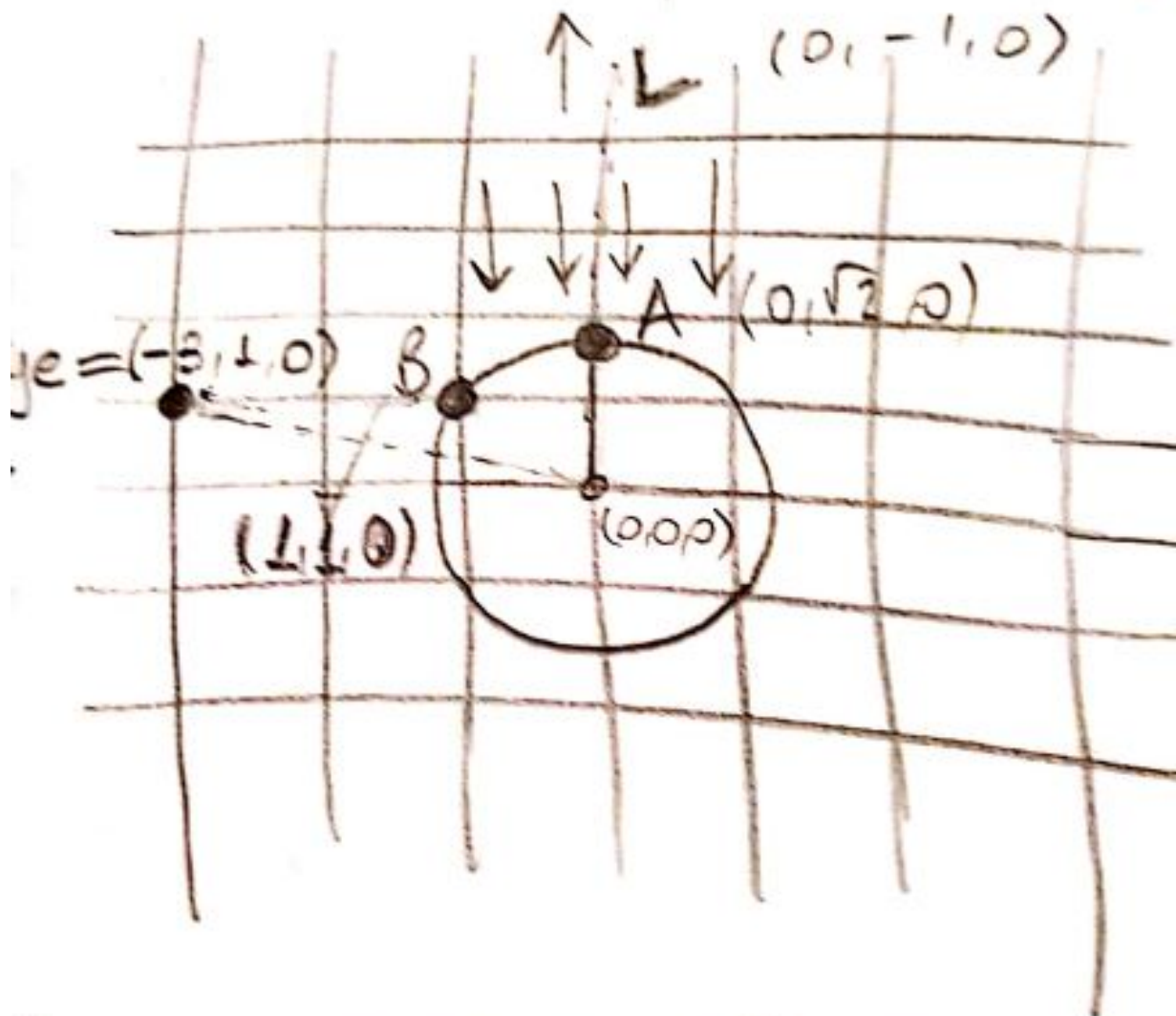


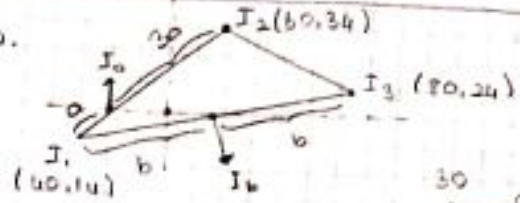
19/ The scene below shows a sphere.  
There is only a directional  
direction  $(0, -1, 0)$  as s



$$I_{L, \text{spec}} = k_s I_L \underbrace{(V \cdot R)}_{\cos \phi}^n, \text{ if } V \cdot R > 0 \text{ and } N \cdot L$$

