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# 1 Introduction

## 2 Basic Definitions

We will denote the set  $\{1, \ldots, n\}$  by [n].

### 2.1 $\lambda$ -calculus $\lambda 2$

In the following let  $\mathcal{V}_T = \{\alpha, a, \beta, b, ...\}$  be a countable set (of type-variables) and  $\mathcal{V}_V = \{x_1, x_2, ...\}$  be a countable set (of value-variables).

**Definition 1.** The set of all  $\lambda 2$  types over  $\mathcal{V}_T$ , denoted by  $T_{\lambda 2}$ , is the smallest set T satisfying the following conditions:

- $\mathcal{V}_T \subseteq \mathbf{T}$ ,
- if  $t_1, t_2 \in T$  then  $t_1 \to t_2 \in T$ , and
- if  $t \in T$  and  $\alpha \in \mathcal{V}_T$  then  $\forall \alpha.t \in T$ .

The set of all  $\lambda 2$  terms over  $\mathcal{V}_T$  and  $\mathcal{V}_V$ , denoted by  $\Lambda_{T_{\lambda 2}}$ , is the smallest set  $\Lambda_T$  satisfying the following conditions:

- $\mathcal{V}_V \subseteq \Lambda_{\mathrm{T}}$ ,
- if  $e_1, e_2 \in \Lambda_T$  then  $e_1e_2 \in \Lambda_T$ ,
- if  $x \in \mathcal{V}_V$ ,  $t \in T_{\lambda 2}$ , and  $e \in \Lambda_T$  then  $\lambda x : t.e \in \Lambda_T$ ,
- if  $\alpha \in \mathcal{V}_T$  and  $e \in \Lambda_T$  then  $\Lambda \alpha.e \in \Lambda_T$ , and
- if  $e \in \Lambda_T$  and  $t \in T_{\lambda 2}$  then  $e \in \Lambda_T$ .

**Definition 2.** Let  $e \in \Lambda_{T_{\lambda_2}}$ . The <u>free variables of e</u>, denoted by FV(e), are defined inductively as follows:

$$FV(e) = \begin{cases} \{x\} & \text{if } e = x \\ FV(e_1) \cup FV(e_2) & \text{if } e = e_1e_2 \\ FV(e') \setminus \{x\} & \text{if } e = \lambda x : t.e' \\ FV(e') & \text{if } e = \Lambda \alpha.e' \\ FV(e') & \text{if } e = e't \end{cases}$$

Or is this definition better?

**Definition 3.** Let  $e \in \Lambda_{T_{\lambda_2}}$ . The <u>free variables of e</u>, denoted by FV(e), are defined inductively as follows:

$$FV(y) = \{x\}$$

$$FV(e_1e_2) = FV(e_1) \cup FV(e_2)$$

$$FV(\lambda x : t.e') = FV(e') \setminus \{x\}$$

$$FV(\Lambda \alpha.e') = FV(e')$$

$$FV(e't) = FV(e')$$

**Definition 4.** Let  $\mathcal{V}$  be a finite subset of  $\mathcal{V}_T$ . A  $\underline{\lambda 2}$ -basis  $\Gamma = \{(x_1 : t_1), \dots, (x_n : t_n)\}$  is a mapping from  $\mathcal{V}$  to  $T_{\lambda 2}$ . If the kind of basis is clear from the context we abbreviate  $\lambda 2$ -basis to basis.

The free variables of a  $\lambda 2$ -basis  $\Gamma$ , denoted by  $FV(\Gamma)$ , are  $\bigcup \{FV(t) \mid (x:t) \in \Gamma\}$ .

**Definition 5.** Let e be in  $\Lambda_{T_{\lambda_2}}$ , t in  $T_{\lambda_2}$ , and  $\Gamma$  be a basis. A statement e:t is <u>derivable</u> from  $\Gamma$ , denoted by  $\Gamma \vdash e:t$ , if e:t can be produced using the following rules.

$$\begin{array}{ll} (\operatorname{Axiom}) & \Gamma, x: t \vdash x: t \\ \\ (\lambda\text{-Introduction}) & \frac{\Gamma, x: t_1 \vdash e: t_2}{\Gamma \vdash \lambda x: t_1.e: t_1 \to t_2} \\ \\ (\lambda\text{-Elimination}) & \frac{\Gamma \vdash e_1: t_1 \to t_2 \quad \Gamma \vdash e_2: t_1}{\Gamma \vdash e_1 e_2: t_2} \\ \\ (\forall\text{-Introduction}) & \frac{\Gamma \vdash e: t}{\Gamma \vdash \Lambda \alpha.e: \forall \alpha.t} \qquad \alpha \notin \operatorname{FV}(\Gamma) \\ \\ (\forall\text{-Elimination}) & \frac{\Gamma \vdash e: \forall \alpha.t}{\Gamma \vdash et': t \left[\alpha:=t'\right]} & t' \in \mathcal{T}_{\lambda 2} \end{array}$$

**Definition 6.** The inhabitation problem for  $\lambda 2$ , denoted by **INHAB**, is defined as follows. Given a  $\lambda 2$  type t.

Is there a  $\lambda 2$  term M such that  $\emptyset \vdash M : t$ ?

But we can rephrase this problem so that it becomes more general: Given a basis  $\Gamma$  and a  $\lambda 2$  type t.

Is there a  $\lambda 2$  term M such that  $\Gamma \vdash M : t$ ?

Obviously the second version is a special case of the first one. For the other direction consider a basis  $\Gamma = \{(x_1 : t_1), \dots, (x_n : t_n)\}$  and a  $\lambda 2$  type t. Clearly, for every term  $M, \Gamma \vdash M : t$  holds iff  $\emptyset \vdash \lambda x_1 : t_1 \dots \lambda x_n : t_n M : t_1 \to \dots \to t_n \to t$ .

### 2.2 first-order logic

**Definition 7.** A <u>ranked set</u> is a tuple  $(\Sigma, rk)$ , where  $\Sigma$  is a countable set and  $rk: \Sigma \to \mathbb{N}$  is a function that maps every symbol from  $\Sigma$  to a natural number (its rank).

If the function rk is understood we will just write  $\Sigma$  instead of  $(\Sigma, rk)$ . The set of all elements in  $\Sigma$  with a certain rank k, denoted by  $\Sigma^{(k)}$ , is defined as  $\Sigma^{(k)} := rk^{-1}(k)$ .

For the remainder of this section let  $\mathcal{V} = \{y_1, y_2, \dots\}$  be a countable set (of variables),  $\mathcal{F}$  a ranked set (of function symbols), and  $\mathcal{P}$  a ranked set (of predicate symbols).

**Definition 8.** The set of terms over  $(\mathcal{V}, \mathcal{F})$ , denoted by  $\mathcal{T}_{(\mathcal{V}, \mathcal{F})}$ , is the smallest set  $\mathcal{T}$  satisfying the following conditions:

- $\mathcal{V} \subseteq \mathcal{T}$ , and
- for every  $k \in \mathbb{N}$  if  $f \in \mathcal{F}^{(k)}$  and  $t_1, t_2, \dots, t_k \in \mathcal{T}$  then  $f(t_1, t_2, \dots, t_k) \in \mathcal{T}$ .

