



Red Hat Enterprise Linux 8

Configuring basic system settings

Set up the essential functions of your system and customize your system environment

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Abstract

Perform basic system administration tasks, configure the environment settings, register your system, and configure network access and system security. Administer users, groups, and file permissions. Use system roles for managing system configurations interface on multiple RHEL systems. Use systemd for efficient service management. Configure the Network Time Protocol (NTP) with chrony. Backup and restore your system using ReaR. Install and use dynamic programming languages such as Python 3 and PHP.

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CHAPTER 1. CONFIGURING AND MANAGING BASIC NETWORK ACCESS

NetworkManager creates a connection profile for each Ethernet adapter that is installed in a host. By default, this profile uses DHCP for both IPv4 and IPv6 connections. Modify this automatically-created profile or add a new one in the following cases:

- The network requires custom settings, such as a static IP address configuration.
- You require multiple profiles because the host roams among different networks.

Red Hat Enterprise Linux provides administrators different options to configure Ethernet connections. For example:

- Use `nmcli` to configure connections on the command line.
- Use `nmtui` to configure connections in a text-based user interface.
- Use the GNOME Settings menu or `nm-connection-editor` application to configure connections in a graphical interface.
- Use `nmstatectl` to configure connections through the Nmstate API.
- Use RHEL system roles to automate the configuration of connections on one or multiple hosts.

1.1. CONFIGURING THE NETWORK AND HOST NAME IN THE GRAPHICAL INSTALLATION MODE

Follow the steps in this procedure to configure your network and host name.

Procedure

1. From the **Installation Summary** window, click **Network and Host Name**.
2. From the list in the left-hand pane, select an interface. The details are displayed in the right-hand pane.
3. Toggle the **ON/OFF** switch to enable or disable the selected interface.
You cannot add or remove interfaces manually.
4. Click **+** to add a virtual network interface, which can be either: Team, Bond, Bridge, or VLAN.
5. Click **-** to remove a virtual interface.
6. Click **Configure** to change settings such as IP addresses, DNS servers, or routing configuration for an existing interface (both virtual and physical).
7. Type a host name for your system in the **Host Name** field.
The host name can either be a fully qualified domain name (FQDN) in the format **hostname.domainname**, or a short host name without the domain. Many networks have a Dynamic Host Configuration Protocol (DHCP) service that automatically supplies connected systems with a domain name. To allow the DHCP service to assign the domain name to this system, specify only the short host name.

Host names can only contain alphanumeric characters and `-` or `..`. Host name should be equal to

or less than 64 characters. Host names cannot start or end with `-` and `..`. To be compliant with DNS, each part of a FQDN should be equal to or less than 63 characters and the FQDN total length, including dots, should not exceed 255 characters.

The value **localhost** means that no specific static host name for the target system is configured, and the actual host name of the installed system is configured during the processing of the network configuration, for example, by NetworkManager using DHCP or DNS.

When using static IP and host name configuration, it depends on the planned system use case whether to use a short name or FQDN. Red Hat Identity Management configures FQDN during provisioning but some 3rd party software products may require a short name. In either case, to ensure availability of both forms in all situations, add an entry for the host in `/etc/hosts` in the format **IP FQDN short-alias**.

8. Click **Apply** to apply the host name to the installer environment.
9. Alternatively, in the **Network and Hostname** window, you can choose the Wireless option. Click **Select network** in the right-hand pane to select your wifi connection, enter the password if required, and click **Done**.

Additional resources

- [Automatically installing RHEL](#)
- For more information about network device naming standards, see [Configuring and managing networking](#).

1.2. CONFIGURING AN ETHERNET CONNECTION BY USING **nmcli**

If you connect a host to the network over Ethernet, you can manage the connection's settings on the command line by using the **nmcli** utility.

Prerequisites

- A physical or virtual Ethernet Network Interface Controller (NIC) exists in the server's configuration.

Procedure

1. List the NetworkManager connection profiles:

```
# nmcli connection show
NAME                UUID                                TYPE    DEVICE
Wired connection 1  a5eb6490-cc20-3668-81f8-0314a27f3f75  ethernet  enp1s0
```

By default, NetworkManager creates a profile for each NIC in the host. If you plan to connect this NIC only to a specific network, adapt the automatically-created profile. If you plan to connect this NIC to networks with different settings, create individual profiles for each network.

2. If you want to create an additional connection profile, enter:

```
# nmcli connection add con-name <connection-name> ifname <device-name> type
ethernet
```

Skip this step to modify an existing profile.

- Optional: Rename the connection profile:

```
# nmcli connection modify "Wired connection 1" connection.id "Internal-LAN"
```

On hosts with multiple profiles, a meaningful name makes it easier to identify the purpose of a profile.

- Display the current settings of the connection profile:

```
# nmcli connection show Internal-LAN
...
connection.interface-name: enp1s0
connection.autoconnect:   yes
ipv4.method:              auto
ipv6.method:              auto
...
```

- Configure the IPv4 settings:

- To use DHCP, enter:

```
# nmcli connection modify Internal-LAN ipv4.method auto
```

Skip this step if **ipv4.method** is already set to **auto** (default).

- To set a static IPv4 address, network mask, default gateway, DNS servers, and search domain, enter:

```
# nmcli connection modify Internal-LAN ipv4.method manual ipv4.addresses
192.0.2.1/24 ipv4.gateway 192.0.2.254 ipv4.dns 192.0.2.200 ipv4.dns-search
example.com
```

- Configure the IPv6 settings:

- To use stateless address autoconfiguration (SLAAC), enter:

```
# nmcli connection modify Internal-LAN ipv6.method auto
```

Skip this step if **ipv6.method** is already set to **auto** (default).

- To set a static IPv6 address, network mask, default gateway, DNS servers, and search domain, enter:

```
# nmcli connection modify Internal-LAN ipv6.method manual ipv6.addresses
2001:db8:1::fffe/64 ipv6.gateway 2001:db8:1::fffe ipv6.dns 2001:db8:1::ffbb
ipv6.dns-search example.com
```

- To customize other settings in the profile, use the following command:

```
# nmcli connection modify <connection-name> <setting> <value>
```

Enclose values with spaces or semicolons in quotes.

- Activate the profile:

-

nmcli connection up Internal-LAN

Verification

1. Display the IP settings of the NIC:

```
# ip address show enp1s0
2: enp1s0: <BROADCAST,MULTICAST,UP,LOWER_UP> mtu 1500 qdisc fq_codel state UP
group default qlen 1000
    link/ether 52:54:00:17:b8:b6 brd ff:ff:ff:ff:ff:ff
    inet 192.0.2.1/24 brd 192.0.2.255 scope global noprefixroute enp1s0
        valid_lft forever preferred_lft forever
    inet6 2001:db8:1::fffe/64 scope global noprefixroute
        valid_lft forever preferred_lft forever
```

2. Display the IPv4 default gateway:

```
# ip route show default
default via 192.0.2.254 dev enp1s0 proto static metric 102
```

3. Display the IPv6 default gateway:

```
# ip -6 route show default
default via 2001:db8:1::fffe dev enp1s0 proto static metric 102 pref medium
```

4. Display the DNS settings:

```
# cat /etc/resolv.conf
search example.com
nameserver 192.0.2.200
nameserver 2001:db8:1::ffbb
```

If multiple connection profiles are active at the same time, the order of **nameserver** entries depend on the DNS priority values in these profiles and the connection types.

5. Use the **ping** utility to verify that this host can send packets to other hosts:

```
# ping <host-name-or-IP-address>
```

Troubleshooting

- Verify that the network cable is plugged-in to the host and a switch.
- Check whether the link failure exists only on this host or also on other hosts connected to the same switch.
- Verify that the network cable and the network interface are working as expected. Perform hardware diagnosis steps and replace defective cables and network interface cards.
- If the configuration on the disk does not match the configuration on the device, starting or restarting NetworkManager creates an in-memory connection that reflects the configuration of the device. For further details and how to avoid this problem, see the Red Hat Knowledgebase solution [NetworkManager duplicates a connection after restart of NetworkManager service](#) .

Additional resources

- **nm-settings(5)** man page on your system

1.3. CONFIGURING AN ETHERNET CONNECTION BY USING **NMTUI**

If you connect a host to the network over Ethernet, you can manage the connection's settings in a text-based user interface by using the **nmtui** application. Use **nmtui** to create new profiles and to update existing ones on a host without a graphical interface.



NOTE

In **nmtui**:

- Navigate by using the cursor keys.
- Press a button by selecting it and hitting **Enter**.
- Select and clear checkboxes by using **Space**.
- To return to the previous screen, use **ESC**.

Prerequisites

- A physical or virtual Ethernet Network Interface Controller (NIC) exists in the server's configuration.

Procedure

1. If you do not know the network device name you want to use in the connection, display the available devices:

```
# nmcli device status
DEVICE  TYPE    STATE      CONNECTION
enp1s0  ethernet unavailable --
...
```

2. Start **nmtui**:

```
# nmtui
```

3. Select **Edit a connection**, and press **Enter**.
4. Choose whether to add a new connection profile or to modify an existing one:
 - To create a new profile:
 - i. Press **Add**.
 - ii. Select **Ethernet** from the list of network types, and press **Enter**.
 - To modify an existing profile, select the profile from the list, and press **Enter**.
5. Optional: Update the name of the connection profile.

On hosts with multiple profiles, a meaningful name makes it easier to identify the purpose of a profile.

6. If you create a new connection profile, enter the network device name into the **Device** field.
7. Depending on your environment, configure the IP address settings in the **IPv4 configuration** and **IPv6 configuration** areas accordingly. For this, press the button next to these areas, and select:
 - **Disabled**, if this connection does not require an IP address.
 - **Automatic**, if a DHCP server dynamically assigns an IP address to this NIC.
 - **Manual**, if the network requires static IP address settings. In this case, you must fill further fields:
 - i. Press **Show** next to the protocol you want to configure to display additional fields.
 - ii. Press **Add** next to **Addresses**, and enter the IP address and the subnet mask in Classless Inter-Domain Routing (CIDR) format.
If you do not specify a subnet mask, NetworkManager sets a **/32** subnet mask for IPv4 addresses and **/64** for IPv6 addresses.
 - iii. Enter the address of the default gateway.
 - iv. Press **Add** next to **DNS servers**, and enter the DNS server address.
 - v. Press **Add** next to **Search domains**, and enter the DNS search domain.

Figure 1.1. Example of an Ethernet connection with static IP address settings

The screenshot shows the 'Edit Connection' window in the nmtui application. The window title is 'Edit Connection'. It displays the configuration for a connection named 'Example-Connection' on the device 'enp7s0'. The connection type is 'ETHERNET'. The IPv4 configuration is set to 'Manual' with the following settings: Address '192.0.2.1/24', Gateway '192.0.2.254', DNS servers '192.0.2.200', and Search domains 'example.com'. The IPv6 configuration is also set to 'Manual' with Address '2001:db8:1::1/64', Gateway '2001:db8:1::fffe', DNS servers '2001:db8:1::ffbb', and Search domains 'example.com'. Both IPv4 and IPv6 sections include routing options: 'Never use this network for default route', 'Ignore automatically obtained routes', 'Ignore automatically obtained DNS parameters', and 'Require IPv4/IPv6 addressing for this connection'. At the bottom, there are checkboxes for 'Automatically connect' and 'Available to all users', both of which are checked. The window has '<Cancel>' and '<OK>' buttons at the bottom right.

Profile name: Example-Connection
Device: enp7s0

= ETHERNET <Show>

= IPv4 CONFIGURATION <Manual> <Hide>

Addresses: 192.0.2.1/24 <Remove> <Add...>
Gateway: 192.0.2.254
DNS servers: 192.0.2.200 <Remove> <Add...>
Search domains: example.com <Remove> <Add...>

Routing (No custom routes) <Edit...>
☐ Never use this network for default route
☐ Ignore automatically obtained routes
☐ Ignore automatically obtained DNS parameters
☐ Require IPv4 addressing for this connection

= IPv6 CONFIGURATION <Manual> <Hide>

Addresses: 2001:db8:1::1/64 <Remove> <Add...>
Gateway: 2001:db8:1::fffe
DNS servers: 2001:db8:1::ffbb <Remove> <Add...>
Search domains: example.com <Remove> <Add...>

Routing (No custom routes) <Edit...>
☐ Never use this network for default route
☐ Ignore automatically obtained routes
☐ Ignore automatically obtained DNS parameters
☐ Require IPv6 addressing for this connection

☒ Automatically connect
☒ Available to all users

<Cancel> <OK>

8. Press **OK** to create and automatically activate the new connection.
9. Press **Back** to return to the main menu.
10. Select **Quit**, and press **Enter** to close the **nmtui** application.

Verification

1. Display the IP settings of the NIC:

```
# ip address show enp1s0
```

```
2: enp1s0: <BROADCAST,MULTICAST,UP,LOWER_UP> mtu 1500 qdisc fq_codel state UP
group default qlen 1000
link/ether 52:54:00:17:b8:b6 brd ff:ff:ff:ff:ff:ff
```

```

inet 192.0.2.1/24 brd 192.0.2.255 scope global noprefixroute enp1s0
    valid_lft forever preferred_lft forever
inet6 2001:db8:1::fffe/64 scope global noprefixroute
    valid_lft forever preferred_lft forever

```

2. Display the IPv4 default gateway:

```

# ip route show default
default via 192.0.2.254 dev enp1s0 proto static metric 102

```

3. Display the IPv6 default gateway:

```

# ip -6 route show default
default via 2001:db8:1::fffe dev enp1s0 proto static metric 102 pref medium

```

4. Display the DNS settings:

```

# cat /etc/resolv.conf
search example.com
nameserver 192.0.2.200
nameserver 2001:db8:1::ffbb

```

If multiple connection profiles are active at the same time, the order of **nameserver** entries depend on the DNS priority values in these profiles and the connection types.

5. Use the **ping** utility to verify that this host can send packets to other hosts:

```

# ping <host-name-or-IP-address>

```

Troubleshooting

- Verify that the network cable is plugged-in to the host and a switch.
- Check whether the link failure exists only on this host or also on other hosts connected to the same switch.
- Verify that the network cable and the network interface are working as expected. Perform hardware diagnosis steps and replace defective cables and network interface cards.
- If the configuration on the disk does not match the configuration on the device, starting or restarting NetworkManager creates an in-memory connection that reflects the configuration of the device. For further details and how to avoid this problem, see the Red Hat Knowledgebase solution [NetworkManager duplicates a connection after restart of NetworkManager service](#).

Additional resources

- [Configuring NetworkManager to avoid using a specific profile to provide a default gateway](#)
- [Configuring the order of DNS servers](#)

1.4. CONFIGURING AN ETHERNET CONNECTION WITH A DYNAMIC IP ADDRESS BY USING THE NETWORK RHEL SYSTEM ROLE WITH AN INTERFACE NAME

To connect a Red Hat Enterprise Linux host to an Ethernet network, create a NetworkManager connection profile for the network device. By using Ansible and the **network** RHEL system role, you can automate this process and remotely configure connection profiles on the hosts defined in a playbook.

You can use the **network** RHEL system role to configure an Ethernet connection that retrieves its IP addresses, gateways, and DNS settings from a DHCP server and IPv6 stateless address autoconfiguration (SLAAC). With this role you can assign the connection profile to the specified interface name.

Prerequisites

- [You have prepared the control node and the managed nodes](#)
- You are logged in to the control node as a user who can run playbooks on the managed nodes.
- The account you use to connect to the managed nodes has **sudo** permissions on them.
- A physical or virtual Ethernet device exists in the servers' configuration.
- A DHCP server and SLAAC are available in the network.
- The managed nodes use the NetworkManager service to configure the network.

Procedure

1. Create a playbook file, for example `~/playbook.yml`, with the following content:

```
---
- name: Configure the network
  hosts: managed-node-01.example.com
  tasks:
    - name: Ethernet connection profile with dynamic IP address settings
      ansible.builtin.include_role:
        name: redhat.rhel_system_roles.network
      vars:
        network_connections:
          - name: enp1s0
            interface_name: enp1s0
            type: ethernet
            autoconnect: yes
            ip:
              dhcp4: yes
              auto6: yes
            state: up
```

The settings specified in the example playbook include the following:

dhcp4: yes

Enables automatic IPv4 address assignment from DHCP, PPP, or similar services.

auto6: yes

Enables IPv6 auto-configuration. By default, NetworkManager uses Router Advertisements. If the router announces the **managed** flag, NetworkManager requests an IPv6 address and prefix from a DHCPv6 server.

For details about all variables used in the playbook, see the `/usr/share/ansible/roles/rhel-system-roles.network/README.md` file on the control node.

2. Validate the playbook syntax:

```
$ ansible-playbook --syntax-check ~/playbook.yml
```

Note that this command only validates the syntax and does not protect against a wrong but valid configuration.

3. Run the playbook:

```
$ ansible-playbook ~/playbook.yml
```

Verification

- Query the Ansible facts of the managed node and verify that the interface received IP addresses and DNS settings:

```
# ansible managed-node-01.example.com -m ansible.builtin.setup
```

```
...
  "ansible_default_ipv4": {
    "address": "192.0.2.1",
    "alias": "enp1s0",
    "broadcast": "192.0.2.255",
    "gateway": "192.0.2.254",
    "interface": "enp1s0",
    "macaddress": "52:54:00:17:b8:b6",
    "mtu": 1500,
    "netmask": "255.255.255.0",
    "network": "192.0.2.0",
    "prefix": "24",
    "type": "ether"
  },
  "ansible_default_ipv6": {
    "address": "2001:db8:1::1",
    "gateway": "2001:db8:1::fffe",
    "interface": "enp1s0",
    "macaddress": "52:54:00:17:b8:b6",
    "mtu": 1500,
    "prefix": "64",
    "scope": "global",
    "type": "ether"
  },
  ...
  "ansible_dns": {
    "nameservers": [
      "192.0.2.1",
      "2001:db8:1::ffbb"
    ],
    "search": [
      "example.com"
    ]
  },
  ...
```

Additional resources

- `/usr/share/ansible/roles/rhel-system-roles.network/README.md` file
- `/usr/share/doc/rhel-system-roles/network/` directory

1.5. ADDITIONAL RESOURCES

- [Configuring and managing networking](#)

CHAPTER 2. REGISTERING THE SYSTEM AND MANAGING SUBSCRIPTIONS

Subscriptions cover products installed on Red Hat Enterprise Linux, including the operating system itself. If you have not registered the system, you have no access to the RHEL repositories. You cannot install software updates such as security, bug fixes. Even if you have a self-support subscription, it grants access to the knowledge base while more resources remain unavailable in the lack of subscriptions. By purchasing subscriptions and using Red Hat Content Delivery Network (CDN), you can track:

- Registered systems
- Products installed on registered systems
- Subscriptions attached to the installed products

2.1. REGISTERING A SYSTEM BY USING THE COMMAND LINE

Subscriptions cover products installed on Red Hat Enterprise Linux, including the operating system itself. If you have not registered the system, you have no access to the RHEL repositories. You cannot install software updates such as security, bug fixes. Even if you have a self-support subscription, it grants access to the knowledge base while more resources remain unavailable in the lack of subscriptions. You need register the system to activate and manage Red Hat Enterprise Linux subscription for your Red Hat account.



NOTE

To register the system with Red Hat Insights, you can use the **rhc connect** utility. For details, see [Setting up remote host configuration](#).

Prerequisites

- You have an active subscription of the Red Hat Enterprise Linux system.

Procedure

- Register and subscribe the system:

```
# subscription-manager register
Registering to:          subscription.rhsm.redhat.com:443/subscription
Username: <example_username>
Password: <example_password>
The system has been registered with ID: 37to907c-ece6-49ea-9174-20b87ajk9ee7
The registered system name is:    client1.example.com
```

The command prompts you to enter username and password of Red Hat Customer Portal account.

If the registration process fails, you can register the system with a specific pool. For details, proceed with the following steps:

- Determine the pool ID of a subscription:

```
# subscription-manager list --available --all
```

This command displays all available subscriptions for your Red Hat account. For every subscription, various characteristics are displayed, including the pool ID.

- Attach the appropriate subscription to your system by replacing `<example_pool_id>` with the pool ID determined in the previous step:

```
# subscription-manager attach --pool=<example_pool_id>
```

Verification

- Verify the system under **Inventory** → **Systems** in the Hybrid Cloud Console.

Additional resources

- [Understanding Red Hat Subscription Management](#)
- [Understanding your workflow for subscribing with Red Hat products](#)
- [Viewing your subscription inventory in the Hybrid Cloud Console](#)

2.2. REGISTERING A SYSTEM BY USING THE WEB CONSOLE

Subscriptions cover products installed on Red Hat Enterprise Linux, including the operating system itself. If you have not registered the system, you have no access to the RHEL repositories. You cannot install software updates such as security, bug fixes. Even if you have a self-support subscription, it grants access to the knowledge base while more resources remain unavailable in the lack of subscriptions. You can register a newly installed Red Hat Enterprise Linux with account credentials in the Red Hat web console.

Prerequisites

- You have an active subscription of the RHEL system.
- You have installed the RHEL 8 web console.
- You have enabled the cockpit service.
- Your user account is allowed to log in to the web console.
For instructions, see [Installing and enabling the web console](#).

Procedure

1. Open `https://<ip_address_or_hostname>:9090` in a browser, and log in to the web console.
2. In the **Health** field on the **Overview** page, click the **Not registered** warning, or click **Subscriptions** in the main menu to move to page with your subscription information.
3. In the **Overview** field, click **Register**.
4. In the **Register system** dialog, select the registration method.
Optional: Enter your organization's name or ID. If your account belongs to more than one organization on the Red Hat Customer Portal, you must add the organization name or ID. To get the organization ID, check with your Technical Account Manager at Red Hat.
5. If you do not want to connect your system to Red Hat Insights, clear the **Insights** checkbox.

6. Click **Register**.

Verification

- Check details of your subscription in [the Hybrid Cloud Console](#).

2.3. REGISTERING A SYSTEM IN THE GNOME DESKTOP ENVIRONMENT

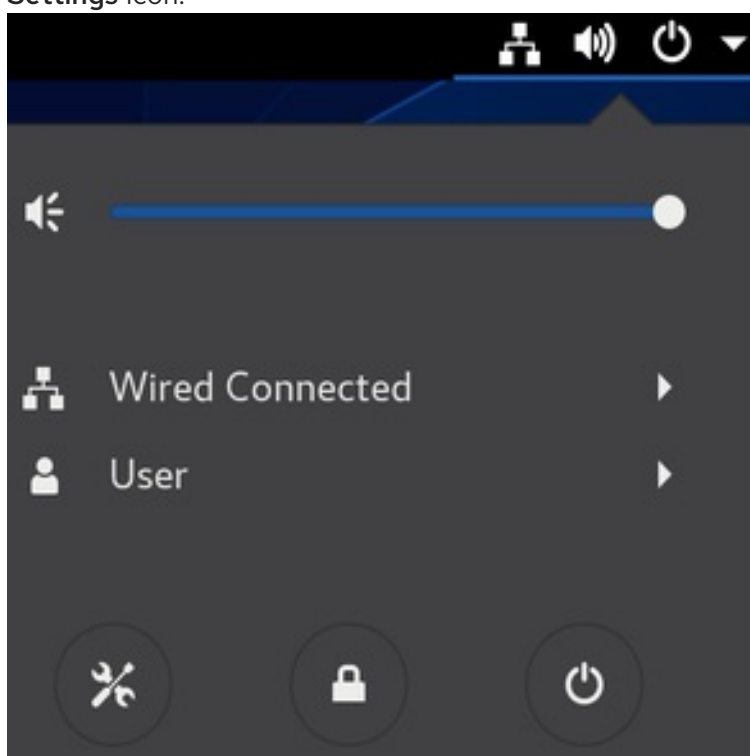
Subscriptions cover products installed on Red Hat Enterprise Linux, including the operating system itself. If you have not registered the system, you have no access to the RHEL repositories. You can not install software updates such as security, bug fixes. Even if you have a self-support subscription, it grants access to the knowledge base while more resources remain unavailable in the lack of subscriptions. Follow the steps in this procedure to enroll the system with your Red Hat account.

Prerequisites

- You have created a [Red Hat account](#).
- You are a root user and logged in to the GNOME desktop environment. For details, see [Register and subscribe RHEL system to Red Hat Subscription Manager](#).

Procedure

1. Open the **system menu**, which is accessible from the upper-right screen corner, and click the **Settings** icon.



2. In the **Details** → **About** section, click **Register**.
3. Select **Registration Server**.
4. If you are not using the Red Hat server, enter the server address in the **URL** field.
5. In the **Registration Type** menu, select **Red Hat Account**

6. Under **Registration Details**:

- Enter your Red Hat account user name in the **Login** field.
- Enter your Red Hat account password in the **Password** field.
- Enter the name of your organization in the **Organization** field.

7. Click **Register**.

2.4. REGISTERING RHEL 8 USING THE INSTALLER GUI

You can register a Red Hat Enterprise Linux 8 by using the RHEL installer GUI.

Prerequisites

- You have a valid user account on the Red Hat Customer Portal. See the [Create a Red Hat Login page](#).
- You have a valid Activation Key and Organization id.

Procedure

1. From the **Installation Summary** screen, under **Software**, click **Connect to Red Hat**
2. Authenticate your Red Hat account using the **Account** or **Activation Key** option.
3. Optional: In the **Set System Purpose** field select the **Role**, **SLA**, and **Usage** attribute that you want to set from the drop-down menu.
At this point, your Red Hat Enterprise Linux 8 system has been successfully registered.

CHAPTER 3. ACCESSING THE RED HAT SUPPORT

If you require help with troubleshooting a problem, you can contact Red Hat Support.

Procedure

- Log in to the Red Hat Support web site and choose one of the following options:
 - Open a new support case.
 - Initiate a live chat with a Red Hat expert.
 - Contact a Red Hat expert by making a call or sending an email.

3.1. USING THE SOSREPORT UTILITY TO COLLECT DAIGNOSTIC INFORMATION ABOUT A SYSTEM TO ATTACH IT TO A SUPPORT TICKET

The **sosreport** command collects configuration details, system information and diagnostic information from a Red Hat Enterprise Linux system.

The following section describes how to use the **sosreport** command to produce reports for your support cases.

Prerequisites

- A valid user account on the Red Hat Customer Portal. See [Create a Red Hat Login](#) .
- An active subscription for the RHEL system.
- A support-case number.

Procedure

1. Install the **sos** package:

```
# yum install sos
```

2. Generate a report:

```
# sosreport
```

Optionally, pass the **-upload** option to the command to automatically upload and attach the report to a support case. This requires internet access and your Customer Portal credentials.

3. Optional: Manually attach the report to your support case.
See the Red Hat Knowledgebase solution [How can I attach a file to a Red Hat support case?](#) for more information.

Additional resources

- [What is an sosreport and how to create one in Red Hat Enterprise Linux?](#) (Red Hat Knowledgebase)

CHAPTER 4. CHANGING BASIC ENVIRONMENT SETTINGS

Configuration of basic environment settings is a part of the installation process. The following sections guide you when you change them later. The basic configuration of the environment includes:

- Date and time
- System locales
- Keyboard layout
- Language

4.1. CONFIGURING THE DATE AND TIME

Accurate timekeeping is important for several reasons. In Red Hat Enterprise Linux, timekeeping is ensured by the **NTP** protocol, which is implemented by a daemon running in user space. The user-space daemon updates the system clock running in the kernel. The system clock can keep time by using various clock sources.

Red Hat Enterprise Linux 8 uses the **chronyd** daemon to implement **NTP**. **chronyd** is available from the **chrony** package. For more information, see [Using the chrony suite to configure NTP](#).

4.1.1. Manually configuring the date, time, and timezone settings

To display the current date and time, use either of these steps.

Procedure

1. Optional: List the timezones:

```
# timedatectl list-timezones  
  
Europe/Berlin
```

2. Set the time zone:

```
# timedatectl set-timezone <time_zone>
```

3. Set the date and time:

```
# timedatectl set-time <YYYY-mm-dd HH:MM-SS>
```

Verification

1. Display the date, time, and timezone:

```
# date  
Mon Mar 30 16:02:59 CEST 2020
```

2. To see more details, use the `timedatectl` command:

```
# timedatectl
```

```

Local time: Mon 2020-03-30 16:04:42 CEST
Universal time: Mon 2020-03-30 14:04:42 UTC
RTC time: Mon 2020-03-30 14:04:41
Time zone: Europe/Prague (CEST, +0200)
System clock synchronized: yes
NTP service: active
RTC in local TZ: no

```

Additional resources

- **date(1)** and **timedatectl(1)** man pages

4.2. CONFIGURING TIME SETTINGS BY USING THE WEB CONSOLE

You can set a time zone and synchronize the system time with a Network Time Protocol (NTP) server in the RHEL web console.

Prerequisites

- You have installed the RHEL 8 web console.
- You have enabled the cockpit service.
- Your user account is allowed to log in to the web console.
For instructions, see [Installing and enabling the web console](#).

Procedure

1. Log in to the RHEL 8 web console.
For details, see [Logging in to the web console](#).
2. Click the current system time in **Overview**.
3. Click **System time**.
4. In the **Change System Time** dialog box, change the time zone if necessary.
5. In the **Set Time** drop-down menu, select one of the following:

Manually

Use this option if you need to set the time manually, without an NTP server.

Automatically using NTP server

This is a default option, which synchronizes time automatically with the preset NTP servers.

Automatically using specific NTP servers

Use this option only if you need to synchronize the system with a specific NTP server.
Specify the DNS name or the IP address of the server.

6. Click **Change**.

Verification

- Check the system time displayed in the **System** tab.

Additional resources

- [Using the Chrony suite to configure NTP](#)

4.3. CONFIGURING THE SYSTEM LOCALE

System-wide locale settings are stored in the **/etc/locale.conf** file that is read at early boot by the **systemd** daemon. Every service or user inherits the locale settings configured in **/etc/locale.conf**, unless individual programs or individual users override them.

Procedure

1. Optional: Display the current system locales settings:

```
# localectl status
System Locale: LANG=en_US.UTF-8
VC Keymap: de-nodeadkeys
X11 Layout: de
X11 Variant: nodeadkeys
```

2. List available system locale settings:

```
$ localectl list-locales
C.UTF-8
...
en_US.UTF-8
en_ZA.UTF-8
en_ZW.UTF-8
...
```

3. Update the system locale setting:

For example:

+

```
# localectl set-locales LANG=en_US.UTF-8
```



NOTE

The GNOME Terminal does not support non-UTF8 system locales. For more information, see the Red Hat Knowledgebase solution [The gnome-terminal application fails to start when the system locale is set to non-UTF8](#).

Additional resources

- **man localectl(1)**, **man locale(7)**, and **man locale.conf(5)**

4.4. CONFIGURING THE KEYBOARD LAYOUT

The keyboard layout settings control the layout used on the text console and graphical user interfaces.

Procedure

1. To list available keymaps:

```
$ localectl list-keymaps
ANSI-dvorak
al
al-plisi
amiga-de
amiga-us
...
```

2. To display the current status of keymaps settings:

```
$ localectl status
...
VC Keymap: us
...
```

3. To set or change the default system keymap. For example:

```
# localectl set-keymap us
```

Additional resources

- **man localectl(1)**, **man locale(7)**, and **man locale.conf(5)** man pages

4.5. CHANGING THE FONT SIZE IN TEXT CONSOLE MODE

You can change the font size in the virtual console.

