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1 Introduction

2 Basic Definitions

We will denote the set $\{1, \ldots, n\}$ by [n].

2.1 λ -calculus $\lambda 2$

$$FV(\Gamma) = \bigcup \{FV(t) \mid (x:t) \in \Gamma\}$$

Definition 1. Let $\mathcal{V}_T = \{\alpha, \beta, \dots\}$ be a countable set (of type-variables) the <u>set of all $\lambda 2$ types over \mathcal{V}_T , denoted by $T_{\lambda 2}$, is the smallest set T satisfying the following conditions:</u>

- $\mathcal{V}_T \subseteq \mathcal{T}$,
- if $t_1, t_2 \in T$ then $t_1 \to t_2 \in T$, and
- if $t \in T$ and $\alpha \in \mathcal{V}_T$ then $\forall \alpha.t \in T$.

Definition 2. Let \mathcal{V}_T be a countable set (of type-variables) and $\mathcal{V}_V = \{x_1, x_2, \dots\}$ a countable set (of value-variables) the set of all $\lambda 2$ terms over \mathcal{V}_T and \mathcal{V}_V , denoted by $\Lambda_{T_{\lambda 2}}$, is the smallest set Λ_T satisfying the following conditions:

- $\mathcal{V}_V \subseteq \Lambda_T$,
- if $e_1, e_2 \in \Lambda_T$ then $e_1e_2 \in \Lambda_T$,
- if $x \in \mathcal{V}_V$, $t \in T_{\lambda 2}$, and $e \in \Lambda_T$ then $\lambda x : t \cdot e \in \Lambda_T$,
- if $\alpha \in \mathcal{V}_T$ and $e \in \Lambda_T$ then $\Lambda \alpha . e \in \Lambda_T$, and
- if $e \in \Lambda_T$ and $t \in T_{\lambda 2}$ then $e t \in \Lambda_T$.

Definition 3. The free variables of a term e, denoted by FV(e), are defined inductively as follows:

$$FV(e) = \begin{cases} \{x\} & \text{if } e = x \\ FV(e_1) \cup FV(e_2) & \text{if } e = e_1 e_2 \\ FV(e') \setminus \{x\} & \text{if } e = \lambda x : t.e' \\ FV(e') & \text{if } e = \Lambda \alpha.e' \\ FV(e') & \text{if } e = e' t \end{cases}$$

Definition 4. A basis is a finite subset of $\mathcal{V}_V \times \Lambda_{T_{\lambda_2}}$

 $\lambda 2$ deduction Rules

$$\begin{array}{ll} (\operatorname{Axiom}) & \Gamma, x: t \vdash x: t \\ \\ (\lambda\text{-Introduction}) & \frac{\Gamma, x: t_1 \vdash e: t_2}{\Gamma \vdash \lambda x. e: t_1 \to t_2} \\ \\ (\lambda\text{-Elimination}) & \frac{\Gamma \vdash e_1: t_1 \to t_2 \quad \Gamma \vdash e_2: t_1}{\Gamma \vdash e_1 e_2: t_2} \\ \\ (\forall\text{-Introduction}) & \frac{\Gamma \vdash e: t}{\Gamma \vdash \Lambda \alpha. e: \forall \alpha. t} \qquad \qquad \alpha \notin \operatorname{FV}(\Gamma) \\ \\ (\forall\text{-Elimination}) & \frac{\Gamma \vdash e: \forall \alpha. t}{\Gamma \vdash e t': t \left[\alpha:=t'\right]} \end{array}$$

2.2 first-order logic

Definition 5. A <u>ranked set</u> is a tuple (Σ, rk) , where Σ is a countable set and $rk : \Sigma \to \mathbb{N}$ is a function that maps every symbol from Σ to a natural number (its rank).

If the function rk is understood we will just write Σ instead of (Σ, rk) . The set of all elements with a certain rank k in Σ , denoted by $\Sigma^{(k)}$, is defined by $\Sigma^{(k)} := rk^{-1}(k)$. In the following we will write $\Sigma = \{P^{(0)}, Q^{(3)}\}$ to say that $\Sigma = \{P, Q\}$, rk(P) = 0, and rk(Q) = 3.