The set of first-order formulas over  $(\mathcal{V}, \mathcal{F}, \mathcal{P})$ , denoted by  $\mathcal{L}_{(\mathcal{V}, \mathcal{F}, \mathcal{P})}$ , is the smallest set  $\mathcal{L}$  satisfying the following conditions:

- for every  $k \in \mathbb{N}$  if  $P \in \mathcal{P}^{(k)}$  and  $t_1, t_2, \dots, t_k \in \mathcal{T}_{(\mathcal{V}, \mathcal{F})}$  then  $P(t_1, t_2, \dots, t_k) \in \mathcal{L}$ .
- If  $\varphi, \psi \in \mathcal{L}$  then  $(\varphi \wedge \psi)$ ,  $(\varphi \vee \psi)$ ,  $\neg \varphi \in \mathcal{L}$ , and
- if  $y \in \mathcal{V}$  and  $\varphi \in \mathcal{L}$  then  $\exists y \varphi, \forall y \varphi \in \mathcal{L}$ .

We introduce an additional binary operation  $\to$  on formulas, where for some  $\varphi$ ,  $\psi \in \mathcal{L}_{(\mathcal{V},\mathcal{F},\mathcal{P})}$  the formula  $(\varphi \to \psi)$  is defined as  $(\neg \varphi \lor \psi)$ . For nullary relation symbols P we will abbreviate P() to P.

**Definition 9.** The <u>variables of a term  $t \in \mathcal{T}_{(\mathcal{V},\mathcal{F})}$ , denoted by V(t), are defined by:</u>

$$V(t) = \begin{cases} \{y\} & \text{if } t = y \\ V(t_1) \cup V(t_2) \cup \dots \cup V(t_k) & \text{if } t = f(t_1, t_2, \dots, t_k) \end{cases}$$

The free variables of a formula  $\varphi \in \mathcal{L}_{(\mathcal{V},\mathcal{F},\mathcal{P})}$ , denoted by  $\mathrm{FV}(\varphi)$ , are defined as follows:

$$\mathrm{FV}(\varphi) = \begin{cases} \mathrm{V}(t_1) \cup \mathrm{V}(t_2) \cup \cdots \cup \mathrm{V}(t_k) & \text{if } \varphi = P(t_1, t_2, \dots, t_k) \\ \mathrm{FV}(\psi) & \text{if } \varphi = \neg \psi \\ \mathrm{FV}(\varphi_1) \cup \mathrm{FV}(\varphi_2) & \text{if } \varphi = (\varphi_1 \wedge \varphi_2) \text{ or } \varphi = (\varphi_1 \vee \varphi_2) \\ \mathrm{FV}(\psi) \setminus \{y\} & \text{if } \varphi = \forall y \psi \text{ or } \varphi = \exists y \psi \end{cases}$$

**Definition 10.** Let y be in  $\mathcal{V}$  and  $t, t' \in \mathcal{T}_{(\mathcal{V}, \mathcal{F})}$ . The <u>substitution of y by t' in t</u>, denoted by t[y := t'], is defined as follows:

$$t[y := t'] = \begin{cases} t' & \text{if } t = y \\ z & \text{if } t = z \text{ and } z \neq y \\ f(t_1[x := t'], \dots, t_k[x := t']) & \text{if } t = f(t_1, \dots, t_k) \end{cases}$$

Now we can lift this definition to formulas, let  $\varphi$  be in  $\mathcal{L}_{(\mathcal{V},\mathcal{F},\mathcal{P})}$ . The <u>substitution of</u> y by t' in  $\varphi$ , denoted by  $\varphi[y:=t']$ , is defined as follows:

$$\varphi\left[x := t'\right] = \begin{cases} P(t_1 [y := t'], \dots, t_k [y := t']) & \text{if } \varphi = P(t_1, \dots, t_k) \\ \psi\left[y := t'\right] & \text{if } \varphi = \neg \psi \\ \varphi_1 [y := t'] \circ \varphi_2 [y := t'] & \text{if } \varphi = (\varphi_1 \circ \varphi_2), \circ \in \{\land, \lor\} \\ \varphi & \text{if } \varphi = \forall y \psi \text{ or } \varphi = \exists y \psi \\ Qz(\psi\left[y := t'\right]) & \text{if } \varphi = Qz\psi, Q \in \{\forall, \exists\} \text{ and } z \neq y \end{cases}$$

Now we come to the semantics of first-order formulas.

**Definition** 11. An interpretation I over  $(\mathcal{V}, \mathcal{F}, \mathcal{P})$  is a triple  $(\Delta, \cdot^I, \omega)$  where  $\Delta$  is a nonempty set (which we call domain),  $\cdot^I$  is a function such that  $f^I \colon \Delta^k \to \Delta$  is a function for every  $k \in \mathbb{N}, f \in \mathcal{F}^{(k)}$  and  $P^I \subseteq \Delta^k$  is a relation for every  $k \in \mathbb{N}, f \in \mathcal{P}^{(k)}$   $\omega$  is a function from  $\mathcal{V}$  to  $\Delta$ .

Let  $I = (\Delta, \cdot^I, \omega)$  be an interpretation,  $x \in \mathcal{V}$ , and  $d \in \Delta$  the interpretation  $I[x \to d]$  is defined as  $(\Delta, \cdot^I, \omega[x \to d])$  where

$$(\omega [x \to d])(y) = \begin{cases} d & \text{if } y = x \\ \omega(y) & \text{otherwise.} \end{cases}$$

**Definition 12.** Let  $I = (\Delta, \cdot^I, \omega)$  be an interpretation and t a term. The <u>interpretation</u> of t under I, denoted by  $t^I$ , is defined as follows:

$$t^{I} = \begin{cases} \omega(x) & \text{if } t = x\\ f^{I}(t_{1}^{I}, \dots, t_{k}^{I}) & \text{if } t = f(t_{1}, \dots, t_{k}) \end{cases}$$

Let  $\varphi$  be a formula. The <u>interpretation of  $\varphi$  under I, denoted by  $\varphi^I$ , is defined recursively as follows:</u>

$$\varphi^I = \begin{cases} \top & \text{if } \varphi = P(t_1, \dots, t_k) \text{ and } (t_1^I, \dots, t_k^I) \in P^I \\ \bot & \text{if } \varphi = P(t_1, \dots, t_k) \text{ and } (t_1^I, \dots, t_k^I) \notin P^I \\ \text{not } \psi^I & \text{if } \varphi = \neg \psi \\ \varphi_1^I \text{ and } \varphi_2^I & \text{if } \varphi = (\varphi_1 \wedge \varphi_2) \\ \varphi_1^I \text{ or } \varphi_2^I & \text{if } \varphi = (\varphi_1 \vee \varphi_2) \\ \text{exists } d \in \Delta \ \psi^{I[x \to d]} & \text{if } \varphi = \exists x \psi \\ \text{forall } d \in \Delta \ \psi^{I[x \to d]} & \text{if } \varphi = \forall x \psi \end{cases}$$

The interpretation I is a <u>model</u> of  $\varphi$ , denoted by  $I \models \varphi$ , if  $\varphi^I = \top$ .