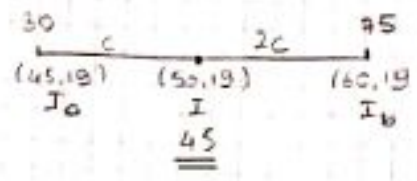
$$L = (0, -1, 0) \quad N = (0, 1, 0)$$

Q6. a.



$$I_0 = (45, 19)$$

$$I_1 = (60, 19)$$



$$I_0 = \frac{1}{4} \cdot 40 + \frac{3}{4} \cdot 10$$

$$= 30$$

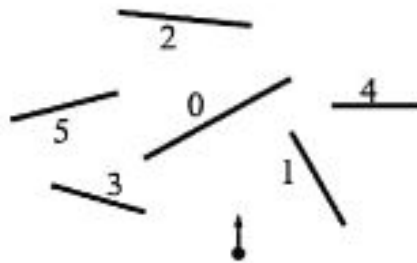
$$I_1 = \frac{1}{2} \cdot 100 + \frac{1}{2} \cdot 10$$

$$= 75$$

b. A Phong shader assumes the same input as Gouraud shading which means that it expects a normal for every vertex.

Q10. What is a-z-buffer? How can we handle transparent object in a scene and anti-aliasing by using a-z-buffer?

- An anti-aliasing, z-buffer, visibility detection method.
- Accumulation buffer
  - stores a variety of surface data in addition to depth values
  - allows a pixel color to be computed as a combination of different surface colors for transparency and anti-aliasing effects
- At each pixel, maintain a list of polygons sorted by depth.
- Algorithm: write-drawing a pixel (first pass):
  - If polygon is opaque and covers pixel, insert into list, removing all polygons further away.
  - If polygon is transparent or only partially covers pixel, insert into list, but don't remove further polygons.
- Algorithm: Rendering pass (At each pixel, traverse buffer using polygon colors and coverage masks to calculate composite pixel color)
- Advantage: can do more than z-buffer (anti-aliasing, transparent surfaces without ordering)
- Disadvantage: not implemented in hardware and software imp. is slow over rendering, depth quantization problems.



Q6 Consider a triangle in the image plane. The intensities  $I(x,y)$  at the three vertices are

$$I_1 = I(40, 14) = 10$$

$$I_2 = I(60, 34) = 90$$

$$I_3 = I(80, 24) = 140$$

(a) Using Gouraud shading, calculate the intensity at the point  $(50,19)$ , i.e.  $I(50, 19)$ .

(b) Describe how you could modify your method in order to calculate the intensities using Phong shading?

Q7 The top part of the diagram below represents the cross section of a surface, with light source and viewing position. On the graph template below it sketch the ambient, diffuse, and specular illumination as functions of  $x$ . Assume the Phong illumination model, i.e.

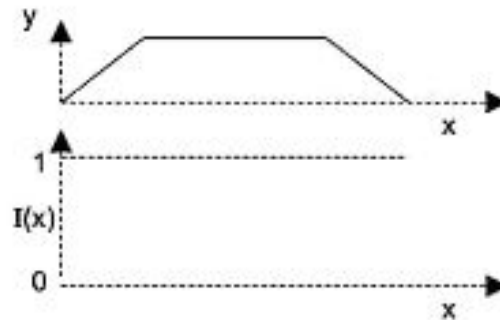
$$I = k_a I_a + k_d I_d(N.L) + k_s I_s(R.V)^n,$$

where  $k_a = 0.2$ ,  $k_d = 0.6$ ,  $k_s = 0.6$ ,  $I_a = I_d = I_s = 1.0$ ,  $n = 300$ .

eye



light



Q8. a) Given the following function call to `gluPerspective`:

`gluPerspective(60.0,0.8,4.0,100);`

where the first parameter is the viewing angle, the second parameter is the aspect ratio of the clipping window (width/height), the third parameter is the distance of the near plane to the viewing origin, and the fourth parameter is the distance of the far plane to the viewing origin. Find the `glFrustum` parameters:

`glFrustum(xwmin, xwmax, ywmin, ywmax, dnear, dfar)`

c) How can we obtain an oblique perspective projection using `glFrustum` function?

Q9. Briefly explain how we apply ray casting algorithm to calculate the volume of an object in the scene? Assume the rays are parallel to  $z$  axis and a pixel has a unit area  $A_{\text{p}}$ .