In the following let $\mathcal{V} = \{x_0, x_1, \dots\}$ be a countable set (of variables), \mathcal{F} a ranked set (of function symbols), and \mathcal{P} a ranked set (of predicate symbols).

Definition 6. The set of <u>terms over</u> $(\mathcal{V}, \mathcal{F})$, denoted by $\mathcal{T}_{(\mathcal{V}, \mathcal{F})}$, is the smallest set \mathcal{T} satisfying the following conditions:

- $\mathcal{V} \subseteq \mathcal{T}$, and
- for every $k \in \mathbb{N}$ if $f \in \mathcal{F}^{(k)}$ and $t_1, t_2, \dots, t_k \in \mathcal{T}$ then $f(t_1, t_2, \dots, t_k) \in \mathcal{T}$.

The set of first-order formulas over $(\mathcal{V}, \mathcal{F}, \mathcal{P})$, denoted by $\mathcal{L}_{(\mathcal{V}, \mathcal{F}, \mathcal{P})}$, is the smallest set \mathcal{L} satisfying the following conditions:

- for every $k \in \mathbb{N}$ if $P \in \mathcal{P}^{(k)}$ and $t_1, t_2, \dots, t_k \in \mathcal{T}_{(\mathcal{V}, \mathcal{F})}$ then $P(t_1, t_2, \dots, t_k) \in \mathcal{L}$.
- If $\varphi, \psi \in \mathcal{L}$ then $(\varphi \wedge \psi), (\varphi \vee \psi), \neg \varphi \in \mathcal{L}$, and
- if $x \in \mathcal{V}$ and $\varphi \in \mathcal{L}$ then $\exists x \varphi, \forall x \varphi \in \mathcal{L}$.

To define the free variables of a formula we first need to define the variables of a term.

Definition 7. The variables of a term $t \in \mathcal{T}_{(\mathcal{V},\mathcal{F})}$, denoted by V(t), are defined by:

$$V(t) = \begin{cases} \{x\} & \text{if } t = x \\ V(t_1) \cup V(t_2) \cup \dots \cup V(t_k) & \text{if } t = f(t_1, t_2, \dots, t_k) \end{cases}$$

Definition 8. The free variables of a formula $\varphi \in \mathcal{L}_{(\mathcal{V},\mathcal{F},\mathcal{P})}$, denoted by $FV(\varphi)$, are defined as follows:

$$FV(\varphi) = \begin{cases} V(t_1) \cup V(t_2) \cup \dots \cup V(t_k) & \text{if } \varphi = P(t_1, t_2, \dots, t_k) \\ FV(\varphi_1) \cup FV(\varphi_2) & \text{if } \varphi = \varphi_1 \circ \varphi_2, \circ \in \{\land, \lor\} \\ FV(\psi) \setminus \{x\} & \text{if } \varphi = Qx\psi, \ Q \in \{\forall, \exists\} \end{cases}$$

Definition 9. Let x be in \mathcal{V} and $t, t' \in \mathcal{T}_{(\mathcal{V}, \mathcal{F})}$. The <u>substitution of x by t' in t, denoted by t[x := t'], is defined as follows:</u>

$$t[x := t'] = \begin{cases} t' & \text{if } t = x \\ y & \text{if } t = y \text{ and } y \neq x \\ f(t_1[x := t'], \dots, t_k[x := t']) & \text{if } t = f(t_1, \dots, t_k) \end{cases}$$

Now we can lift this definition to formulas, let φ be in $\mathcal{L}_{(\mathcal{V},\mathcal{F},\mathcal{P})}$. The <u>substitution of</u> x by t' in φ , denoted by $\varphi[x:=t']$, is defined as follows:

$$\varphi\left[x := t'\right] = \begin{cases} P(t_1\left[x := t'\right], \dots, t_k\left[x := t'\right]) & \text{if } \varphi = P(t_1, \dots, t_k) \\ \psi\left[x := t'\right] & \text{if } \varphi = \neg \psi \\ \varphi_1\left[x := t'\right] \circ \varphi_2\left[x := t'\right] & \text{if } \varphi = (\varphi_1 \circ \varphi_2), \circ \in \{\land, \lor\} \\ \varphi & \text{if } \varphi = Qx\psi, \ Q \in \{\forall, \exists\} \\ Qy(\psi\left[x := t'\right]) & \text{if } \varphi = Qy\psi, \ Q \in \{\forall, \exists\} \text{ and } y \neq x \end{cases}$$

Now we come to the semantics of first-order formulas.