When we define an interpretation I and we have a nullary predicate symbol P we write  $P^I = \top$  instead of  $P^I = \{()\}$  and  $P^I = \bot$  for  $P^I = \emptyset$  (this works because  $P()^I = \top$  iff  $() \in P^I$ ).

**Definition 13.** Let  $\Gamma$  be a finite set of first-oder formulas.

We say that an interpretation I is a <u>model</u> of  $\Gamma$ , denoted by  $I \models \Gamma$ , if  $I \models \psi$  for every  $\psi$  in  $\Gamma$ .

The formula  $\varphi$  is a <u>semantic consequence</u> of  $\Gamma$ , denoted by  $\Gamma \vdash \varphi$ , if every model of  $\Gamma$  is also a model of  $\varphi$ .

The free variables of  $\Gamma$ , denoted by  $FV(\Gamma)$ , are  $\bigcup \{FV(\varphi) \mid \varphi \in \Gamma\}$ .

### 2.3 two-counter automaton

We will use a version of two-counter automaton which only has two types of transitions. First it can increment a register and second it can decrement a register or jump if the register is already zero. Formally:

**Definition 14.** A deterministic two-counter automaton is a 4-tuple  $M = (\mathcal{Q}, Q_0, Q_f, R)$ ,

where Q is a finite set (of states),

 $Q_0$  is in Q (the initial state),

 $Q_f$  is in  $\mathcal{Q}$  (the final state), and

R is a function from  $\mathcal{Q} \setminus \{Q_f\}$  to  $\mathcal{R}_{\mathcal{Q}}$ , where  $\mathcal{R}_{\mathcal{Q}} = \{+(i,Q') \mid i \in \{1,2\}, Q' \in \mathcal{Q}\}$  $\cup \{-(i,Q_1,Q_2) \mid i \in \{1,2\}, Q_1, Q_2 \in \mathcal{Q}\}$ 

A <u>configuration</u> C of our automaton is a triple  $\langle Q, m, n \rangle$ , where  $Q \in \mathcal{Q}$  and  $m, n \in \mathbb{N}$ . Let r be in  $R(Q \setminus \{Q_f\})$ , then  $\Rightarrow_M^r$  is a binary relation on the configurations of M such that two configurations  $\langle Q, m, n \rangle$ ,  $\langle \widehat{Q}, \widehat{m}, \widehat{n} \rangle$  of M are in the in the relation if all of the following conditions hold:

- $Q \neq Q_f$ , r = R(Q),
- if r = +(1, Q') for some  $Q' \in \mathcal{Q}$  then  $\widehat{Q} = Q'$ ,  $\widehat{m} = m + 1$ , and  $\widehat{n} = n$ ,
- if r = +(2, Q') for some  $Q' \in \mathcal{Q}$  then  $\widehat{Q} = Q'$ ,  $\widehat{m} = m$ , and  $\widehat{n} = n + 1$ ,
- if  $r = -(1, Q_1, Q_2)$  for some  $Q_1, Q_2 \in \mathcal{Q}$  then if m = 0 then  $\widehat{Q} = Q_2$ ,  $\widehat{m} = 0$ , and  $\widehat{n} = n$ , if  $m \ge 1$  then  $\widehat{Q} = Q_1$ ,  $\widehat{m} = m - 1$ , and  $\widehat{n} = n$ ,
- if  $r=-(2,Q_1,Q_2)$  for some  $Q_1,Q_2\in\mathcal{Q}$  then if n=0 then  $\widehat{Q}=Q_2,\,\widehat{m}=m,$  and  $\widehat{n}=0,$ if  $n\geq 1$  then  $\widehat{Q}=Q_1,\,\widehat{m}=m,$  and  $\widehat{n}=n-1.$

The <u>transition relation of M</u>, denoted by  $\Rightarrow_M$ , is defined as  $\bigcup_{r \in R(Q \setminus \{Q_f\})} \Rightarrow_M^r$ . We denote the transitive reflexive closure of  $\Rightarrow_M$  by  $\Rightarrow_M^*$ 

Let m, n be in  $\mathbb{N}$ , we say that  $\underline{M}$  terminates on input (m,n) if there exist  $\widehat{m}, \widehat{n} \in \mathbb{N}$  such that  $\langle Q_0, m, n \rangle \Rightarrow_M^* \langle Q_f, \widehat{m}, \widehat{n} \rangle$ .

**Definition 15.** The halting problem for two-counter automaton, denoted by  $\mathbf{HALT}$ , is defined as follows. Given a two-counter automaton M.

Does M terminate on input (0,0)?

It is well known that **HALT** is undecidable.

# 3 System P

### 3.1 Definitions

In the following let  $\mathcal{V}_P = \{\alpha, a, \beta, b, ...\}$  be a countably infinite subset of  $\mathcal{V}_T$  (of variables). Let  $\mathcal{P}_P = \{P, Q, ...\}$  be a set (of predicate symbols) and  $\mathcal{P}$  a ranked set such that  $\mathcal{P}^{(0)} = \{\mathbf{false}\}$ ,  $\mathcal{P}^{(2)} = \mathcal{P}_P$ , and  $\mathcal{P}^{(k)} = \emptyset$  for all  $k \in \mathbb{N} \setminus \{0, 2\}$ . A first-order logic formula  $\varphi$  over  $(\mathcal{V}_P, \emptyset, \mathcal{P})$  is an

**atomic formula** if  $\varphi =$ **false** or  $\varphi = P(a, b)$  for some  $P \in \mathcal{P}_P$  and  $a, b \in \mathcal{V}_P$ .

**universal formula** if  $\varphi = \forall \overrightarrow{\alpha}(A_1 \to A_2 \to \cdots \to A_n)$  where  $A_i$  is an atomic formula for  $i \in [n], A_i \neq \mathbf{false}$  for  $i \in [n-1]$  and for each  $\alpha \in \mathrm{FV}(\varphi) \cap \mathrm{FV}(A_n)$  there exists an  $i \in [n-1]$  such that  $\alpha \in \mathrm{FV}(A_i)$ .

**existential formula** if there exists  $n \ge 0$ , atomic formulas  $A_i \ne \mathbf{false}$  for  $i \in [n]$  such that  $\varphi = \forall \overrightarrow{\alpha}(A_1 \to A_2 \to \cdots \to A_{n-1} \to \forall \beta(A_n \to \mathbf{false}) \to \mathbf{false})$ .