Procedure

1. Display the currently-used font file:

```
# cat /etc/vconsole.conf

FONT="eurlatgr"
```

2. List the available font files:

```
# ls -l /usr/lib/kbd/consolefonts/*.psfu.gz

/usr/lib/kbd/consolefonts/eurlatgr.psfu.gz
/usr/lib/kbd/consolefonts/LatArCyrHeb-08.psfu.gz
/usr/lib/kbd/consolefonts/LatArCyrHeb-14.psfu.gz
/usr/lib/kbd/consolefonts/LatArCyrHeb-16.psfu.gz
/usr/lib/kbd/consolefonts/LatArCyrHeb-16+.psfu.gz
/usr/lib/kbd/consolefonts/LatArCyrHeb-19.psfu.gz
```

Select a font file that supports your character set and code page.

3. Optional: To test a font file, load it temporarily:

```
# setfont LatArCyrHeb-16.psfu.gz
```

The **setfont** utility applies the font file immediately and terminals use the new and font size until you reboot or apply a different font file.

4. To return to the font file defined in **/etc/vconsole.conf**, enter **setfont** without any parameters.
5. Edit the **/etc/vconsole.conf** file and set the **FONT** variable to the font file RHEL should load at boot time, for example:

```
FONT=LatArCyrHeb-16
```

6. Reboot the host

```
# reboot
```


CHAPTER 5. USING SECURE COMMUNICATIONS BETWEEN TWO SYSTEMS WITH OPENSSH

SSH (Secure Shell) is a protocol which provides secure communications between two systems using a client-server architecture and allows users to log in to server host systems remotely. Unlike other remote communication protocols, such as FTP or Telnet, SSH encrypts the login session, which prevents intruders from collecting unencrypted passwords from the connection.

5.1. GENERATING SSH KEY PAIRS

You can log in to an OpenSSH server without entering a password by generating an SSH key pair on a local system and copying the generated public key to the OpenSSH server. Each user who wants to create a key must run this procedure.

To preserve previously generated key pairs after you reinstall the system, back up the `~/.ssh/` directory before you create new keys. After reinstalling, copy it back to your home directory. You can do this for all users on your system, including **root**.

Prerequisites

- You are logged in as a user who wants to connect to the OpenSSH server by using keys.
- The OpenSSH server is configured to allow key-based authentication.

Procedure

1. Generate an ECDSA key pair:

```
$ ssh-keygen -t ecdsa
Generating public/private ecdsa key pair.
Enter file in which to save the key (/home/<username>/.ssh/id_ecdsa):
Enter passphrase (empty for no passphrase): <password>
Enter same passphrase again: <password>
Your identification has been saved in /home/<username>/.ssh/id_ecdsa.
Your public key has been saved in /home/<username>/.ssh/id_ecdsa.pub.
The key fingerprint is:
SHA256:Q/x+qms4j7PCQ0qFd09iZEFHA+SqwBKRNau72oZfaCI
<username>@<localhost.example.com>
The key's randomart image is:
+---[ECDSA 256]---+
|.00..0=++      |
|.. 0 .00 .     |
|. .. 0. 0      |
|...0.+...      |
|0.00.0 +S .    |
|.=.+ .0        |
|E.*+ . . .     |
|.=.+ +.. 0     |
| . 00*+0.      |
+----[SHA256]-----+
```

You can also generate an RSA key pair by using the **ssh-keygen** command without any parameter or an Ed25519 key pair by entering the **ssh-keygen -t ed25519** command. Note that the Ed25519 algorithm is not FIPS-140-compliant, and OpenSSH does not work with Ed25519

keys in FIPS mode.

2. Copy the public key to a remote machine:

```
$ ssh-copy-id <username>@<ssh-server-example.com>
/usr/bin/ssh-copy-id: INFO: attempting to log in with the new key(s), to filter out any that are
already installed
<username>@<ssh-server-example.com>'s password:
...
Number of key(s) added: 1

Now try logging into the machine, with: "ssh '<username>@<ssh-server-example.com>'" and
check to make sure that only the key(s) you wanted were added.
```

Replace **<username>@<ssh-server-example.com>** with your credentials.

If you do not use the **ssh-agent** program in your session, the previous command copies the most recently modified **~/.ssh/id*.pub** public key if it is not yet installed. To specify another public-key file or to prioritize keys in files over keys cached in memory by **ssh-agent**, use the **ssh-copy-id** command with the **-i** option.

Verification

- Log in to the OpenSSH server by using the key file:

```
$ ssh -o PreferredAuthentications=publickey <username>@<ssh-server-example.com>
```

Additional resources

- **ssh-keygen(1)** and **ssh-copy-id(1)** man pages on your system

5.2. SETTING KEY-BASED AUTHENTICATION AS THE ONLY METHOD ON AN OPENSSSH SERVER

To improve system security, enforce key-based authentication by disabling password authentication on your OpenSSH server.

Prerequisites

- The **openssh-server** package is installed.
- The **sshd** daemon is running on the server.
- You can already connect to the OpenSSH server by using a key.
See the [Generating SSH key pairs](#) section for details.

Procedure

1. Open the **/etc/ssh/sshd_config** configuration in a text editor, for example:

```
# vi /etc/ssh/sshd_config
```

2. Change the **PasswordAuthentication** option to **no**:

—

```
PasswordAuthentication no
```

3. On a system other than a new default installation, check that the **PubkeyAuthentication** parameter is either not set or set to **yes**.
4. Set the **ChallengeResponseAuthentication** directive to **no**.
Note that the corresponding entry is commented out in the configuration file and the default value is **yes**.
5. To use key-based authentication with NFS-mounted home directories, enable the **use_nfs_home_dirs** SELinux boolean:

```
# setsebool -P use_nfs_home_dirs 1
```

6. If you are connected remotely, not using console or out-of-band access, test the key-based login process before disabling password authentication.
7. Reload the **sshd** daemon to apply the changes:

```
# systemctl reload sshd
```

Additional resources

- **sshd_config(5)** and **setsebool(8)** man pages on your system

5.3. CACHING YOUR SSH CREDENTIALS BY USING SSH-AGENT

To avoid entering a passphrase each time you initiate an SSH connection, you can use the **ssh-agent** utility to cache the private SSH key for a login session. If the agent is running and your keys are unlocked, you can log in to SSH servers by using these keys but without having to enter the key's password again. The private key and the passphrase remain secure.

Prerequisites

- You have a remote host with the SSH daemon running and reachable through the network.
- You know the IP address or hostname and credentials to log in to the remote host.
- You have generated an SSH key pair with a passphrase and transferred the public key to the remote machine.
See the [Generating SSH key pairs](#) section for details.

Procedure

1. Add the command for automatically starting **ssh-agent** in your session to the `~/.bashrc` file:
 - a. Open `~/.bashrc` in a text editor of your choice, for example:

```
$ vi ~/.bashrc
```

- b. Add the following line to the file:

```
eval $(ssh-agent)
```

- c. Save the changes, and quit the editor.
2. Add the following line to the `~/.ssh/config` file:

```
AddKeysToAgent yes
```

With this option and **ssh-agent** started in your session, the agent prompts for a password only for the first time when you connect to a host.

Verification

- Log in to a host which uses the corresponding public key of the cached private key in the agent, for example:

```
$ ssh <example.user>@<ssh-server@example.com>
```

Note that you did not have to enter the passphrase.

5.4. AUTHENTICATING BY SSH KEYS STORED ON A SMART CARD

You can create and store ECDSA and RSA keys on a smart card and authenticate by the smart card on an OpenSSH client. Smart-card authentication replaces the default password authentication.

Prerequisites

- On the client side, the **opensc** package is installed and the **pcscd** service is running.

Procedure

1. List all keys provided by the OpenSC PKCS #11 module including their PKCS #11 URIs and save the output to the **keys.pub** file:

```
$ ssh-keygen -D pkcs11: > keys.pub
```

2. Transfer the public key to the remote server. Use the **ssh-copy-id** command with the **keys.pub** file created in the previous step:

```
$ ssh-copy-id -f -i keys.pub <username@ssh-server-example.com>
```

3. Connect to `<ssh-server-example.com>` by using the ECDSA key. You can use just a subset of the URI, which uniquely references your key, for example:

```
$ ssh -i "pkcs11:id=%01?module-path=/usr/lib64/pkcs11/opensc-pkcs11.so" <ssh-server-example.com>
Enter PIN for 'SSH key':
[ssh-server-example.com] $
```

Because OpenSSH uses the **p11-kit-proxy** wrapper and the OpenSC PKCS #11 module is registered to the **p11-kit** tool, you can simplify the previous command:

```
$ ssh -i "pkcs11:id=%01" <ssh-server-example.com>
Enter PIN for 'SSH key':
[ssh-server-example.com] $
```

If you skip the **id=** part of a PKCS #11 URI, OpenSSH loads all keys that are available in the proxy module. This can reduce the amount of typing required:

```
$ ssh -i pkcs11: <ssh-server-example.com>
Enter PIN for 'SSH key':
[ssh-server-example.com] $
```

4. Optional: You can use the same URI string in the `~/.ssh/config` file to make the configuration permanent:

```
$ cat ~/.ssh/config
IdentityFile "pkcs11:id=%01?module-path=/usr/lib64/pkcs11/opensc-pkcs11.so"
$ ssh <ssh-server-example.com>
Enter PIN for 'SSH key':
[ssh-server-example.com] $
```

The **ssh** client utility now automatically uses this URI and the key from the smart card.

Additional resources

- **p11-kit(8)**, **opensc.conf(5)**, **pcscd(8)**, **ssh(1)**, and **ssh-keygen(1)** man pages on your system

5.5. ADDITIONAL RESOURCES

- **sshd(8)**, **ssh(1)**, **scp(1)**, **sftp(1)**, **ssh-keygen(1)**, **ssh-copy-id(1)**, **ssh_config(5)**, **sshd_config(5)**, **update-crypto-policies(8)**, and **crypto-policies(7)** man pages on your system
- [Configuring SELinux for applications and services with non-standard configurations](#)
- [Controlling network traffic using firewalld](#)

CHAPTER 6. CONFIGURING BASIC SYSTEM SECURITY

Computer security is the protection of computer systems and their hardware, software, information, and services from theft, damage, disruption, and misdirection. Ensuring computer security is an essential task, in particular in enterprises that process sensitive data and handle business transactions.

This section covers only the basic security features that you can configure after installation of the operating system.

6.1. ENABLING THE FIREWALLD SERVICE

A firewall is a network security system that monitors and controls incoming and outgoing network traffic according to configured security rules. A firewall typically establishes a barrier between a trusted secure internal network and another outside network.

The **firewalld** service, which provides a firewall in Red Hat Enterprise Linux, is automatically enabled during installation.

To enable the **firewalld** service, follow this procedure.

Procedure

- Display the current status of **firewalld**:

```
$ systemctl status firewalld
```

```
• firewalld.service - firewalld - dynamic firewall daemon
  Loaded: loaded (/usr/lib/systemd/system/firewalld.service; disabled; vendor preset:
  enabled)
  Active: inactive (dead)
  ...
```

- If **firewalld** is not enabled and running, switch to the **root** user, and start the **firewalld** service and enable to start it automatically after the system restarts:

```
# systemctl enable --now firewalld
```

Verification

- Check that **firewalld** is running and enabled:

```
$ systemctl status firewalld
```

```
• firewalld.service - firewalld - dynamic firewall daemon
  Loaded: loaded (/usr/lib/systemd/system/firewalld.service; enabled; vendor preset:
  enabled)
  Active: active (running)
  ...
```

Additional resources

- [Using and configuring firewalld](#)
- **man firewalld(1)**

6.2. MANAGING FIREWALL IN THE RHEL 8 WEB CONSOLE

To configure the **firewalld** service in the web console, navigate to **Networking → Firewall**.

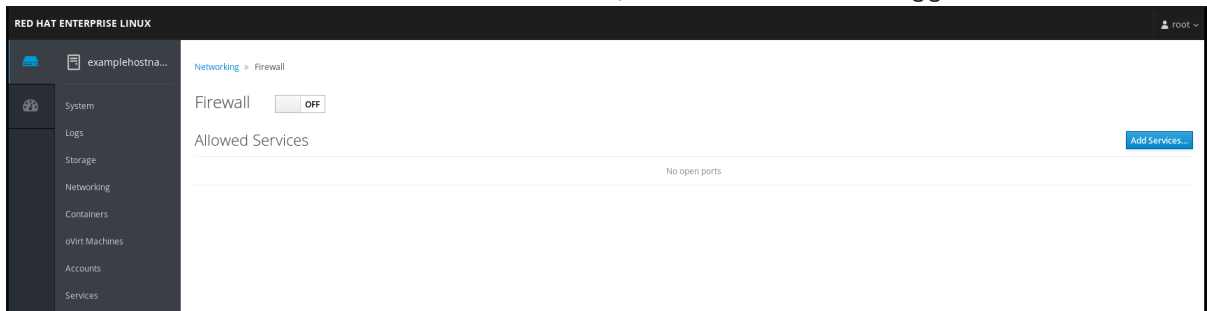
By default, the **firewalld** service is enabled.

Prerequisites

- You have installed the RHEL 8 web console.
- You have enabled the cockpit service.
- Your user account is allowed to log in to the web console.
For instructions, see [Installing and enabling the web console](#).

Procedure

1. Log in to the RHEL 8 web console.
For details, see [Logging in to the web console](#).
2. To enable or disable **firewalld** in the web console, switch the **Firewall** toggle button.



NOTE

Additionally, you can define more fine-grained access through the firewall to a service using the **Add services** button.

6.3. MANAGING BASIC SELINUX SETTINGS

Security-Enhanced Linux (SELinux) is an additional layer of system security that determines which processes can access which files, directories, and ports. These permissions are defined in SELinux policies. A policy is a set of rules that guide the SELinux security engine.

SELinux has two possible states:

- Disabled
- Enabled

When SELinux is enabled, it runs in one of the following modes:

- Enabled
 - Enforcing
 - Permissive

In **enforcing mode**, SELinux enforces the loaded policies. SELinux denies access based on SELinux policy rules and enables only the interactions that are explicitly allowed. Enforcing mode is the safest SELinux mode and is the default mode after installation.

In **permissive mode**, SELinux does not enforce the loaded policies. SELinux does not deny access, but reports actions that break the rules to the `/var/log/audit/audit.log` log. Permissive mode is the default mode during installation. Permissive mode is also useful in some specific cases, for example when troubleshooting problems.

Additional resources

- [Using SELinux](#)

6.4. SWITCHING SELINUX MODES IN THE RHEL 8 WEB CONSOLE

You can set SELinux mode through the RHEL 8 web console in the **SELinux** menu item.

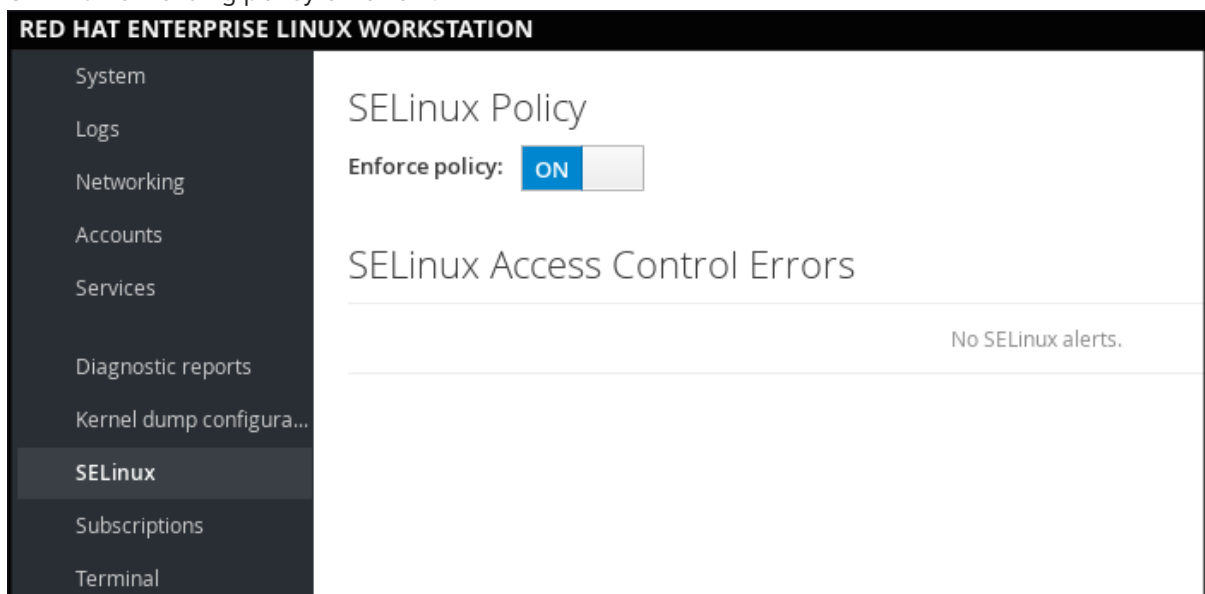
By default, SELinux enforcing policy in the web console is on, and SELinux operates in enforcing mode. By turning it off, you switch SELinux to permissive mode. Note that this selection is automatically reverted on the next boot to the configuration defined in the `/etc/sysconfig/selinux` file.

Prerequisites

- You have installed the RHEL 8 web console.
- You have enabled the cockpit service.
- Your user account is allowed to log in to the web console.
For instructions, see [Installing and enabling the web console](#).

Procedure

1. Log in to the RHEL 8 web console.
For details, see [Logging in to the web console](#).
2. In the web console, use the **Enforce policy** toggle button in the SELinux menu item to turn SELinux enforcing policy on or off.



6.5. ADDITIONAL RESOURCES

- [Generating SSH key pairs](#)
- [Setting an OpenSSH server for key-based authentication](#)
- [Security hardening](#)
- [Using SELinux](#)
- [Securing networks](#)
- [Deploying the same SELinux configuration on multiple systems](#)

CHAPTER 7. INTRODUCTION TO RHEL SYSTEM ROLES

By using RHEL system roles, you can remotely manage the system configurations of multiple RHEL systems across major versions of RHEL.

Important terms and concepts

The following describes important terms and concepts in an Ansible environment:

Control node

A control node is the system from which you run Ansible commands and playbooks. Your control node can be an Ansible Automation Platform, Red Hat Satellite, or a RHEL 9, 8, or 7 host. For more information, see [Preparing a control node on RHEL 8](#).

Managed node

Managed nodes are the servers and network devices that you manage with Ansible. Managed nodes are also sometimes called hosts. Ansible does not have to be installed on managed nodes. For more information, see [Preparing a managed node](#).

Ansible playbook

In a playbook, you define the configuration you want to achieve on your managed nodes or a set of steps for the system on the managed node to perform. Playbooks are Ansible's configuration, deployment, and orchestration language.

Inventory

In an inventory file, you list the managed nodes and specify information such as IP address for each managed node. In the inventory, you can also organize the managed nodes by creating and nesting groups for easier scaling. An inventory file is also sometimes called a hostfile.

Available roles and modules on a Red Hat Enterprise Linux 8 control node

Roles provided by the **rhel-system-roles** package:

- **ad_integration**: Active Directory integration
- **bootloader**: GRUB boot loader management
- **certificate**: Certificate issuance and renewal
- **cockpit**: Web console installation and configuration
- **crypto_policies**: System-wide cryptographic policies
- **fapolicy**: File access policy daemon configuration
- **firewall**: Firewalld management
- **ha_cluster**: HA Cluster management
- **journald**: Systemd journald management
- **kdump**: Kernel Dumps management
- **kernel_settings**: Kernel settings management
- **logging**: Configuring logging
- **metrics**: Performance monitoring and metrics

- **nbde_client**: Network Bound Disk Encryption client
- **nbde_server**: Network Bound Disk Encryption server
- **network**: Networking configuration
- **podman**: Podman container management
- **postfix**: Postfix configuration
- **postgresql**: PostgreSQL configuration
- **rhc**: Subscribing RHEL and configuring Insights client
- **selinux**: SELinux management
- **ssh**: SSH client configuration
- **sshd**: SSH server configuration
- **storage**: Storage management
- **systemd**: Managing systemd units
- **timesync**: Time synchronization
- **tlog**: Terminal session recording
- **vpn**: Configuring IPsec VPNs

Roles provided by the **ansible-collection-microsoft-sql** package:

- **microsoft.sql.server**: Microsoft SQL Server

Modules provided by the **ansible-collection-redhat-rhel_mgmt** package:

- **rhel_mgmt.ipmi_boot**: Setting boot devices
- **rhel_mgmt.ipmi_power**: Setting the system power state
- **rhel_mgmt.redfish_command**: Managing out-of-band controllers (OOB)
- **rhel_mgmt.redfish_command**: Querying information from OOB controllers
- **rhel_mgmt.redfish_command**: Managing BIOS, UEFI, and OOB controllers

Additional resources

- [Automating system administration by using RHEL system roles](#)
- [Red Hat Enterprise Linux \(RHEL\) system roles](#)
- `/usr/share/ansible/roles/rhel-system-roles.<role_name>/README.md` file
- `/usr/share/doc/rhel-system-roles/<role_name>/` directory

CHAPTER 8. CONFIGURING LOGGING

Most services in Red Hat Enterprise Linux log status messages, warnings, and errors. You can use the **rsyslogd** service to log these entries to local files or to a remote logging server.

8.1. CONFIGURING A REMOTE LOGGING SOLUTION

To ensure that logs from various machines in your environment are recorded centrally on a logging server, you can configure the **Rsyslog** application to record logs that fit specific criteria from the client system to the server.

8.1.1. The Rsyslog logging service

The Rsyslog application, in combination with the **systemd-journald** service, provides local and remote logging support in Red Hat Enterprise Linux. The **rsyslogd** daemon continuously reads **syslog** messages received by the **systemd-journald** service from the Journal. **rsyslogd** then filters and processes these **syslog** events and records them to **rsyslog** log files or forwards them to other services according to its configuration.

The **rsyslogd** daemon also provides extended filtering, encryption protected relaying of messages, input and output modules, and support for transportation using the TCP and UDP protocols.

In **/etc/rsyslog.conf**, which is the main configuration file for **rsyslog**, you can specify the rules according to which **rsyslogd** handles the messages. Generally, you can classify messages by their source and topic (facility) and urgency (priority), and then assign an action that should be performed when a message fits these criteria.

In **/etc/rsyslog.conf**, you can also see a list of log files maintained by **rsyslogd**. Most log files are located in the **/var/log/** directory. Some applications, such as **httpd** and **samba**, store their log files in a subdirectory within **/var/log/**.

Additional resources

- **rsyslogd(8)** and **rsyslog.conf(5)** man pages on your system
- Documentation installed with the **rsyslog-doc** package in the **/usr/share/doc/rsyslog/html/index.html** file

8.1.2. Installing Rsyslog documentation

The Rsyslog application has extensive online documentation that is available at <https://www.rsyslog.com/doc/>, but you can also install the **rsyslog-doc** documentation package locally.

Prerequisites

- You have activated the **AppStream** repository on your system.
- You are authorized to install new packages using **sudo**.

Procedure

- Install the **rsyslog-doc** package:

```
# yum install rsyslog-doc
```

Verification

- Open the `/usr/share/doc/rsyslog/html/index.html` file in a browser of your choice, for example:

```
$ firefox /usr/share/doc/rsyslog/html/index.html &
```

8.1.3. Configuring a server for remote logging over TCP

The Rsyslog application enables you to both run a logging server and configure individual systems to send their log files to the logging server. To use remote logging through TCP, configure both the server and the client. The server collects and analyzes the logs sent by one or more client systems.

With the Rsyslog application, you can maintain a centralized logging system where log messages are forwarded to a server over the network. To avoid message loss when the server is not available, you can configure an action queue for the forwarding action. This way, messages that failed to be sent are stored locally until the server is reachable again. Note that such queues cannot be configured for connections using the UDP protocol.

The **omfwd** plug-in provides forwarding over UDP or TCP. The default protocol is UDP. Because the plug-in is built in, it does not have to be loaded.

By default, **rsyslog** uses TCP on port **514**.

Prerequisites

- Rsyslog is installed on the server system.
- You are logged in as **root** on the server.
- The **policycoreutils-python-utils** package is installed for the optional step using the **semanage** command.
- The **firewalld** service is running.

Procedure

1. Optional: To use a different port for **rsyslog** traffic, add the **syslogd_port_t** SELinux type to port. For example, enable port **30514**:

```
# semanage port -a -t syslogd_port_t -p tcp 30514
```

2. Optional: To use a different port for **rsyslog** traffic, configure **firewalld** to allow incoming **rsyslog** traffic on that port. For example, allow TCP traffic on port **30514**:

```
# firewall-cmd --zone=<zone-name> --permanent --add-port=30514/tcp
success
# firewall-cmd --reload
```

3. Create a new file in the `/etc/rsyslog.d/` directory named, for example, **remotelog.conf**, and insert the following content:

```
# Define templates before the rules that use them
# Per-Host templates for remote systems
template(name="TmplAuthpriv" type="list") {
```

```

    constant(value="/var/log/remote/auth/")
    property(name="hostname")
    constant(value="/")
    property(name="programname" SecurePath="replace")
    constant(value=".log")
}

template(name="TmplMsg" type="list") {
    constant(value="/var/log/remote/msg/")
    property(name="hostname")
    constant(value="/")
    property(name="programname" SecurePath="replace")
    constant(value=".log")
}

# Provides TCP syslog reception
module(load="imtcp")

# Adding this ruleset to process remote messages
ruleset(name="remote1"){
    authpriv.* action(type="omfile" DynaFile="TmplAuthpriv")
    *.info;mail.none;authpriv.none;cron.none
    action(type="omfile" DynaFile="TmplMsg")
}

input(type="imtcp" port="30514" ruleset="remote1")

```

4. Save the changes to the **/etc/rsyslog.d/remotelog.conf** file.
5. Test the syntax of the **/etc/rsyslog.conf** file:

```

# rsyslogd -N 1
rsyslogd: version 8.1911.0-2.el8, config validation run...
rsyslogd: End of config validation run. Bye.

```

6. Make sure the **rsyslog** service is running and enabled on the logging server:

```
# systemctl status rsyslog
```

7. Restart the **rsyslog** service.

```
# systemctl restart rsyslog
```

8. Optional: If **rsyslog** is not enabled, ensure the **rsyslog** service starts automatically after reboot:

```
# systemctl enable rsyslog
```

Your log server is now configured to receive and store log files from the other systems in your environment.

Additional resources

- **rsyslogd(8)**, **rsyslog.conf(5)**, **semanage(8)**, and **firewall-cmd(1)** man pages on your system

- Documentation installed with the **rsyslog-doc** package in the `/usr/share/doc/rsyslog/html/index.html` file

8.1.4. Configuring remote logging to a server over TCP

You can configure a system for forwarding log messages to a server over the TCP protocol. The **omfwd** plug-in provides forwarding over UDP or TCP. The default protocol is UDP. Because the plug-in is built in, you do not have to load it.

Prerequisites

- The **rsyslog** package is installed on the client systems that should report to the server.
- You have configured the server for remote logging.
- The specified port is permitted in SELinux and open in firewall.
- The system contains the **polycoreutils-python-utils** package, which provides the **semanage** command for adding a non-standard port to the SELinux configuration.

Procedure

1. Create a new file in the `/etc/rsyslog.d/` directory named, for example, **10-remotelog.conf**, and insert the following content:

```
*.* action(type="omfwd"
        queue.type="linkedlist"
        queue.filename="example_fwd"
        action.resumeRetryCount="-1"
        queue.saveOnShutdown="on"
        target="example.com" port="30514" protocol="tcp"
    )
```

Where:

- The **queue.type="linkedlist"** setting enables a LinkedList in-memory queue,
- The **queue.filename** setting defines a disk storage. The backup files are created with the **example_fwd** prefix in the working directory specified by the preceding global **workDirectory** directive.
- The **action.resumeRetryCount -1** setting prevents **rsyslog** from dropping messages when retrying to connect if server is not responding,
- The **queue.saveOnShutdown="on"** setting saves in-memory data if **rsyslog** shuts down.
- The last line forwards all received messages to the logging server. Port specification is optional.
With this configuration, **rsyslog** sends messages to the server but keeps messages in memory if the remote server is not reachable. A file on disk is created only if **rsyslog** runs out of the configured memory queue space or needs to shut down, which benefits the system performance.

**NOTE**

Rsyslog processes configuration files **/etc/rsyslog.d/** in the lexical order.

2. Restart the **rsyslog** service.

```
# systemctl restart rsyslog
```

Verification

To verify that the client system sends messages to the server, follow these steps:

1. On the client system, send a test message:

```
# logger test
```

2. On the server system, view the **/var/log/messages** log, for example:

```
# cat /var/log/remote/msg/hostname/root.log  
Feb 25 03:53:17 hostname root[6064]: test
```

Where *hostname* is the host name of the client system. Note that the log contains the user name of the user that entered the **logger** command, in this case **root**.

Additional resources

- **rsyslogd(8)** and **rsyslog.conf(5)** man pages on your system
- Documentation installed with the **rsyslog-doc** package in the **/usr/share/doc/rsyslog/html/index.html** file

8.1.5. Configuring TLS-encrypted remote logging

By default, Rsyslog sends remote-logging communication in the plain text format. If your scenario requires to secure this communication channel, you can encrypt it using TLS.

To use encrypted transport through TLS, configure both the server and the client. The server collects and analyzes the logs sent by one or more client systems.

You can use either the **ossli** network stream driver (OpenSSL) or the **gtls** stream driver (GnuTLS).

**NOTE**

If you have a separate system with higher security, for example, a system that is not connected to any network or has stricter authorizations, use the separate system as the certifying authority (CA).

You can customize your connection settings with stream drivers on the server side on the **global**, **module**, and **input** levels, and on the client side on the **global** and **action** levels. The more specific configuration overrides the more general configuration. This means, for example, that you can use **ossli** in global settings for most connections and **gtls** on the input and action settings only for specific connections.

Prerequisites

- You have **root** access to both the client and server systems.
- The following packages are installed on the server and the client systems:
 - The **rsyslog** package.
 - For the **ossl** network stream driver, the **rsyslog-openssl** package.
 - For the **gtls** network stream driver, the **rsyslog-gnutls** package.
 - For generating certificates by using the **certtool** command, the **gnutls-utils** package.
- On your logging server, the following certificates are in the **/etc/pki/ca-trust/source/anchors/** directory and your system configuration is updated by using the **update-ca-trust** command:
 - **ca-cert.pem** - a CA certificate that can verify keys and certificates on logging servers and clients.
 - **server-cert.pem** - a public key of the logging server.
 - **server-key.pem** - a private key of the logging server.
- On your logging clients, the following certificates are in the **/etc/pki/ca-trust/source/anchors/** directory and your system configuration is updated by using **update-ca-trust**:
 - **ca-cert.pem** - a CA certificate that can verify keys and certificates on logging servers and clients.
 - **client-cert.pem** - a public key of a client.
 - **client-key.pem** - a private key of a client.