Definition 10. An interpretation I over $(\mathcal{V}, \mathcal{F}, \mathcal{P})$ is a triple $(\Delta, \cdot^I, \omega)$ where Δ is a nonempty set (which we call domain),

is a function such that $f^I: \Delta^k \to \Delta \text{ is a function for every } k \in \mathbb{N}, \ f \in \mathcal{F}^{(k)} \text{ and }$ $P^I \subseteq \Delta^k \text{ is a relation for every } k \in \mathbb{N}, \ f \in \mathcal{P}^{(k)}$ ω is a function from \mathcal{V} to Δ .

Let $I = (\Delta, \cdot^I, \omega)$ be an interpretation, $x \in \mathcal{V}$, and $d \in \Delta$ the interpretation $I[x \to d]$ is defined as $(\Delta, \cdot^I, \omega[x \to d])$ where

$$(\omega[x \to d])(y) = \begin{cases} d & \text{if } y = x \\ \omega(y) & \text{otherwise.} \end{cases}$$

Definition 11. Let $I = (\Delta, \cdot^I, \omega)$ be an interpretation and t a term the <u>interpretation</u> of t under I, denoted by t^I , is defined as follows:

$$t^{I} = \begin{cases} \omega(x) & \text{if } t = x\\ f^{I}(t_{1}^{I}, \dots, t_{k}^{I}) & \text{if } t = f(t_{1}, \dots, t_{k}) \end{cases}$$

Definition 12. Let $I = (\Delta, \cdot^I, \omega)$ be an interpretation and φ a formula the <u>interpretation</u> of φ under I, denoted by φ^I , is defined recursively as follows:

$$\varphi^{I} = \begin{cases} \top & \text{if } \varphi = P(t_{1}, \dots, t_{k}) \text{ and } (t_{1}^{I}, \dots, t_{k}^{I}) \in P^{I} \\ \bot & \text{if } \varphi = P(t_{1}, \dots, t_{k}) \text{ and } (t_{1}^{I}, \dots, t_{k}^{I}) \notin P^{I} \\ \text{not } \psi^{I} & \text{if } \varphi = \neg \psi \\ \varphi_{1}^{I} \text{ and } \varphi_{2}^{I} & \text{if } \varphi = (\varphi_{1} \wedge \varphi_{2}) \\ \varphi_{1}^{I} \text{ or } \varphi_{2}^{I} & \text{if } \varphi = (\varphi_{1} \vee \varphi_{2}) \\ \text{exists } d \in \Delta \ \psi^{I[x \to d]} & \text{if } \varphi = \exists x \psi \\ \text{forall } d \in \Delta \ \psi^{I[x \to d]} & \text{if } \varphi = \forall x \psi \end{cases}$$

The interpretation I is a <u>model</u> of φ , denoted by $I \models \varphi$, if $\varphi^I = \top$.

Definition 13. Let Γ be a finite set of first-oder formulas.

We say that an interpretation I is a model of Γ if $I \models \psi$ for every ψ in Γ .

The formula φ is a <u>semantic consequence</u> of Γ , denoted by $\Gamma \vdash \varphi$, if every model of Γ is also a model of φ .

The free variables of Γ , denoted by $FV(\Gamma)$, are $\bigcup \{FV(\varphi) \mid \varphi \in \Gamma\}$.