The set of formulas of System  $\mathbf{P}$  (= set of  $\mathbf{P}$ -formulas) over  $(\mathcal{V}_P, \mathcal{P}_P)$  is the set of all first-order formulas over  $(\mathcal{V}_P, \emptyset, \mathcal{P})$  that are either an atomic, universal or existential formula.

**Definition 16.** A finite set of **P**-formulas  $\Gamma$  is called **P**-basis, or basis if it is clear whether a **P**-basis or a  $\lambda$ **2**-basis is meant.

**Definition 17.** Let A be a **P**-formula, and  $\Gamma$  be a **P**-basis. The formula A is a semantic consequence of  $\Gamma$  if A can be produced using the following deduction rules.

$$\begin{array}{ll} (\operatorname{Axiom}) & \Gamma, A \vdash A \\ \\ (\to \operatorname{-Introduction}) & \frac{\Gamma, A \vdash B}{\Gamma \vdash A \to B} \\ \\ (\to \operatorname{-Elimination}) & \frac{\Gamma \vdash A \to B \quad \Gamma \vdash A}{\Gamma \vdash B} \\ \\ (\forall \operatorname{-Introduction}) & \frac{\Gamma \vdash B}{\Gamma \vdash \forall \alpha B} & \alpha \notin \operatorname{FV}(\Gamma) \\ \\ (\forall \operatorname{-Elimination}) & \frac{\Gamma \vdash \forall \alpha B}{\Gamma \vdash B \ [\alpha := b]} & b \in \mathcal{V}_P \end{array}$$

We define a general consequence relation in which we demand that **false** is interpreted with  $\perp$ . In this relation existential formulas will behave like the name suggests. Formally:

**Definition 18.** Let  $\Gamma$  be a basis. The **P**-formula A is a sematic consequence with falsity, denoted by  $\Gamma \vdash_f A$ , if for every interpretation I

$$I \models \Gamma$$
 and  $\mathbf{false}^I = \bot$  implies  $I \models A$ .

This allows us to add the following deduction rule.

$$(\exists \text{-Introduction}) \qquad \frac{\Gamma, A [\alpha := a] \vdash_{\mathrm{f}} B}{\Gamma, \forall \alpha (A \to \mathbf{false}) \to \mathbf{false} \vdash_{\mathrm{f}} B} \qquad a \notin FV(\Gamma, A, B)$$

*Proof.* Let  $I = (\Delta, \cdot^I, \omega)$  be a model of  $\Gamma, \forall \alpha(A \to \mathbf{false}) \to \mathbf{false}$  with  $\mathbf{false}^I = \bot$  and  $a \in \mathcal{V}_P$  a variable such that  $a \notin FV(\Gamma, A, B)$ .

$$\begin{split} I &\models \Gamma, \forall \alpha (A \to \mathbf{false}) \to \mathbf{false} \Rightarrow I \models \forall \alpha (A \to \mathbf{false}) \to \mathbf{false} \\ &\Rightarrow (\forall \alpha (A \to \mathbf{false}))^I \to \mathbf{false}^I \\ &\Rightarrow (\forall \alpha (A \to \mathbf{false}))^I \to \bot \\ &\Rightarrow \neg (\forall \alpha (A \to \mathbf{false}))^I \\ &\Rightarrow \neg (\forall d \in \Delta \colon (A \to \mathbf{false})^{I[\alpha \mapsto d]}) \\ &\Rightarrow \exists d \in \Delta \colon \neg (A^{I[\alpha \mapsto d]} \to \mathbf{false}^{I[\alpha \mapsto d]}) \\ &\Rightarrow \exists d \in \Delta \colon \neg (\neg A^{I[\alpha \mapsto d]}) \\ &\Rightarrow \exists d \in \Delta \colon \neg (\neg A^{I[\alpha \mapsto d]}) \\ &\Rightarrow \exists d \in \Delta \colon A^{I[\alpha \mapsto d]} \end{split}$$

Together with  $a \notin FV(\Gamma, A)$ , it follows that  $I[a \mapsto d]$  is a model of  $\Gamma, A[\alpha := a]$ . Which implies  $I[a \mapsto d] \models B$ . Since a is not free in B we conclude that I is also a model of B.

**Definition 19.** The problem to decide whether a given set of **P**-formulas is consistent, denoted by **CONS**, is defined as follows. Given a set of **P**-formulas  $\Gamma$ .

Does  $\Gamma \vdash$  **false** not hold?

### 3.2 CONS is undecidable

We will show that  $\mathbf{HALT} \leq \mathbf{CONS}$  then the undecidability of  $\mathbf{CONS}$  directly follows from the undecidability of  $\mathbf{HALT}$ . For a given two-counter automaton M we will effectively construct a  $\mathbf{P}$ -basis  $\Gamma_M$  such that

M terminates on input (0,0) iff  $\Gamma_M \vdash \mathbf{false}$  holds in system P.

Let  $M = (Q, Q_0, Q_f, R)$  be a two-counter automaton, w.l.o.g.  $S, P, R_1, R_2, E, D \notin Q$ . In the following we will consider **P**-formulas over  $(\mathcal{V}_P, \mathcal{P}_P)$ , where  $\mathcal{P}_P = \mathcal{Q} \uplus \{S, P, R_1, R_2, E, D\}$ . We will abbreviate P(a, a) to P(a), note that this way we can use binary predicate symbols as unary ones.

Intuitively Q(a) stands for "a is in state Q",  $R_i(a, m)$  stands for "in a the value of register i is m" for  $i \in \{1, 2\}$ , S(a, b) states that "b is a successor of a", P(a, b) states that "b is a predecessor of a", E(a) marks "a as the end of chain", and D(a) states that "a is not the end of a chain".

For a configuration  $C = \langle Q, m, n \rangle$  of M we define a set of **P**-formulas  $\Gamma_C$ . It contains the following formulas:

- $\bullet$  Q(a)
- $R_1(a, a_0), P(a_{i-1}, a_i)$  for  $i \in \{1, \dots, m\}$
- $R_2(a,b_0), P(b_{i-1},b_i)$  for  $i \in \{1,\ldots,n\}$
- $D(a), D(a_i), D(b_j)$  for  $i \in \{0, \dots, m-1\}$  and  $j \in \{0, \dots, n-1\}$
- $\bullet$   $E(a_m), E(b_n)$

Next we need sets of **P**-formulas for all possible transitions. For every  $Q \in \mathcal{Q} \setminus \{Q_f\}$  and  $r \in \mathcal{R}_{\mathcal{Q}}$  we define  $\Gamma_{Q,r}$ . If r = +(1,Q') for some  $Q' \in \mathcal{Q}$  then  $\Gamma_{Q,+(1,Q')}$  contains the following formulas:

- $\forall \alpha \beta (Q(\alpha) \to S(\alpha, \beta) \to Q'(\beta))$ change of state
- $\forall \alpha \beta \gamma \delta(Q(\alpha) \to S(\alpha, \beta) \to R_1(\alpha, \gamma) \to R_1(\beta, \delta) \to P(\delta, \gamma))$ increment register 1
- $\forall \alpha \beta \delta(Q(\alpha) \to S(\alpha, \beta) \to R_1(\beta, \delta) \to D(\delta))$ prevent zero in register 1
- $\forall \alpha \beta \gamma (Q(\alpha) \to S(\alpha, \beta) \to R_2(\alpha, \gamma) \to R_2(\beta, \gamma))$ do not change the value register 2

If  $r=-(1,Q_1,Q_2)$  for some  $Q_1,Q_2\in\mathcal{Q}$  then  $\Gamma_{Q,-(1,Q_1,Q_2)}$  contains the following formulas:

- $\forall \alpha \beta \gamma(Q(\alpha) \to S(\alpha, \beta) \to R_1(\alpha, \gamma) \to E(\gamma) \to Q_2(\beta))$ jump to  $Q_2$  if register 1 is zero
- $\forall \alpha \beta \gamma (Q(\alpha) \to S(\alpha, \beta) \to R_1(\alpha, \gamma) \to E(\gamma) \to R_1(\beta, \gamma))$ if register 1 is zero it stays zero
- $\forall \alpha \beta \gamma(Q(\alpha) \to S(\alpha, \beta) \to R_1(\alpha, \gamma) \to D(\gamma) \to Q_1(\beta))$ change state to  $Q_1$  if register 1 is greater zero
- $\forall \alpha \beta \gamma \delta(Q(\alpha) \to S(\alpha, \beta) \to R_1(\alpha, \gamma) \to D(\gamma) \to P(\gamma, \delta) \to R_1(\beta, \delta))$  decrement register 1
- $\forall \alpha \beta \gamma (Q(\alpha) \to S(\alpha, \beta) \to R_2(\alpha, \gamma) \to R_2(\beta, \gamma))$ do not change register 2 in both cases

For r = +(2, Q') for some  $Q' \in \mathcal{Q}$  or  $r = -(2, Q_1, Q_2)$  for some  $Q_1, Q_2 \in \mathcal{Q}$  the sets  $\Gamma_{Q,r}$  are defined analogously.

We also need a set  $\Gamma_1$  to ensure that our representation works correctly. The following formula are in  $\Gamma_1$ :

- $\forall \alpha \beta (S(\alpha, \beta) \to D(\beta))$ no successor is the end of a chain
- $\forall \alpha(D(\alpha) \to \forall \beta(R_1(\alpha, \beta) \to \mathbf{false}) \to \mathbf{false})$ every element that represents a configuration has a value for register 1
- $\forall \alpha(D(\alpha) \to \forall \beta(R_2(\alpha, \beta) \to \mathbf{false}) \to \mathbf{false})$ every element that represents a configuration has a value for register 2
- $\forall \alpha (\forall \beta (S(\alpha, \beta) \rightarrow \mathbf{false}) \rightarrow \mathbf{false})$ every element has a successor

We define  $\Gamma_{\overline{M}}$  as  $\bigcup_{Q \in \mathcal{Q} \setminus \{Q_f\}} \Gamma_{Q,R(Q)} \cup \{ \forall \alpha (Q_f(\alpha) \to \mathbf{false}) \} \cup \Gamma_1$ . Finally we can define  $\Gamma_M$  as  $\Gamma_{C_1} \cup \Gamma_{\overline{M}}$ , where  $C_1 = \langle Q_0, 0, 0 \rangle$  is the initial configuration.

#### Claim 20.

 $\Gamma_M \vdash false \ holds \ in \ system \ P \implies M \ terminates \ on \ input \ (0,0)$ 

*Proof.* Assume M does not terminate then there is an infinite chain  $C_1 \Rightarrow_M C_2 \Rightarrow_M C_3 \Rightarrow_M \dots$   $(C_i = \langle Q_i, m_i, n_i \rangle \text{ for } i \in \mathbb{N}^+)$ . Now we construct a model of  $\Gamma_M$  which interprets **false** with  $\bot$  this contradicts  $\Gamma_M \vdash \textbf{false}$ .

To illustrate the idea we will use a graphical notation for an interpretation I. By  $d_1 \stackrel{R}{\to} d_2$  we say that  $(d_1, d_2) \in R^I$ . And we use  $\frac{P}{d}$  to say that  $(d, d) \in P^I$  for predicate

symbols that are used as unary predicate symbols. As domain for our interpretation we will use the natural numbers. Every number will have two tasks: firstly it will represent itself as a possible value for register 1 or 2 and secondly every number i greater than zero will also represent the i<sup>th</sup> configuration of our infinite computation. Now the idea for our model of  $\Gamma_M$  looks like this:

$$0 \xrightarrow{R_1} Q_1 \xrightarrow{Q_{m_i}} Q_{m_i} \xrightarrow{S} \cdots \xrightarrow{S} Q_{n_i} \xrightarrow{S} \cdots \xrightarrow{P} n_i \xrightarrow{P} \cdots \xrightarrow{P} i \xrightarrow{P} \cdots$$

We have  $0 \in E^I$  and all other numbers are in  $D^I$ . Here is the more formal definition of our model  $I = (\mathbb{N}, \cdot^I, \omega)$ .

$$P^{I} = \{(i+1,i) \mid i \in \mathbb{N}\} \qquad \qquad R_{1}^{I} = \{(i,m_{i}) \mid i \in \mathbb{N}\} \qquad R_{2}^{I} = \{(i,n_{i}) \mid i \in \mathbb{N}\}$$

$$Q^{I} = \{(i,i) \mid i \in \mathbb{N}^{+}, Q = Q_{i}\} \qquad D^{I} = \{(i,i) \mid i \in \mathbb{N}^{+}\} \qquad E^{I} = \{(0,0)\}$$

$$S^{I} = \{(i,i+1) \mid i \in \mathbb{N}\} \qquad \text{false}^{I} = \bot$$

$$a^{I} = 1$$
  $a_{0}^{I} = 0$   $b_{0}^{I} = 0$ 

Since there are no free variables in  $\Gamma_M$  we can just set  $\omega(x) = 0$  for every  $x \in \mathcal{V}_P$ . It is easy to see that I is indeed a model of  $\Gamma_M$ .

Claim 21. Let  $C = \langle Q, m, n \rangle$  be a configuration of M. If a final configuration (i.e. a configuration  $\langle Q_f, m', n' \rangle$  for some  $n', m' \in \mathbb{N}$ ) is reachable from C then  $\Gamma_C \cup \Gamma_{\overline{M}} \vdash \mathbf{false}$ .

*Proof.* By induction on the length i of the computation.