Procedure

1. Configure the server for receiving encrypted logs from your client systems:
 - a. Create a new file in the **/etc/rsyslog.d/** directory named, for example, **securelogser.conf**.
 - b. To encrypt the communication, the configuration file must contain paths to certificate files on your server, a selected authentication method, and a stream driver that supports TLS encryption. Add the following lines to the **/etc/rsyslog.d/securelogser.conf** file:

```
# Set certificate files
global(
    DefaultNetstreamDriverCAFile="/etc/pki/ca-trust/source/anchors/ca-cert.pem"
    DefaultNetstreamDriverCertFile="/etc/pki/ca-trust/source/anchors/server-cert.pem"
    DefaultNetstreamDriverKeyFile="/etc/pki/ca-trust/source/anchors/server-key.pem"
)

# TCP listener
module(
    load="imtcp"
    PermittedPeer=["client1.example.com", "client2.example.com"]
    StreamDriver.AuthMode="x509/name"
    StreamDriver.Mode="1"
    StreamDriver.Name="ossl"
)
```

```
# Start up listener at port 514
input(
    type="imtcp"
    port="514"
)
```

**NOTE**

If you prefer the GnuTLS driver, use the **StreamDriver.Name="gtls"** configuration option. See the documentation installed with the **rsyslog-doc** package for more information about less strict authentication modes than **x509/name**.

- c. Save the changes to the **/etc/rsyslog.d/securelogser.conf** file.
- d. Verify the syntax of the **/etc/rsyslog.conf** file and any files in the **/etc/rsyslog.d/** directory:

```
# rsyslogd -N 1
rsyslogd: version 8.1911.0-2.el8, config validation run (level 1)...
rsyslogd: End of config validation run. Bye.
```

- e. Make sure the **rsyslog** service is running and enabled on the logging server:

```
# systemctl status rsyslog
```

- f. Restart the **rsyslog** service:

```
# systemctl restart rsyslog
```

- g. Optional: If Rsyslog is not enabled, ensure the **rsyslog** service starts automatically after reboot:

```
# systemctl enable rsyslog
```

2. Configure clients for sending encrypted logs to the server:

- a. On a client system, create a new file in the **/etc/rsyslog.d/** directory named, for example, **securelogcli.conf**.
- b. Add the following lines to the **/etc/rsyslog.d/securelogcli.conf** file:

```
# Set certificate files
global(
    DefaultNetstreamDriverCAFile="/etc/pki/ca-trust/source/anchors/ca-cert.pem"
    DefaultNetstreamDriverCertFile="/etc/pki/ca-trust/source/anchors/client-cert.pem"
    DefaultNetstreamDriverKeyFile="/etc/pki/ca-trust/source/anchors/client-key.pem"
)

# Set up the action for all messages
*. * action(
    type="omfwd"
    StreamDriver="oss"
)
```

```
StreamDriverMode="1"
StreamDriverPermittedPeers="server.example.com"
StreamDriverAuthMode="x509/name"
target="server.example.com" port="514" protocol="tcp"
)
```



NOTE

If you prefer the GnuTLS driver, use the **StreamDriver.Name="gtls"** configuration option.

- c. Save the changes to the **/etc/rsyslog.d/securelogcli.conf** file.
- d. Verify the syntax of the **/etc/rsyslog.conf** file and other files in the **/etc/rsyslog.d/** directory:

```
# rsyslogd -N 1
rsyslogd: version 8.1911.0-2.el8, config validation run (level 1)...
rsyslogd: End of config validation run. Bye.
```

- e. Make sure the **rsyslog** service is running and enabled on the logging server:

```
# systemctl status rsyslog
```

- f. Restart the **rsyslog** service:

```
# systemctl restart rsyslog
```

- g. Optional: If Rsyslog is not enabled, ensure the **rsyslog** service starts automatically after reboot:

```
# systemctl enable rsyslog
```

Verification

To verify that the client system sends messages to the server, follow these steps:

1. On the client system, send a test message:

```
# logger test
```

2. On the server system, view the **/var/log/messages** log, for example:

```
# cat /var/log/remote/msg/<hostname>/root.log
Feb 25 03:53:17 <hostname> root[6064]: test
```

Where **<hostname>** is the hostname of the client system. Note that the log contains the user name of the user that entered the logger command, in this case **root**.

Additional resources

- **certtool(1)**, **openssl(1)**, **update-ca-trust(8)**, **rsyslogd(8)**, and **rsyslog.conf(5)** man pages on your system

- Documentation installed with the **rsyslog-doc** package at **/usr/share/doc/rsyslog/html/index.html**.
- [Using the logging system role with TLS](#) .

8.1.6. Configuring a server for receiving remote logging information over UDP

The **Rsyslog** application enables you to configure a system to receive logging information from remote systems. To use remote logging through UDP, configure both the server and the client. The receiving server collects and analyzes the logs sent by one or more client systems. By default, **rsyslog** uses UDP on port **514** to receive log information from remote systems.

Follow this procedure to configure a server for collecting and analyzing logs sent by one or more client systems over the UDP protocol.

Prerequisites

- Rsyslog is installed on the server system.
- You are logged in as **root** on the server.
- The **polycoreutils-python-utils** package is installed for the optional step using the **semanage** command.
- The **firewalld** service is running.

Procedure

1. Optional: To use a different port for **rsyslog** traffic than the default port **514**:
 - a. Add the **syslogd_port_t** SELinux type to the SELinux policy configuration, replacing **portno** with the port number you want **rsyslog** to use:

```
# semanage port -a -t syslogd_port_t -p udp portno
```

- b. Configure **firewalld** to allow incoming **rsyslog** traffic, replacing **portno** with the port number and **zone** with the zone you want **rsyslog** to use:

```
# firewall-cmd --zone=zone --permanent --add-port=portno/udp
success
# firewall-cmd --reload
```

- c. Reload the firewall rules:

```
# firewall-cmd --reload
```

2. Create a new **.conf** file in the **/etc/rsyslog.d/** directory, for example, **remotelogserv.conf**, and insert the following content:

```
# Define templates before the rules that use them
# Per-Host templates for remote systems
template(name="TmplAuthpriv" type="list") {
    constant(value="/var/log/remote/auth/")
    property(name="hostname")
}
```

```

    constant(value="/")
    property(name="programname" SecurePath="replace")
    constant(value=".log")
}

template(name="TplMsg" type="list") {
    constant(value="/var/log/remote/msg/")
    property(name="hostname")
    constant(value="/")
    property(name="programname" SecurePath="replace")
    constant(value=".log")
}

# Provides UDP syslog reception
module(load="imudp")

# This ruleset processes remote messages
ruleset(name="remote1"){
    authpriv.* action(type="omfile" DynaFile="TplAuthpriv")
    *.info;mail.none;authpriv.none;cron.none
    action(type="omfile" DynaFile="TplMsg")
}

input(type="imudp" port="514" ruleset="remote1")

```

Where **514** is the port number **rsyslog** uses by default. You can specify a different port instead.

3. Verify the syntax of the **/etc/rsyslog.conf** file and all **.conf** files in the **/etc/rsyslog.d/** directory:

```

# rsyslogd -N 1
rsyslogd: version 8.1911.0-2.el8, config validation run...

```

4. Restart the **rsyslog** service.

```

# systemctl restart rsyslog

```

5. Optional: If **rsyslog** is not enabled, ensure the **rsyslog** service starts automatically after reboot:

```

# systemctl enable rsyslog

```

Additional resources

- **rsyslogd(8)**, **rsyslog.conf(5)**, **semanage(8)**, and **firewall-cmd(1)** man pages on your system
- Documentation installed with the **rsyslog-doc** package in the **/usr/share/doc/rsyslog/html/index.html** file

8.1.7. Configuring remote logging to a server over UDP

You can configure a system for forwarding log messages to a server over the UDP protocol. The **omfwd** plug-in provides forwarding over UDP or TCP. The default protocol is UDP. Because the plug-in is built in, you do not have to load it.

Prerequisites

- The **rsyslog** package is installed on the client systems that should report to the server.
- You have configured the server for remote logging as described in [Configuring a server for receiving remote logging information over UDP](#).

Procedure

1. Create a new **.conf** file in the **/etc/rsyslog.d/** directory, for example, **10-remotelogcli.conf**, and insert the following content:

```
*.* action(type="omfwd"
    queue.type="linkedlist"
    queue.filename="example_fwd"
    action.resumeRetryCount="-1"
    queue.saveOnShutdown="on"
    target="example.com" port="portno" protocol="udp"
)
```

Where:

- The **queue.type="linkedlist"** setting enables a LinkedList in-memory queue.
- The **queue.filename** setting defines a disk storage. The backup files are created with the **example_fwd** prefix in the working directory specified by the preceding global **workDirectory** directive.
- The **action.resumeRetryCount -1** setting prevents **rsyslog** from dropping messages when retrying to connect if the server is not responding.
- The **enabled queue.saveOnShutdown="on"** setting saves in-memory data if **rsyslog** shuts down.
- The **portno** value is the port number you want **rsyslog** to use. The default value is **514**.
- The last line forwards all received messages to the logging server, port specification is optional.
With this configuration, **rsyslog** sends messages to the server but keeps messages in memory if the remote server is not reachable. A file on disk is created only if **rsyslog** runs out of the configured memory queue space or needs to shut down, which benefits the system performance.



NOTE

Rsyslog processes configuration files **/etc/rsyslog.d/** in the lexical order.

2. Restart the **rsyslog** service.

```
# systemctl restart rsyslog
```

3. Optional: If **rsyslog** is not enabled, ensure the **rsyslog** service starts automatically after reboot:

```
# systemctl enable rsyslog
```

Verification

To verify that the client system sends messages to the server, follow these steps:

1. On the client system, send a test message:

```
# logger test
```

2. On the server system, view the `/var/log/remote/msg/hostname/root.log` log, for example:

```
# cat /var/log/remote/msg/hostname/root.log
Feb 25 03:53:17 hostname root[6064]: test
```

Where **hostname** is the host name of the client system. Note that the log contains the user name of the user that entered the logger command, in this case **root**.

Additional resources

- **rsyslogd(8)** and **rsyslog.conf(5)** man pages on your system
- Documentation installed with the **rsyslog-doc** package at `/usr/share/doc/rsyslog/html/index.html`

8.1.8. Load balancing helper in Rsyslog

When used in a cluster, you can improve Rsyslog load balancing by modifying the **RebindInterval** setting.

RebindInterval specifies an interval at which the current connection is broken and is re-established. This setting applies to TCP, UDP, and RELP traffic. The load balancers perceive it as a new connection and forward the messages to another physical target system.

RebindInterval is helpful in scenarios when a target system has changed its IP address. The Rsyslog application caches the IP address when the connection is established, therefore, the messages are sent to the same server. If the IP address changes, the UDP packets are lost until the Rsyslog service restarts. Re-establishing the connection ensures the IP is resolved by DNS again.

Example usage of RebindInterval for TCP, UDP, and RELP traffic

```
action(type="omfwd" protocol="tcp" RebindInterval="250" target="example.com" port="514" ...)
```

```
action(type="omfwd" protocol="udp" RebindInterval="250" target="example.com" port="514" ...)
```

```
action(type="omrelp" RebindInterval="250" target="example.com" port="6514" ...)
```

8.1.9. Configuring reliable remote logging

With the Reliable Event Logging Protocol (RELP), you can send and receive **syslog** messages over TCP with a much reduced risk of message loss. RELP provides reliable delivery of event messages, which makes it useful in environments where message loss is not acceptable. To use RELP, configure the **imrelp** input module, which runs on the server and receives the logs, and the **omrelp** output module, which runs on the client and sends logs to the logging server.

Prerequisites

- You have installed the **rsyslog**, **librelp**, and **rsyslog-relp** packages on the server and the client systems.
- The specified port is permitted in SELinux and open in the firewall.

Procedure

1. Configure the client system for reliable remote logging:

- a. On the client system, create a new **.conf** file in the **/etc/rsyslog.d/** directory named, for example, **relpclient.conf**, and insert the following content:

```
module(load="omrelp")
*. * action(type="omrelp" target="_target_IP_" port="_target_port_")
```

Where:

- **target_IP** is the IP address of the logging server.
 - **target_port** is the port of the logging server.
- b. Save the changes to the **/etc/rsyslog.d/relpclient.conf** file.
 - c. Restart the **rsyslog** service.

```
# systemctl restart rsyslog
```

- d. Optional: If **rsyslog** is not enabled, ensure the **rsyslog** service starts automatically after reboot:

```
# systemctl enable rsyslog
```

2. Configure the server system for reliable remote logging:

- a. On the server system, create a new **.conf** file in the **/etc/rsyslog.d/** directory named, for example, **relpserv.conf**, and insert the following content:

```
ruleset(name="relp"){
*. * action(type="omfile" file="_log_path_")
}

module(load="imrelp")
input(type="imrelp" port="_target_port_" ruleset="relp")
```

Where:

- **log_path** specifies the path for storing messages.
 - **target_port** is the port of the logging server. Use the same value as in the client configuration file.
- b. Save the changes to the **/etc/rsyslog.d/relpserv.conf** file.
 - c. Restart the **rsyslog** service.


```
# systemctl restart rsyslog
```

- d. Optional: If **rsyslog** is not enabled, ensure the **rsyslog** service starts automatically after reboot:

```
# systemctl enable rsyslog
```

Verification

To verify that the client system sends messages to the server, follow these steps:

1. On the client system, send a test message:

```
# logger test
```

2. On the server system, view the log at the specified **log_path**, for example:

```
# cat /var/log/remote/msg/hostname/root.log
Feb 25 03:53:17 hostname root[6064]: test
```

Where **hostname** is the host name of the client system. Note that the log contains the user name of the user that entered the logger command, in this case **root**.

Additional resources

- **rsyslogd(8)** and **rsyslog.conf(5)** man pages on your system
- Documentation installed with the **rsyslog-doc** package in the **/usr/share/doc/rsyslog/html/index.html** file

8.1.10. Supported Rsyslog modules

To expand the functionality of the Rsyslog application, you can use specific modules. Modules provide additional inputs (Input Modules), outputs (Output Modules), and other functionalities. A module can also provide additional configuration directives that become available after you load the module.

You can list the input and output modules installed on your system by entering the following command:

```
# ls /usr/lib64/rsyslog/{i,o}m*
```

You can view the list of all available **rsyslog** modules in the **/usr/share/doc/rsyslog/html/configuration/modules/idx_output.html** file after you install the **rsyslog-doc** package.

8.1.11. Configuring the netconsole service to log kernel messages to a remote host

When logging to disk or using a serial console is not possible, you can use the **netconsole** kernel module and the same-named service to log kernel messages over a network to a remote **rsyslog** service.

Prerequisites

- A system log service, such as **rsyslog** is installed on the remote host.

- The remote system log service is configured to receive incoming log entries from this host.

Procedure

1. Install the **netconsole-service** package:

```
# yum install netconsole-service
```

2. Edit the **/etc/sysconfig/netconsole** file and set the **SYSLOGADDR** parameter to the IP address of the remote host:

```
# SYSLOGADDR=192.0.2.1
```

3. Enable and start the **netconsole** service:

```
# systemctl enable --now netconsole
```

Verification

- Display the **/var/log/messages** file on the remote system log server.

8.1.12. Additional resources

- Documentation installed with the **rsyslog-doc** package in the **/usr/share/doc/rsyslog/html/index.html** file
- **rsyslog.conf(5)** and **rsyslogd(8)** man pages on your system
- [Configuring system logging without journald or with minimized journald usage](#) Knowledgebase article
- [Negative effects of the RHEL default logging setup on performance and their mitigations](#) Knowledgebase article
- The [Using the Logging system role](#) chapter

8.2. USING THE LOGGING SYSTEM ROLE

As a system administrator, you can use the **logging** system role to configure a Red Hat Enterprise Linux host as a logging server to collect logs from many client systems.

8.2.1. Filtering local log messages by using the logging RHEL system role

You can use the property-based filter of the **logging** RHEL system role to filter your local log messages based on various conditions. As a result, you can achieve for example:

- Log clarity: In a high-traffic environment, logs can grow rapidly. The focus on specific messages, like errors, can help to identify problems faster.
- Optimized system performance: Excessive amount of logs is usually connected with system performance degradation. Selective logging for only the important events can prevent resource depletion, which enables your systems to run more efficiently.

- Enhanced security: Efficient filtering through security messages, like system errors and failed logins, helps to capture only the relevant logs. This is important for detecting breaches and meeting compliance standards.

Prerequisites

- [You have prepared the control node and the managed nodes](#)
- You are logged in to the control node as a user who can run playbooks on the managed nodes.
- The account you use to connect to the managed nodes has **sudo** permissions on them.

Procedure

1. Create a playbook file, for example `~/playbook.yml`, with the following content:

```
---
- name: Deploy the logging solution
  hosts: managed-node-01.example.com
  tasks:
    - name: Filter logs based on a specific value they contain
      ansible.builtin.include_role:
        name: redhat.rhel_system_roles.logging
      vars:
        logging_inputs:
          - name: files_input
            type: basics
        logging_outputs:
          - name: files_output0
            type: files
            property: msg
            property_op: contains
            property_value: error
            path: /var/log/errors.log
          - name: files_output1
            type: files
            property: msg
            property_op: "!contains"
            property_value: error
            path: /var/log/others.log
        logging_flows:
          - name: flow0
            inputs: [files_input]
            outputs: [files_output0, files_output1]
```

The settings specified in the example playbook include the following:

logging_inputs

Defines a list of logging input dictionaries. The **type: basics** option covers inputs from **systemd** journal or Unix socket.

logging_outputs

Defines a list of logging output dictionaries. The **type: files** option supports storing logs in the local files, usually in the `/var/log/` directory. The **property: msg**; **property: contains**; and **property_value: error** options specify that all logs that contain the **error** string are stored in

the `/var/log/errors.log` file. The **property: msg**; **property: !contains**; and **property_value: error** options specify that all other logs are put in the `/var/log/others.log` file. You can replace the **error** value with the string by which you want to filter.

logging_flows

Defines a list of logging flow dictionaries to specify relationships between **logging_inputs** and **logging_outputs**. The **inputs: [files_input]** option specifies a list of inputs, from which processing of logs starts. The **outputs: [files_output0, files_output1]** option specifies a list of outputs, to which the logs are sent.

For details about all variables used in the playbook, see the `/usr/share/ansible/roles/rhel-system-roles.logging/README.md` file on the control node.

2. Validate the playbook syntax:

```
$ ansible-playbook --syntax-check ~/playbook.yml
```

Note that this command only validates the syntax and does not protect against a wrong but valid configuration.

3. Run the playbook:

```
$ ansible-playbook ~/playbook.yml
```

Verification

1. On the managed node, test the syntax of the `/etc/rsyslog.conf` file:

```
# rsyslogd -N 1
rsyslogd: version 8.1911.0-6.el8, config validation run...
rsyslogd: End of config validation run. Bye.
```

2. On the managed node, verify that the system sends messages that contain the **error** string to the log:

- a. Send a test message:

```
# logger error
```

- b. View the `/var/log/errors.log` log, for example:

```
# cat /var/log/errors.log
Aug  5 13:48:31 hostname root[6778]: error
```

Where **hostname** is the host name of the client system. Note that the log contains the user name of the user that entered the logger command, in this case **root**.

Additional resources

- `/usr/share/ansible/roles/rhel-system-roles.logging/README.md` file
- `/usr/share/doc/rhel-system-roles/logging/` directory
- **rsyslog.conf(5)** and **syslog(3)** man pages on your system

8.2.2. Applying a remote logging solution by using the logging RHEL system role

You can use the **logging** RHEL system role to configure a remote logging solution, where one or more clients take logs from the **systemd-journal** service and forward them to a remote server. The server receives remote input from the **remote_rsyslog** and **remote_files** configurations, and outputs the logs to local files in directories named by remote host names.

As a result, you can cover use cases where you need for example:

- Centralized log management: Collecting, accessing, and managing log messages of multiple machines from a single storage point simplifies day-to-day monitoring and troubleshooting tasks. Also, this use case reduces the need to log into individual machines to check the log messages.
- Enhanced security: Storing log messages in one central place increases chances they are in a secure and tamper-proof environment. Such an environment makes it easier to detect and respond to security incidents more effectively and to meet audit requirements.
- Improved efficiency in log analysis: Correlating log messages from multiple systems is important for fast troubleshooting of complex problems that span multiple machines or services. That way you can quickly analyze and cross-reference events from different sources.

Prerequisites

- [You have prepared the control node and the managed nodes](#)
- You are logged in to the control node as a user who can run playbooks on the managed nodes.
- The account you use to connect to the managed nodes has **sudo** permissions on them.
- Define the ports in the SELinux policy of the server or client system and open the firewall for those ports. The default SELinux policy includes ports 601, 514, 6514, 10514, and 20514. To use a different port, see [modify the SELinux policy on the client and server systems](#).

Procedure

1. Create a playbook file, for example `~/playbook.yml`, with the following content:

```
---
- name: Deploy the logging solution
  hosts: managed-node-01.example.com
  tasks:
    - name: Configure the server to receive remote input
      ansible.builtin.include_role:
        name: redhat.rhel_system_roles.logging
      vars:
        logging_inputs:
          - name: remote_udp_input
            type: remote
            udp_ports: [ 601 ]
          - name: remote_tcp_input
            type: remote
            tcp_ports: [ 601 ]
        logging_outputs:
          - name: remote_files_output
            type: remote_files
```

```

logging_flows:
  - name: flow_0
    inputs: [remote_udp_input, remote_tcp_input]
    outputs: [remote_files_output]

- name: Deploy the logging solution
  hosts: managed-node-02.example.com
  tasks:
    - name: Configure the server to output the logs to local files in directories named by
      remote host names
      ansible.builtin.include_role:
        name: redhat.rhel_system_roles.logging
      vars:
        logging_inputs:
          - name: basic_input
            type: basics
        logging_outputs:
          - name: forward_output0
            type: forwards
            severity: info
            target: <host1.example.com>
            udp_port: 601
          - name: forward_output1
            type: forwards
            facility: mail
            target: <host1.example.com>
            tcp_port: 601
        logging_flows:
          - name: flows0
            inputs: [basic_input]
            outputs: [forward_output0, forward_output1]

```

The settings specified in the first play of the example playbook include the following:

logging_inputs

Defines a list of logging input dictionaries. The **type: remote** option covers remote inputs from the other logging system over the network. The **udp_ports: [601]** option defines a list of UDP port numbers to monitor. The **tcp_ports: [601]** option defines a list of TCP port numbers to monitor. If both **udp_ports** and **tcp_ports** is set, **udp_ports** is used and **tcp_ports** is dropped.

logging_outputs

Defines a list of logging output dictionaries. The **type: remote_files** option makes output store logs to the local files per remote host and program name originated the logs.

logging_flows

Defines a list of logging flow dictionaries to specify relationships between **logging_inputs** and **logging_outputs**. The **inputs: [remote_udp_input, remote_tcp_input]** option specifies a list of inputs, from which processing of logs starts. The **outputs: [remote_files_output]** option specifies a list of outputs, to which the logs are sent.

The settings specified in the second play of the example playbook include the following:

logging_inputs

Defines a list of logging input dictionaries. The **type: basics** option covers inputs from **systemd** journal or Unix socket.

logging_outputs

Defines a list of logging output dictionaries. The **type: forwards** option supports sending logs to the remote logging server over the network. The **severity: info** option refers to log messages of the informative importance. The **facility: mail** option refers to the type of system program that is generating the log message. The **target: <host1.example.com>** option specifies the hostname of the remote logging server. The **udp_port: 601/tcp_port: 601** options define the UDP/TCP ports on which the remote logging server listens.

logging_flows

Defines a list of logging flow dictionaries to specify relationships between **logging_inputs** and **logging_outputs**. The **inputs: [basic_input]** option specifies a list of inputs, from which processing of logs starts. The **outputs: [forward_output0, forward_output1]** option specifies a list of outputs, to which the logs are sent.

For details about all variables used in the playbook, see the **/usr/share/ansible/roles/rhel-system-roles.logging/README.md** file on the control node.

2. Validate the playbook syntax:

```
$ ansible-playbook --syntax-check ~/playbook.yml
```

Note that this command only validates the syntax and does not protect against a wrong but valid configuration.

3. Run the playbook:

```
$ ansible-playbook ~/playbook.yml
```

Verification

1. On both the client and the server system, test the syntax of the **/etc/rsyslog.conf** file:

```
# rsyslogd -N 1
rsyslogd: version 8.1911.0-6.el8, config validation run (level 1), master config
/etc/rsyslog.conf
rsyslogd: End of config validation run. Bye.
```

2. Verify that the client system sends messages to the server:

- a. On the client system, send a test message:

```
# logger test
```

- b. On the server system, view the **/var/log/<host2.example.com>/messages** log, for example:

```
# cat /var/log/<host2.example.com>/messages
Aug 5 13:48:31 <host2.example.com> root[6778]: test
```

Where **<host2.example.com>** is the host name of the client system. Note that the log contains the user name of the user that entered the logger command, in this case **root**.

Additional resources

- **/usr/share/ansible/roles/rhel-system-roles.logging/README.md** file

- `/usr/share/doc/rhel-system-roles/logging/` directory
- `rsyslog.conf(5)` and `syslog(3)` manual pages

8.2.3. Using the logging RHEL system role with TLS

Transport Layer Security (TLS) is a cryptographic protocol designed to allow secure communication over the computer network.

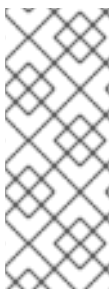
You can use the **logging** RHEL system role to configure a secure transfer of log messages, where one or more clients take logs from the **systemd-journal** service and transfer them to a remote server while using TLS.

Typically, TLS for transferring logs in a remote logging solution is used when sending sensitive data over less trusted or public networks, such as the Internet. Also, by using certificates in TLS you can ensure that the client is forwarding logs to the correct and trusted server. This prevents attacks like "man-in-the-middle".

8.2.3.1. Configuring client logging with TLS

You can use the **logging** RHEL system role to configure logging on RHEL clients and transfer logs to a remote logging system using TLS encryption.

This procedure creates a private key and a certificate. Next, it configures TLS on all hosts in the clients group in the Ansible inventory. The TLS protocol encrypts the message transmission for secure transfer of logs over the network.



NOTE

You do not have to call the **certificate** RHEL system role in the playbook to create the certificate. The **logging** RHEL system role calls it automatically when the **logging_certificates** variable is set.

In order for the CA to be able to sign the created certificate, the managed nodes must be enrolled in an IdM domain.

Prerequisites

- [You have prepared the control node and the managed nodes](#)
- You are logged in to the control node as a user who can run playbooks on the managed nodes.
- The account you use to connect to the managed nodes has **sudo** permissions on them.
- The managed nodes are enrolled in an IdM domain.

Procedure

1. Create a playbook file, for example `~/playbook.yml`, with the following content:

```
---
- name: Configure remote logging solution using TLS for secure transfer of logs
  hosts: managed-node-01.example.com
  tasks:
    - name: Deploying files input and forwards output with certs
```



```

ansible.builtin.include_role:
  name: redhat.rhel_system_roles.logging
vars:
  logging_certificates:
    - name: logging_cert
      dns: ['www.example.com']
      ca: ipa
      principal: "logging/{{ inventory_hostname }}@IDM.EXAMPLE.COM"
  logging_pki_files:
    - ca_cert: /local/path/to/ca_cert.pem
      cert: /local/path/to/logging_cert.pem
      private_key: /local/path/to/logging_cert.pem
  logging_inputs:
    - name: input_name
      type: files
      input_log_path: /var/log/containers/*.log
  logging_outputs:
    - name: output_name
      type: forwards
      target: your_target_host
      tcp_port: 514
      tls: true
      pki_authmode: x509/name
      permitted_server: 'server.example.com'
  logging_flows:
    - name: flow_name
      inputs: [input_name]
      outputs: [output_name]

```

The settings specified in the example playbook include the following:

logging_certificates

The value of this parameter is passed on to **certificate_requests** in the **certificate** RHEL system role and used to create a private key and certificate.

logging_pki_files

Using this parameter, you can configure the paths and other settings that logging uses to find the CA, certificate, and key files used for TLS, specified with one or more of the following sub-parameters: **ca_cert**, **ca_cert_src**, **cert**, **cert_src**, **private_key**, **private_key_src**, and **tls**.



NOTE

If you are using **logging_certificates** to create the files on the managed node, do not use **ca_cert_src**, **cert_src**, and **private_key_src**, which are used to copy files not created by **logging_certificates**.

ca_cert

Represents the path to the CA certificate file on the managed node. Default path is **/etc/pki/tls/certs/ca.pem** and the file name is set by the user.

cert

Represents the path to the certificate file on the managed node. Default path is **/etc/pki/tls/certs/server-cert.pem** and the file name is set by the user.

private_key

Represents the path to the private key file on the managed node. Default path is **/etc/pki/tls/private/server-key.pem** and the file name is set by the user.

ca_cert_src

Represents the path to the CA certificate file on the control node which is copied to the target host to the location specified by **ca_cert**. Do not use this if using **logging_certificates**.

cert_src

Represents the path to a certificate file on the control node which is copied to the target host to the location specified by **cert**. Do not use this if using **logging_certificates**.

private_key_src

Represents the path to a private key file on the control node which is copied to the target host to the location specified by **private_key**. Do not use this if using **logging_certificates**.

tls

Setting this parameter to **true** ensures secure transfer of logs over the network. If you do not want a secure wrapper, you can set **tls: false**.

For details about all variables used in the playbook, see the **/usr/share/ansible/roles/rhel-system-roles.logging/README.md** file on the control node.

2. Validate the playbook syntax:

```
$ ansible-playbook --syntax-check ~/playbook.yml
```

Note that this command only validates the syntax and does not protect against a wrong but valid configuration.

3. Run the playbook:

```
$ ansible-playbook ~/playbook.yml
```

Additional resources

- **/usr/share/ansible/roles/rhel-system-roles.logging/README.md** file
- **/usr/share/doc/rhel-system-roles/logging/** directory
- **/usr/share/ansible/roles/rhel-system-roles.certificate/README.md** file
- **/usr/share/doc/rhel-system-roles/certificate/** directory
- [Requesting certificates using RHEL system roles](#) .
- **rsyslog.conf(5)** and **syslog(3)** manual pages

8.2.3.2. Configuring server logging with TLS

You can use the **logging** RHEL system role to configure logging on RHEL servers and set them to receive logs from a remote logging system using TLS encryption.

This procedure creates a private key and a certificate. Next, it configures TLS on all hosts in the server group in the Ansible inventory.



NOTE

You do not have to call the **certificate** RHEL system role in the playbook to create the certificate. The **logging** RHEL system role calls it automatically.

In order for the CA to be able to sign the created certificate, the managed nodes must be enrolled in an IdM domain.

Prerequisites

- You have prepared the control node and the managed nodes
- You are logged in to the control node as a user who can run playbooks on the managed nodes.
- The account you use to connect to the managed nodes has **sudo** permissions on them.
- The managed nodes are enrolled in an IdM domain.

Procedure

1. Create a playbook file, for example `~/playbook.yml`, with the following content:

```
---
- name: Configure remote logging solution using TLS for secure transfer of logs
  hosts: managed-node-01.example.com
  tasks:
    - name: Deploying remote input and remote_files output with certs
      ansible.builtin.include_role:
        name: redhat.rhel_system_roles.logging
      vars:
        logging_certificates:
          - name: logging_cert
            dns: ['www.example.com']
            ca: ipa
            principal: "logging/{{ inventory_hostname }}@IDM.EXAMPLE.COM"
        logging_pki_files:
          - ca_cert: /local/path/to/ca_cert.pem
            cert: /local/path/to/logging_cert.pem
            private_key: /local/path/to/logging_cert.pem
        logging_inputs:
          - name: input_name
            type: remote
            tcp_ports: [514]
            tls: true
            permitted_clients: ['clients.example.com']
        logging_outputs:
          - name: output_name
            type: remote_files
            remote_log_path: /var/log/remote/%FROMHOST%/PROGRAMNAME:::secpath-
              replace%.log
            async_writing: true
            client_count: 20
            io_buffer_size: 8192
        logging_flows:
```

```
- name: flow_name
  inputs: [input_name]
  outputs: [output_name]
```

The settings specified in the example playbook include the following:

logging_certificates

The value of this parameter is passed on to **certificate_requests** in the **certificate** RHEL system role and used to create a private key and certificate.

logging_pki_files

Using this parameter, you can configure the paths and other settings that logging uses to find the CA, certificate, and key files used for TLS, specified with one or more of the following sub-parameters: **ca_cert**, **ca_cert_src**, **cert**, **cert_src**, **private_key**, **private_key_src**, and **tls**.