3 System P

3.1 Definitions

Let $\mathcal{V}_P = \{\alpha, \beta, \ldots\}$ be a countably infinite set (of variables) and $\mathcal{P}_P = \{false^{(0)}, P^{(2)}, Q^{(2)}, \ldots\}$ a ranked set (of predicate symbols) such that $\mathcal{P}_P^{(0)} = \{false\}, \ \mathcal{P}_P^{(2)} = \{P, Q, \ldots\}$ is a countably infinite set, and $\mathcal{P}_P^{(k)} = \emptyset$ for all $k \in \mathbb{N} \setminus \{0, 2\}$. A first-order logic formula φ over $(\mathcal{V}_P, \emptyset, \mathcal{P}_P)$ is an

atomic formula if $\varphi = false$ or $\varphi = P(\alpha, \beta)$ for some $P \in \mathcal{P}_P$ and $\alpha, \beta \in \mathcal{V}_P$.

universal formula if $\varphi = \forall \overrightarrow{\alpha}(A_1 \to A_2 \to \cdots \to A_n)$ where A_i is an atomic formula for $i \in [n], A_i \neq false$ for $i \in [n-1]$ and for each $\alpha \in \mathrm{FV}(\varphi) \cap \mathrm{FV}(A_n)$ there exists an $i \in [n-1]$ such that $\alpha \in \mathrm{FV}(A_i)$.

existential formula if there exits $n \ge 0$, atomic formulas $A_i \ne false$ for $i \in [n]$ such that $\varphi = \forall \overrightarrow{\alpha}(A_1 \to A_2 \to \cdots \to A_{n-1} \to \forall \beta(A_n \to false) \to false)$.

The set of formulas of System **P** over $(\mathcal{V}_P, \mathcal{P}_P)$ is the set of all first-order formulas over $(\mathcal{V}_P, \emptyset, \mathcal{P}_P)$ that are either an atomic, universal or existential formula. Deduction Rules

$$\begin{array}{ll} (\operatorname{Axiom}) & \Gamma, A \vdash A \\ \\ (\to \operatorname{-Introduction}) & \frac{\Gamma, A \vdash B}{\Gamma \vdash A \to B} \\ \\ (\to \operatorname{-Elimination}) & \frac{\Gamma \vdash A \to B \quad \Gamma \vdash A}{\Gamma \vdash B} \\ \\ (\forall \operatorname{-Introduction}) & \frac{\Gamma \vdash B}{\Gamma \vdash \forall \alpha B} & \alpha \notin \operatorname{FV}(\Gamma) \\ \\ (\forall \operatorname{-Elimination}) & \frac{\Gamma \vdash \forall \alpha B}{\Gamma \vdash B \ [\alpha := b]} \end{array}$$

An Interpretation I of a P formula is a tuple $I=(\Delta,\cdot^I)$ where Δ is a set (called domain), $P^I\subseteq \Delta^k$ and $\alpha^I\in \Delta...$

If we interpret *false* with the logical constant false (\bot) (denoted by \vdash_f) we can add a new deduction rule.

$$(\exists \text{-Introduction}) \qquad \frac{\Gamma, A \left[\alpha := a\right] \vdash_f B}{\Gamma, \forall \alpha (A \to false) \to false \vdash_f B} \qquad a \notin FV(\Gamma, A, B)$$

Proof. Let $I = (\Delta, \cdot^I)$ be a model of $\Gamma, \forall \alpha (A \to false) \to false$ with $false^I = \bot$.

$$\begin{split} I &\models \Gamma, \forall \alpha (A \to false) \to false \Rightarrow I \models \forall \alpha (A \to false) \to false \\ &\Rightarrow (\forall \alpha (A \to false))^I \to false^I \\ &\Rightarrow (\forall \alpha (A \to false))^I \to \bot \\ &\Rightarrow \neg (\forall \alpha (A \to false))^I \\ &\Rightarrow \neg (\forall d \in \Delta : (A \to false)^{I[\alpha \mapsto d]}) \\ &\Rightarrow \exists d \in \Delta : \neg (A^{I[\alpha \mapsto d]} \to false^{I[\alpha \mapsto d]}) \\ &\Rightarrow \exists d \in \Delta : \neg (A^{I[\alpha \mapsto d]} \to \bot) \\ &\Rightarrow \exists d \in \Delta : \neg (A^{I[\alpha \mapsto d]}) \\ &\Rightarrow \exists d \in \Delta : A^{I[\alpha \mapsto d]}) \end{split}$$

Together with $a \notin FV(\Gamma, A)$, it follows that $I[a \mapsto d]$ is a model of $\Gamma, A[\alpha := a]$. Which implies $I[a \mapsto d] \models B$. Since a is not free in B we conclude that I is also a model of B.