Q10. What is a-buffer? How can we handle transparent objects in a scene and antialiasing by using a-buffer?



- "Plot Storing"
- "Constant Intensity"
- No "interpolation"
- Apply calculate

### Sayfa 1

Q3.  $I = k_0 I_0 + I_L k_d (L.N) + I_L k_s (R.V)^3$

$R = 2(L.N)N - L / L = (0.07, 0.7)$

$\sqrt{k_0 \cdot I_0} = 0.05$

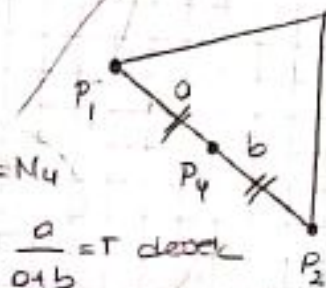
$V = (0, 0, 1)$

$\sqrt{I_L k_d} = 0.3$

$\sqrt{I_L k_s} = 0.12$

$\frac{a}{a+b} N_2 + \frac{b}{a+b} N_1 = N_u$

$1 - \frac{a}{a+b} = \frac{a}{a+b} = \tau$  devesek



$N_1 = (0, 1, 0)$  ve  $N_2 = (0, 0, 1)$   $N_u = \frac{N_1 + N_2}{2}$

$\frac{N_u}{|N_u|}$

$|N_u| = \sqrt{(0.5)^2 + (0.5)^2} = \sqrt{0.5}$

birim vektör değeri.

birim normal vektör

$N = (0, \sqrt{0.5}, \sqrt{0.5})$

NOTE: vektör çarpımı  
 $x_1 x_2 + y_1 y_2 + z_1 z_2$

$R = 2(L.N)N - L$

$= 2(L.N) \cdot (0, \sqrt{0.5}, \sqrt{0.5}) - (0, 0.7, 0.7)$   
 $= 2(0 \times 0 + \sqrt{0.5} \times 0.7 + \sqrt{0.5} \times 0.7)(0, \sqrt{0.5}, \sqrt{0.5}) - (0, 0.7, 0.7)$   
 $= 2.8 \times \sqrt{0.5} (0, \sqrt{0.5}, \sqrt{0.5}) - (0, 0.7, 0.7)$   
 $= (0, 1.4, 1.4) - (0, 0.7, 0.7)$   
 $= (0, 0.7, 0.7)$

$R.V = 0.7$  /  $L.N = 2.8 \times \sqrt{0.5}$

$I = 0.05 + 0.3 \times 1.4 \times \sqrt{0.5} + 0.12 \times 0.7$

$I = k_0 I_0 + I_L k_d (L.N) + I_L k_s (R.V)^3$

**Q1.** Suppose a perspective projection is given by  $glFrustum(-5, 5, -5, 5, 5, 25)$ .

- Sketch the frustum in 3D.
- If eye position is at  $P(0, 0, 0)$ , what is the coordinates of the point  $P_{proj}(3, 3, 7)$  on the projection plane.

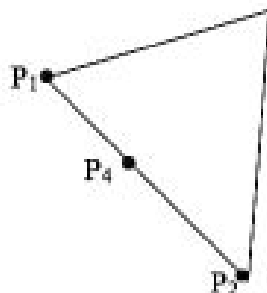
**Q2.** Two Bezier curves are given with control point  $p_0, p_1, p_2, p_3$  and  $q_0, q_1, q_2, q_3$ . What conditions should be met to join these two curves to have a circular closed curve? Sketch the final curve and show the control points.

**Q3.** The coordinate values of the points in the following figure are given as  $P_1=(1,2)$ ,  $P_2=(5,0)$ ,  $P_4=(3,1)$  and the normal vectors on the points  $P_1$  and  $P_2$  are given as  $N_1=(0,1,0)$  and  $N_2=(0,0,1)$ , respectively.

The other parameters are given as follows:

$V=(0,0,1)$ ,  $L=(0,0.7,0.7)$ ,  $I_L=0.6$ ,  $K_d=0.1$ ,  $I_d=0.5$ ,  $K_d=0.5$ ,  $K_s=0.2$ ,  $n_s=1$ .

Find the illumination intensity at the point  $P_4$  using Phong shading model.