NOTE

If you are using **logging_certificates** to create the files on the managed node, do not use **ca_cert_src**, **cert_src**, and **private_key_src**, which are used to copy files not created by **logging_certificates**.

ca_cert

Represents the path to the CA certificate file on the managed node. Default path is **/etc/pki/tls/certs/ca.pem** and the file name is set by the user.

cert

Represents the path to the certificate file on the managed node. Default path is **/etc/pki/tls/certs/server-cert.pem** and the file name is set by the user.

private_key

Represents the path to the private key file on the managed node. Default path is **/etc/pki/tls/private/server-key.pem** and the file name is set by the user.

ca_cert_src

Represents the path to the CA certificate file on the control node which is copied to the target host to the location specified by **ca_cert**. Do not use this if using **logging_certificates**.

cert_src

Represents the path to a certificate file on the control node which is copied to the target host to the location specified by **cert**. Do not use this if using **logging_certificates**.

private_key_src

Represents the path to a private key file on the control node which is copied to the target host to the location specified by **private_key**. Do not use this if using **logging_certificates**.

tls

Setting this parameter to **true** ensures secure transfer of logs over the network. If you do not want a secure wrapper, you can set **tls: false**.

For details about all variables used in the playbook, see the **/usr/share/ansible/roles/rhel-system-roles.logging/README.md** file on the control node.

2. Validate the playbook syntax:

```
$ ansible-playbook --syntax-check ~/playbook.yml
```

Note that this command only validates the syntax and does not protect against a wrong but valid configuration.

3. Run the playbook:

```
$ ansible-playbook ~/playbook.yml
```

Additional resources

- `/usr/share/ansible/roles/rhel-system-roles/logging/README.md` file
- `/usr/share/doc/rhel-system-roles/logging/` directory
- [Requesting certificates using RHEL system roles](#) .
- `rsyslog.conf(5)` and `syslog(3)` manual pages

8.2.4. Using the logging RHEL system roles with RELP

Reliable Event Logging Protocol (RELP) is a networking protocol for data and message logging over the TCP network. It ensures reliable delivery of event messages and you can use it in environments that do not tolerate any message loss.

The RELP sender transfers log entries in the form of commands and the receiver acknowledges them once they are processed. To ensure consistency, RELP stores the transaction number to each transferred command for any kind of message recovery.

You can consider a remote logging system in between the RELP Client and RELP Server. The RELP Client transfers the logs to the remote logging system and the RELP Server receives all the logs sent by the remote logging system. To achieve that use case, you can use the **logging** RHEL system role to configure the logging system to reliably send and receive log entries.

8.2.4.1. Configuring client logging with RELP

You can use the **logging** RHEL system role to configure a transfer of log messages stored locally to the remote logging system with RELP.

This procedure configures RELP on all hosts in the **clients** group in the Ansible inventory. The RELP configuration uses Transport Layer Security (TLS) to encrypt the message transmission for secure transfer of logs over the network.

Prerequisites

- [You have prepared the control node and the managed nodes](#)
- You are logged in to the control node as a user who can run playbooks on the managed nodes.
- The account you use to connect to the managed nodes has **sudo** permissions on them.

Procedure

1. Create a playbook file, for example `~/playbook.yml`, with the following content:

```
-
```

```

---
- name: Configure client-side of the remote logging solution using RELP
  hosts: managed-node-01.example.com
  tasks:
    - name: Deploy basic input and RELP output
      ansible.builtin.include_role:
        name: redhat.rhel_system_roles.logging
      vars:
        logging_inputs:
          - name: basic_input
            type: basics
        logging_outputs:
          - name: relp_client
            type: relp
            target: logging.server.com
            port: 20514
            tls: true
            ca_cert: /etc/pki/tls/certs/ca.pem
            cert: /etc/pki/tls/certs/client-cert.pem
            private_key: /etc/pki/tls/private/client-key.pem
            pki_authmode: name
            permitted_servers:
              - '*.server.example.com'
        logging_flows:
          - name: example_flow
            inputs: [basic_input]
            outputs: [relp_client]

```

The settings specified in the example playbook include the following:

target

This is a required parameter that specifies the host name where the remote logging system is running.

port

Port number the remote logging system is listening.

tls

Ensures secure transfer of logs over the network. If you do not want a secure wrapper you can set the **tls** variable to **false**. By default **tls** parameter is set to true while working with RELP and requires key/certificates and triplets **{ca_cert, cert, private_key}** and/or **{ca_cert_src, cert_src, private_key_src}**.

- If the **{ca_cert_src, cert_src, private_key_src}** triplet is set, the default locations **/etc/pki/tls/certs** and **/etc/pki/tls/private** are used as the destination on the managed node to transfer files from control node. In this case, the file names are identical to the original ones in the triplet
- If the **{ca_cert, cert, private_key}** triplet is set, files are expected to be on the default path before the logging configuration.
- If both triplets are set, files are transferred from local path from control node to specific path of the managed node.

ca_cert

Path to the CA certificate file on the managed node. Default: **/etc/pki/tls/certs/ca.pem**

Represents the path to CA certificate. Default path is **/etc/pki/tls/certs/ca.pem** and the file name is set by the user.

cert

Represents the path to certificate. Default path is **/etc/pki/tls/certs/server-cert.pem** and the file name is set by the user.

private_key

Represents the path to private key. Default path is **/etc/pki/tls/private/server-key.pem** and the file name is set by the user.

ca_cert_src

Represents local CA certificate file path which is copied to the managed node. If **ca_cert** is specified, it is copied to the location.

cert_src

Represents the local certificate file path which is copied to the managed node. If **cert** is specified, it is copied to the location.

private_key_src

Represents the local key file path which is copied to the managed node. If **private_key** is specified, it is copied to the location.

pki_authmode

Accepts the authentication mode as **name** or **fingerprint**.

permitted_servers

List of servers that will be allowed by the logging client to connect and send logs over TLS.

inputs

List of logging input dictionary.

outputs

List of logging output dictionary.

For details about all variables used in the playbook, see the **/usr/share/ansible/roles/rhel-system-roles.logging/README.md** file on the control node.

2. Validate the playbook syntax:

```
$ ansible-playbook --syntax-check ~/playbook.yml
```

Note that this command only validates the syntax and does not protect against a wrong but valid configuration.

3. Run the playbook:

```
$ ansible-playbook ~/playbook.yml
```

Additional resources

- **/usr/share/ansible/roles/rhel-system-roles.logging/README.md** file
- **/usr/share/doc/rhel-system-roles/logging/** directory
- **rsyslog.conf(5)** and **syslog(3)** manual pages

8.2.4.2. Configuring server logging with RELP

You can use the **logging** RHEL system role to configure a server for receiving log messages from the remote logging system with RELP.

This procedure configures RELP on all hosts in the **server** group in the Ansible inventory. The RELP configuration uses TLS to encrypt the message transmission for secure transfer of logs over the network.

Prerequisites

- You have prepared the control node and the managed nodes
- You are logged in to the control node as a user who can run playbooks on the managed nodes.
- The account you use to connect to the managed nodes has **sudo** permissions on them.

Procedure

1. Create a playbook file, for example `~/playbook.yml`, with the following content:

```
---
- name: Configure server-side of the remote logging solution using RELP
  hosts: managed-node-01.example.com
  tasks:
    - name: Deploying remote input and remote_files output
      ansible.builtin.include_role:
        name: redhat.rhel_system_roles.logging
      vars:
        logging_inputs:
          - name: relp_server
            type: relp
            port: 20514
            tls: true
            ca_cert: /etc/pki/tls/certs/ca.pem
            cert: /etc/pki/tls/certs/server-cert.pem
            private_key: /etc/pki/tls/private/server-key.pem
            pki_authmode: name
            permitted_clients:
              - '*client.example.com'
        logging_outputs:
          - name: remote_files_output
            type: remote_files
        logging_flows:
          - name: example_flow
            inputs: [relp_server]
            outputs: [remote_files_output]
```

The settings specified in the example playbook include the following:

port

Port number the remote logging system is listening.

tls

Ensures secure transfer of logs over the network. If you do not want a secure wrapper you can set the **tls** variable to **false**. By default **tls** parameter is set to true while working with RELP and requires key/certificates and triplets **{ca_cert, cert, private_key}** and/or **{ca_cert_src, cert_src, private_key_src}**.

- If the **{ca_cert_src, cert_src, private_key_src}** triplet is set, the default locations **/etc/pki/tls/certs** and **/etc/pki/tls/private** are used as the destination on the managed node to transfer files from control node. In this case, the file names are identical to the original ones in the triplet
- If the **{ca_cert, cert, private_key}** triplet is set, files are expected to be on the default path before the logging configuration.
- If both triplets are set, files are transferred from local path from control node to specific path of the managed node.

ca_cert

Represents the path to CA certificate. Default path is **/etc/pki/tls/certs/ca.pem** and the file name is set by the user.

cert

Represents the path to the certificate. Default path is **/etc/pki/tls/certs/server-cert.pem** and the file name is set by the user.

private_key

Represents the path to private key. Default path is **/etc/pki/tls/private/server-key.pem** and the file name is set by the user.

ca_cert_src

Represents local CA certificate file path which is copied to the managed node. If **ca_cert** is specified, it is copied to the location.

cert_src

Represents the local certificate file path which is copied to the managed node. If **cert** is specified, it is copied to the location.

private_key_src

Represents the local key file path which is copied to the managed node. If **private_key** is specified, it is copied to the location.

pki_authmode

Accepts the authentication mode as **name** or **fingerprint**.

permitted_clients

List of clients that will be allowed by the logging server to connect and send logs over TLS.

inputs

List of logging input dictionary.

outputs

List of logging output dictionary.

For details about all variables used in the playbook, see the **/usr/share/ansible/roles/rhel-system-roles.logging/README.md** file on the control node.

2. Validate the playbook syntax:

```
$ ansible-playbook --syntax-check ~/playbook.yml
```

Note that this command only validates the syntax and does not protect against a wrong but valid configuration.

3. Run the playbook:

```
$ ansible-playbook ~/playbook.yml
```

Additional resources

- `/usr/share/ansible/roles/rhel-system-roles.logging/README.md` file
- `/usr/share/doc/rhel-system-roles/logging/` directory
- `rsyslog.conf(5)` and `syslog(3)` manual pages

8.2.5. Additional resources

- [Preparing a control node and managed nodes to use RHEL system roles](#)
- Documentation installed with the **rhel-system-roles** package in `/usr/share/ansible/roles/rhel-system-roles.logging/README.html`.
- [RHEL system roles](#)
- **ansible-playbook(1)** man page on your system

CHAPTER 9. TROUBLESHOOTING PROBLEMS BY USING LOG FILES

Log files contain messages about the system, including the kernel, services, and applications running on it. These contain information that helps troubleshoot issues or monitor system functions. The logging system in Red Hat Enterprise Linux is based on the built-in **syslog** protocol. Particular programs use this system to record events and organize them into log files, which are useful when auditing the operating system and troubleshooting various problems.

9.1. SERVICES HANDLING SYSLOG MESSAGES

The following two services handle **syslog** messages:

- The **systemd-journald** daemon

The **systemd-journald** daemon collects messages from various sources and forwards them to **Rsyslog** for further processing. The **systemd-journald** daemon collects messages from the following sources:

- Kernel
- Early stages of the boot process
- Standard and error output of daemons as they start up and run
- **Syslog**
- The **Rsyslog** service

The **Rsyslog** service sorts the **syslog** messages by type and priority and writes them to the files in the **/var/log** directory. The **/var/log** directory persistently stores the log messages.

9.2. LOG FILES STORING SYSLOG MESSAGES

The following log files under the **/var/log** directory store **syslog** messages.

- **/var/log/messages** - all **syslog** messages except the following
- **/var/log/secure** - security and authentication-related messages and errors
- **/var/log/maillog** - mail server-related messages and errors
- **/var/log/cron** - log files related to periodically executed tasks
- **/var/log/boot.log** - log files related to system startup



NOTE

The above mentioned list contains only some files and the actual list of files in the **/var/log/** directory depends on which services and applications log in to this directory.

9.3. VIEWING LOGS USING THE COMMAND LINE

The Journal is a component of systemd that helps to view and manage log files. It addresses problems connected with traditional logging, closely integrated with the rest of the system, and supports various logging technologies and access management for log entries.

You can use the **journalctl** command to view messages in the system journal using the command line.

Table 9.1. Viewing system information

Command	Description
journalctl	Shows all collected journal entries.
journalctl FILEPATH	Shows logs related to a specific file. For example, the journalctl /dev/sda command displays logs related to the /dev/sda file system.
journalctl -b	Shows logs for the current boot.
journalctl -k -b -1	Shows kernel logs for the current boot.

Table 9.2. Viewing information about specific services

Command	Description
journalctl -b _SYSTEMD_UNIT=<name.service>	Filters log to show entries matching the systemd service.
journalctl -b _SYSTEMD_UNIT=<name.service> _PID=<number>	Combines matches. For example, this command shows logs for systemd-units that match <name.service> and the PID <number> .
journalctl -b _SYSTEMD_UNIT=<name.service> _PID=<number> + _SYSTEMD_UNIT=<name2.service>	The plus sign (+) separator combines two expressions in a logical OR. For example, this command shows all messages from the <name.service> service process with the PID plus all messages from the <name2.service> service (from any of its processes).
journalctl -b _SYSTEMD_UNIT=<name.service> _SYSTEMD_UNIT=<name2.service>	This command shows all entries matching either expression, referring to the same field. Here, this command shows logs matching a systemd-unit <name.service> or a systemd-unit <name2.service> .

Table 9.3. Viewing logs related to specific boots

Command	Description
---------	-------------

Command	Description
journalctl --list-boots	Shows a tabular list of boot numbers, their IDs, and the timestamps of the first and last message pertaining to the boot. You can use the ID in the next command to view detailed information.
journalctl --boot=ID _SYSTEMD_UNIT=<name.service>	Shows information about the specified boot ID.

9.4. REVIEWING LOGS IN THE WEB CONSOLE

Learn how to access, review and filter logs in the RHEL web console.

9.4.1. Reviewing logs in the web console

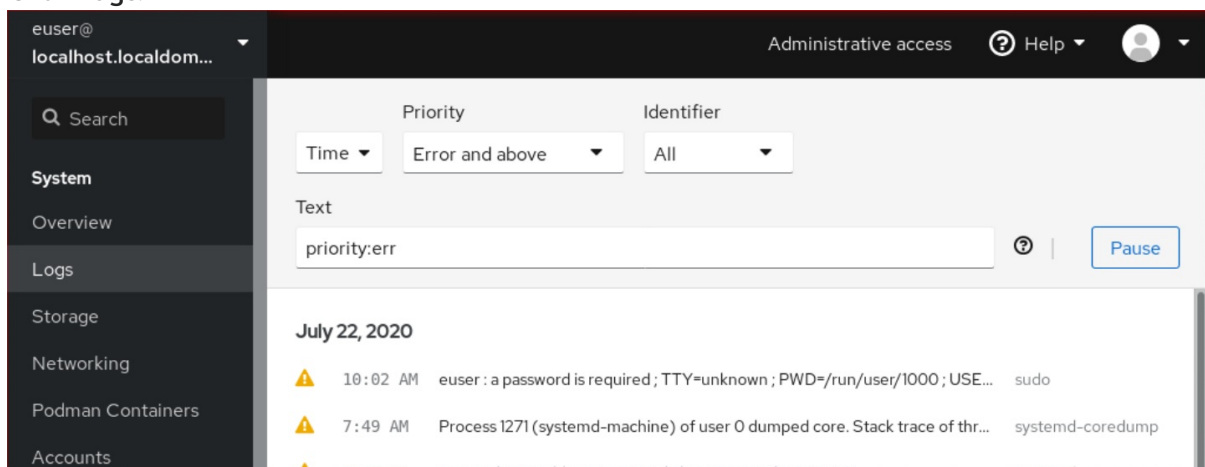
The RHEL 8 web console Logs section is a UI for the **journalctl** utility. You can access system logs in the web console interface.

Prerequisites

- You have installed the RHEL 8 web console.
- You have enabled the cockpit service.
- Your user account is allowed to log in to the web console.
For instructions, see [Installing and enabling the web console](#).

Procedure

1. Log in to the RHEL 8 web console.
For details, see [Logging in to the web console](#).
2. Click **Logs**.



3. Open log entry details by clicking on your selected log entry in the list.

**NOTE**

You can use the **Pause** button to pause new log entries from appearing. Once you resume new log entries, the web console will load all log entries that were reported after you used the **Pause** button.

You can filter the logs by time, priority or identifier. For more information, see [Filtering logs in the web console](#).

9.4.2. Filtering logs in the web console

You can filter log entries in the web console.

Prerequisites

- You have installed the RHEL 8 web console.
- You have enabled the cockpit service.
- Your user account is allowed to log in to the web console.
For instructions, see [Installing and enabling the web console](#).

Procedure

1. Log in to the RHEL 8 web console.
For details, see [Logging in to the web console](#).
2. Click **Logs**.
3. By default, web console shows the latest log entries. To filter by a specific time range, click the **Time** drop-down menu and choose a preferred option.
4. **Error and above** severity logs list is shown by default. To filter by different priority, click the **Error and above** drop-down menu and choose a preferred priority.
5. By default, web console shows logs for all identifiers. To filter logs for a particular identifier, click the **All** drop-down menu and select an identifier.
6. To open a log entry, click on a selected log.

9.4.3. Text search options for filtering logs in the web console

The text search option functionality provides a big variety of options for filtering logs. If you decide to filter logs by using the text search, you can use the predefined options that are defined in the three drop-down menus, or you can type the whole search yourself.

Drop-down menus

There are three drop-down menus that you can use to specify the main parameters of your search:

- **Time:** This drop-down menu contains predefined searches for different time ranges of your search.
- **Priority:** This drop-down menu provides options for different priority levels. It corresponds to the **journalctl --priority** option. The default priority value is **Error and above**. It is set every time you do not specify any other priority.

- **Identifier:** In this drop-down menu, you can select an identifier that you want to filter. Corresponds to the **journalctl --identifier** option.

Quantifiers

There are six quantifiers that you can use to specify your search. They are covered in the Options for filtering logs table.

Log fields

If you want to search for a specific log field, it is possible to specify the field together with its content.

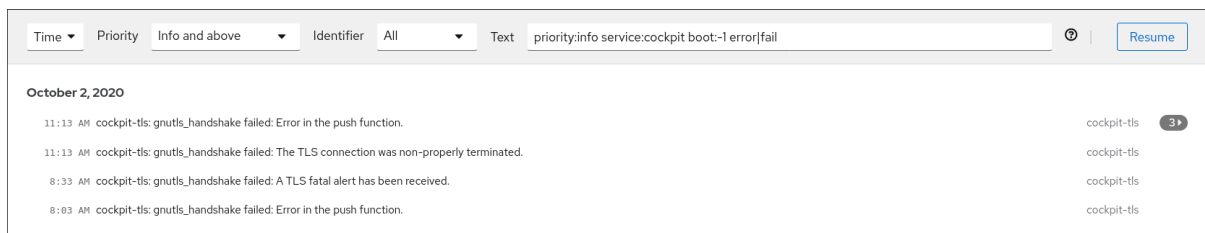
Free-form text search in logs messages

You can filter any text string of your choice in the logs messages. The string can also be in the form of a regular expressions.

Advanced logs filtering I

Filter all log messages identified by 'systemd' that happened since October 22, 2020 midnight and journal field 'JOB_TYPE' is either 'start' or 'restart'.

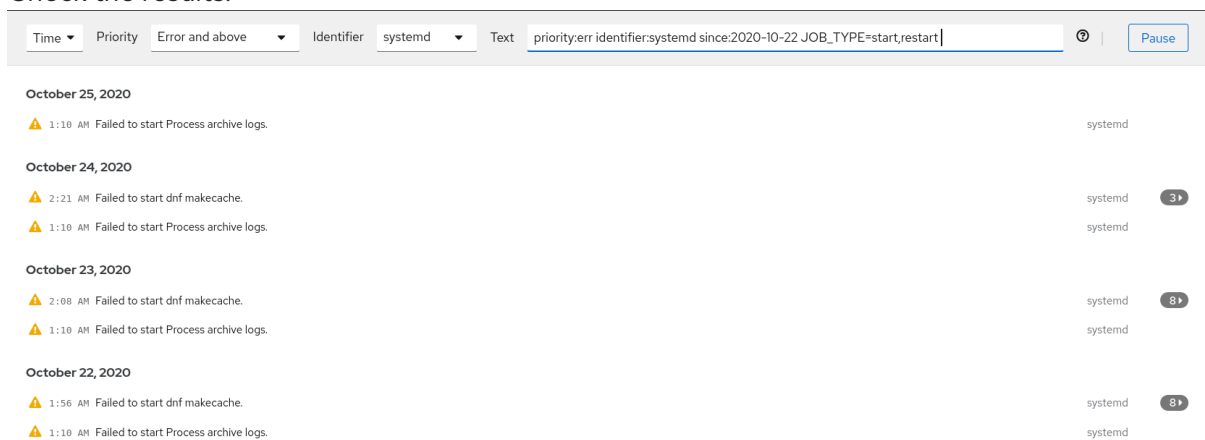
1. Type **identifier:systemd since:2020-10-22 JOB_TYPE=start,restart** to search field.
2. Check the results.



Advanced logs filtering II

Filter all log messages that come from 'cockpit.service' systemd unit that happened in the boot before last and the message body contains either "error" or "fail".

1. Type **service:cockpit boot:-1 error|fail** to the search field.
2. Check the results.



9.4.4. Using a text search box to filter logs in the web console

You can filter logs according to different parameters by using the text search box in the web console. The search combines usage of the filtering drop-down menus, quantifiers, log fields, and free-form string search.

Prerequisites

- You have installed the RHEL 8 web console.
- You have enabled the cockpit service.
- Your user account is allowed to log in to the web console.
For instructions, see [Installing and enabling the web console](#).

Procedure

1. Log in to the RHEL web console.
For details, see [Logging in to the web console](#).
2. Click **Logs**.
3. Use the drop-down menus to specify the three main quantifiers - time range, priority, and identifier(s) - you want to filter.
The **Priority** quantifier always has to have a value. If you do not specify it, it automatically filters the **Error and above** priority. Notice that the options you set reflect in the text search box.
4. Specify the log field you want to filter.
You can add several log fields.
5. You can use a free-form string to search for anything else. The search box also accepts regular expressions.

9.4.5. Options for logs filtering

There are several **journalctl** options, which you can use for filtering logs in the web console, that may be useful. Some of these are already covered as part of the drop-down menus in the web console interface.

Table 9.4. Table

Option name	Usage	Notes
priority	Filter output by message priorities. Takes a single numeric or textual log level. The log levels are the usual syslog log levels. If a single log level is specified, all messages with this log level or a lower (therefore more important) log level are shown.	Covered in the Priority drop-down menu.
identifier	Show messages for the specified syslog identifier SYSLOG_IDENTIFIER. Can be specified multiple times.	Covered in the Identifier drop-down menu.

Option name	Usage	Notes
follow	Shows only the most recent journal entries, and continuously prints new entries as they are appended to the journal.	Not covered in a drop-down.
service	Show messages for the specified systemd unit. Can be specified multiple times.	Is not covered in a drop-down. Corresponds to the journalctl --unit parameter.
boot	<p>Show messages from a specific boot.</p> <p>A positive integer will look up the boots starting from the beginning of the journal, and an equal-or-less-than zero integer will look up boots starting from the end of the journal. Therefore, 1 means the first boot found in the journal in chronological order, 2 the second and so on; while -0 is the last boot, -1 the boot before last, and so on.</p>	Covered only as Current boot or Previous boot in the Time drop-down menu. Other options need to be written manually.
since	<p>Start showing entries on or newer than the specified date, or on or older than the specified date, respectively. Date specifications should be of the format "2012-10-30 18:17:16". If the time part is omitted, "00:00:00" is assumed. If only the seconds component is omitted, ":00" is assumed. If the date component is omitted, the current day is assumed.</p> <p>Alternatively the strings "yesterday", "today", "tomorrow" are understood, which refer to 00:00:00 of the day before the current day, the current day, or the day after the current day, respectively. "now" refers to the current time. Finally, relative times may be specified, prefixed with "-" or "+", referring to times before or after the current time, respectively.</p>	Not covered in a drop-down.

9.5. ADDITIONAL RESOURCES

- **journalctl(1)** man page on your system
- [Configuring a remote logging solution](#)

CHAPTER 10. MANAGING USERS AND GROUPS

Preventing unauthorized access to files and processes requires accurate user and group management. If you do not manage accounts centrally or you require a user account or group only on a specific system, you can create them locally on a host.

10.1. INTRODUCTION TO MANAGING USER AND GROUP ACCOUNTS

The control of users and groups is a core element of Red Hat Enterprise Linux (RHEL) system administration. Each RHEL user has distinct login credentials and can be assigned to various groups to customize their system privileges.

10.1.1. Introduction to users and groups

A user who creates a file is the owner of that file *and* the group owner of that file. The file is assigned separate read, write, and execute permissions for the owner, the group, and those outside that group. The file owner can be changed only by the **root** user. Access permissions to the file can be changed by both the **root** user and the file owner. A regular user can change group ownership of a file they own to a group of which they are a member of.

Each user is associated with a unique numerical identification number called *user ID (UID)*. Each group is associated with a *group ID (GID)*. Users within a group share the same permissions to read, write, and execute files owned by that group.

10.1.2. Configuring reserved user and group IDs

By default, RHEL reserves user and group IDs below 1000 for system users and groups. You can find the reserved user and group IDs in the **setup** package. The UID's and GID's of users and groups created before you changed the **UID_MIN** and **GID_MIN** values do not change. The reserved user and group IDs are documented in the:

`/usr/share/doc/setup/uidgid`

To assign IDs to the new users and groups starting at 5000, as the reserved range can increase in the future.

Modify the **UID_MIN** and **GID_MIN** parameters in the `/etc/login.defs` file to define a start ID other than the defaults (1000).



WARNING

Do not raise IDs reserved by the system above 1000 by changing **SYS_UID_MAX** to avoid conflict with systems that retain the 1000 limit.

Procedure

1. Open the `/etc/login.defs` file in an editor.
2. Set the **UID_MIN** variable, for example:

```
# Min/max values for automatic uid selection in useradd
#
UID_MIN          5000
```

3. Set the **GID_MIN** variable, for example:

```
# Min/max values for automatic gid selection in groupadd
#
GID_MIN          5000
```

The dynamically assigned UIDs and GIDs for the regular users now start at 5000.

10.1.3. User private groups

RHEL uses the *user private group* (**UPG**) system configuration, which makes Linux groups easier to manage. A user private group is created whenever a new user is added to the system. The user private group has the same name as the user for which it was created and that user is the only member of the user private group.

UPGs simplify the collaboration on a project between multiple users. In addition, UPG system configuration makes it safe to set default permissions for a newly created file or directory, as it allows both the user, and the group this user is a part of, to make modifications to the file or directory.

A list of all local groups is stored in the **/etc/group** configuration file.

10.2. GETTING STARTED WITH MANAGING USER ACCOUNTS

Red Hat Enterprise Linux is a multi-user operating system, which enables multiple users on different computers to access a single system installed on one machine. Every user operates under its own account, and managing user accounts thus represents a core element of Red Hat Enterprise Linux system administration.

The following are the different types of user accounts:

- **Normal user accounts:**
Normal accounts are created for users of a particular system. Such accounts can be added, removed, and modified during normal system administration.
- **System user accounts:**
System user accounts represent a particular applications identifier on a system. Such accounts are generally added or manipulated only at software installation time, and they are not modified later.



WARNING

System accounts are presumed to be available locally on a system. If these accounts are configured and provided remotely, such as in the instance of an LDAP configuration, system breakage and service start failures can occur.

For system accounts, user IDs below 1000 are reserved. For normal accounts, you can use IDs starting at 1000. To define the min/max IDs for users and groups, system users and system groups, see the **/etc/login.defs** file.

- **Group:**

A group is an entity which ties together multiple user accounts for a common purpose, such as granting access to particular files.

10.2.1. Managing accounts and groups using command line tools

Use the following basic command-line tools to manage user accounts and groups.

Procedure

- Create a new user account:

```
# useradd example.user
```

- Assign a new password to a user account belonging to *example.user*:

```
# passwd example.user
```

- Add a user to a group:

```
# usermod -a -G example.group example.user
```

Additional resources

- **useradd(8)**, **passwd(1)**, and **usermod(8)** man pages

10.3. MANAGING USERS FROM THE COMMAND LINE

You can manage users and groups using the command-line interface (**CLI**). This enables you to add, remove, and modify users and user groups in Red Hat Enterprise Linux environment.

10.3.1. Adding a new user from the command line

You can use the **useradd** utility to add a new user.

Prerequisites

- You have **Root** access

Procedure

- Add a new user, use:

```
# useradd <options> <username>
```

Replace *options* with the command-line options for the **useradd** command, and replace *username* with the name of the user.

Example 10.1. Adding a new user

To add the user **sarah** with user ID **5000**, use:

```
# useradd -u 5000 sarah
```

Verification

- To verify the new user is added, use the **id** utility.

```
# id sarah
```

The command returns:

```
uid=5000(sarah) gid=5000(sarah) groups=5000(sarah)
```

Additional resources

- **useradd** man page

10.3.2. Adding a new group from the command line

You can use the **groupadd** utility to add a new group.

Prerequisites

- You have **Root** access

Procedure

- To add a new group, use:

```
# groupadd options group-name
```

Replace *options* with the command-line options for the **groupadd** command, and replace *group-name* with the name of the group.

Example 10.2. Adding a new group

To add the group **sysadmins** with group ID **5000**, use:

```
# groupadd -g 5000 sysadmins
```

Verification

- To verify the new group is added, use the **tail** utility.

```
# getent group sysadmin
```

The command returns:

```
sysadmins:x:5000:
```

Additional resources

- **groupadd** man page

10.3.3. Adding a user to a supplementary group from the command line

You can add a user to a supplementary group to manage permissions or enable access to certain files or devices.

Prerequisites

- You have **root** access

Procedure

- To add a group to the supplementary groups of the user, use:

```
# usermod --append -G <group_name> <username>
```

Verification

- To verify the new groups is added to the supplementary groups of the user **sysadmin**, use:

```
# groups <username>
```

10.3.4. Creating a group directory

Under the UPG system configuration, you can apply the *set-group identification permission* (**setgid** bit) to a directory. The **setgid** bit makes managing group projects that share a directory simpler. When you apply the **setgid** bit to a directory, files created within that directory are automatically assigned to a group that owns the directory. Any user that has the permission to write and execute within this group can now create, modify, and delete files in the directory.