3.2 Provability in System P is undecidable

 Γ_C :

- *Q*(*a*)
- $R_1(a, a_0), P(a_{i-1}, a_i)$ for $i \in \{1, \dots, m\}$
- $R_2(a,b_0), P(b_{i-1},b_i)$ for $i \in \{1,\ldots,n\}$
- $D(a), D(a_i), D(b_j)$ for $i \in \{1, ..., m\}$ and $j \in \{1, ..., n\}$
- $E(a_m), E(b_n)$

+(Q,1,Q'):

- $\forall \alpha \beta(Q(\alpha) \to S(\alpha, \beta) \to Q'(\beta))$ change of state
- $\forall \alpha \beta \gamma \delta(Q(\alpha) \to S(\alpha, \beta) \to R_1(\alpha, \gamma) \to R_1(\beta, \delta) \to P(\delta, \gamma))$ increment register 1
- $\forall \alpha \beta \delta(Q(\alpha) \to S(\alpha, \beta) \to R_1(\beta, \delta) \to D(\delta))$ prevent zero
- $\forall \alpha \beta \gamma (Q(\alpha) \to S(\alpha, \beta) \to R_2(\alpha, \gamma) \to R_2(\beta, \gamma))$ do not change register 2

 $-(Q,1,Q_1,Q_2):$

- $\forall \alpha \beta \gamma (Q(\alpha) \to S(\alpha, \beta) \to R_1(\alpha, \gamma) \to E(\gamma) \to Q_2(\beta))$ jump on zero
- $\forall \alpha \beta \gamma (Q(\alpha) \to S(\alpha, \beta) \to R_1(\alpha, \gamma) \to E(\gamma) \to R_1(\beta, \gamma))$ register 1 stays zero
- $\forall \alpha \beta \gamma(Q(\alpha) \to S(\alpha, \beta) \to R_1(\alpha, \gamma) \to D(\gamma) \to Q_1(\beta))$ change state if register 1 is greater zero
- $\forall \alpha \beta \gamma \delta(Q(\alpha) \to S(\alpha, \beta) \to R_1(\alpha, \gamma) \to D(\gamma) \to P(\gamma, \delta) \to R_1(\beta, \delta))$ decrement register 1
- $\forall \alpha \beta \gamma (Q(\alpha) \to S(\alpha, \beta) \to R_2(\alpha, \gamma) \to R_2(\beta, \gamma))$ do not change register 2

Lemma 14.

M terminates on input (0,0) iff $\Gamma_M \vdash \text{false holds in system } P$.

Claim 15.

 $\Gamma_M \vdash \text{false holds in system } P \implies M \text{ terminates on input } (0,0)$

Proof. Assume M does not terminate then there is an infinite chain $C_1 \Rightarrow_M C_2 \Rightarrow_M C_3 \Rightarrow_M \ldots$ $(C_i = \langle Q_i, m_i, n_i \rangle)$ Now we construct a model of Γ_M which interprets false with \bot this contradicts $\Gamma_M \vdash false$.

To illustrate the idea we will use a graphical notation for an interpretation I. By $d_1 \stackrel{\mathrm{R}}{\to} d_2$ we say that $(d_1, d_2) \in R^I$. And we use $\frac{\mathrm{P}}{d}$ to say that $d \in P^I$ for unary predicate symbols. Now the idea for our model of Γ_M looks like this:

$$0 \xrightarrow{P} 1 \xrightarrow{P} \cdots \xrightarrow{P} m_{i} \xrightarrow{S} \cdots \xrightarrow{P} n_{i} \xrightarrow{P} \cdots \xrightarrow{P} i \xrightarrow{P} \cdots$$

We have $0 \in E^I$ and all other numbers are in D^I . Here is the more formal definition of our model $I = (\mathbb{N}, \cdot^I)$.