**Q4** Work out how to represent the following object using constructive solid geometry (CSG). You may assume the following primitives whose parameters can be set: sphere, cylinder, cone, torus, box (cuboid). Describe your construction method, detailing the operations on the primitives: Draw a labelled binary tree to illustrate the processing of the primitives (leaf nodes) to create the final object (root node)



- Q5**
- Construct the binary space partition tree for the line segments shown below, adding the objects to your tree in numerical order.  
Note: Use the convention that the number identifier is on the front of the line segment, and segments to the front side of a segment will be represented by the right sub-tree of the corresponding node in the BSP tree.
  - Show the traversal order of the BSP tree given the eye point shown with a dot and arrow in the picture. Show intermediate stages of computation of the traversal.



## Flat Shading

- "Constant Intensity"
- No interpolation
- Applies only one illumination calculation for each primitive

## Drawback

- the direction to the light
- the direction to

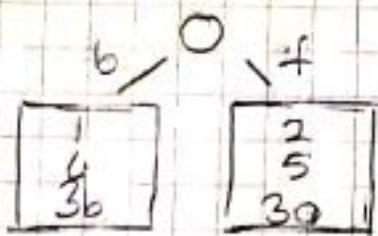
Advan

Q5

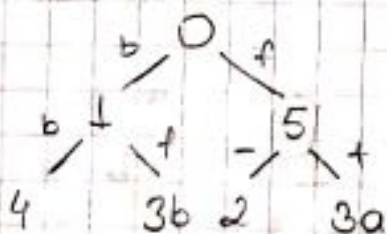
(a) Construct the binary space partition tree for the line segments shown below.

Note: Use the convention that the number identifier is on the front of the line segment. and segments to the front side of a segment will be processed by the right sub-tree of the corresponding node in the BSP tree.

(b) Show the traversal order of the BSP tree given the point shown with a dot and arrow in the picture. Show intermediate stages of construction of the traversal.



3' ü paraboloidik.



- ✓ eye is front of the root "back, root, front"
- ✓ eye is back of the root "front, root, back"

b) (1, 4, 3b), 0, (5, 2, 3a)

(3b, 1, 4), 0, (3a, 5, 2)

3. Briefly explain how we apply ray casting algo to calculate the volume of an object in the scene?

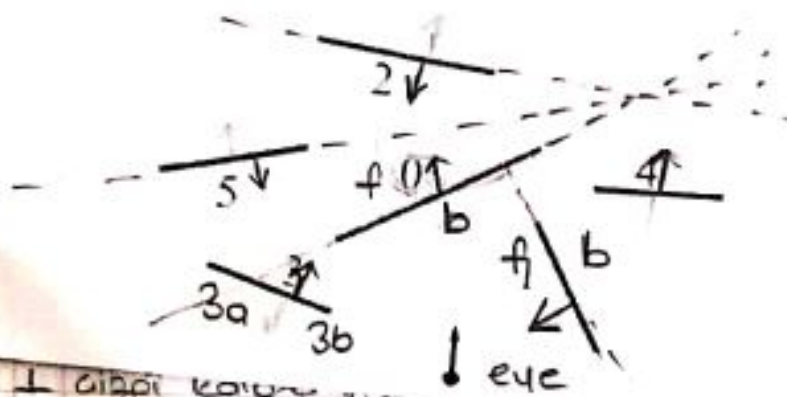
Assume that rays are parallel to  $z$  axis and a pixel has a unit area

- Shading
- "Constant Intensity"
  - No Interpolation
  - Applies only one Illumination calculation for each primitive

- Drawback
- the direction to the light
  - the direction to the eye

Advantage

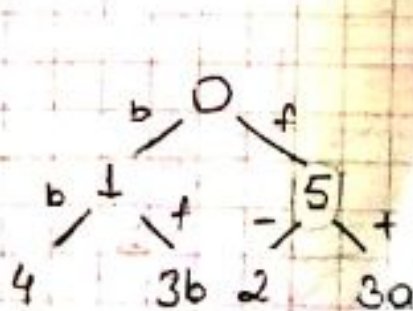
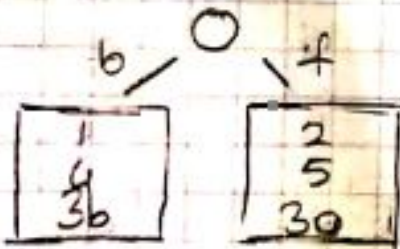
Sayılar önde  
yazılıyor.



Her noktada 1 algı kazanır

Oyun old. taraf front ve öğe ta sağda yer alır

3'ü parçaladık.