Prerequisites

- You have **Root** access

Procedure

1. Create a directory:

```
# mkdir <directory-name>
```

2. Create a group:

```
# groupadd <group-name>
```

3. Add users to the group:

```
# usermod --append -G <group_name> <username>
```

4. Associate the user and group ownership of the directory with the *group-name* group:

```
# chgrp <group_name> <directory>
```

5. Set the write permissions to allow the users to create and modify files and directories and set the **setgid** bit to make this permission be applied within the directory:

```
# chmod g+rxws <directory>
```

Verification

- To verify the correctness of set permissions, use:

```
# ls -ld <directory>
```

The command returns:

```
*drwx__rws__r-x.* 2 root __group-name_ 6 Nov 25 08:45 _directory-name_
```

10.3.5. Removing a user on the command line

You can remove a user account by using the command line. In addition, below mentioned are the commands to remove the user account, and optionally remove the user data and metadata, such as their home directory and configuration files.

- You have **root** access.
- The user currently exists.
- Ensure that the user is logged out:

```
# loginctl terminate-user user-name
```

- To only remove the user account, and not the user data:

```
# userdel user-name
```

- To remove the user, the data, and the metadata:
 - a. Remove the user, their home directory, their mail spool, and their SELinux user mapping:

```
# userdel --remove --selinux-user user-name
```

- b. Remove additional user metadata:

```
# rm -rf /var/lib/AccountsService/users/user-name
```

This directory stores information that the system needs about the user before the home directory is available. Depending on the system configuration, the home directory might not be available until the user authenticates at the login screen.



IMPORTANT

If you do not remove this directory and you later recreate the same user, the recreated user will still use certain settings inherited from the removed user.

Additional resources

- **userdel(8)** man page

10.4. MANAGING USER ACCOUNTS IN THE WEB CONSOLE

The RHEL web console provides a graphical interface for adding, editing, and removing system user accounts.

You can also set password expiration and terminate user sessions in the web console.

10.4.1. Adding new accounts by using the web console

You can add user accounts to the system and set administration rights to the accounts through the RHEL web console.

Prerequisites

- You have installed the RHEL 8 web console.
- You have enabled the cockpit service.
- Your user account is allowed to log in to the web console.
For instructions, see [Installing and enabling the web console](#).

Procedure

1. Log in to the RHEL 8 web console.
For details, see [Logging in to the web console](#).
2. Click **Accounts**.
3. Click **Create New Account**.
4. In the **Full Name** field, enter the full name of the user.
The RHEL web console automatically suggests a user name from the full name and fills it in the **User Name** field. If you do not want to use the original naming convention consisting of the first letter of the first name and the whole surname, update the suggestion.
5. In the **Password/Confirm** fields, enter the password and retype it for verification that your password is correct.
The color bar below the fields shows you the security level of the entered password, which does not allow you to create a user with a weak password.
6. Click **Create** to save the settings and close the dialog box.
7. Select the newly created account.
8. In the **Groups** drop-down menu, select the groups that you want to add to the new account.

New User

Terminate session

Delete

Full name

New User

User name

nuser

Groups

nuser

Last login

Never

Options

☐ Disallow interactive password
 ☒ Never expire account
 [edit](#)

Password

Set password

Force change

Never expire password

[edit](#)

Verification

- You can see the new account in the **Accounts** settings and you can use its credentials to connect to the system.

10.4.2. Enforcing password expiration in the web console

By default, user accounts have set passwords to never expire. You can set system passwords to expire after a defined number of days. When the password expires, the user must change its password at the next login attempt before the user can access the system.

Prerequisites

- You have installed the RHEL 8 web console.
- You have enabled the cockpit service.
- Your user account is allowed to log in to the web console.
For instructions, see [Installing and enabling the web console](#).

Procedure

- Log in to the RHEL 8 web console.
- Click **Accounts**.
- Select the user account for which you want to enforce password expiration.
- Click **edit** on the **Password** line.

Password

Set password

Force change

Require password change on March 2, 2024

edit

- In the **Password expiration** dialog box, select **Require password change every ... days** and enter a positive whole number representing the number of days after which the password expires.
- Click **Change**.
The web console immediately shows the date of the future password change request on the **Password** line.

10.5. EDITING USER GROUPS USING THE COMMAND LINE

A user belongs to a certain set of groups that allow a logical collection of users with a similar access to files and folders. You can edit the primary and supplementary user groups from the command line to change the user's permissions.

10.5.1. Primary and supplementary user groups

A group is an entity which ties together multiple user accounts for a common purpose, such as granting access to particular files.

On RHEL, user groups can act as primary or supplementary. Primary and supplementary groups have the following properties:

Primary group

- Every user has just one primary group at all times.
- You can change the user's primary group.

Supplementary groups

- You can add an existing user to an existing supplementary group to manage users with the same security and access privileges within the group.
- Users can be members of zero, one, or multiple supplementary groups.

10.5.2. Listing the primary and supplementary groups of a user

You can list the groups of users to see which primary and supplementary groups they belong to.

Procedure

- Display the names of the primary and any supplementary group of a user:

```
$ groups user-name
```

If you do not provide a user name, the command displays the group membership for the current user. The first group is the primary group followed by the optional supplementary groups.

Example 10.3. Listing of groups for user sarah:

```
$ groups sarah
```

The output displays:

```
sarah : sarah wheel developer
```

User **sarah** has a primary group **sarah** and is a member of supplementary groups **wheel** and **developer**.

10.5.3. Changing the primary group of a user

You can change the primary group of an existing user to a new group.

Prerequisites:

1. **root** access
2. The new group must exist

Procedure

- Change the primary group of a user:

```
# usermod -g <group-name> <user-name>
```



NOTE

When you change a user's primary group, the command also automatically changes the group ownership of all files in the user's home directory to the new primary group. You must fix the group ownership of files outside of the user's home directory manually.

- Verify that you changed the primary group of the user:

```
$ groups <username>
```

10.5.4. Adding a user to a supplementary group from the command line

You can add a user to a supplementary group to manage permissions or enable access to certain files or devices.

Prerequisites

- You have **root** access

Procedure

- To add a group to the supplementary groups of the user, use:

```
# usermod --append -G <group_name> <username>
```

Verification

- To verify the new groups is added to the supplementary groups of the user **sysadmin**, use:

```
# groups <username>
```

10.5.5. Removing a user from a supplementary group

You can remove an existing user from a supplementary group to limit their permissions or access to files and devices.

Prerequisites

- You have **root** access

Procedure

- Remove a user from a supplementary group:

```
# gpasswd -d <user-name> <group-name>
```

Verification

- Verify that you removed the user sarah from the secondary group developers:

```
$ groups <username>
```

10.5.6. Changing all of the supplementary groups of a user

You can overwrite the list of supplementary groups that you want the user to remain a member of.

Prerequisites

- You have **root** access.
- The supplementary groups must exist.

Procedure

- Overwrite a list of user's supplementary groups:

```
# usermod -G <group-names> <username>
```

To add the user to several supplementary groups at once, separate the group names using commas and no intervening spaces. For example: **wheel,developer**.



IMPORTANT

If the user is currently a member of a group that you do not specify, the command removes the user from the group.

Verification

- Verify that you set the list of the supplementary groups correct:

```
# groups <username>
```

10.6. CHANGING AND RESETTING THE ROOT PASSWORD

If the existing root password is no longer satisfactory, you can change it both as the **root** user and a non-root user.

10.6.1. Changing the root password as the root user

You can use the **passwd** command to change the **root** password as the **root** user.

Prerequisites

- You have **Root** access

Procedure

- To change the **root** password, use:

```
# passwd
```

You are prompted to enter your current password before you can change it.

10.6.2. Changing or resetting the forgotten root password as a non-root user

You can use the **passwd** command to change or reset the forgotten **root** password as a non-root user.

Prerequisites

- You are able to log in as a non-root user.
- You have permissions to execute commands as root by using **sudo**.

Procedure

- To change or reset the **root** password as a non-root user that belongs to the **wheel** group, use:

```
$ sudo passwd root
```

You are prompted to enter your current non-root password before you can change the **root** password.

10.6.3. Resetting the root password

If you are unable to log in as root user and have no non-root user with sudo permissions, you can reset the root password or do not belong to the administrative **wheel** group, you can reset the root password by booting the system into the special mode. In this mode, the boot process stops before the system hands over the control from the **initramfs** to the actual system.

Procedure

1. Reboot the system and, on the GRUB boot screen, press the **e** key to interrupt the boot process.
The kernel boot parameters appear.

```
load_video
set gfx_payload=keep
insmod gzio
linux ($root)/vmlinuz-4.18.0-80.el8.x86_64 root=/dev/mapper/rhel-root ro crash\
kernel=auto resume=/dev/mapper/rhel-swap rd.lvm.lv/swap rhgb quiet
initrd ($root)/initramfs-4.18.0-80.el8.x86_64.img $tuned_initrd
```

2. Set the cursor to the end of the line that starts with **linux**.
3. Append **rd.break** to the end of the line that starts with **linux**.
4. Press **Ctrl+x** to start the system with the changed parameters.
The **switch_root** prompt appears.
5. Remount the file system as writable:

```
# mount -o remount,rw /sysroot
```

By default, the file system is mounted as read-only in the **/sysroot** directory. Remounting the file system as writable allows you to change the password.

6. Enter the **chroot** environment:

```
# chroot /sysroot
```

7. Reset the **root** password:

```
# passwd
```

Follow the instructions displayed by the command line to finalize the change of the **root** password.

8. Enable the SELinux relabeling process on the next system boot:

```
# touch /.autorelabel
```

9. Exit the **chroot** environment:

```
# exit
```

10. Exit the **switch_root** prompt, to reboot the system:

```
exit
```

11. Wait until the SELinux relabeling process is finished. Note that relabeling a large disk can take a long time. The system reboots automatically when the process is complete.

Verification

1. Log in as the **root** user by using the new root password.
2. Optional: Display the user name associated with the current effective user ID:

```
# whoami
```

CHAPTER 11. MANAGING SUDO ACCESS

System administrators can grant **sudo** access to allow non-root users to execute administrative commands that are normally reserved for the root user.

11.1. USER AUTHORIZATIONS IN SUDOERS

The **/etc/sudoers** file and, by default, drop-in files in the **/etc/sudoers.d/** directory specify which users can use the **sudo** command to execute commands as other user. The rules can apply to individual users and user groups. You can also define rules for groups of hosts, commands, and even users more easily by using aliases.

When a user enters a command with **sudo** for which the user does not have authorization, the system records a message that contains the string **<username> : user NOT in sudoers** to the journal log.

The default **/etc/sudoers** file provides information and examples of authorizations. You can activate a specific example rule by uncommenting the corresponding line. The section with user authorizations is marked with the following introduction:

```
## Next comes the main part: which users can run what software on
## which machines (the sudoers file can be shared between multiple
## systems).
```

You can create new **sudoers** authorizations and modify existing authorizations by using the following format:

```
<username> <hostname.example.com>=(<run_as_user>:<run_as_group>) <path/to/command>
```

Where:

- **<username>** is the user that enters the command, for example, **user1**. If the value starts with **%**, it defines a group, for example, **%group1**.
- **<hostname.example.com>** is the name of the host on which the rule applies.
- The section **(<run_as_user>:<run_as_group>)** defines the user or group as which the command is executed. If you omit this section, **<username>** can execute the command as root.
- **<path/to/command>** is the complete absolute path to the command. You can also limit the user to only performing a command with specific options and arguments by adding those options after the command path. If you do not specify any options, the user can use the command with all options.

You can apply the rule to all users, hosts, or commands by replacing any of these variables with **ALL**.



WARNING

By using **ALL** in some or multiple segments of a rule, can cause serious security risks.

You can negate the arguments by using the **!** operator. For example, **!root** specifies all users except root. Note that allowing specific users, groups, and commands is more secure than disallowing specific users, groups, and commands. This is because allow rules also block new unauthorized users or groups.



WARNING

Avoid using negative rules for commands because users can overcome such rules by renaming commands with the **alias** command.

The system reads the **/etc/sudoers** file from beginning to end. Therefore, if the file contains multiple entries for a user, the entries are applied in order. In case of conflicting values, the system uses the last match, even if it is not the most specific match.

To preserve the rules during system updates and for easier fixing of errors, enter new rules by creating new files in the **/etc/sudoers.d/** directory instead of entering rules directly to the **/etc/sudoers** file. The system reads the files in the **/etc/sudoers.d** directory when it reaches the following line in the **/etc/sudoers** file:

```
#includedir /etc/sudoers.d
```

Note that the number sign (**#**) at the beginning of this line is part of the syntax and does not mean the line is a comment. The names of files in that directory must not contain a period and must not end with a tilde (~).

Additional resources

- **sudoers(5)** man page

11.2. ADDING A SUDO RULE TO ALLOW MEMBERS OF A GROUP TO EXECUTE COMMANDS AS ROOT

System administrators can allow non-root users to execute administrative commands by granting them **sudo** access. The **sudo** command provides users with administrative access without using the password of the root user.

When users need to perform an administrative command, they can precede that command with **sudo**. If the user has authorization for the command, the command is executed as if they were root.

Be aware of the following limitations:

- Only users listed in the sudoers configuration file can use the **sudo** command.
- The command is executed in the shell of the user, not in the root shell. However, there are some exceptions such as when full **sudo** privileges are granted to any user. In such cases, users can switch to and run the commands in root shell. For example:
 - **sudo -i**
 - **sudo su -**

Prerequisites

- You have root access to the system.

Procedure

1. As root, open the **/etc/sudoers** file.

```
# visudo
```

The **/etc/sudoers** file defines the policies applied by the **sudo** command.

2. In the **/etc/sudoers** file, find the lines that grant **sudo** access to users in the administrative **wheel** group.

```
## Allows people in group wheel to run all commands
%wheel    ALL=(ALL)    ALL
```

3. Make sure the line that starts with **%wheel** is not commented out with the number sign (**#**).
4. Save any changes, and exit the editor.
5. Add users you want to grant **sudo** access to into the administrative **wheel** group.

```
# usermod --append -G wheel <username>
```

Replace **<username>** with the name of the user.

Verification

- Log in as a member of the **wheel** group and run:

```
# sudo whoami
root
```

Additional resources

- **sudo(8)**, **sudoers(5)** and **visudo(8)** man pages

11.3. ENABLING UNPRIVILEGED USERS TO RUN CERTAIN COMMANDS

As an administrator, you can allow unprivileged users to enter certain commands on specific workstations by configuring a policy in the **/etc/sudoers.d/** directory. This is more secure than granting full **sudo** access to a user or giving someone the root password for the following reasons:

- More granular control over privileged actions. You can allow a user to perform certain actions on specific hosts instead of giving them full administrative access.
- Better logging. When a user performs an action through **sudo**, the action is logged with their user name and not just root.
- Transparent control. You can set email notifications for every time the user attempts to use **sudo** privileges.

Prerequisites

- You have root access to the system.

Procedure

1. Create a new file in the **/etc/sudoers.d** directory:

```
# visudo -f /etc/sudoers.d/<filename>
```

The file opens automatically in an editor.

2. Add the following line to the **/etc/sudoers.d/<filename>** file:

```
<username> <hostname.example.com> = (<run_as_user>:<run_as_group>)
<path/to/command>
```

- Replace **<username>** with the name of the user.
- Replace **<hostname.example.com>** with the URL of the host.
- Replace **(<run_as_user>:<run_as_group>)** with the user or group as to which the command can be executed. If you omit this section, **<username>** can execute the command as root.
- Replace **<path/to/command>** with the complete absolute path to the command. You can also limit the user to only performing a command with specific options and arguments by adding those options after the command path. If you do not specify any options, the user can use the command with all options.
- To allow two and more commands on the same host on one line, you can list them separated by a comma followed by a space.

For example, to allow **user1** to execute the **dnf** and **reboot** commands on **host1.example.com**, enter:

```
user1 host1.example.com = /bin/dnf, /sbin/reboot
```

1. Optional: To receive email notifications every time a user attempts to use **sudo** privileges, add the following lines to the file:

```
Defaults    mail_always
Defaults    mailto="<email@example.com>"
```

2. Save the changes, and exit the editor.

Verification

1. To verify if a user can run a command with **sudo** privileges, switch the account:

```
# su <username> -
```

2. As the user, enter the command with the **sudo** command:

```
$ sudo whoami
[sudo] password for <username>:
```

■

Enter the user's **sudo** password.

3. If the privileges are configured correctly, sudo executes the command as the configured user. For example, with the **dnf** command, it shows the following output:

```
...  
usage: dnf [options] COMMAND  
...
```

If the system returns the following error message, the user is not allowed to run commands with sudo.

```
<username> is not in the sudoers file. This incident will be reported.
```

- + If the system returns the following error message, the configuration was not completed correctly.

```
<username> is not allowed to run sudo on <host.example.com>.
```

- + If the system returns the following error message, the command is not correctly defined in the rule for the user.

```
`Sorry, user _<username>_ is not allowed to execute '_<path/to/command>_' as root on  
_<host.example.com>_`
```

Additional resources

- **visudo(8)**, and **sudoers(5)** man pages

CHAPTER 12. MANAGING FILE SYSTEM PERMISSIONS

File system permissions control the ability of user and group accounts to read, modify, and execute the contents of the files and to enter directories. Set permissions carefully to protect your data against unauthorized access.

12.1. MANAGING FILE PERMISSIONS

Every file or directory has three levels of ownership:

- User owner (**u**).
- Group owner (**g**).
- Others (**o**).

Each level of ownership can be assigned the following permissions:

- Read (**r**).
- Write (**w**).
- Execute (**x**).

Note that the execute permission for a file allows you to execute that file. The execute permission for a directory allows you to access the contents of the directory, but not execute it.

When a new file or directory is created, the default set of permissions are automatically assigned to it. The default permissions for a file or directory are based on two factors:

- Base permission.
- The *user file-creation mode mask* (**umask**).

12.1.1. Base file permissions

Whenever a new file or directory is created, a base permission is automatically assigned to it. Base permissions for a file or directory can be expressed in *symbolic* or *octal* values.

Permission	Symbolic value	Octal value
No permission	---	0
Execute	--x	1
Write	-w-	2
Write and execute	-wx	3
Read	r--	4
Read and execute	r-x	5

Read and write	rw-	6
Read, write, execute	rwX	7

The base permission for a directory is **777 (drwxrwxrwx)**, which grants everyone the permissions to read, write, and execute. This means that the directory owner, the group, and others can list the contents of the directory, create, delete, and edit items within the directory, and descend into it.

Note that individual files within a directory can have their own permission that might prevent you from editing them, despite having unrestricted access to the directory.

The base permission for a file is **666 (-rw-rw-rw-)**, which grants everyone the permissions to read and write. This means that the file owner, the group, and others can read and edit the file.

Example 12.1. Permissions for a file

If a file has the following permissions:

```
$ ls -l
-rwxrw----. 1 sysadmins sysadmins 2 Mar 2 08:43 file
```

- **-** indicates it is a file.
- **rwx** indicates that the file owner has permissions to read, write, and execute the file.
- **rw-** indicates that the group has permissions to read and write, but not execute the file.
- **---** indicates that other users have no permission to read, write, or execute the file.
- **.** indicates that the SELinux security context is set for the file.

Example 12.2. Permissions for a directory

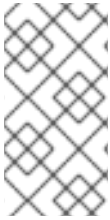
If a directory has the following permissions:

```
$ ls -dl directory
drwxr-----. 1 sysadmins sysadmins 2 Mar 2 08:43 directory
```

- **d** indicates it is a directory.
- **rwx** indicates that the directory owner has the permissions to read, write, and access the contents of the directory.
As a directory owner, you can list the items (files, subdirectories) within the directory, access the content of those items, and modify them.
- **r-x** indicates that the group has permissions to read the content of the directory, but not write – create new entries or delete files. The **x** permission means that you can also access the directory using the **cd** command.
- **---** indicates that other users have no permission to read, write, or access the contents of the directory.

As someone who is not a user owner, or as a group, you cannot list the items within the directory, access information about those items, or modify them.

- . indicates that the SELinux security context is set for the directory.



NOTE

The base permission that is automatically assigned to a file or directory is **not** the default permission the file or directory ends up with. When you create a file or directory, the base permission is altered by the *umask*. The combination of the base permission and the *umask* creates the default permission for files and directories.

12.1.2. User file-creation mode mask

The user file-creation mode mask (*umask*) is variable that controls how file permissions are set for newly created files and directories. The *umask* automatically removes permissions from the base permission value to increase the overall security of a Linux system. The *umask* can be expressed in *symbolic* or *octal* values.

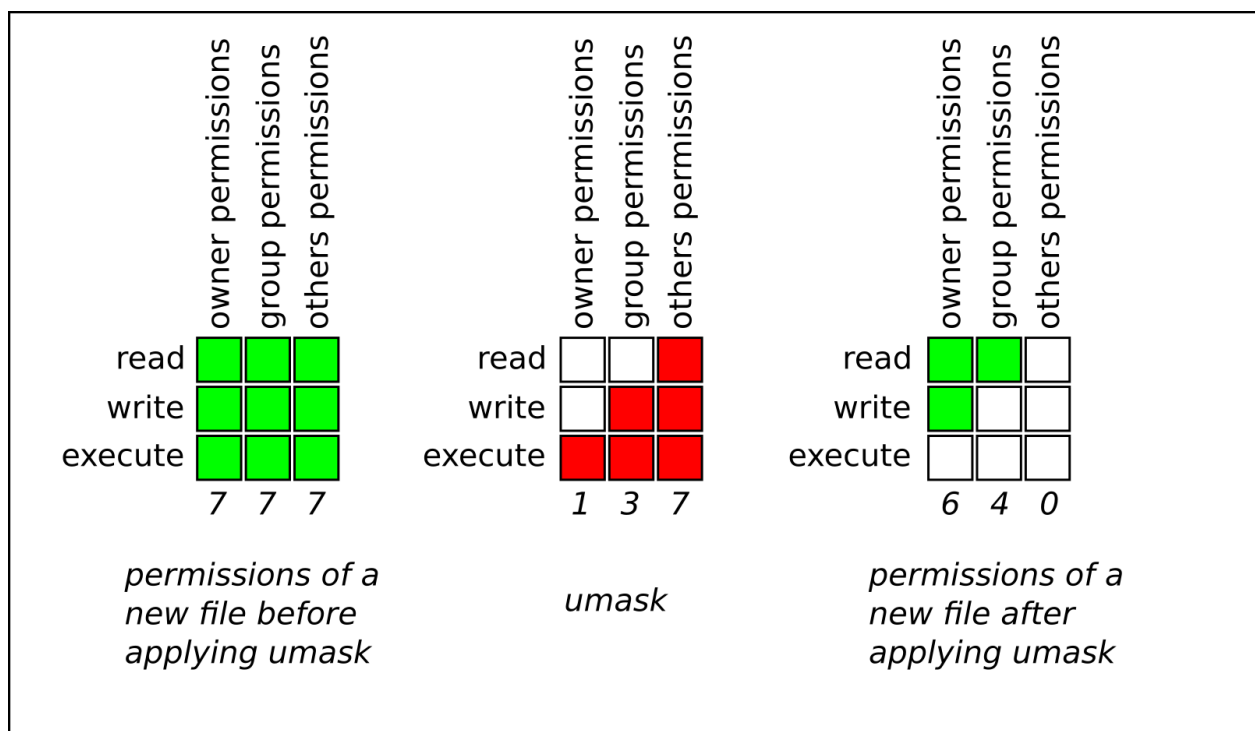
Permission	Symbolic value	Octal value
Read, write, and execute	rwX	0
Read and write	rw-	1
Read and execute	r-X	2
Read	r--	3
Write and execute	-wX	4
Write	-w-	5
Execute	--X	6
No permissions	---	7

The default *umask* for a standard user is **0002**. The default *umask* for a **root** user is **0022**.

The first digit of the *umask* represents special permissions (sticky bit,). The last three digits of the *umask* represent the permissions that are removed from the user owner (**u**), group owner (**g**), and others (**o**) respectively.

Example 12.3. Applying the umask when creating a file

The following example illustrates how the *umask* with an octal value of **0137** is applied to the file with the base permission of **777**, to create the file with the default permission of **640**.



12.1.3. Default file permissions

The default permissions are set automatically for all newly created files and directories. The value of the default permissions is determined by applying the *umask* to the base permission.

Example 12.4. Default permissions for a directory created by a standard user

When a **standard user** creates a new **directory**, the *umask* is set to **002 (rwxrwxr-x)**, and the base permissions for a directory are set to **777 (rwxrwxrwx)**. This brings the default permissions to **775 (drwxrwxr-x)**.

	Symbolic value	Octal value
Base permission	rwxrwxrwx	777
Umask	rwxrwxr-x	002
Default permission	rwxrwxr-x	775

This means that the directory owner and the group can list the contents of the directory, create, delete, and edit items within the directory, and descend into it. Other users can only list the contents of the directory and descend into it.

Example 12.5. Default permissions for a file created by a standard user

When a **standard user** creates a new **file**, the *umask* is set to **002 (rwxrwxr-x)**, and the base permissions for a file are set to **666 (rw-rw-rw-)**. This brings the default permissions to **664 (-rw-rw-r-)**.

	Symbolic value	Octal value
Base permission	rw-rw-rw-	666
Umask	rw-rw-rw-	002
Default permission	rw-rw-r--	664

This means that the file owner and the group can read and edit the file, while other users can only read the file.

Example 12.6. Default permissions for a directory created by the root user

When a **root user** creates a new **directory**, the *umask* is set to **022 (rwxr-xr-x)**, and the base permissions for a directory are set to **777 (rwxrwxrwx)**. This brings the default permissions to **755 (rwxr-xr-x)**.

	Symbolic value	Octal value
Base permission	rwxrwxrwx	777
Umask	rwxr-xr-x	022
Default permission	rwxr-xr-x	755

This means that the directory owner can list the contents of the directory, create, delete, and edit items within the directory, and descend into it. The group and others can only list the contents of the directory and descend into it.

Example 12.7. Default permissions for a file created by the root user

When a **root user** creates a new **file**, the *umask* is set to **022 (rwxr-xr-x)**, and the base permissions for a file are set to **666 (rw-rw-rw-)**. This brings the default permissions to **644 (-rw-r--r--)**.

	Symbolic value	Octal value
Base permission	rw-rw-rw-	666
Umask	rwxr-xr-x	022
Default permission	rw-r--r--	644

This means that the file owner can read and edit the file, while the group and others can only read the file.

**NOTE**

For security reasons, regular files cannot have execute permissions by default, even if the `umask` is set to **000** (**rw-rw-rw-**). However, directories can be created with execute permissions.

12.1.4. Changing file permissions using symbolic values

You can use the **chmod** utility with symbolic values (a combination of letters and signs) to change file permissions for a file or directory.

You can assign the following *permissions*:

- Read (**r**)
- Write (**w**)
- Execute (**x**)

Permissions can be assigned to the following *levels of ownership*:

- User owner (**u**)
- Group owner (**g**)
- Other (**o**)
- All (**a**)

To add or remove permissions you can use the following *signs*:

- **+** to add the permissions on top of the existing permissions
- **-** to remove the permissions from the existing permission
- **=** to remove the existing permissions and explicitly define the new ones

Procedure

- To change the permissions for a file or directory, use:

```
$ chmod <level><operation><permission> file-name
```

Replace **<level>** with the [level of ownership](#) you want to set the permissions for. Replace **<operation>** with one of the [signs](#). Replace **<permission>** with the [permissions](#) you want to assign. Replace **file-name** with the name of the file or directory. For example, to grant everyone the permissions to read, write, and execute (**rw-rw-rw-**) **my-script.sh**, use the **chmod a=rwx my-script.sh** command.

See [Base file permissions](#) for more details.

Verification

- To see the permissions for a particular file, use:

```
$ ls -l file-name
```

Replace *file-name* with the name of the file.

- To see the permissions for a particular directory, use:

```
$ ls -dl directory-name
```

Replace *directory-name* with the name of the directory.

- To see the permissions for all the files within a particular directory, use:

```
$ ls -l directory-name
```

Replace *directory-name* with the name of the directory.

Example 12.8. Changing permissions for files and directories

- To change file permissions for **my-file.txt** from **-rw-rw-r--** to **-rw-----**, use:

1. Display the current permissions for **my-file.txt**:

```
$ ls -l my-file.txt
-rw-rw-r--. 1 username username 0 Feb 24 17:56 my-file.txt
```

2. Remove the permissions to read, write, and execute (**rw**x) the file from group owner (**g**) and others (**o**):

```
$ chmod go= my-file.txt
```

Note that any permission that is not specified after the equals sign (=) is automatically prohibited.

3. Verify that the permissions for **my-file.txt** were set correctly:

```
$ ls -l my-file.txt
-rw-----. 1 username username 0 Feb 24 17:56 my-file.txt
```

- To change file permissions for **my-directory** from **drwxrwx---** to **drwxrwxr-x**, use:

1. Display the current permissions for **my-directory**:

```
$ ls -dl my-directory
drwxrwx---. 2 username username 4096 Feb 24 18:12 my-directory
```

2. Add the read and execute (**r-x**) access for all users (**a**):

```
$ chmod o+rx my-directory
```

3. Verify that the permissions for **my-directory** and its content were set correctly:

```
$ ls -dl my-directory
drwxrwxr-x. 2 username username 4096 Feb 24 18:12 my-directory
```

12.1.5. Changing file permissions using octal values

You can use the **chmod** utility with octal values (numbers) to change file permissions for a file or directory.

Procedure

- To change the file permissions for an existing file or directory, use:

```
$ chmod octal_value file-name
```

Replace *file-name* with the name of the file or directory. Replace *octal_value* with an octal value. See [Base file permissions](#) for more details.

12.2. MANAGING THE ACCESS CONTROL LIST

Each file and directory can only have one user owner and one group owner at a time. If you want to grant a user permissions to access specific files or directories that belong to a different user or group while keeping other files and directories private, you can utilize Linux Access Control Lists (ACLs).

12.2.1. Setting the Access Control List

You can use the **setfacl** utility to set the ACL for a file or directory.

Prerequisites

- You have the **root** access.

Procedure

- To display the current ACL for a particular file or directory, run:

```
$ getfacl file-name
```

Replace *file-name* with the name of the file or directory.

- To set the ACL for a file or directory, use:

```
# setfacl -m u:username:symbolic_value file-name
```

Replace *username* with the name of the user, *symbolic_value* with a symbolic value, and *file-name* with the name of the file or directory. For more information see the **setfacl** man page on your system.

Example 12.9. Modifying permissions for a group project

The following example describes how to modify permissions for the **group-project** file owned by the **root** user that belongs to the **root** group so that this file is:

- Not executable by anyone.
- The user **andrew** has the **rw-** permissions.
- The user **susan** has the **---** permissions.

- Other users have the **r--** permissions.

Procedure

```
# setfacl -m u:andrew:rw- group-project
# setfacl -m u:susan:--- group-project
```

Verification

- To verify that the user **andrew** has the **rw-** permission, the user **susan** has the **---** permission, and other users have the **r--** permission, use:

```
$ getfacl group-project
```

The output returns:

```
# file: group-project
# owner: root
# group: root
user:andrew:rw-
user:susan:---
group::r--
mask::rw-
other::r--
```

12.3. MANAGING THE UMASK

You can use the **umask** utility to display, set, or change the current or default value of the *umask*.

12.3.1. Displaying the current value of the umask

You can use the **umask** utility to display the current value of the *umask* in symbolic or octal mode.

Procedure

- To display the current value of the *umask* in symbolic mode, use:

```
$ umask -S
```

- To display the current value of the *umask* in the octal mode, use:

```
$ umask
```



NOTE

When displaying the *umask* in octal mode, you may notice it displayed as a four digit number (**0002** or **0022**). The first digit of the *umask* represents a special bit (sticky bit, SGID bit, or SUID bit). If the first digit is set to **0**, the special bit is not set.