Induction Base: i = 0

Since a final configuration is reachable in 0 steps C must be this final configuration. So  $C = \langle Q_f, m, n \rangle$  for some  $n, m \in \mathbb{N}$ . Hence,  $Q_f(a)$  is in  $\Gamma_C$  for some  $a \in \mathcal{V}_P$  and  $\forall \alpha (Q_f(\alpha) \to \mathbf{false})$  is in  $\Gamma_{\overline{M}}$ , we can easily deduce false.

$$\frac{\Gamma_C \cup \Gamma_{\overline{M}} \vdash \forall \alpha (Q_f(\alpha) \to \mathbf{false})}{\Gamma_C \cup \Gamma_{\overline{M}} \vdash Q_f(a) \to \mathbf{false}} \qquad \Gamma_C \cup \Gamma_{\overline{M}} \vdash Q_f(a)}{\Gamma_C \cup \Gamma_{\overline{M}} \vdash \mathbf{false}}$$

Induction Step: i = i' + 1

Since  $I \models \mathbf{false}$  holds trivially if I interprets  $\mathbf{false}$  with  $\top$  we only need to consider models of  $\Gamma_C \cup \Gamma_{\overline{M}}$  that interpret  $\mathbf{false}$  with  $\bot$  (note that there are no such models if M terminates which is exactly what we want to proof). As result of this observation we can use the  $\exists$ -Introduction rule.

From the fact that a final configuration is reachable from C in i steps we can deduce that there exists a configuration  $D = \langle \widehat{Q}, \widehat{m}, \widehat{n} \rangle$  such that  $C \Rightarrow_M^r D$  for some  $r \in \mathcal{R}_{\mathcal{Q}}$  and a final configuration is reachable from D in i' steps. We also know that  $C = \langle Q, m, n \rangle$  for some  $Q \in \mathcal{Q} \setminus \{Q_f\}$  and some  $m, n \in \mathbb{N}$ . The set  $\Gamma_C$  contains the formulas:

$$R_1(a, a_0), P(a_{i-1}, a_i) \text{ and } D(a_{i-1}) \text{ for } i \in \{1, \dots, n\},$$
  
 $R_2(a, b_0), P(b_{i-1}, b_i) \text{ and } D(b_{i-1}) \text{ for } i \in \{1, \dots, m\},$   
 $Q(a), D(a), E(a_n) \text{ and } E(b_m).$ 

And  $\Gamma_D$  contains the formulas:

$$R_1(\widehat{a}, \widehat{a}_0), P(\widehat{a}_{i-1}, \widehat{a}_i) \text{ and } D(\widehat{a}_{i-1}) \text{ for } i \in \{1, \dots, \widehat{n}\},$$
  
 $R_2(\widehat{a}, \widehat{b}_0), P(\widehat{b}_{i-1}, \widehat{b}_i) \text{ and } D(\widehat{b}_{i-1}) \text{ for } i \in \{1, \dots, \widehat{m}\},$   
 $Q(\widehat{a}), D(\widehat{a}), E(\widehat{a}_{\widehat{n}}) \text{ and } E(\widehat{b}_{\widehat{m}}).$ 

The basic idea is to deduce  $\Gamma_D$  from  $\Gamma_C \cup \Gamma_{\overline{M}}$  and then apply the induction hypothesis to  $\Gamma_D \cup \Gamma_{\overline{M}}$ .

$$\frac{\frac{IH}{\Gamma_C \cup \Gamma_{\overline{M}} \cup \Gamma_D \vdash_{\mathbf{f}} \mathbf{false}} \quad \Gamma_C \cup \Gamma_{\overline{M}} \vdash_{\mathbf{f}} \Gamma_D}{\Gamma_C \cup \Gamma_{\overline{M}} \vdash_{\mathbf{f}} \mathbf{false}}$$

We achieve this by looking at the four possible cases for the type of the rule r. We will only consider the cases r = +(1, Q') and  $r = -(1, Q_1, Q_2)$ , the two remaining cases r = +(2, Q') and  $r = -(2, Q_1, Q_2)$  follow by exchanging the roles of register 1 and register 2 in the first two cases.

First we need a new free variable representing the configuration D. Also the value in register 2 does not change, because in both cases we are only concerned with register 1. For the succeeding tableau proofs we will abbreviate **false** by **f** and we will drop  $\Gamma_C \cup \Gamma_{\overline{M}}$  and only write new formulas on the left side of  $\vdash_{\mathbf{f}}$ .

We first introduce a new variable representing D (let  $b \in \mathcal{V}_P \setminus \text{FV}(\Gamma_C \cup \Gamma_{\overline{M}})$ ).

Since register 2 should not change we need  $R_2(b, b_0)$ . Again we will just drop S(a, b) and D(b) on the left side for comprehensibility.

$$\underbrace{\frac{\vdash_{\mathbf{f}} \forall \alpha \beta \gamma (Q(\alpha) \rightarrow S(\alpha, \beta) \rightarrow R_2(\alpha, \gamma) \rightarrow R_2(\beta, \gamma))}{\vdash_{\mathbf{f}} Q(a) \rightarrow S(a, b) \rightarrow R_2(a, b_0) \rightarrow R_2(b, b_0)}_{\vdash_{\mathbf{f}} S(a, b) \rightarrow R_2(a, b_0) \rightarrow R_2(b, b_0)} \underbrace{\frac{\vdash_{\mathbf{f}} S(a, b) \rightarrow R_2(a, b_0) \rightarrow R_2(b, b_0)}{\vdash_{\mathbf{f}} R_2(a, b_0) \rightarrow R_2(b, b_0)}}_{\vdash_{\mathbf{f}} R_2(b, b_0)}$$

$$\underbrace{\frac{\vdash_{\mathbf{f}} R_2(b, b_0) \rightarrow \mathbf{f}}{\vdash_{\mathbf{f}} R_2(b, b_0)}}_{\vdash_{\mathbf{f}} R_2(b, b_0)}$$

For the case that r = +(1, Q'), we have that  $\widehat{Q} = Q'$ ,  $\widehat{m} = m + 1$ , and  $\widehat{n} = n$ . So we need to increment register 1 and ensure that the state of b is Q'.

$$\begin{array}{c} \vdots \\ \hline Q'(b) \vdash_{\mathbf{f}} \mathbf{f} \\ \hline \vdash_{\mathbf{f}} Q'(b) \to \mathbf{f} \end{array} \begin{array}{c} \vdash_{\mathbf{f}} \forall \alpha \beta (Q(\alpha) \to S(\alpha,\beta) \to Q'(\beta)) \\ \hline \vdash_{\mathbf{f}} Q(a) \to S(a,b) \to Q'(b) \\ \hline \vdash_{\mathbf{f}} S(a,b) \to Q'(b) \\ \hline \vdash_{\mathbf{f}} Q'(b) \end{array} \begin{array}{c} \vdash_{\mathbf{f}} S(a,b) \\ \hline \vdash_{\mathbf{f}} Q'(b) \\ \hline \vdash_{\mathbf{f}} \mathbf{f} \end{array}$$

To increment register 1 we need a new free variable as anchor for register 1 (let  $d \in \mathcal{V}_P \setminus \text{FV}(\Gamma_C \cup \Gamma_{\overline{M}})$  and  $d \neq b$ ).