- ✓ eye is front of the root "back, r"
- ✓ eye is back of the root "front, r"

b) (1, 4, 3b), 0, (5, 2, 3a)

(3b, 1, 4), 0, (3a, 5, 2)

Q9. Briefly explain how we apply ray casting algo to calculate the vol of an object in the scene?



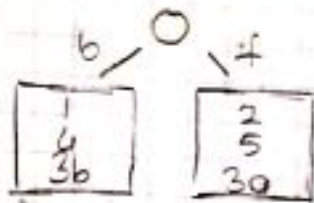
## 25. BSP Tree

Nesneleri ortalamak için doğru numaralandır.

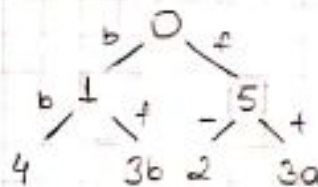
Kayfı bir ağız seç.

Her adımda 1 ağız koluna kadar kömeye devam et.

Odanın diğer tarafı front ve arka doğru sağda yer alır



3'ü parçaladık



- ✓ eye is front of the root "back, root, front"
- ✓ eye is back of the root "front, root, back"

b) (1, 4, 3b), 0, (5, 2, 3a)

(3b, 1, 4), 0, (3a, 5, 2)

Q9. Briefly explain how we apply ray casting algo to calculate the volume of an object in the scene?

Assume that rays are parallel to  $z$  axis and a pixel has a unit area. App

$$x = x_0 + t \Delta x \quad \checkmark \text{ For Sphere ;}$$

$$y = y_0 + t \Delta y \quad (x-a)^2 + (y-b)^2 + (z-c)^2 = r^2$$

$$z = z_0 + t \Delta z \quad \checkmark \text{ Eğer denklemin kökü varsa raylar birbirine paralel}$$

Algorithm: Cast ray from viewpoint through each pixel to find front-most surface.



## Flat Shading

5. Pyramid shape on screen. Each face of the different color.

function triangle (a, b, c, color) {

```

    var baseColors = [
        vec3(1.0, 0.0, 0.0),
        vec3(0.0, 1.0, 0.0),
        vec3(0.0, 0.0, 1.0),
        vec3(0.0, 0.0, 0.0)
    ],

```

1,

```

    colors.push(baseColors[colors]);
    points.push(a);
    colors.push(baseColors[colors]);
    points.push(b);
    colors.push(baseColors[colors]);
    points.push(c);
}
function tetra (a, b, c, d) {
    triangle(a, c, b, 0);
    triangle(a, c, d, 1);
    triangle(a, b, d, 2);
    triangle(b, d, c, 3);
}

```

function tetra (a, b, c, d) {

```

    triangle(a, c, b, 0);
    triangle(a, c, d, 1);
    triangle(a, b, d, 2);
    triangle(b, d, c, 3);
}

```

1. What is a Z-buffer and what is it used for? ✓ It cannot handle visibility when an object occludes another object. For this, need to enable z-b.

◆ An image-space algorithm

◆ For each pixel, we want to draw the closest object projecting to that pixel. But, the objects are processed in any order

◆ So, for each pixel, we keep the distance of the currently drawn object

For all pixels, this information called DEPTH-TEST or Z-buffer.

2. How does it work?

1. Initialize Z-buffer with a max value corresponding to far plane

2. For each fragment, compute its depth with the current value in Z-buffer

- If greater, ignore.

- otherwise, use it to set the color in color buffer and update the value in Z-buffer

3. Advantages and Disadvantages

✓ Computing the required depth values is simple

✓ Over-rendering

✓ Depth quantization errors can be avoided

✓ Can't easily do transparency or filtering.

- for anti-aliasing

4. Can you name another method for the same problem? Compare it.

A-buffer (Accumulation buffer)

- stores a variety of surface info, in addition to depth values

- allows a pixel color to be computed as a combination of different surface colors for transparency and anti-aliasing.

A-buffer

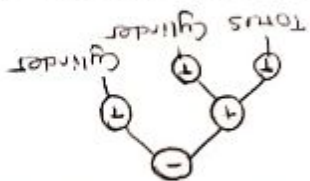
• Can do more than Z-buffer  
anti-aliasing transparent surfaces without ordering

• Coverage mask idea can be used in other visibility algorithms

• Still at heart a Z-buffer: over-rendering and depth quantization problems.