12.3.2. Setting the umask using symbolic values

You can use the **umask** utility with symbolic values (a combination letters and signs) to set the *umask* for the current shell session

You can assign the following *permissions*:

- Read (**r**)
- Write (**w**)
- Execute (**x**)

Permissions can be assigned to the following *levels of ownership*:

- User owner (**u**)
- Group owner (**g**)
- Other (**o**)
- All (**a**)

To add or remove permissions you can use the following *signs*:

- **+** to add the permissions on top of the existing permissions
- **-** to remove the permissions from the existing permission
- **=** to remove the existing permissions and explicitly define the new ones



NOTE

Any permission that is not specified after the equals sign (**=**) is automatically prohibited.

Procedure

- To set the *umask* for the current shell session, use:

```
$ umask -S <level><operation><permission>
```

Replace **<level>** with the [level of ownership](#) you want to set the *umask* for. Replace **<operation>** with one of the [signs](#). Replace **<permission>** with the [permissions](#) you want to assign. For example, to set the *umask* to **u=rwx,g=rwx,o=rwx**, use **umask -S a=rwx**.

See [User file-creation mode](#) for more details.



NOTE

The *umask* is only valid for the current shell session.

12.3.3. Setting the umask using octal values

You can use the **umask** utility with octal values (numbers) to set the *umask* for the current shell session.

Procedure

- To set the *umask* for the current shell session, use:

```
$ umask octal_value
```

Replace *octal_value* with an octal value. See [User file-creation mode mask](#) for more details.



NOTE

The *umask* is only valid for the current shell session.

12.3.4. Changing the default umask for the non-login shell

You can change the default **bash** umask for standard users by modifying the **/etc/bashrc** file.

Prerequisites

- You have the **root** access.

Procedure

1. Open the **/etc/bashrc** file in the editor.
2. Modify the following sections to set a new default **bash umask**:

```
if [ $UID -gt 199 ] && [ "id -gn" = "id -un" ]; then
    umask 002
else
    umask 022
fi
```

Changing the **UID -gt 199**, will apply the new umask for all **IDs >= 199** and impact services and security.

Replace the default octal value of the *umask* (**002**) with another octal value. See [User file-creation mode mask](#) for more details.

1. Save the changes and exit the editor.

12.3.5. Changing the default umask for the login shell

You can change the default **bash umask** for the **root** user by modifying the **/etc/profile** file.

Prerequisites

- **root** access

Procedure

1. As **root**, open the **/etc/profile** file in the editor.
2. Modify the following sections to set a new default **bash umask**:

```
if [ $UID -gt 199 ] && [ "/usr/bin/id -gn" = "/usr/bin/id -un" ]; then
    umask 002
```

```
else
    umask 022
fi
```

Replace the default octal value of the *umask* (**022**) with another octal value. See [User file-creation mode mask](#) for more details.

3. Save the changes and exit the editor.

12.3.6. Changing the default umask for a specific user

You can change the default *umask* for a specific user by modifying the **.bashrc** for that user.

Procedure

- Append the line that specifies the octal value of the *umask* into the **.bashrc** file for the particular user.

```
$ echo 'umask octal_value' >> /home/username/.bashrc
```

Replace *octal_value* with an octal value and replace *username* with the name of the user. See [User file-creation mode mask](#) for more details.

12.3.7. Setting default permissions for newly created home directories

You can change the permission modes for home directories of newly created users by modifying the **/etc/login.defs** file.

Procedure

1. As **root**, open the **/etc/login.defs** file in the editor.
2. Modify the following section to set a new default *HOME_MODE*:

```
# HOME_MODE is used by useradd(8) and newusers(8) to set the mode for new
# home directories.
# If HOME_MODE is not set, the value of UMASK is used to create the mode.
HOME_MODE    0700
```

Replace the default octal value (**0700**) with another octal value. The selected mode will be used to create the permissions for the home directory.

3. If *HOME_MODE* is set, save the changes and exit the editor.
4. If *HOME_MODE* is not set, modify the *UMASK* to set the mode for the newly created home directories:

```
# Default initial "umask" value used by login(1) on non-PAM enabled systems.
# Default "umask" value for pam_umask(8) on PAM enabled systems.
# UMASK is also used by useradd(8) and newusers(8) to set the mode for new
# home directories if HOME_MODE is not set.
# 022 is the default value, but 027, or even 077, could be considered
# for increased privacy. There is no One True Answer here: each sysadmin
```



```
# must make up their mind.
```

```
UMASK      022
```

Replace the default octal value (**022**) with another octal value. See [User file-creation mode mask](#) for more details.

5. Save the changes and exit the editor.

CHAPTER 13. MANAGING SYSTEMD

As a system administrator, you can manage critical aspects of your system with **systemd**. Serving as a system and service manager for Linux operating systems, **systemd** software suite provides tools and services for controlling, reporting, and system initialization. Key features of **systemd** include:

- Parallel start of system services during boot
- On-demand activation of daemons
- Dependency-based service control logic

The basic object that **systemd** manages is a *systemd unit*, a representation of system resources and services. A **systemd** unit consists of a name, type and a configuration file that defines and manages a particular task. You can use unit files to configure system behavior. See the following examples of various systemd unit types:

Service

Controls and manages individual system services.

Target

Represents a group of units that define system states.

Device

Manages hardware devices and their availability.

Mount

Handles file system mounting.

Timer

Schedules tasks to run at specific intervals.

13.1. SYSTEMD UNIT FILES LOCATIONS

You can find the unit configuration files in one of the following directories:

Table 13.1. systemd unit files locations

Directory	Description
/usr/lib/systemd/system/	systemd unit files distributed with installed RPM packages.
/run/systemd/system/	systemd unit files created at run time. This directory takes precedence over the directory with installed service unit files.
/etc/systemd/system/	systemd unit files created by using the systemctl enable command as well as unit files added for extending a service. This directory takes precedence over the directory with runtime unit files.

The default configuration of **systemd** is defined during the compilation and you can find the configuration in the **/etc/systemd/system.conf** file. By editing this file, you can modify the default configuration by overriding values for **systemd** units globally.

For example, to override the default value of the timeout limit, which is set to 90 seconds, use the **DefaultTimeoutStartSec** parameter to input the required value in seconds.

```
DefaultTimeoutStartSec=required value
```

13.2. MANAGING SYSTEM SERVICES WITH SYSTEMCTL

As a system administrator, you can manage system services by using the **systemctl** utility. You can perform various tasks, such as starting, stopping, restarting running services, enabling and disabling services to start at boot, listing available services, and displaying system services statuses.

13.2.1. Listing system services

You can list all currently loaded service units and display the status of all available service units.

Procedure

Use the **systemctl** command to perform any of the following tasks:

- List all currently loaded service units:

```
$ systemctl list-units --type service
UNIT                                LOAD    ACTIVE SUB    DESCRIPTION
abrt-ccpp.service                  loaded active exited Install ABRT coredump hook
abrt-oops.service                  loaded active running ABRT kernel log watcher
abrt-d.service                     loaded active running ABRT Automated Bug Reporting Tool
...
systemd-vconsole-setup.service     loaded active exited Setup Virtual Console
tog-pegasus.service                loaded active running OpenPegasus CIM Server

LOAD    = Reflects whether the unit definition was properly loaded.
ACTIVE  = The high-level unit activation state, or a generalization of SUB.
SUB      = The low-level unit activation state, values depend on unit type.

46 loaded units listed. Pass --all to see loaded but inactive units, too.
To show all installed unit files use 'systemctl list-unit-files'
```

By default, the **systemctl list-units** command displays only active units. For each service unit file, the command provides an overview of the following parameters:

UNIT

The full name of the service unit

LOAD

The load state of the configuration file

ACTIVE or SUB

The current high-level and low-level unit file activation state

DESCRIPTION

A short description of the unit's purpose and functionality

- List **all loaded units regardless of their state** by using the following command with the **--all** or **-a** command line option:

```
$ systemctl list-units --type service --all
```

- List the status (**enabled** or **disabled**) of all available service units:

```
$ systemctl list-unit-files --type service
UNIT FILE          STATE
abrt-ccpp.service  enabled
abrt-oops.service   enabled
abrttd.service      enabled
...
wpa_supplicant.service disabled
ypbind.service      disabled

208 unit files listed.
```

For each service unit, this command displays:

UNIT FILE

The full name of the service unit

STATE

The information whether the service unit is enabled or disabled to start automatically during boot

Additional resources

- [Displaying system service status](#)

13.2.2. Displaying system service status

You can inspect any service unit to get detailed information and verify the state of the service, whether it is enabled to start during boot or currently running. You can also view services that are ordered to start after or before a particular service unit.

Procedure

- Display detailed information about a service unit that corresponds to a system service:

```
$ systemctl status <name>.service
```

Replace **<name>** with the name of the service unit you want to inspect (for example, **gdm**).

This command displays the following information:

- The name of the selected service unit followed by a short description
- One or more fields described in [Available service unit information](#)
- The execution of the service unit: if the unit is executed by the **root** user
- The most recent log entries

Table 13.2. Available service unit information

Field	Description
Loaded	Information whether the service unit has been loaded, the absolute path to the unit file, and a note whether the unit is enabled to start during boot.
Active	Information whether the service unit is running followed by a time stamp.
Main PID	The process ID and the name of the corresponding system service.
Status	Additional information about the corresponding system service.
Process	Additional information about related processes.
CGroup	Additional information about related control groups (cgroups).

- Verify that a particular service unit is running:

```
$ systemctl is-active <name>.service
```

- Determine whether a particular service unit is enabled to start during boot:

```
$ systemctl is-enabled <name>.service
```

**NOTE**

Both **systemctl is-active** and **systemctl is-enabled** commands return an exit status of **0** if the specified service unit is running or enabled.

- Check what services **systemd** orders to start before the specified service unit

```
# systemctl list-dependencies --after <name>.service
```

For example, to view the list of services ordered to start before **gdm**, enter:

```
# systemctl list-dependencies --after gdm.service
gdm.service
├─dbus.socket
├─getty@tty1.service
├─livesys.service
├─plymouth-quit.service
├─system.slice
└─systemd-journald.socket
```

```
| systemd-user-sessions.service
| basic.target
| [output truncated]
```

- Check what services **systemd** orders to start after the specified service unit:

```
| # systemctl list-dependencies --before <name>.service
```

For example, to view the list of services **systemd** orders to start after **gdm**, enter:

```
| # systemctl list-dependencies --before gdm.service
gdm.service
| dracut-shutdown.service
| graphical.target
|   | systemd-readahead-done.service
|   | systemd-readahead-done.timer
|   | systemd-update-utmp-runlevel.service
|   |
| shutdown.target
|   | systemd-reboot.service
|   | final.target
|   | systemd-reboot.service
```

Additional resources

- [Listing system services](#)

13.2.3. Starting and stopping a systemd unit

You can start system service in the current session by using the **systemctl start** command.

Prerequisites

- You have the Root access.

Procedure

- Start a system service in the current session:

```
| # *systemctl start <systemd_unit> *
```

Replace **<systemd_unit>** with the name of the service unit you want to start (for example, **httpd.service**).



NOTE

In **systemd**, positive and negative dependencies between services exist. Starting a particular service may require starting one or more other services (**positive dependency**) or stopping one or more services (**negative dependency**).

When you attempt to start a new service, **systemd** resolves all dependencies automatically, without explicit notification to the user. This means that if you are already running a service, and you attempt to start another service with a negative dependency, the first service is automatically stopped.

For example, if you are running the **sendmail** service, and you attempt to start the **postfix** service, **systemd** first automatically stops **sendmail**, because these two services are conflicting and cannot run on the same port.

Additional resources

- **systemctl(1)** man page on your system
- [Enabling a system service to start at boot](#)
- [Displaying system service status](#)

13.2.4. Stopping a system service

If you want to stop a system service in the current session, use the **systemctl stop** command.

Prerequisites

- Root access

Procedure

- Stop a system service:

```
# systemctl stop <name>.service
```

Replace **<name>** with the name of the service unit you want to stop (for example, **bluetooth**).

Additional resources

- **systemctl(1)** man page on your system
- [Disabling a system service to start at boot](#)
- [Displaying system service status](#)

13.2.5. Restarting and Reload a system service

You can restart system service in the current session using the **restart** command to perform the following actions:

- Stop the selected service unit in the current session and immediately start it again.
- Restart a service unit only if the corresponding service is already running.

- Reload configuration of a system service without interrupting its execution.

Prerequisites

- You have the Root access.

Procedure

- Restart a system service:

```
# systemctl restart <name>.service
```

Replace **<name>** with the name of the service unit you want to restart (for example, **httpd**).

If the selected service unit is not running, this command starts it.

- Restart a service unit only if the corresponding service is already running:

```
# systemctl try-restart <name>.service
```

- Reload the configuration without interrupting service execution:

```
# systemctl reload <name>.service
```



NOTE

System services that do not support this feature, ignore this command. To restart such services, use the **reload-or-restart** and **reload-or-try-restart** commands instead.

Additional resources

- **systemctl** man page on your system
- [Displaying system service status](#)

13.2.6. Enabling a system service to start at boot

You can enable a service to start automatically at boot, these changes apply with the next reboot.

Prerequisites

- You have Root access.

Procedure

- Verify whether the unit is masked:

```
# systemctl status <systemd_unit>
```

- If the unit is masked, unmask it first:

```
# systemctl unmask <systemd_unit>
```


- Enable a service to start at boot time:

```
# systemctl enable <systemd_unit>
```

Replace **<systemd_unit>** with the name of the service unit you want to enable (for example, **httpd**).

Optionally, pass the **--now** option to the command to also start the unit right now.

Additional resources

- **systemctl (1)** man page on your system
- [Displaying system service status](#)
- [Starting a system service](#)

13.2.7. Disabling a system service to start at boot

You can prevent a service unit from starting automatically at boot time. If you disable a service, it will not start at boot, but you can start it manually. You can also mask a service, so that it cannot be started manually. Masking is a way of disabling a service that makes the service permanently unusable until it is unmasked again.

Prerequisites

- You have Root access.

Procedure

- Disable a service to start at boot:

```
# systemctl disable <name>.service
```

Replace **<name>** with the name of the service unit you want to disable (for example, **bluetooth**). Optionally, pass the **--now** command to also stop the service if it is currently running.

- Optional: To prevent that the unit can be accidentally started by an administrator or as a dependency of other units, mask the service:

```
# systemctl mask <name>.service
```

Additional resources

- **systemctl (1)** man page on your system
- [Displaying system service status](#)
- [Stopping a system service](#)

13.3. BOOTING INTO A TARGET SYSTEM STATE

As a system administrator, you can control the boot process of your system, and define the state you want your system to boot into. This is called a **systemd** target, and it is a set of **systemd** units that your system starts to reach a certain level of functionality. While working with systemd targets, you can view the default target, select a target at runtime, change the default boot target, boot into emergency or rescue target.

13.3.1. Target unit files

Targets in **systemd** are groups of related units that act as synchronization points during the start of your system. Target unit files, which end with the **.target** file extension, represent the **systemd** targets. The purpose of target units is to group together various **systemd** units through a chain of dependencies.

Consider the following example:

- Similarly, the **multi-user.target** unit starts other essential system services such as NetworkManager (**NetworkManager.service**) or D-Bus (**dbus.service**) and activates another target unit named **basic.target**.

You can set the following **systemd** targets as default or current targets:

Table 13.3. Common systemd targets

rescue	unit target that pulls in the base system and spawns a rescue shell
multi-user	unit target for setting up a multi-user system
graphical	unit target for setting up a graphical login screen
emergency	unit target that starts an emergency shell on the main console

Additional resources

- **systemd.special(7)** and **systemd.target(5)** man pages on your system

13.3.2. Changing the default target to boot into

The **default.target** symbolic link refers to the systemd target that the system should boot into. When the system starts, systemd resolves this link and boots into the defined target. You can find the currently selected default target unit in the **/etc/systemd/system/default.target** file. Each target represents a certain level of functionality and is used for grouping other units. Additionally, target units serve as synchronization points during boot. You can change the default target your system boots into. When you set a default target unit, the current target remains unchanged until the next reboot.

Prerequisites

- You have Root access.

Procedure

1. Determine the current default target unit **systemd** uses to start the system:

```
# systemctl get-default
graphical.target
```

- List the currently loaded targets:

```
# systemctl list-units --type target
```

- Configure the system to use a different target unit by default:

```
# systemctl set-default <name>.target
```

Replace **<name>** with the name of the target unit you want to use by default.

Example:

```
# systemctl set-default multi-user.target
Removed /etc/systemd/system/default.target
Created symlink /etc/systemd/system/default.target -> /usr/lib/systemd/system/multi-
user.target
```

- Verify the default target unit:

```
# systemctl get-default
multi-user.target
```

- Optional: Switch to the new default target:

```
# systemctl isolate default.target
```

Alternatively, reboot the system.

Additional resources

- systemctl(1)**, **systemd.special(7)**, and **bootup(7)** man pages on your system

13.3.3. Changing the current target

On a running system, you can change the target unit in the current boot without reboot. If you switch to a different target, **systemd** starts all services and their dependencies that this target requires, and stops all services that the new target does not enable. Manually switching to a different target is only a temporary operation. When you reboot the host, systemd boots again into the default target.

Procedure

- Optional: Display the list of targets you can select:

```
# systemctl list-units --type target
```



NOTE

You can only isolate targets that have the **AllowIsolate=yes** option set in the unit files.

2. Change to a different target unit in the current boot:

```
# systemctl isolate <name>.target
```

Replace *<name>* with the name of the target unit you want to use in the current boot.

Example:

```
# systemctl isolate multi-user.target
```

This command starts the target unit named **multi-user** and all dependent units, and immediately stops all other unit.

Additional resources

- **systemctl(1)** man page on your system

13.3.4. Booting to rescue mode

You can boot to the *rescue mode* that provides a single-user environment for troubleshooting or repair if the system cannot get to a later target, and the regular booting process fails. In rescue mode, the system attempts to mount all local file systems and start certain important system services, but it does not activate network interfaces.

Prerequisites

- Root access

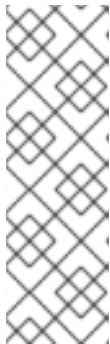
Procedure

- To enter the rescue mode, change the current target in the current session:

```
# systemctl rescue
```

Broadcast message from root@localhost on pts/0 (Fri 2023-03-24 18:23:15 CEST):

The system is going down to rescue mode NOW!



NOTE

This command is similar to **systemctl isolate rescue.target**, but it also sends an informative message to all users that are currently logged into the system.

To prevent **systemd** from sending a message, enter the following command with the **--no-wall** command-line option:

```
# systemctl --no-wall rescue
```

Troubleshooting

If your system is not able to enter the rescue mode, you can boot to *emergency mode*, which provides the most minimal environment possible. In emergency mode, the system mounts the root file system only for reading, does not attempt to mount any other local file systems, does not activate network interfaces, and only starts a few essential services.

13.3.5. Troubleshooting the boot process

As a system administrator, you can select a non-default target at boot time to troubleshoot the boot process. Changing the target at boot time affects only a single boot. You can boot to *emergency mode*, which provides the most minimal environment possible.

Procedure

1. Reboot the system, and interrupt the boot loader menu countdown by pressing any key except the Enter key, which would initiate a normal boot.
2. Move the cursor to the kernel entry that you want to start.
3. Press the E key to edit the current entry.
4. Move to the end of the line that starts with **linux** and press Ctrl+E to jump to the end of the line:

```
linux ($root)/vmlinuz-5.14.0-70.22.1.el9_0.x86_64 root=/dev/mapper/rhel-root ro crash\
kernel=auto resume=/dev/mapper/rhel-swap rd.lvm.lv/swap rhgb quiet
```

5. To choose an alternate boot target, append the **systemd.unit=** parameter to the end of the line that starts with **linux**:

```
linux ($root)/vmlinuz-5.14.0-70.22.1.el9_0.x86_64 root=/dev/mapper/rhel-root ro crash\
kernel=auto resume=/dev/mapper/rhel-swap rd.lvm.lv/swap rhgb quiet
systemd.unit=<name>.target
```

Replace **<name>** with the name of the target unit you want to use. For example, **systemd.unit=emergency.target**

6. Press Ctrl+X to boot with these settings.

13.4. SHUTTING DOWN, SUSPENDING, AND HIBERNATING THE SYSTEM

As a system administrator, you can use different power management options to manage power consumption, perform a proper shutdown to ensure that all data is saved, or restart the system to apply changes and updates.

13.4.1. System shutdown

To shut down the system, you can either use the **systemctl** utility directly, or call this utility through the **shutdown** command.

Using the **shutdown** utility has the following advantages:

- In RHEL 8, you can schedule a shutdown by using the **time** argument. This also gives users warning that a system shutdown has been scheduled.

13.4.2. Scheduling a system shutdown

As a system administrator, you can schedule a delayed shutdown to give users time to save their work and log off the system. Use the **shutdown** command to perform the following operations:

- Shut down the system and power off the machine at a certain time:

```
# shutdown --poweroff hh:mm
```

Where **hh:mm** is the time in the 24-hour time notation. To prevent new logins, the `/run/nologin` file is created 5 minutes before system shutdown.

When you use the time argument, you can notify users logged in to the system of the planned shutdown by specifying an optional *wall message*, for example **shutdown --poweroff 13:59 "Attention. The system will shut down at 13:59"**.

- Shut down and halt the system after a delay, without powering off the machine:

```
# shutdown --halt +m
```

Where **+m** is the delay time in minutes. You can use the **now** keyword as an alias for **+0**.

- Cancel a pending shutdown

```
# shutdown -c
```

Additional resources

- **shutdown(8)** manual page
- [Shutting down the system using the systemctl command](#)

13.4.3. Shutting down the system using the systemctl command

As a system administrator, you can shut down the system and power off the machine or shut down and halt the system without powering off the machine by using the **systemctl** command.

Prerequisites

- Root access

Procedure

Use the **systemctl** command to perform any of the following tasks:

- Shut down the system and power off the machine:

```
# systemctl poweroff
```

- Shut down and halt the system without powering off the machine:

```
# systemctl halt
```



NOTE

By default, running either of these commands causes **systemd** to send an informative message to all users that are currently logged into the system. To prevent **systemd** from sending this message, run the selected command with the **--no-wall** command line option.

13.4.4. Restarting the system

When you restart the system, **systemd** stops all running programs and services, the system shuts down, and then immediately starts again.

Prerequisites

- You have Root access.

Procedure

- Restart the system:

```
# systemctl reboot
```



NOTE

By default, when you use this command, **systemd** sends an informative message to all users that are currently logged into the system. To prevent **systemd** from sending this message, run this command with the **--no-wall** option.

13.4.5. Optimizing power consumption by suspending and hibernating the system

As a system administrator, you can manage power consumption, save energy on your systems, and preserve the current state of your system. To do so, apply one of the following modes:

- Suspend
- Hibernate
- Hybrid Sleep
- Suspend-then-hibernate

Prerequisites

- You have Root access.

Procedure

Choose the appropriate method for power saving:

- **Suspend** Suspending saves the system state in RAM and with the exception of the RAM module, powers off most of the devices in the machine. When you turn the machine back on, the system then restores its state from RAM without having to boot again. Because the system state is saved in RAM and not on the hard disk, restoring the system from suspend mode is significantly faster than from hibernation. However, the suspended system state is also vulnerable to power outages. To suspend the system, run:

```
# systemctl suspend
```

- **Hibernate** Hibernating saves the system state on the hard disk drive and powers off the machine. When you turn the machine back on, the system then restores its state from the saved data without having to boot again. Because the system state is saved on the hard disk and not

in RAM, the machine does not have to maintain electrical power to the RAM module. However, as a consequence, restoring the system from hibernation is significantly slower than restoring it from suspend mode. To hibernate the system, run:

```
# systemctl hibernate
```

- **Hybrid sleep** This combines elements of both hibernation and suspending. The system first saves the current state on the the hard disk drive, and enters a low-power state similar to suspending, which allows the system to resume more quickly. The benefit of hybrid sleep is that if the system loses power during the sleep state, it can still recover the previous state from the saved image on the hard disk, similar to hibernation. To hibernate and suspend the system, run:

```
# systemctl hybrid-sleep
```

- **Suspend-then-hibernate** This mode first suspends the system, which results in saving the current system state to RAM and putting the system in a low-power mode. The system hibernates if it remains suspended for a specific period of time that you can define in the **HibernateDelaySec** parameter. Hibernation saves the system state to the hard disk drive and shuts down the system completely. The suspend-then-hibernate mode provides the benefit of conserving battery power while you are still able to quickly resume work. Additionally, this mode ensures that your data is saved in case of a power failure. Suspend and then hibernate the system:

```
# systemctl suspend-then-hibernate
```

13.4.6. Changing the power button behavior

When you press the power button on your computer, it suspends or shuts down the system by default. You can customize this behavior according to your preferences.

13.4.6.1. Changing the behavior of the power button when pressing the button and GNOME is not running

When you press the power button in a non-graphical **systemd** target, it shuts down the system by default. You can customize this behavior according to your preferences.

Prerequisites

- Administrative access.

Procedure

1. Edit the **/etc/systemd/logind.conf** configuration file and set the **HandlePowerKey=poweroff** variable to one of the following options:

poweroff

Shut down the computer.

reboot

Reboot the system.

halt

Initiate a system halt.

kexec

Initiate a **kexec** reboot.

suspend

Suspend the system.

hibernate

Initiate system hibernation.

ignore

Do nothing.

For example, to reboot the system upon pressing the power button, use this setting:

```
HandlePowerKey=reboot
```

13.4.6.2. Changing the behavior of the power button when pressing the button and GNOME is running

On the graphical login screen or in the graphical user session, pressing the power button suspends the machine by default. This happens both in cases when the user presses the power button physically or when pressing a virtual power button from a remote console. You can select a different power button behavior.

Procedure

1. Create a local database for system-wide settings in the **/etc/dconf/db/local.d/01-power** file with the following content:

```
[org/gnome/settings-daemon/plugins/power]
power-button-action=<value>
```

Replace **<value>** with one of the following power button actions:

nothing

Does nothing .

suspend

Suspends the system.

hibernate

Hibernates the system.

interactive

Shows a pop-up query asking the user what to do.

With interactive mode, the system powers off automatically after 60 seconds when pressing the power button. However, you can choose a different behavior from the pop-up query.

2. Optional: Override the user's setting, and prevent the user from changing it. Enter the following configuration in the **/etc/dconf/db/local.d/locks/01-power** file:

```
/org/gnome/settings-daemon/plugins/power/power-button-action
```

3. Update the system databases:

```
# dconf update
```

■

4. Log out and back in again for the system-wide settings to take effect.

CHAPTER 14. CONFIGURING TIME SYNCHRONIZATION

Accurate timekeeping in an IT environment is important. A consistent time across all network devices improves the traceability of log files and certain protocols rely on synchronized clocks. For example, Kerberos uses time stamps to prevent replay attacks. The user space daemon updates the system clock running in the kernel. Starting with Red Hat Enterprise Linux 8, the **NTP** protocol is implemented by the **chronyd** daemon, available from the repositories in the **chrony** package.

14.1. INTRODUCTION TO CHRONY SUITE

The implementation of the **Network Time Protocol (NTP)** is **chrony**. You can use **chrony**:

- To synchronize the system clock with **NTP** servers
- To synchronize the system clock with a reference clock, for example a GPS receiver
- To synchronize the system clock with a manual time input
- As an **NTPv4(RFC 5905)** server or peer to provide a time service to other computers in the network

chrony performs well in a wide range of conditions:

- including intermittent network connections
- heavily congested networks
- changing temperatures (ordinary computer clocks are sensitive to temperature)
- systems that do not run continuously, or run on a virtual machine.

Typical accuracy between two machines synchronized over the Internet is within a few milliseconds, and for machines on a LAN within tens of microseconds. Hardware timestamping or a hardware reference clock may improve accuracy between two machines synchronized to a sub-microsecond level.

chrony consists of **chronyd**, a daemon that runs in user space, and **chronyc**, a command line program which can be used to monitor the performance of **chronyd** and to change various operating parameters when it is running.

The **chronyd** daemon can be monitored and controlled by the command line utility **chronyc**. This utility provides a command prompt which allows entering a number of commands to query the current state of **chronyd** and make changes to its configuration. By default, **chronyd** accepts only commands from a local instance of **chronyc**, but it can be configured to accept monitoring commands also from remote hosts. The remote access should be restricted.

14.2. USING CHRONYC TO CONTROL CHRONYD

You can control **chronyd** by using the **chronyc** command line utility.

Procedure

1. To make changes to the local instance of **chronyd** using the command line utility **chronyc** in interactive mode, enter the following command as **root**:

```
# chronyc
```

chronyc must run as **root** if some of the restricted commands are to be used.

The **chronyc** command prompt will be displayed as follows:

```
chronyc>
```

2. To list all of the commands, type **help**.
3. Alternatively, the utility can also be invoked in non-interactive command mode if called together with a command as follows:

```
chronyc command
```



NOTE

Changes made using **chronyc** are not permanent, they will be lost after a **chronyd** restart. For permanent changes, modify **/etc/chrony.conf**.

14.3. MIGRATING TO CHRONY

In Red Hat Enterprise Linux 7, users could choose between **ntp** and **chrony** to ensure accurate timekeeping. For differences between **ntp** and **chrony**, **ntpd** and **chronyd**, see [Differences between ntpd and chronyd](#).

Starting with Red Hat Enterprise Linux 8, **ntp** is no longer supported. **chrony** is enabled by default. For this reason, you might need to migrate from **ntp** to **chrony**.

Migrating from **ntp** to **chrony** is straightforward in most cases. The corresponding names of the programs, configuration files and services are:

Table 14.1. Corresponding names of the programs, configuration files and services when migrating from ntp to chrony

ntp name	chrony name
/etc/ntp.conf	/etc/chrony.conf
/etc/ntp/keys	/etc/chrony.keys
ntpd	chronyd
ntpq	chronyc
ntpd.service	chronyd.service
ntp-wait.service	chrony-wait.service

The **ntpdate** and **sntp** utilities, which are included in the **ntp** distribution, can be replaced with **chronyd** using the **-q** option or the **-t** option. The configuration can be specified on the command line to avoid reading **/etc/chrony.conf**. For example, instead of running **ntpdate ntp.example.com**, **chronyd** could be started as:

```
# chronyd -q 'server ntp.example.com iburst'
2018-05-18T12:37:43Z chronyd version 3.3 starting (+CMDMON +NTP +REFCLOCK +RTC
+PRIVDROP +SCFILTER +SIGND +ASYNCDNS +SECHASH +IPV6 +DEBUG)
2018-05-18T12:37:43Z Initial frequency -2.630 ppm
2018-05-18T12:37:48Z System clock wrong by 0.003159 seconds (step)
2018-05-18T12:37:48Z chronyd exiting
```

The **ntpstat** utility, which was previously included in the **ntp** package and supported only **ntpd**, now supports both **ntpd** and **chronyd**. It is available in the **ntpstat** package.

14.3.1. Migration script

A Python script called **ntp2chrony.py** is included in the documentation of the **chrony** package (**/usr/share/doc/chrony**). The script automatically converts an existing **ntp** configuration to **chrony**. It supports the most common directives and options in the **ntp.conf** file. Any lines that are ignored in the conversion are included as comments in the generated **chrony.conf** file for review. Keys that are specified in the **ntp** key file, but are not marked as trusted keys in **ntp.conf** are included in the generated **chrony.keys** file as comments.