$$\begin{array}{c} \vdots \\ \hline R_1(b,d) \vdash_{\mathbf{f}} \mathbf{f} \\ \hline \forall \beta(R_1(b,\beta) \to \mathbf{f}) \to \mathbf{f} \vdash_{\mathbf{f}} \mathbf{f} \\ \hline \vdash_{\mathbf{f}} (\forall \beta(R_1(b,\beta) \to \mathbf{f}) \to \mathbf{f}) \to \mathbf{f} \\ \hline \vdash_{\mathbf{f}} (\forall \beta(R_1(b,\beta) \to \mathbf{f}) \to \mathbf{f}) \\ \hline \\ \vdash_{\mathbf{f}} \mathbf{f} \end{array} \qquad \begin{array}{c} \vdash_{\mathbf{f}} \forall \alpha(D(\alpha) \to \forall \beta(R_1(\alpha,\beta) \to \mathbf{f}) \to \mathbf{f}) \\ \hline \vdash_{\mathbf{f}} D(b) \to \forall \beta(R_1(b,\beta) \to \mathbf{f}) \to \mathbf{f} \\ \hline \vdash_{\mathbf{f}} \mathbf{f} \\ \hline \\ \vdash_{\mathbf{f}} \mathbf{f} \end{array}$$

Now we need to connect d with  $a_0$  (the anchor of a for register 1).

$$\underbrace{ \begin{array}{c} \vdash_{\mathbf{f}} \forall \alpha \beta \gamma \delta(Q(\alpha) \rightarrow S(\alpha,\beta) \rightarrow R_1(\alpha,\gamma) \rightarrow R_1(\beta,\delta) \rightarrow P(\delta,\gamma)) \\ \hline \\ P(Q(a) \rightarrow S(a,b) \rightarrow R_1(a,a_0) \rightarrow R_1(b,d) \rightarrow Q'(b) & \vdash_{\mathbf{f}} Q(a) \\ \hline \vdots & \hline \\ P(d,a_0) \vdash_{\mathbf{f}} \mathbf{f} \\ \hline \vdash_{\mathbf{f}} P(d,a_0) \rightarrow \mathbf{f} & \underbrace{ \begin{array}{c} \vdash_{\mathbf{f}} R_1(a,a_0) \rightarrow R_1(b,d) \rightarrow Q'(b) & \vdash_{\mathbf{f}} R_1(a,a_0) \\ \hline \\ \vdash_{\mathbf{f}} R_1(b,d) \rightarrow Q'(b) & \vdash_{\mathbf{f}} R_1(a,a_0) \\ \hline \\ \vdash_{\mathbf{f}} P(d,a_0) & \hline \\ \vdash_{\mathbf{f}} P(d,a_0) & \hline \\ \hline \end{array} }$$

At last we have to make sure that we do not get an artificial zero by deducing D(d).

$$\underbrace{ \begin{array}{c} \vdash_{\mathbf{f}} \forall \alpha \beta \delta(Q(\alpha) \to S(\alpha,\beta) \to R_1(\beta,\delta) \to D(\delta)) \\ \vdots \\ \hline D(d) \vdash_{\mathbf{f}} \mathbf{f} \\ \hline \vdash_{\mathbf{f}} D(d) \to \mathbf{f} \end{array} }_{\vdash_{\mathbf{f}} D(d) \to \mathbf{f}} \underbrace{ \begin{array}{c} \vdash_{\mathbf{f}} Q(a) \to S(a,b) \to R_1(b,d) \to D(d) & \vdash_{\mathbf{f}} Q(a) \\ \hline \vdash_{\mathbf{f}} S(a,b) \to R_1(b,d) \to D(d) & \vdash_{\mathbf{f}} S(a,b) \\ \hline \vdash_{\mathbf{f}} R_1(b,d) \to D(d) & \vdash_{\mathbf{f}} R_1(b,d) \\ \hline \vdash_{\mathbf{f}} D(d) \\ \hline \\ \vdash_{\mathbf{f}} \mathbf{f} \end{array} }_{\vdash_{\mathbf{f}} \mathbf{f}}$$

Now we already have deduced  $\Gamma_D$ , to see why define  $\widehat{a} := b$ ,  $\widehat{b}_i := b_i$  for  $i \in \{0, \ldots, m\}$ ,  $\widehat{a}_0 := d$ , and  $\widehat{a}_{i+1} := a_i$  for  $i \in \{0, \ldots, n\}$ . Hence we can deduce **false** by induction hypothesis.

The other case, that  $r = -(Q, 1, Q_1, Q_2)$ , has to be split into two cases again. If m = 0 then  $\hat{Q} = Q_2$ ,  $\hat{m} = 0$ , and  $\hat{n} = n$ . We only need to ensure that the successor state is  $Q_2$  and that register 1 is still zero.

$$\begin{array}{c} \underbrace{ \begin{array}{c} \vdash_{\mathbf{f}} \forall \alpha \beta \gamma(Q(\alpha) \rightarrow S(\alpha,\beta) \rightarrow R_1(\alpha,\gamma) \rightarrow E(\gamma) \rightarrow Q_2(\beta)) \\ \hline \vdash_{\mathbf{f}} Q(a) \rightarrow S(a,b) \rightarrow R_1(a,a_0) \rightarrow E(a_0) \rightarrow Q_2(b) & \vdash_{\mathbf{f}} Q(a) \\ \hline \vdots & \underbrace{ \begin{array}{c} \vdash_{\mathbf{f}} S(a,b) \rightarrow R_1(a,a_0) \rightarrow E(a_0) \rightarrow Q_2(b) & \vdash_{\mathbf{f}} S(a,b) \\ \hline Q_2(b) \vdash_{\mathbf{f}} \mathbf{f} & \underbrace{ \begin{array}{c} \vdash_{\mathbf{f}} R_1(a,a_0) \rightarrow E(a_0) \rightarrow Q_2(b) & \vdash_{\mathbf{f}} R_1(a,a_0) \\ \hline \hline \vdash_{\mathbf{f}} Q_2(b) \rightarrow \mathbf{f} & \underbrace{ \begin{array}{c} \vdash_{\mathbf{f}} E(a_0) \rightarrow Q_2(b) & \vdash_{\mathbf{f}} E(a_0) \\ \hline \hline \vdash_{\mathbf{f}} Q_2(b) & \vdash_{\mathbf{f}} \mathbf{f} \end{array} } \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) \rightarrow F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \hline \hline \vdash_{\mathbf{f}} G(a_0) \rightarrow G(a_0) & \underbrace{ \begin{array}{c} \vdash_{\mathbf{f}} E(a_0) \rightarrow G(a_0) \\ \hline \hline \vdash_{\mathbf{f}} G(a_0) & \vdash_{\mathbf{f}} E(a_0) \\ \hline \hline \hline \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0) \\ \hline \end{array} }_{ \begin{array}{c} \vdash_{\mathbf{f}} F(a_0) & \vdash_{\mathbf{f}} F(a_0)$$