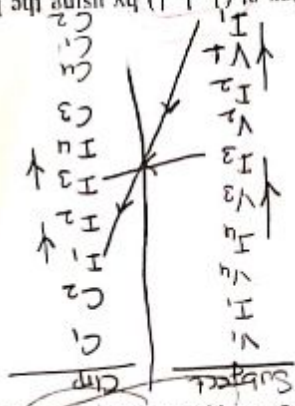
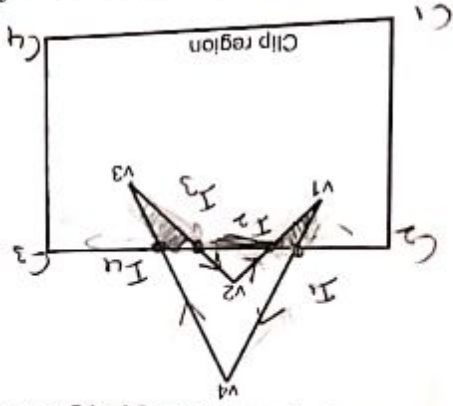
primitives such as a sphere, cylinder, cone, torus, box (cube). Describe your construction with details of the operations on the primitives. Draw a labeled binary tree to illustrate the processing of the primitives (leaf nodes) to create the final object (root node).



Q2. [17] A line is given with endpoints (2,3) and (8,7). Determine the pixels for drawing this line using Bresenham's algorithm. Show your decision parameter at each step clearly.

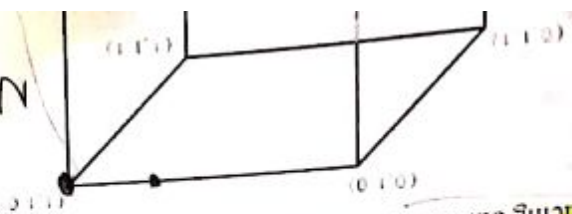
Q3. [17] Calculate and write the transformation matrix for rotating the ABCD parallelogram with vertices A(1,2), B(4,5), C(5,8), D(2,5) 45° counter-clockwise.

Q4. [16] For following polygon in the clip region, apply Weiler-Atherton polygon clipping algorithm.



Sutherland  
Hodgman

Q5. [17] Calculate the intensity of the vertex at (1, 1, 1) by using the basic (Phong) illumination model.  $V=(0,0,1)$ ,  $I_L=0.8$ ,  $K_d=0.1$ ,  $K_s=0.5$ ,  $K_r=0.2$ ,  $p_s=1$ ,  $p_r=0.5$ ,  $L=(0.71,0.0,0.71)$ . Assume that all the normals of the cube's sides are facing outwards, i.e., away from the cube.



$$R = 2(L \cdot N) \bar{N} - L$$

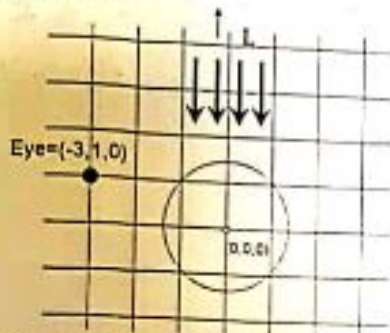
$$N = \frac{|P|}{|P|}$$

Student ID:

Name Surname:

20 points for each question

Q1. The scene below shows a sphere of radius  $\sqrt{2}$  centred at the origin. There is only a directional light in the scene towards the direction  $(0, -1, 0)$  as shown. The eye location is at  $(-3, 1, 0)$ .



(i) At what point (coordinates) on the sphere will we get maximal specular reflection? Explain your answer.

(ii) At what point (coordinates) on the sphere will we get maximal diffuse reflection? Explain your answer.

Q2. We discussed three surface rendering methods in the course. These were flat shading, Gouraud shading, and Phong shading. Explain these methods briefly and state their advantages and disadvantages.

Q3. Write an OpenGL program to display a solid pyramid object on screen using perspective projection. Each face of the pyramid should be a different color. Your program output should be similar to the image below (but in color).



Q4. Calculate 3 different points that will be on the Bezier curve created using control points  $p_1=(1,4)$ ,  $p_2=(3,7)$ ,  $p_3=(11,5)$ , and  $p_4=(7,1)$ .

Q5. We have two triangles: one with vertices  $P_1=(2,1,-1)$ ,  $P_2=(4,2,-1)$ , and  $P_3=(3,3,-2)$ ; and the other with  $Q_1=(2,4,-1)$ ,  $Q_2=(3,4,-3)$ , and  $Q_3=(4,5,-2)$ . Determine an order between these polygons using Depth-sort algorithm. Explain your steps and final decision clearly.