$$P^{I} = \{(i+1,i) \mid i \in \mathbb{N}\} \qquad R_{1}^{I} = \{(i,m_{i}) \mid i \in \mathbb{N}\} \qquad R_{2}^{I} = \{(i,n_{i}) \mid i \in \mathbb{N}\}$$

$$Q^{I} = \{i \in \mathbb{N} \setminus \{0\} \mid Q = Q_{i}\} \qquad D^{I} = \mathbb{N} \setminus \{0\} \qquad E^{I} = \{0\}$$

$$S^{I} = \{(i,i+1) \mid i \in \mathbb{N}\}$$

$$a^{I} = 1$$
 $a_{0}^{I} = 0$ $b_{0}^{I} = 0$

Claim 16. If a final state is reachable from C then $\Gamma_C \cup \Gamma \vdash$ false.

Proof. By induction on the length of the computation. For the tableau proofs we will abbreviate false by f.

Induction Base trivial ...

Induction Step

$$C \Rightarrow_M^r D$$

We need to make a case distinction on the rule r.

Case r = +(Q, 1, Q')

Basic idea:

$$\frac{IH}{\frac{\Gamma_C \cup \Gamma \cup \Gamma_D \vdash f}{\Gamma_C \cup \Gamma \vdash \Gamma_D}}$$

Since $I \models false$ holds trivially if I interprets false with \top we only need to consider models (note that there are none if M terminates which is exactly what we want to proof) of $\Gamma_C \cup \Gamma$ that interpret false with \bot (so we can use our new deduction rule).

We will just drop $\Gamma_C \cup \Gamma$ and only write new formulas on the left side. We first introduce the new variables needed for Γ_D (let $b, d \in \mathcal{V}_P \backslash FV(\Gamma_C \cup \Gamma)$). Intuitively b will represent the successor state and d will be the anchor for register one.

$$\frac{\vdots \qquad S(a,b) \vdash_f \forall \alpha \beta(S(\alpha,\beta) \to D(\beta))}{S(a,b),D(b) \vdash_f f} \frac{S(a,b) \vdash_f S(a,b) \to D(b) S(a,b) \vdash_f S(a,b)}{S(a,b) \vdash_f D(b)} \\ \frac{S(a,b) \vdash_f f}{\forall \beta(S(a,\beta) \to f) \to f) \to f} \frac{\vdots \qquad S(a,b) \vdash_f f}{\vdash_f (\forall \beta(S(a,\beta) \to f) \to f) \to f} \\ \frac{\vdash_f (\forall \beta(S(a,\beta) \to f) \to f) \to f}{\vdash_f f} \frac{\vdash_f \forall \alpha(\forall \beta(S(\alpha,\beta) \to f) \to f)}{\vdash_f f} \\ \frac{\vdash_f f}{}$$

The formula $R_1(b,d)$ can be acquired in a similar way. Again we will just drop S(a,b) and D(b) on the left side for comprehensibility.

Now we have all the new free variables we need and we continue by ensuring that these variables fulfill all the formulas in Γ_D .

$$\frac{\vdots \frac{\vdash_{f} \forall \alpha \beta(Q(\alpha) \to S(\alpha, \beta) \to Q'(\beta))}{\vdash_{f} Q(a) \to S(a, b) \to Q'(b)} \vdash_{f} Q(a)}{Q'(b) \vdash_{f} f} \frac{\vdash_{f} S(a, b) \to Q'(b)}{\vdash_{f} S(a, b) \to Q'(b)} \vdash_{f} S(a, b)}{\vdash_{f} Q'(b)}$$

$$\vdash_{f} f$$

Starting from $Q'(b) \vdash_f false$ we can connect d and a_0 .

