0~5V)	B 3
4	Temp	_
5	St2	