By default, the script does not overwrite any files. If **/etc/chrony.conf** or **/etc/chrony.keys** already exist, the **-b** option can be used to rename the file as a backup. The script supports other options. The **--help** option prints all supported options.

An example of an invocation of the script with the default **ntp.conf** provided in the **ntp** package is:

```
# python3 /usr/share/doc/chrony/ntp2chrony.py -b -v
Reading /etc/ntp.conf
Reading /etc/ntp/crypto/pw
Reading /etc/ntp/keys
Writing /etc/chrony.conf
Writing /etc/chrony.keys
```

The only directive ignored in this case is **disable monitor**, which has a chrony equivalent in the **noclientlog** directive, but it was included in the default **ntp.conf** only to mitigate an amplification attack.

The generated **chrony.conf** file typically includes a number of **allow** directives corresponding to the restrict lines in **ntp.conf**. If you do not want to run **chronyd** as an **NTP** server, remove all **allow** directives from **chrony.conf**.

14.4. USING CHRONY

The following sections describe how to start, and stop **chronyd**, and how to check if **chrony** is synchronized. Sections also describe how to manually adjust System Clock.

14.4.1. Managing chrony

You can start, stop, and check the status of **chronyd**.

1. The **chrony** suite is installed by default on Red Hat Enterprise Linux. To ensure that it is, run the following command as **root**:

```
# yum install chrony
```

The default location for the **chrony** daemon is **/usr/sbin/chronyd**. The command line utility will be installed to **/usr/bin/chronyc**.

2. To check the status of **chronyd**, issue the following command:

```
$ systemctl status chronyd
chronyd.service - NTP client/server
   Loaded: loaded (/usr/lib/systemd/system/chronyd.service; enabled)
   Active: active (running) since Wed 2013-06-12 22:23:16 CEST; 11h ago
```

3. To start **chronyd**, issue the following command as **root**:

```
# systemctl start chronyd
```

To ensure **chronyd** starts automatically at system start, issue the following command as **root**:

```
# systemctl enable chronyd
```

4. To stop **chronyd**, issue the following command as **root**:

```
# systemctl stop chronyd
```

To prevent **chronyd** from starting automatically at system start, issue the following command as **root**:

```
# systemctl disable chronyd
```

14.4.2. Checking if chrony is synchronized

You can check if **chrony** is synchronized with the use of the **tracking**, **sources**, and **sourcestats** commands.

Procedure

1. To check **chrony** tracking, enter:

```
$ chronyc tracking
Reference ID    : CB00710F (ntp-server.example.net)
Stratum        : 3
Ref time (UTC) : Fri Jan 27 09:49:17 2017
System time    : 0.000006523 seconds slow of NTP time
Last offset    : -0.000006747 seconds
RMS offset     : 0.000035822 seconds
Frequency      : 3.225 ppm slow
Residual freq  : 0.000 ppm
Skew           : 0.129 ppm
Root delay     : 0.013639022 seconds
Root dispersion : 0.001100737 seconds
Update interval : 64.2 seconds
Leap status    : Normal
```

2. The **chronyc sources** command displays information about the current time sources that **chronyd** is accessing.

\$ chronyc sources

```

210 Number of sources = 3
MS Name/IP address      Stratum Poll Reach LastRx Last sample
=====
====
#* GPS0                  0  4  377  11  -479ns[ -621ns] /- 134ns
^? a.b.c                 2  6  377  23  -923us[ -924us] +/- 43ms
^ d.e.f                  1  6  377  21  -2629us[-2619us] +/- 86ms

```

You can specify the optional **-v** argument to print more verbose information. In this case, extra caption lines are shown as a reminder of the meanings of the columns.

3. The **sourcestats** command displays information about the drift rate and offset estimation process for each of the sources currently being examined by **chronyd**. To check **chrony** source statistics, issue the following command:

\$ chronyc sourcestats

```

210 Number of sources = 1
Name/IP Address      NP NR Span Frequency Freq Skew Offset Std Dev
=====
====
abc.def.ghi          11  5 46m  -0.001   0.045   1us  25us

```

The optional argument **-v** can be specified, meaning verbose. In this case, extra caption lines are shown as a reminder of the meanings of the columns.

Additional resources

- **chronyc(1)** man page on your system

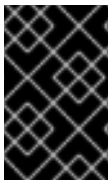
14.4.3. Manually adjusting the System Clock

You can manually adjust the System Clock.

Procedure

- To step the system clock immediately, bypassing any adjustments in progress by slewing, enter:

```
# chronyc makestep
```

**IMPORTANT**

If the **rtcf** directive is used, the real-time clock should not be manually adjusted. Random adjustments would interfere with **chrony**'s need to measure the rate at which the real-time clock drifts.

14.4.4. Disabling a chrony dispatcher script

The **chrony** dispatcher script manages the online and offline state of the NTP servers. As a system administrator, you can disable the dispatcher script to keep **chronyd** polling the servers constantly.

The NetworkManager executes the **chrony** dispatcher script during interface reconfiguration, stop or start operations. However, if you configure certain interfaces or routes outside of NetworkManager, you can encounter the following situation:

1. The dispatcher script might run when no route to the NTP servers exists, causing the NTP servers to switch to the offline state.
2. If you establish the route later, the script does not run again by default, and the NTP servers remain in the offline state.

To ensure that **chronyd** can synchronize with your NTP servers, which have separately managed interfaces, disable the dispatcher script.

Procedure

- To disable the **chrony** dispatcher script, edit the **/etc/NetworkManager/dispatcher.d/20-chrony-onoffline** file as follows:

```
#!/bin/sh
exit 0
```



NOTE

When you upgrade or reinstall the **chrony** package, the packaged version of the dispatcher script replaces your modified dispatcher script.

14.4.5. Setting up chrony in an isolated network

For a network that is never connected to the Internet, one computer is selected to be the primary timeserver. The other computers are either direct clients of the server, or clients of clients. On the server, the drift file must be manually set with the average rate of drift of the system clock. If the server is rebooted, it will obtain the time from surrounding systems and calculate an average to set its system clock. Thereafter it resumes applying adjustments based on the drift file. The drift file will be updated automatically when the **settime** command is used.

To set up **chrony** for a system in an isolated network, follow the steps mentioned below:

Procedure

1. On the system selected to be the server, edit **/etc/chrony.conf** as follows:

```
driftfile /var/lib/chrony/drift
commandkey 1
keyfile /etc/chrony.keys
initstepslew 10 client1 client3 client6
local stratum 8
manual
allow <subnet>
```

Where **<subnet>** is the network from which the clients are allowed to connect. Use Classless Inter-Domain Routing (CIDR) notation to specify the subnet.

2. On the systems selected to be direct clients of the server, edit the **/etc/chrony.conf** as follows:

```
server <server_fqdn>
driftfile /var/lib/chrony/drift
logdir /var/log/chrony
log measurements statistics tracking
```



```
keyfile /etc/chrony.keys
commandkey 24
local stratum 10
initstepslew 20 ntp1.example.net
allow <server_ip_address>
```

Where **<server_fqdn>** is the host name of the server, and **<server_ip_address>** is the address of the server. Clients with this configuration will resynchronize with the server if it restarts.

On the client systems which are not to be direct clients of the server, the **/etc/chrony.conf** file should be the same except that the **local** and **allow** directives should be omitted.

In an isolated network, you can also use the **local** directive that enables a local reference mode, which allows **chronyd** operating as an **NTP** server to appear synchronized to real time, even when it was never synchronized or the last update of the clock happened a long time ago.

To allow multiple servers in the network to use the same local configuration and to be synchronized to one another, without confusing clients that poll more than one server, use the **orphan** option of the **local** directive which enables the orphan mode. Each server needs to be configured to poll all other servers with **local**. This ensures that only the server with the smallest reference ID has the local reference active and other servers are synchronized to it. When the server fails, another one will take over.

14.4.6. Configuring remote monitoring access

The **chronyc** utility can access **chronyd** by using the following methods:

- IPv4 or IPv6.
- A domain socket, which is accessible locally by the **root** and **chrony** user.

By default, **chronyc** connects to the Unix domain socket. The default path is **/var/run/chrony/chronyd.sock**. If this connection fails, **chronyc** tries to connect to 127.0.0.1 and then ::1.

Only the following monitoring commands, which do not affect the behavior of **chronyd**, are allowed from the network:

- activity
- manual list
- rtcddata
- smoothing
- sources
- sourcestats
- tracking
- waitsync

The set of hosts from which **chronyd** accepts these commands can be configured by using the following methods:

- You can use the **cmdallow** directive in the configuration file of **chronyd**.

- Run the **cmdallow** command in **chronyc**.

By default, the commands are accepted only from localhost (127.0.0.1 or ::1).

All other commands are allowed only through the Unix domain socket. When sent over the network, **chronyd** responds with a **Not authorised** error, even if it is from localhost.

The following procedure describes how to access chronyd remotely with **chronyc**.

Procedure

1. Configure **chrony** to listen on local interface by adding the following to the **/etc/chrony.conf** file:

```
bindcmdaddress 0.0.0.0
```

and

```
bindcmdaddress ::
```

2. Allow commands from remote IP addresses, networks, and subnet:
Add the following content to the **/etc/chrony.conf** file:

```
cmdallow 192.168.1.0/24
```

```
cmdallow 2001:db8::/64
```

3. Open port 323 in the firewall to allow connections from remote systems:

```
# firewall-cmd --permanent --add-port=323/udp
```

4. Reload the firewall configuration:

```
# firewall-cmd --reload
```

Additional resources

- **chrony.conf(5)** man page on your system

14.4.7. Managing time synchronization using RHEL system roles

You can manage time synchronization on multiple target machines using the **timesync** role. The **timesync** role installs and configures an NTP or PTP implementation to operate as an NTP or PTP client to synchronize the system clock.

Note that using the **timesync** role also facilitates [migration to chrony](#), because you can use the same playbook on all versions of Red Hat Enterprise Linux starting with RHEL 6 regardless of whether the system uses **ntp** or **chrony** to implement the NTP protocol.

**WARNING**

The **timesync** role replaces the configuration of the given or detected provider service on the managed host. Previous settings are lost, even if they are not specified in the role variables. The only preserved setting is the choice of provider if the **timesync_ntp_provider** variable is not defined.

The following example shows how to apply the **timesync** role in a situation with just one pool of servers.

Example 14.1. An example playbook applying the timesync role for a single pool of servers

```
---
- hosts: timesync-test
  vars:
    timesync_ntp_servers:
      - hostname: 2.rhel.pool.ntp.org
        pool: yes
        iburst: yes
  roles:
    - rhel-system-roles.timesync
```

For a detailed reference on **timesync** role variables, install the **rhel-system-roles** package, and see the **README.md** or **README.html** files in the `/usr/share/doc/rhel-system-roles/timesync` directory.

Additional resources

- [Preparing a control node and managed nodes to use RHEL system roles](#)

14.4.8. Additional resources

- **chronyc(1)** and **chronyd(8)** man pages on your system
- [Frequently Asked Questions](#)

14.5. CHRONY WITH HW TIMESTAMPING

Hardware timestamping (HW) in some Network Interface Controller (NICs) provides accurate timestamping of incoming and outgoing packets. **NTP** timestamps are usually created by the kernel and **chronyd** with the use of the system clock. However, when HW timestamping is enabled, the NIC uses its own clock to generate the timestamps when packets are entering or leaving the link layer or the physical layer. When used with **NTP**, hardware timestamping can significantly improve the accuracy of synchronization. For best accuracy, both **NTP** servers and **NTP** clients need to use hardware timestamping. Under ideal conditions, a sub-microsecond accuracy may be possible.

Another protocol for time synchronization that uses hardware timestamping is **PTP**.

Unlike **NTP**, **PTP** relies on assistance in network switches and routers. If you want to achieve the best accuracy of synchronization, use **PTP** on networks that have switches and routers with **PTP** support, and prefer **NTP** on networks that do not have such switches and routers.

14.5.1. Verifying support for hardware timestamping

To verify that hardware timestamping with **NTP** is supported by an interface, use the **ethtool -T** command. An interface can be used for hardware timestamping with **NTP** if **ethtool** lists the **SOF_TIMESTAMPING_TX_HARDWARE** and **SOF_TIMESTAMPING_TX_SOFTWARE** capabilities and also the **HWTSTAMP_FILTER_ALL** filter mode.

Procedure

- Display a device's time stamping capabilities and associated PTP hardware clock:

```
# ethtool -T enp1s0
```

14.5.2. Enabling hardware timestamping

You can enable hardware timestamping on one or multiple interfaces by using the **hwtimestamp** directive in the **/etc/chrony.conf** file. The directive can either specify a single interface, or a wildcard character can be used to enable hardware timestamping on all interfaces that support it.

Procedure

1. Edit the **/etc/chrony.conf** file and make the following changes:

- a. Add the **hwtimestamp** setting for interfaces which support hardware timestamping. For example:

```
hwtimestamp enp1s0
hwtimestamp eno*
```

You can use the ***** wildcard if no other application, such as **ptp4l** uses hardware timestamping.

- b. Configure a short client polling interval by appending the **minpoll** and **maxpoll** options to the server setting, for example:

```
server ntp.example.com local minpoll 0 maxpoll 0
```

For hardware timestamping, you must configure a shorter polling interval than the default range (64-1024 seconds) to minimize the offset of the system clock.

- c. Enable the NTP interleaved mode by appending the **xleave** option to the server setting:

```
server ntp.example.com local minpoll 0 maxpoll 0 xleave
```

With this setting, chrony gets the hardware transmit timestamp only after sending a packet. This behavior prevents the server from saving the timestamp in packets to which it responds. With the **xleave** option, chrony can receive transmit timestamps that were generated after the transmission.

- d. Optional: Increase the maximum size of memory allocated for logging of client's access on the server, for example:

```
clientloglimit 100000000
```

The default server configuration allows a few thousands of clients to use the interleaved mode concurrently. By increasing the value of the **clientloglimit** setting, you can configure the server for a large number of clients.

2. Restart the chronyd service:

```
# systemctl restart chronyd
```

Verification

1. Optional: Verify in the **/var/log/messages** log file that hardware timesamping is enabled:

```
chronyd[4081]: Enabled HW timestamping on enp1s0
chronyd[4081]: Enabled HW timestamping on eno1
```

2. If chronyd is configured as an NTP client or peer, display the transmit and receive timestamping modes and the interleaved mode:

```
# chronyc ntpdata
```

Output:

```
[literal,subs="+quotes,verbatim,normal"]
```

```
Remote address : 203.0.113.15 (CB00710F)
Remote port   : 123
Local address  : 203.0.113.74 (CB00714A)
Leap status    : Normal
Version       : 4
Mode          : Server
Stratum       : 1
Poll interval  : 0 (1 seconds)
Precision     : -24 (0.000000060 seconds)
Root delay     : 0.000015 seconds
Root dispersion : 0.000015 seconds
Reference ID   : 47505300 (GPS)
Reference time : Wed May 03 13:47:45 2017
Offset        : -0.000000134 seconds
Peer delay     : 0.000005396 seconds
Peer dispersion : 0.000002329 seconds
Response time  : 0.000152073 seconds
Jitter asymmetry: +0.00
NTP tests      : 111 111 1111
Interleaved    : Yes
Authenticated  : No
TX timestamping : Hardware
RX timestamping : Hardware
```

```
Total TX      : 27
Total RX      : 27
Total valid RX : 27
```

- Report the stability of NTP measurements:

```
# chronyc sourcestats
```

```
Output:
```

```
[literal,subs="+quotes,verbatim,normal"]
```

```
....
```

```
210 Number of sources = 1
```

Name/IP Address	NP	NR	Span	Frequency	Freq Skew	Offset	Std Dev
ntp.local	12	7	11	+0.000	0.019	+0ns	49ns

```
....
```

This stability is reported in the **Std Dev** column. With hardware timestamping enabled, stability of NTP measurements should be in tens or hundreds of nanoseconds, under normal load.

14.5.3. Configuring PTP-NTP bridge

If a highly accurate Precision Time Protocol (**PTP**) primary timeserver is available in a network that does not have switches or routers with **PTP** support, a computer may be dedicated to operate as a **PTP** client and a stratum-1 **NTP** server. Such a computer needs to have two or more network interfaces, and be close to the primary timeserver or have a direct connection to it. This will ensure highly accurate synchronization in the network.

Procedure

- Configure the **ptp4l** and **phc2sys** programs from the **linuxptp** packages to use one interface to synchronize the system clock using **PTP**.
- Configure **chronyd** to provide the system time using the other interface:

```
bindaddress 203.0.113.74
hwtimestamp enp1s0
local stratum 1
```

- Restart the chronyd service:

```
# systemctl restart chronyd
```

14.6. ACHIEVING SOME SETTINGS PREVIOUSLY SUPPORTED BY NTP IN CHRONY

Some settings that were in previous major version of Red Hat Enterprise Linux supported by **ntp**, are not supported by **chrony**. The following sections list such settings, and describe ways to achieve them on a system with **chrony**.

14.6.1. Monitoring by ntpq and ntpdc

chronyd cannot be monitored by the **ntpq** and **ntpd** utilities from the **ntp** distribution, because **chrony** does not support the **NTP** modes 6 and 7. It supports a different protocol and **chronyc** is the client implementation. For more information, see the **chronyc(1)** man page on your system.

To monitor the status of the system clock synchronized by **chronyd**, you can:

- Use the tracking command
- Use the **ntpstat** utility, which supports **chrony** and provides a similar output as it used to with **ntpd**

Example 14.2. Using the tracking command

```
$ chronyc -n tracking
Reference ID   : 0A051B0A (10.5.27.10)
Stratum       : 2
Ref time (UTC) : Thu Mar 08 15:46:20 2018
System time    : 0.000000338 seconds slow of NTP time
Last offset    : +0.000339408 seconds
RMS offset     : 0.000339408 seconds
Frequency      : 2.968 ppm slow
Residual freq  : +0.001 ppm
Skew           : 3.336 ppm
Root delay     : 0.157559142 seconds
Root dispersion : 0.001339232 seconds
Update interval : 64.5 seconds
Leap status    : Normal
```

Example 14.3. Using the ntpstat utility

```
$ ntpstat
synchronised to NTP server (10.5.27.10) at stratum 2
time correct to within 80 ms
polling server every 64 s
```

14.6.2. Using authentication mechanism based on public key cryptography

In Red Hat Enterprise Linux 7, **ntp** supported **Autokey**, which is an authentication mechanism based on public key cryptography.

In Red Hat Enterprise Linux 8, **chronyd** supports Network Time Security (NTS), a modern secure authentication mechanism, instead of **Autokey**. For more information, see [Overview of Network Time Security \(NTS\) in chrony](#).

14.6.3. Using ephemeral symmetric associations

In Red Hat Enterprise Linux 7, **ntpd** supported ephemeral symmetric associations, which can be mobilized by packets from peers which are not specified in the **ntp.conf** configuration file. In Red Hat Enterprise Linux 8, **chronyd** needs all peers to be specified in **chrony.conf**. Ephemeral symmetric associations are not supported.

Note that using the client/server mode enabled by the **server** or **pool** directive is more secure compared to the symmetric mode enabled by the **peer** directive.

14.6.4. multicast/broadcast client

Red Hat Enterprise Linux 7 supported the broadcast/multicast **NTP** mode, which simplifies configuration of clients. With this mode, clients can be configured to just listen for packets sent to a multicast/broadcast address instead of listening for specific names or addresses of individual servers, which may change over time.

In Red Hat Enterprise Linux 8, **chronyd** does not support the broadcast/multicast mode. The main reason is that it is less accurate and less secure than the ordinary client/server and symmetric modes.

There are several options of migration from an **NTP** broadcast/multicast setup:

- Configure DNS to translate a single name, such as `ntp.example.com`, to multiple addresses of different servers
Clients can have a static configuration using only a single `pool` directive to synchronize with multiple servers. If a server from the pool becomes unreachable, or otherwise unsuitable for synchronization, the clients automatically replace it with another server from the pool.
- Distribute the list of **NTP** servers over DHCP
When NetworkManager gets a list of **NTP** servers from the DHCP server, **chronyd** is automatically configured to use them. This feature can be disabled by adding **PEERNTP=no** to the `/etc/sysconfig/network` file.
- Use the **Precision Time Protocol (PTP)**
This option is suitable mainly for environments where servers change frequently, or if a larger group of clients needs to be able to synchronize to each other without having a designated server.

PTP was designed for multicast messaging and works similarly to the **NTP** broadcast mode. A **PTP** implementation is available in the **linuxptp** package.

PTP normally requires hardware timestamping and support in network switches to perform well. However, **PTP** is expected to work better than **NTP** in the broadcast mode even with software timestamping and no support in network switches.

In networks with very large number of **PTP** clients in one communication path, it is recommended to configure the **PTP** clients with the **hybrid_e2e** option to reduce the amount of network traffic generated by the clients. You can configure a computer running **chronyd** as an **NTP** client, and possibly **NTP** server, to operate also as a primary **PTP** timeserver to distribute synchronized time to a large number of computers using multicast messaging.

14.7. OVERVIEW OF NETWORK TIME SECURITY (NTS) IN CHRONY

Network Time Security (NTS) is an authentication mechanism for Network Time Protocol (NTP), designed to scale substantial clients. It verifies that the packets received from the server machines are unaltered while moving to the client machine. Network Time Security (NTS) includes a Key Establishment (NTS-KE) protocol that automatically creates the encryption keys used between the server and its clients.

**WARNING**

NTS is not compatible with the FIPS and OSPP profile. When you enable the FIPS and OSPP profile, **chronyd** that is configured with NTS can abort with a fatal message. You can disable the OSPP profile and FIPS mode for **chronyd** service by adding the **GNUTLS_FORCE_FIPS_MODE=0** setting to the **/etc/sysconfig/chronyd** file.

14.7.1. Enabling Network Time Security (NTS) on a client

By default, Network Time Security (NTS) is not enabled. You can enable NTS in the **/etc/chrony.conf**. For that, perform the following steps:

Prerequisites

- The time server supports NTS.

Procedure

Edit the **/etc/chrony.conf** file, and make the following changes:

1. Specify the server with the **nts** option in addition to the recommended **iburst** option.

```
For example:
server time.example.com iburst nts
server nts.netnod.se iburst nts
server ptbtime1.ptb.de iburst nts
```

2. Add the following setting to avoid repeating the Network Time Security-Key Establishment (NTS-KE) session during system boot:

```
ntsdumpdir /var/lib/chrony
```

3. Add the following line to **/etc/sysconfig/network** to disable synchronization with Network Time Protocol (NTP) servers provided by **DHCP**:

```
PEERNTP=no
```

4. Restart the **chronyd** service:

```
systemctl restart chronyd
```

Verification

- Verify if the **NTS** keys were successfully established:

```
# chronyc -N authdata

Name/IP address  Mode KeyID Type KLen Last Atmp  NAK Cook CLen
=====
```

```
time.example.com NTS 1 15 256 33m 0 0 8 100
nts.netnod.se NTS 1 15 256 33m 0 0 8 100
ptbtime1.ptb.de NTS 1 15 256 33m 0 0 8 100
```

The **KeyID**, **Type**, and **KLen** should have non-zero values. If the value is zero, check the system log for error messages from **chronyd**.

- Verify the client is making NTP measurements:

chronyc -N sources

```
MS Name/IP address Stratum Poll Reach LastRx Last sample
=====
time.example.com 3      6 377 45 +355us[ +375us] +/- 11ms
nts.netnod.se 1      6 377 44 +237us[ +237us] +/- 23ms
ptbtime1.ptb.de 1      6 377 44 -170us[ -170us] +/- 22ms
```

The **Reach** column should have a non-zero value; ideally 377. If the value rarely gets 377 or never gets to 377, it indicates that NTP requests or responses are getting lost in the network.

Additional resources

- **chrony.conf(5)** man page on your system

14.7.2. Enabling Network Time Security (NTS) on a time server

If you run your own Network Time Protocol (NTP) server, you can enable the server Network Time Security (NTS) support to facilitate its clients to synchronize securely.

If the NTP server is a client of other servers, that is, it is not a Stratum 1 server, it should use NTS or symmetric key for its synchronization.

Prerequisites

- Server private key in **PEM** format
- Server certificate with required intermediate certificates in **PEM** format

Procedure

1. Edit the **/etc/chrony.conf** file, and make the following changes:

```
ntsserverkey /etc/pki/tls/private/<ntp-server.example.net>.key
ntsservercert /etc/pki/tls/certs/<ntp-server.example.net>.crt
```

2. Set permissions on both the private key and the certificate file that allow the chrony user to read the files, for example

```
# chown root:chrony /etc/pki/tls/private/<ntp-server.example.net>.key
/etc/pki/tls/certs/<ntp-server.example.net>.crt

# chmod 644 /etc/pki/tls/private/<ntp-server.example.net>.key /etc/pki/tls/certs/<ntp-
server.example.net>.crt
```

3. Ensure that the **ntsdumpdir /var/lib/chrony** setting is present.
4. Open the required ports in firewallld:

```
# firewall-cmd --permanent --add-port={323/udp,4460/tcp}
# firewall-cmd --reload
```

5. Restart the **chronyd** service:

```
# systemctl restart chronyd
```

Verification

1. Perform a test from a client machine:

```
$ chronyd -Q -t 3 'server
```

```
ntp-server.example.net iburst nts maxsamples 1'
2021-09-15T13:45:26Z chronyd version 4.1 starting (+CMDMON +NTP +REFCLOCK +RTC
+PRIVDROP +SCFILTER +SIGND +ASYNCDNS +NTS +SECHASH +IPV6 +DEBUG)
2021-09-15T13:45:26Z Disabled control of system clock
2021-09-15T13:45:28Z System clock wrong by 0.002205 seconds (ignored)
2021-09-15T13:45:28Z chronyd exiting
```

The **System clock wrong** message indicates the NTP server is accepting NTS-KE connections and responding with NTS-protected NTP messages.

2. Verify the NTS-KE connections and authenticated NTP packets observed on the server:

```
# chronyc serverstats
```

```
NTP packets received      : 7
NTP packets dropped       : 0
Command packets received  : 22
Command packets dropped   : 0
Client log records dropped : 0
NTS-KE connections accepted: 1
NTS-KE connections dropped : 0
Authenticated NTP packets: 7
```

If the value of the **NTS-KE connections accepted** and **Authenticated NTP packets** field is a non-zero value, it means that at least one client was able to connect to the NTS-KE port and send an authenticated NTP request.

CHAPTER 15. USING LANGPACKS

Langpacks are meta-packages which install extra add-on packages containing translations, dictionaries and locales for every package installed on the system.

On a Red Hat Enterprise Linux 8 system, **langpacks** installation is based on the **langpacks-<langcode>** language meta-packages and RPM weak dependencies (Supplements tag).

There are two prerequisites to be able to use **langpacks** for a selected language. If these prerequisites are fulfilled, the language meta-packages pull their langpack for the selected language automatically in the transaction set.

Prerequisites

- The **langpacks-<langcode>** language meta-package for the selected language has been installed on the system.

On Red Hat Enterprise Linux 8, the langpacks meta packages are installed automatically with the initial installation of the operating system using the Anaconda installer, because these packages are available in the in Application Stream repository.

For more information, see [Checking languages that provide langpacks](#).

- The base package, for which you want to search the locale packages, has already been installed on the system.

15.1. CHECKING LANGUAGES THAT PROVIDE LANGPACKS

Follow this procedure to check which languages provide langpacks.

Procedure

- Execute the following command:

```
# yum list langpacks-*
```

15.2. WORKING WITH RPM WEAK DEPENDENCY-BASED LANGPACKS

This section describes multiple actions that you may want to perform when querying RPM weak dependency-based langpacks, installing or removing language support.

15.2.1. Listing already installed language support

To list the already installed language support, use this procedure.

Procedure

- Execute the following command:

```
# yum list installed langpacks*
```

15.2.2. Checking the availability of language support

To check if language support is available for any language, use the following procedure.

Procedure

- Execute the following command:

```
# yum list available langpacks*
```

15.2.3. Listing packages installed for a language

To list what packages get installed for any language, use the following procedure:

Procedure

- Execute the following command:

```
# yum repoquery --whatsupplements langpacks-<locale_code>
```

15.2.4. Installing language support

To add new a language support, use the following procedure.

Procedure

- Execute the following command:

```
# yum install langpacks-<locale_code>
```

15.2.5. Removing language support

To remove any installed language support, use the following procedure.

Procedure

- Execute the following command:

```
# yum remove langpacks-<locale_code>
```

15.3. SAVING DISK SPACE BY USING GLIBC-LANGPACK-<LOCALE_CODE>

Currently, all locales are stored in the **/usr/lib/locale/locale-archive** file, which requires a lot of disk space.

On systems where disk space is a critical issue, such as containers and cloud images, or only a few locales are needed, you can use the glibc locale langpack packages (**glibc-langpack-<locale_code>**).

To install locales individually, and thus gain a smaller package installation footprint, use the following procedure.

Procedure

- Execute the following command:

```
# yum install glibc-langpack-<locale_code>
```

When installing the operating system with Anaconda, **glibc-langpack-<locale_code>** is installed for the language you used during the installation and also for the languages you selected as additional languages. Note that **glibc-all-langpacks**, which contains all locales, is installed by default, so some locales are duplicated. If you installed **glibc-langpack-<locale_code>** for one or more selected languages, you can delete **glibc-all-langpacks** after the installation to save the disk space.

Note that installing only selected **glibc-langpack-<locale_code>** packages instead of **glibc-all-langpacks** has impact on run time performance.



NOTE

If disk space is not an issue, keep all locales installed by using the **glibc-all-langpacks** package.

CHAPTER 16. DUMPING A CRASHED KERNEL FOR LATER ANALYSIS

To analyze why a system crashed, you can use the **kdump** service to save the contents of the system's memory for later analysis. This section provides a brief introduction to **kdump**, and information about configuring **kdump** using the RHEL web console or using the corresponding RHEL system role.

16.1. WHAT IS KDUMP

kdump is a service that provides a crash dumping mechanism and generates a crash dump or a **vmcore** dump file. **vmcore** includes the contents of the system memory for analysis and troubleshooting. **kdump** uses the **kexec** system call to boot into the second kernel, *capture kernel*, without a reboot. This kernel captures the contents of the crashed kernel's memory and saves it into a file. The second kernel is available in a reserved part of the system memory.



IMPORTANT

A kernel crash dump can be the only information available if a system failure occur. Therefore, operational **kdump** is important in mission-critical environments. Red Hat advises to regularly update and test **kexec-tools** in your normal kernel update cycle. This is important when you install new kernel features.

If you have multiple kernels on a machine, you can enable **kdump** for all installed kernels or for specified kernels only. When you install **kdump**, the system creates a default **/etc/kdump.conf** file. **/etc/kdump.conf** includes the default minimum **kdump** configuration, which you can edit to customize the **kdump** configuration.

16.2. CONFIGURING KDUMP MEMORY USAGE AND TARGET LOCATION IN WEB CONSOLE

You can configure the memory reserve for the **kdump** kernel and also specify the target location to capture the **vmcore** dump file with the RHEL web console interface.

Prerequisites

- The web console must be installed and accessible. For details, see [Installing the web console](#).

Procedure

1. In the web console, open the **Kernel dump** tab and start the **kdump** service by setting the **Kernel crash dump** switch to on.
2. Configure the **kdump** memory usage in the terminal, for example:

```
$ sudo grubby --update-kernel ALL --args crashkernel=512M
```

Restart the system to apply the changes.