Register 1 stays zero.

$$\underbrace{ \begin{array}{c} \vdash_{\mathbf{f}} \forall \alpha \beta \gamma (Q(\alpha) \to S(\alpha,\beta) \to R_1(\alpha,\gamma) \to E(\gamma) \to R_1(\beta,\gamma)) \\ \vdash_{\mathbf{f}} Q(a) \to S(a,b) \to R_1(a,a_0) \to E(a_0) \to R_1(b,a_0) \\ \vdots \\ \hline \vdash_{\mathbf{f}} S(a,b) \to R_1(a,a_0) \to E(a_0) \to R_1(b,a_0) \\ \hline \vdash_{\mathbf{f}} R_1(b,a_0) \vdash_{\mathbf{f}} \mathbf{f} \\ \hline \vdash_{\mathbf{f}} R_1(b,a_0) \to \mathbf{f} \\ \hline \vdash_{\mathbf{f}} R_1(b,a_0) \\ \hline \vdash_{\mathbf{f}} \mathbf{f} \end{array} } \underbrace{ \begin{array}{c} \vdash_{\mathbf{f}} E(a_0) \to R_1(b,a_0) \\ \hline \vdash_{\mathbf{f}} E(a_0) \to R_1(b,a_0) \\ \hline \vdash_{\mathbf{f}} R_1(b,a_0) \\ \hline \vdash_{\mathbf{f}} \mathbf{f} \end{array} }_{\vdash_{\mathbf{f}} R_1(b,a_0)}$$

If we define  $\widehat{a} := b$ ,  $\widehat{b}_i := b_i$  for  $i \in \{0, ..., m\}$ , and  $\widehat{a}_0 := a_0$  then it is clear that we have deduced all formulas required for  $\Gamma_D$ . So we can use the induction hypothesis to deduce **false**.

In the last case m > 0, so  $\widehat{Q} = Q_1$ ,  $\widehat{m} = m - 1$ , and  $\widehat{n} = n$ . First we ensure that b is in state  $Q_1$ .

$$\frac{ \begin{array}{c} \vdash_{\mathbf{f}} \forall \alpha \beta \gamma(Q(\alpha) \to S(\alpha,\beta) \to R_1(\alpha,\gamma) \to D(\gamma) \to Q_1(\beta)) \\ \hline \vdash_{\mathbf{f}} Q(a) \to S(a,b) \to R_1(a,a_0) \to D(a_0) \to Q_1(b) & \vdash_{\mathbf{f}} Q(a) \\ \hline \vdots & \frac{\vdash_{\mathbf{f}} S(a,b) \to R_1(a,a_0) \to D(a_0) \to Q_1(b) & \vdash_{\mathbf{f}} S(a,b) \\ \hline Q_1(b) \vdash_{\mathbf{f}} \mathbf{f} & \frac{\vdash_{\mathbf{f}} R_1(a,a_0) \to D(a_0) \to Q_1(b) & \vdash_{\mathbf{f}} R_1(a,a_0) \\ \hline \vdash_{\mathbf{f}} Q_1(b) \to \mathbf{f} & \frac{\vdash_{\mathbf{f}} D(a_0) \to Q_1(b) & \vdash_{\mathbf{f}} D(a_0) \\ \hline \vdash_{\mathbf{f}} Q_1(b) & \vdash_{\mathbf{f}} \mathbf{f} \end{array}$$

Now we decrement register 1 by taking  $a_1$  (the predecessor of  $a_0$ ) as anchor of b for register 1.

$$\begin{array}{c|c} \vdash_{\mathbf{f}} \forall \alpha \beta \gamma \delta(Q(\alpha) \rightarrow S(\alpha,\beta) \rightarrow R_1(\alpha,\gamma) \rightarrow D(\gamma) \rightarrow P(\gamma,\delta) \rightarrow R_1(\beta,\delta)) \\ \hline \vdash_{\mathbf{f}} Q(a) \rightarrow S(a,b) \rightarrow R_1(a,a_0) \rightarrow D(a_0) \rightarrow P(a_0,a_1) \rightarrow R_1(b,a_1) & \vdash_{\mathbf{f}} Q(a) \\ \hline & \underbrace{\vdash_{\mathbf{f}} S(a,b) \rightarrow R_1(a,a_0) \rightarrow D(a_0) \rightarrow P(a_0,a_1) \rightarrow R_1(b,a_1) & \vdash_{\mathbf{f}} S(a,b)}_{\vdash_{\mathbf{f}} R_1(a,a_0) \rightarrow D(a_0) \rightarrow P(a_0,a_1) \rightarrow R_1(b,a_1) & \vdash_{\mathbf{f}} R_1(a,a_0) \\ \hline \vdots & \underbrace{\vdash_{\mathbf{f}} R_1(b,a_0) \rightarrow D(a_0) \rightarrow P(a_0,a_1) \rightarrow R_1(b,a_1) & \vdash_{\mathbf{f}} D(a_0)}_{\vdash_{\mathbf{f}} R_1(b,a_1) \rightarrow \mathbf{f}} & \underbrace{\vdash_{\mathbf{f}} P(a_0,a_1) \rightarrow R_1(b,a_1) & \vdash_{\mathbf{f}} P(a_0,a_1)}_{\vdash_{\mathbf{f}} R_1(b,a_1)} \\ \hline \vdash_{\mathbf{f}} \mathbf{f} & \underbrace{\vdash_{\mathbf{f}} R_1(b,a_1) \rightarrow R_1(b,a_1) & \vdash_{\mathbf{f}} P(a_0,a_1)}_{\vdash_{\mathbf{f}} R_1(b,a_1)} \\ \hline \end{array}$$

Again it is obvious that we have deduced  $\Gamma_D$  ( $\widehat{a} := b$ ,  $\widehat{b}_i := b_i$  for  $i \in \{0, \dots, m\}$ , and  $\widehat{a}_{i-1} := a_i$  for  $i \in \{1, \dots, n\}$ ). Hence, by induction hypothesis, we can deduce **false**.  $\square$ 

### Lemma 22.

M terminates on input (0,0) iff  $\Gamma_M \vdash \mathbf{false}$  holds in system P.

*Proof.* The  $\Leftarrow$  directions is proven in Claim 20. And the  $\Rightarrow$  direction is a direct consequence of Claim 21 with  $C = \langle Q_0, 0, 0 \rangle$ .

### Theorem 23. CONS is undecidable.

*Proof.* Since by Lemma 22 for a given two-counter automaton M we can effectively construct a set of **P**-formulas  $\Gamma_M$  such that M terminates on input (0,0) iff  $\Gamma_M$  is not consistent. It follows that  $\mathbf{HALT} \leq \mathbf{CONS}$ . Since  $\mathbf{HALT}$  is undecidable we have shown that  $\mathbf{CONS}$  is undecidable too.