$$\frac{ \begin{matrix} \vdash_f \forall \alpha \beta \gamma \delta(Q(\alpha) \rightarrow S(\alpha,\beta) \rightarrow R_1(\alpha,\gamma) \rightarrow R_1(\beta,\delta) \rightarrow P(\delta,\gamma)) \\ \hline \begin{matrix} \vdash_f Q(a) \rightarrow S(a,b) \rightarrow R_1(a,a_0) \rightarrow R_1(b,d) \rightarrow Q'(b) \vdash_f Q(a) \end{matrix}}{ \begin{matrix} \vdash_f S(a,b) \rightarrow R_1(a,a_0) \rightarrow R_1(b,d) \rightarrow Q'(b) \vdash_f S(a,b) \end{matrix}} \\ \vdots \\ \hline \begin{matrix} \vdash_f R_1(a,a_0) \rightarrow R_1(b,d) \rightarrow Q'(b) \vdash_f R_1(a,a_0) \end{matrix}}{ \begin{matrix} \vdash_f R_1(b,d) \rightarrow Q'(b) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) \rightarrow f \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) \rightarrow f \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \hline \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \end{matrix}$$
} \\ \begin{matrix} \begin{matrix} \vdash_f P(d,a_0) & \vdash_f R_1(b,d) \end{matrix}} \\ \end{matrix}} \\ \begin{matrix} \begin{matrix} \vdash_f P(d,a_0)

For register one we still need D(d).

$$\underbrace{\frac{ \vdash_{f} \forall \alpha \beta \delta(Q(\alpha) \rightarrow S(\alpha,\beta) \rightarrow R_{1}(\beta,\delta) \rightarrow D(\delta))}{\vdash_{f} Q(a) \rightarrow S(a,b) \rightarrow R_{1}(b,d) \rightarrow D(d) \vdash_{f} Q(a)}}_{\vdots} \underbrace{\frac{\vdash_{f} S(a,b) \rightarrow R_{1}(b,d) \rightarrow D(d) \vdash_{f} S(a,b)}{\vdash_{f} S(a,b) \rightarrow R_{1}(b,d) \rightarrow D(d) \vdash_{f} S(a,b)}}_{\vdash_{f} D(d)} }_{\vdash_{f} f}$$

Since register two should not change we only need $R_2(b, b_0)$.

$$\underbrace{\frac{ \vdash_{f} \forall \alpha \beta \gamma (Q(\alpha) \to S(\alpha, \beta) \to R_{2}(\alpha, \gamma) \to R_{2}(\beta, \gamma))}{\vdash_{f} Q(a) \to S(a, b) \to R_{2}(a, b_{0}) \to R_{2}(b, b_{0}) \vdash_{f} Q(a)}}_{\vdots \underbrace{\frac{\vdash_{f} S(a, b) \to R_{2}(a, b_{0}) \to R_{2}(b, b_{0}) \vdash_{f} S(a, b)}{\vdash_{f} S(a, b) \to R_{2}(a, b_{0}) \to R_{2}(b, b_{0}) \vdash_{f} R_{2}(a, b_{0})}}_{\vdash_{f} R_{2}(b, b_{0}) \to f} \underbrace{\frac{\vdash_{f} R_{2}(a, b_{0}) \to R_{2}(b, b_{0}) \vdash_{f} R_{2}(a, b_{0})}{\vdash_{f} R_{2}(b, b_{0})}}_{\vdash_{f} f}$$

Now we have Γ_C (Since $P(a_{i-1}, a_i)$ is already in Γ_D) and can deduce false by induction hypothesis.

Case
$$r = -(Q, 1, Q_1, Q_2) \ r1 = 0$$

$$\frac{ \begin{array}{c} \vdash_f \forall \alpha\beta\gamma(Q(\alpha) \to S(\alpha,\beta) \to R_1(\alpha,\gamma) \to E(\gamma) \to Q_2(\beta)) \\ \hline \\ \vdash_f Q(a) \to S(a,b) \to R_1(a,a_0) \to E(a_0) \to Q_2(b) \vdash_f Q(a) \\ \hline \\ \vdash_f S(a,b) \to R_1(a,a_0) \to E(a_0) \to Q_2(b) \vdash_f S(a,b) \\ \hline \\ \vdots \\ \hline \\ \begin{matrix} \vdash_f R_1(a,a_0) \to E(a_0) \to Q_2(b) \vdash_f R_1(a,a_0) \\ \hline \\ \vdash_f R_1(a,a_0) \to Q_2(b) \vdash_f E(a_0) \\ \hline \\ \vdash_f Q_2(b) \to f \\ \hline \\ \vdash_f f \end{matrix}$$