3. In the **Kernel dump** tab, click **Edit** at the end of the **Crash dump location** field.
4. Specify the target directory for saving the **vmcore** dump file:
 - For a local filesystem, select **Local Filesystem** from the drop-down menu.

- For a remote system by using the SSH protocol, select **Remote over SSH** from the drop-down menu and specify the following fields:
 - In the **Server** field, enter the remote server address.
 - In the **SSH key** field, enter the SSH key location.
 - In the **Directory** field, enter the target directory.
- For a remote system by using the NFS protocol, select **Remote over NFS** from the drop-down menu and specify the following fields:
 - In the **Server** field, enter the remote server address.
 - In the **Export** field, enter the location of the shared folder of an NFS server.
 - In the **Directory** field, enter the target directory.

**NOTE**

You can reduce the size of the **vmcore** file by selecting the **Compression** checkbox.

5. Optional: Display the automation script by clicking **View automation script**
A window with the generated script opens. You can browse a shell script and an Ansible playbook generation options tab.
6. Optional: Copy the script by clicking **Copy to clipboard**
You can use this script to apply the same configuration on multiple machines.

Verification

1. Click **Test configuration**.
2. Click **Crash system** under **Test kdump settings**.

**WARNING**

When you start the system crash, the kernel operation stops and results in a system crash with data loss.

Additional resources

- [Supported kdump targets](#)

16.3. KDUMP USING RHEL SYSTEM ROLES

RHEL system roles is a collection of Ansible roles and modules that provide a consistent configuration interface to remotely manage multiple RHEL systems. With the **kdump** role, you can set the basic kernel dump parameters on multiple systems.

**WARNING**

The **kdump** role replaces the **kdump** configuration of the managed hosts entirely by replacing the **/etc/kdump.conf** file. Additionally, if the **kdump** role is applied, all previous **kdump** settings are also replaced, even if they are not specified by the role variables, by replacing the **/etc/sysconfig/kdump** file.

The following example playbook shows how to apply the **kdump** system role to set the location of the crash dump files:

```
---
- hosts: kdump-test
  vars:
    kdump_path: /var/crash
  roles:
    - rhel-system-roles.kdump
```

For a detailed reference on **kdump** role variables, install the **rhel-system-roles** package, and see the **README.md** or **README.html** files in the **/usr/share/doc/rhel-system-roles/kdump** directory.

Additional resources

- [Introduction to RHEL system roles](#)

16.4. ADDITIONAL RESOURCES

- [Installing kdump](#)
- [Configuring kdump on the command line](#)
- [Configuring kdump in the web console](#)

CHAPTER 17. RECOVERING AND RESTORING A SYSTEM

To recover and restore a system using an existing backup, Red Hat Enterprise Linux provides the Relax-and-Recover (ReaR) utility.

You can use the utility as a disaster recovery solution and also for system migration.

The utility enables you to perform the following tasks:

- Produce a bootable image and restore the system from an existing backup, using the image.
- Replicate the original storage layout.
- Restore user and system files.
- Restore the system to a different hardware.

Additionally, for disaster recovery, you can also integrate certain backup software with ReaR.

17.1. SETTING UP REAR AND MANUALLY CREATING A BACKUP

Use the following steps to install the package for using the Relax-and-Recover (ReaR) utility, create a rescue system, configure and generate a backup.

Prerequisites

- Necessary configurations as per the backup restore plan are ready.
Note that you can use the **NETFS** backup method, a fully-integrated and built-in method with ReaR.

Procedure

1. Install the ReaR utility:

```
# yum install rear
```

2. Modify the ReaR configuration file in an editor of your choice, for example:

```
# vi /etc/rear/local.conf
```

3. Add the backup setting details to **/etc/rear/local.conf**. For example, in the case of the **NETFS** backup method, add the following lines:

```
BACKUP=NETFS
BACKUP_URL=backup.location
```

Replace *backup.location* by the URL of your backup location.

4. To configure ReaR to keep the previous backup archive when the new one is created, also add the following line to the configuration file:

```
NETFS_KEEP_OLD_BACKUP_COPY=y
```

5. To make the backups incremental, meaning that only the changed files are backed up on each run, add the following line:

```
BACKUP_TYPE=incremental
```

6. Create a rescue system:

```
# rear mkrescue
```

7. Create a backup as per the restore plan. For example, in the case of the **NETFS** backup method, run the following command:

```
# rear mkbackuponly
```

Alternatively, you can create the rescue system and the backup in a single step by running the following command:

```
# rear mkbackup
```

This command combines the functionality of the **rear mkrescue** and **rear mkbackuponly** commands.

17.2. SCHEDULING REAR

The `/etc/cron.d/rear` crontab file in the **rear** package runs the **rear mkrescue** command automatically at 1:30 AM everyday to schedule the Relax-and-Recover (ReaR) utility for regularly creating a rescue system. The command only creates a rescue system and not the backup of the data. You still need to schedule a periodic backup of data by yourself. For example:

Procedure

- You can add another crontab that will schedule the **rear mkbackuponly** command.
- You can also change the existing crontab to run the **rear mkbackup** command instead of the default `/usr/sbin/rear checklayout || /usr/sbin/rear mkrescue` command.
- You can schedule an external backup, if an external backup method is in use. The details depend on the backup method that you are using in ReaR.

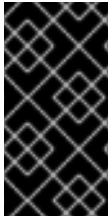


NOTE

The `/etc/cron.d/rear` crontab file provided in the **rear** package is considered deprecated, see [Deprecated functionality shell and command line](#), because it is not sufficient by default to perform a backup.

17.3. USING A REAR RESCUE IMAGE ON THE 64-BIT IBM Z ARCHITECTURE

Basic Relax and Recover (ReaR) functionality is now available on the 64-bit IBM Z architecture and is fully supported since RHEL 8.8. You can create a ReaR rescue image on IBM Z only in the z/VM environment. Backing up and recovering logical partitions (LPARs) has not been tested.



IMPORTANT

ReaR on the 64-bit IBM Z architecture is supported only with the **rear** package version 2.6-9.el8 or later. Earlier versions are available as a Technology Preview feature only. For more information about the support scope of Red Hat Technology Preview features, see <https://access.redhat.com/support/offerings/techpreview>.

The only output method currently available is Initial Program Load (IPL). IPL produces a kernel and an initial RAM disk (initrd) that can be used with the **zipl** boot loader.

Prerequisites

- ReaR is installed.
 - To install ReaR, run the **yum install rear** command

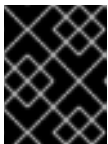
Procedure

Add the following variables to the **/etc/rear/local.conf** to configure ReaR for producing a rescue image on the 64-bit IBM Z architecture:

1. To configure the **IPL** output method, add **OUTPUT=IPL**.
2. To configure the backup method and destination, add **BACKUP** and **BACKUP_URL** variables. For example:

```
BACKUP=NETFS
```

```
BACKUP_URL=nfs://<nfsserver name>/<share path>
```



IMPORTANT

The local backup storage is currently not supported on the 64-bit IBM Z architecture.

3. Optional: You can also configure the **OUTPUT_URL** variable to save the kernel and **initrd** files. By default, the **OUTPUT_URL** is aligned with **BACKUP_URL**.
4. To perform backup and rescue image creation:

```
# rear mkbackup
```

5. This creates the kernel and initrd files at the location specified by the **BACKUP_URL** or **OUTPUT_URL** (if set) variable, and a backup using the specified backup method.
6. To recover the system, use the ReaR kernel and initrd files created in step 3, and boot from a Direct Attached Storage Device (DASD) or a Fibre Channel Protocol (FCP)-attached SCSI device prepared with the **zipl** boot loader, kernel, and **initrd**. For more information, see [Using a Prepared DASD](#).
7. When the rescue kernel and **initrd** get booted, it starts the ReaR rescue environment. Proceed with system recovery.



WARNING

Currently, the rescue process reformats all the DASDs (Direct Attached Storage Devices) connected to the system. Do not attempt a system recovery if there is any valuable data present on the system storage devices. This also includes the device prepared with the zipl boot loader, ReaR kernel, and initrd that were used to boot into the rescue environment. Ensure to keep a copy.

Additional resources

- [Installing under z/VM](#)
- [Using a Prepared DASD](#).

17.4. REAR EXCLUSIONS

The ReaR utility recreates the storage layout of the original system, where the rescue image has been produced, on the disks of the recovered system according to the description in the `/var/lib/rear/layout/disklayout.conf` layout file during the recovery process. The storage layout includes partitions, volume groups, logical volumes, file systems, and other storage components.

ReaR creates the layout file when creating the rescue image and embeds this file in the image. You can also create the layout file by using the **rear savelayout** command. This allows you to quickly create the layout file and examine it, without creating the entire rescue image.

The layout file describes the entire storage layout of the original system with certain exceptions, as ReaR excludes some storage components from the layout file and from being recreated during recovery. The exclusion of storage components from layout is controlled by the following configuration variables:

- **AUTOEXCLUDE_DISKS**
- **AUTOEXCLUDE_MULTIPATH**
- **AUTOEXCLUDE_PATH**
- **EXCLUDE_RECREATE**

You can view the default values for the configuration variables in the `/usr/share/rear/conf/default.conf` file and can change these values in the local `/etc/rear/local.conf` configuration file.

For more information about the syntax of the layout file and the configuration variables that you can use to exclude some storage components, see the **Layout configuration** chapter in the ReaR user guide, which is installed with the ReaR package as `/usr/share/doc/rear/relax-and-recover-user-guide.html`.

You can also configure which files are backed up by the internal **NETFS** and **RSYNC** backup methods. By default, files on all mounted local (disk-based) file systems are backed up by the **rear mkbackup** or **rear mkbackuponly** commands, if the file systems are included in the layout file. Excluding some file systems from the layout file, which is controlled by variables such as **AUTOEXCLUDE_DISKS**, **AUTOEXCLUDE_MULTIPATH**, **AUTOEXCLUDE_PATH**, and **EXCLUDE_RECREATE**, also excludes their content from the backup. You can also exclude some files or a directory tree from the backup without excluding a file system from the layout file by using the **BACKUP_PROG_EXCLUDE**

configuration variable. When all files and directories in a file system are excluded in this way, the file system is recreated during recovery, but it will be empty, because the backup does not contain any data to restore into it. This is useful for file systems that contain temporary data and are not required to be preserved, or for data that is backed up by using methods independent of ReaR.

The **BACKUP_PROG_EXCLUDE** variable is an array of glob(3)-style wildcard patterns that are passed to tar or rsync. Note that the patterns are required to be quoted in order to prevent their expansion by the shell when it reads the configuration file. The default value of this variable is set in the **/usr/share/rear/conf/default.conf** file. The default value contains, for example, the **/tmp/*** pattern that excludes all the files and directories under the **/tmp** directory, but not the **/tmp** directory itself.

If you need to exclude other files and directories, append further patterns to the variable instead of overriding it in order to preserve the default values. For example, to exclude all files and directories under the directory **/data/temp**, use:

```
# BACKUP_PROG_EXCLUDE+=( '/data/temp/*' )
```

The **rear mkbackup** command lists the backup exclude patterns in the log. You can find the log file in the **/var/log/rear** directory. This can be used to verify the excluded rules before performing a full system recovery. For example, the log can contain the following entries:

```
2025-04-29 10:17:41.312431050 Making backup (using backup method NETFS)
2025-04-29 10:17:41.314369109 Backup include list (backup-include.txt contents):
2025-04-29 10:17:41.316197323 /
2025-04-29 10:17:41.318052001 Backup exclude list (backup-exclude.txt contents):
2025-04-29 10:17:41.319857125 /tmp/*
2025-04-29 10:17:41.321644442 /dev/shm/*
2025-04-29 10:17:41.323436363 /var/lib/rear/output/*
```

Here, the whole root file system is included in the backup, with the exception of all files and directories under the **/tmp**, **/dev/shm** and **/var/lib/rear/output** directories.

CHAPTER 18. INSTALLING AND USING DYNAMIC PROGRAMMING LANGUAGES

Red Hat provides different programming languages, such as Python, PHP, and Tcl/Tk. Use them to develop own applications and services.

18.1. INTRODUCTION TO PYTHON

Python is a high-level programming language that supports multiple programming paradigms, such as object-oriented, imperative, functional, and procedural paradigms. Python has dynamic semantics and can be used for general-purpose programming.

With Red Hat Enterprise Linux, many packages that are installed on the system, such as packages providing system tools, tools for data analysis, or web applications, are written in Python. To use these packages, you must have the **python*** packages installed.

18.1.1. Python versions

Two incompatible versions of Python are widely used, Python 2.x and Python 3.x. RHEL 8 provides the following versions of Python.

Table 18.1. Python versions in RHEL 8

Version	Package to install	Command examples	Available since	Life cycle
Python 3.6	python3, python36	python3, python3.6, pip3, pip3.6	RHEL 8.0	full RHEL 8
Python 2.7	python2	python2, pip2	RHEL 8.0	shorter
Python 3.8	python38	python3.8, pip3.8	RHEL 8.2	shorter
Python 3.9	python39	python3.9, pip3.9	RHEL 8.4	shorter
Python 3.11	python3.11	python3.11, pip3.11	RHEL 8.8	shorter
Python 3.12	python3.12	python3.12, pip3.12	RHEL 8.10	shorter

For details about the length of support, see [Red Hat Enterprise Linux Life Cycle](#) and [Red Hat Enterprise Linux Application Streams Life Cycle](#).

Each of the Python versions up to 3.9 is distributed in a separate module. Python 3.11 and Python 3.12 are distributed as suites of non-modular RPM packages, including the **python3.11** and **python3.12** packages.

You can install multiple Python versions in parallel on the same RHEL 8 system.



IMPORTANT

Always specify the version of Python when installing it, invoking it, or otherwise interacting with it. For example, use **python3** instead of **python** in package and command names. All Python-related commands must also include the version, for example, **pip3**, **pip2**, **pip3.8**, **pip3.9**, **pip3.11**, or **pip3.12**.

The unversioned **python** command (**/usr/bin/python**) is not available by default in RHEL 8. You can configure it using the **alternatives** command; for instructions, see [Configuring the unversioned Python](#)

Any manual changes to **/usr/bin/python**, except changes made using the **alternatives** command, might be overwritten upon an update.

As a system administrator, use Python 3 for the following reasons:

- Python 3 represents the main development direction of the Python project.
- Support for Python 2 in the upstream community ended in 2020.
- Popular Python libraries are discontinuing Python 2 support in upstream.
- Python 2 in Red Hat Enterprise Linux 8 will have a shorter life cycle and aims to facilitate a smoother transition to **Python 3** for customers.

For developers, Python 3 has the following advantages over Python 2:

- Python 3 enables you to write expressive, maintainable, and correct code more easily.
- Code written in Python 3 will have greater longevity.
- Python 3 has new features, including **asyncio**, f-strings, advanced unpacking, keyword-only arguments, and chained exceptions.

However, legacy software might require **/usr/bin/python** to be configured to Python 2. For this reason, no default **python** package is distributed with Red Hat Enterprise Linux 8, and you can choose between using Python 2 and 3 as **/usr/bin/python**, as described in [Configuring the unversioned Python](#).



IMPORTANT

System tools in Red Hat Enterprise Linux 8 use Python version 3.6 provided by the internal **platform-python** package, which is not intended to be used directly by customers. It is recommended to use the **python3** or **python3.6** command from the **python36** package for Python 3.6, or to use later Python versions.

Do not remove the **platform-python** package from RHEL 8 because other packages require it.

18.1.2. Notable differences between Python versions

Python versions included in RHEL 8 differ in various aspects.

Python bindings

The **python38** and **python39** modules and the **python3.11** and **python3.12** package suites do not include the same bindings to system tools (RPM, DNF, SELinux, and others) that are provided for the

python36 module. Therefore, use **python36** in instances where the greatest compatibility with the base operating system or binary compatibility is necessary. In unique instances where system bindings are necessary together with later versions of various Python modules, use the **python36** module in combination with third-party upstream Python modules installed through **pip** into Python's **venv** or **virtualenv** environments.

Python 3.11 and Python 3.12 virtual environments must be created using **venv** instead of **virtualenv**

The **virtualenv** utility in RHEL 8, provided by the **python3-virtualenv** package, is not compatible with Python 3.11 and Python 3.12. An attempt to create a virtual environment by using **virtualenv** will fail with an error message, for example:

```
$ virtualenv -p python3.11 venv3.11
```

```
Running virtualenv with interpreter /usr/bin/python3.11
```

```
ERROR: Virtual environments created by virtualenv < 20 are not compatible with Python 3.11.
```

```
ERROR: Use python3.11 -m venv instead.
```

To create Python 3.11 or Python 3.12 virtual environments, use the **python3.11 -m venv** or **python3.12 -m venv** commands instead, which use the **venv** module from the standard library.

18.2. INSTALLING AND USING PYTHON

In Red Hat Enterprise Linux 8, Python 3 is distributed in versions 3.6, 3.8, and 3.9, provided by the **python36**, **python38**, and **python39** modules, and the **python3.11** and **python3.12** package suites in the AppStream repository.



WARNING

Using the unversioned **python** command to install or run Python does not work by default due to ambiguity. Always specify the version of Python, or configure the system default version by using the **alternatives** command.

18.2.1. Installing Python 3

By design, you can install RHEL 8 modules in parallel, including the **python27**, **python36**, **python38**, and **python39** modules, and the **python3.11** and **python3.12** package suites.

You can install Python 3.8, Python 3.9, Python 3.11, and Python 3.12, including packages built for each version, in parallel with Python 3.6 on the same system, with the exception of the **mod_wsgi** module. Due to a limitation of the Apache HTTP Server, only one of the **python3-mod_wsgi**, **python38-mod_wsgi**, **python39-mod_wsgi**, **python3.11-mod_wsgi**, or **python3.12-mod_wsgi** packages can be installed on a system.

Procedure

- To install Python 3.6 from the **python36** module, use:

```
# yum install python3
```

The **python36:3.6** module stream is enabled automatically.

- To install Python 3.8 from the **python38** module, use:

```
# yum install python38
```

The **python38:3.8** module stream is enabled automatically.

- To install Python 3.9 from the **python39** module, use:

```
# yum install python39
```

The **python39:3.9** module stream is enabled automatically.

- To install Python 3.11 from the **python3.11** RPM package, use:

```
# yum install python3.11
```

- To install Python 3.12 from the **python3.12** RPM package, use:

```
# yum install python3.12
```

Verification

- To verify the Python version installed on your system, use the **--version** option with the **python** command specific for your required version of Python.

- For Python 3.6:

```
$ python3 --version
```

- For Python 3.8:

```
$ python3.8 --version
```

- For Python 3.9:

```
$ python3.9 --version
```

- For Python 3.11:

```
$ python3.11 --version
```

- For Python 3.12:

```
$ python3.12 --version
```

Additional resources

- [Installing, managing, and removing user-space components](#)

18.2.2. Installing additional Python 3 packages

Packages with add-on modules for Python 3.6 generally use the **python3-** prefix, packages for Python 3.8 include the **python38-** prefix, packages for Python 3.9 include the **python39-** prefix, packages for Python 3.11 include the **python3.11-** prefix, and packages for Python 3.12 include the **python3.12-** prefix. Always include the prefix when installing additional Python packages, as shown in the examples below.

Procedure

- To install the **Requests** module for Python 3.6, use:

```
# yum install python3-requests
```

- To install the **Cython** extension to Python 3.8, use:

```
# yum install python38-Cython
```

- To install the **pip** package installer from Python 3.9, use:

```
# yum install python39-pip
```

- To install the **pip** package installer from Python 3.11, use:

```
# yum install python3.11-pip
```

- To install the **pip** package installer from Python 3.12, use:

```
# yum install python3.12-pip
```

Additional resources

- [Upstream documentation about Python add-on modules](#)

18.2.3. Installing additional Python 3 tools for developers

Additional Python tools for developers are distributed mostly through the CodeReady Linux Builder (CRB) repository in the respective **python38-devel** or **python39-devel** module, or the **python3.11-*** or **python3.12-*** packages.

The **python3-pytest** package (for Python 3.6) and its dependencies are available in the AppStream repository.

The CRB repository provides:

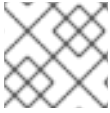
- The **python38-devel** module, which contains the **python38-pytest** package and its dependencies.
- The **python39-devel** module, which contains the **python39-pytest** package and its dependencies, and the **python39-debug** and **python39-Cython** packages.
- The **python3.11-*** packages, which include:
 - **python3.11-pytest** and its dependencies
 - **python3.11-idle**

- **python3.11-debug**
- **python3.11-Cython**
- The **python3.12-*** packages, which include a similar set of packages as **python3.11-***.



IMPORTANT

The content in the CodeReady Linux Builder repository is unsupported by Red Hat.



NOTE

Not all upstream Python-related packages are available in RHEL.

To install the **python3*-pytest** package, use the following procedure.

Procedure

1. For Python 3.8 and later, enable the CodeReady Linux Builder repository:

```
# subscription-manager repos --enable codeready-builder-for-rhel-8-x86_64-rpms
```

2. For Python 3.8 or 3.9, enable the respective **python3*-devel** module, for example:

```
# yum module enable python39-devel
```

3. Install the **python3*-pytest** package:

- For Python 3.6:

```
# yum install python3-pytest
```

- For Python 3.8:

```
# yum install python38-pytest
```

- For Python 3.9:

```
# yum install python39-pytest
```

- For Python 3.11:

```
# yum install python3.11-pytest
```

- For Python 3.12:

```
# yum install python3.12-pytest
```

Additional resources

- [How to enable and make use of content within CodeReady Linux Builder](#)

- [Package manifest](#)

18.2.4. Installing Python 2

Some applications and scripts have not yet been fully ported to Python 3 and require Python 2 to run. Red Hat Enterprise Linux 8 allows parallel installation of Python 3 and Python 2. If you need the Python 2 functionality, install the **python27** module, which is available in the AppStream repository.



WARNING

Note that Python 3 is the main development direction of the Python project. Support for Python 2 is being phased out. The **python27** module has a shorter support period than Red Hat Enterprise Linux 8.

Procedure

- To install Python 2.7 from the **python27** module, use:

```
# yum install python2
```

The **python27:2.7** module stream is enabled automatically.

Packages with add-on modules for Python 2 generally use the **python2-** prefix. Always include the prefix when installing additional Python packages, as shown in the examples below.

- To install the **Requests** module for Python 2, use:

```
# yum install python2-requests
```

- To install the **Cython** extension to Python 2, use:

```
# yum install python2-Cython
```

Verification

- To verify the Python version installed on your system, use:

```
$ python2 --version
```



NOTE

By design, you can install RHEL 8 modules in parallel, including the **python27**, **python36**, **python38**, and **python39** modules.

Additional resources

- [Installing, managing, and removing user-space components in RHEL 8](#)

18.2.5. Migrating from Python 2 to Python 3

As a developer, you may want to migrate your former code that is written in Python 2 to Python 3.

For more information about how to migrate large code bases to Python 3, see [The Conservative Python 3 Porting Guide](#).

Note that after this migration, the original Python 2 code becomes interpretable by the Python 3 interpreter and stays interpretable for the Python 2 interpreter as well.

18.2.6. Using Python

When running the Python interpreter or Python-related commands, always specify the version.

Prerequisites

- Ensure that the required version of Python is installed.
- If you want to download and install third-party applications for Python 3.11 or Python 3.12, install the **python3.11-pip** or **python3.12-pip** package.

Procedure

- To run the Python 3.6 interpreter or related commands, use, for example:

```
$ python3
$ python3 -m venv --help
$ python3 -m pip install package
$ pip3 install package
```

- To run the Python 3.8 interpreter or related commands, use, for example:

```
$ python3.8
$ python3.8 -m venv --help
$ python3.8 -m pip install package
$ pip3.8 install package
```

- To run the Python 3.9 interpreter or related commands, use, for example:

```
$ python3.9
$ python3.9 -m venv --help
$ python3.9 -m pip install package
$ pip3.9 install package
```

- To run the Python 3.11 interpreter or related commands, use, for example:

```
$ python3.11
$ python3.11 -m venv --help
$ python3.11 -m pip install package
$ pip3.11 install package
```

- To run the Python 3.12 interpreter or related commands, use, for example:

```
$ python3.12
```

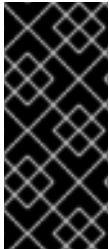
```
$ python3.12 -m venv --help
$ python3.12 -m pip install package
$ pip3.12 install package
```

- To run the Python 2 interpreter or related commands, use, for example:

```
$ python2
$ python2 -m pip install package
$ pip2 install package
```

18.3. CONFIGURING THE UNVERSIONED PYTHON

System administrators can configure the unversioned **python** command, located at `/usr/bin/python`, using the **alternatives** command. Note that the required package, **python3**, **python38**, **python39**, **python3.11**, **python3.12**, or **python2**, must be installed before configuring the unversioned command to the respective version.



IMPORTANT

The `/usr/bin/python` executable is controlled by the **alternatives** system. Any manual changes may be overwritten upon an update.

Additional Python-related commands, such as **pip3**, do not have configurable unversioned variants.

18.3.1. Configuring the unversioned python command directly

You can configure the unversioned **python** command directly to a selected version of Python.

Prerequisites

- Ensure that the required version of Python is installed.

Procedure

- To configure the unversioned **python** command to Python 3.6, use:

```
# alternatives --set python /usr/bin/python3
```

- To configure the unversioned **python** command to Python 3.8, use:

```
# alternatives --set python /usr/bin/python3.8
```

- To configure the unversioned **python** command to Python 3.9, use:

```
# alternatives --set python /usr/bin/python3.9
```

- To configure the unversioned **python** command to Python 3.11, use:

```
# alternatives --set python /usr/bin/python3.11
```

- To configure the unversioned **python** command to Python 3.12, use:

```
# alternatives --set python /usr/bin/python3.12
```

- To configure the unversioned **python** command to Python 2, use:

```
# alternatives --set python /usr/bin/python2
```

18.3.2. Configuring the unversioned python command to the required Python version interactively

You can configure the unversioned **python** command to the required Python version interactively.

Prerequisites

- Ensure that the required version of Python is installed.

Procedure

1. To configure the unversioned **python** command interactively, use:

```
# alternatives --config python
```

2. Select the required version from the provided list.
3. To reset this configuration and remove the unversioned **python** command, use:

```
# alternatives --auto python
```

18.3.3. Additional resources

- **alternatives(8)** and **unversioned-python(1)** man pages on your system

18.4. PACKAGING PYTHON 3 RPMS

Most Python projects use Setuptools for packaging, and define package information in the **setup.py** file. For more information about Setuptools packaging, see the [Setuptools documentation](#).

You can also package your Python project into an RPM package, which provides the following advantages compared to Setuptools packaging:

- Specification of dependencies of a package on other RPMs (even non-Python)
- Cryptographic signing
With cryptographic signing, content of RPM packages can be verified, integrated, and tested with the rest of the operating system.

18.4.1. The spec file description for a Python package

A **spec** file contains instructions that the **rpmbuild** utility uses to build an RPM. The instructions are included in a series of sections. A **spec** file has two main parts in which the sections are defined:

- Preamble (contains a series of metadata items that are used in the Body)

- Body (contains the main part of the instructions)

An RPM SPEC file for Python projects has some specifics compared to non-Python RPM SPEC files. Most notably, a name of any RPM package of a Python library must always include the prefix determining the version, for example, **python3** for Python 3.6, **python38** for Python 3.8, **python39** for Python 3.9, **python3.11** for Python 3.11, or **python3.12** for Python 3.12.

Other specifics are shown in the following **spec** file **example for the python3-detox package**. For description of such specifics, see the notes below the example.

```
%global modname detox 1

Name:      python3-detox 2
Version:   0.12
Release:   4%{?dist}
Summary:   Distributing activities of the tox tool
License:   MIT
URL:       https://pypi.io/project/detox
Source0:   https://pypi.io/packages/source/d/%{modname}/%{modname}-%{version}.tar.gz

BuildArch: noarch

BuildRequires: python36-devel 3
BuildRequires: python3-setuptools
BuildRequires: python36-rpm-macros
BuildRequires: python3-six
BuildRequires: python3-tox
BuildRequires: python3-py
BuildRequires: python3-eventlet

%?python_enable_dependency_generator 4

%description

Detox is the distributed version of the tox python testing tool. It makes efficient use of multiple CPUs
by running all possible activities in parallel.
Detox has the same options and configuration that tox has, so after installation you can run it in the
same way and with the same options that you use for tox.

$ detox

%prep
%autosetup -n %{modname}-%{version}

%build
%py3_build 5

%install
%py3_install

%check
%{__python3} setup.py test 6

%files -n python3-%{modname}
%doc CHANGELOG
```

```
%license LICENSE
%{_bindir}/detox
%{python3_sitelib}/%{modname}/
%{python3_sitelib}/%{modname}-%{version}*

%changelog
...
```

- 1 The **modname** macro contains the name of the Python project. In this example it is **detox**.
- 2 When packaging a Python project into RPM, the **python3** prefix always needs to be added to the original name of the project. The original name here is **detox** and the **name of the RPM** is **python3-detox**.
- 3 **BuildRequires** specifies what packages are required to build and test this package. In **BuildRequires**, always include items providing tools necessary for building Python packages: **python36-devel** and **python3-setuptools**. The **python36-rpm-macros** package is required so that files with **/usr/bin/python3** interpreter directives are automatically changed to **/usr/bin/python3.6**.
- 4 Every Python package requires some other packages to work correctly. Such packages need to be specified in the **spec** file as well. To specify the **dependencies**, you can use the **%python_enable_dependency_generator** macro to automatically use dependencies defined in the **setup.py** file. If a package has dependencies that are not specified using **Setuptools**, specify them within additional **Requires** directives.
- 5 The **%py3_build** and **%py3_install** macros run the **setup.py build** and **setup.py install** commands, respectively, with additional arguments to specify installation locations, the interpreter to use, and other details.
- 6 The **check** section provides a macro that runs the correct version of Python. The **%{__python3}** macro contains a path for the Python 3 interpreter, for example **/usr/bin/python3**. We recommend to always use the macro rather than a literal path.

18.4.2. Common macros for Python 3 RPMs

In a **spec** file, always use the macros that are described in the following Macros for Python 3 RPMs table rather than hardcoding their values.

In macro names, always use **python3** or **python2** instead of unversioned **python**. Configure the particular Python 3 version in the **BuildRequires** section of the **SPEC** file to **python36-rpm-macros**, **python38-rpm-macros**, **python39-rpm-macros**, **python3.11-rpm-macros**, or **python3.12-rpm-macros**.

Table 18.2. Macros for Python 3 RPMs

Macro	Normal Definition	Description
%{__python3}	/usr/bin/python3	Python 3 interpreter
%{python3_version}	3.6	The full version of the Python 3 interpreter.

Macro	Normal Definition	Description
<code>%{python3_sitelib}</code>	<code>/usr/lib/python3.6/site-packages</code>	Where pure-Python modules are installed.
<code>%{python3_sitelib64}</code>	<code>/usr/lib64/python3.6/site-packages</code>	Where modules containing architecture-specific extensions are installed.
<code>%py3_build</code>		Runs the setup.py build command with arguments suitable for a system package.
<code>%py3_install</code>		Runs the setup.py install command with arguments suitable for a system package.

18.4.3. Automatic provides for Python RPMs

When packaging a Python project, make sure that the following directories are included in the resulting RPM if these directories are present:

- **.dist-info**
- **.egg-info**
- **.egg-link**

From these directories, the RPM build process automatically generates virtual **pythonX.Ydist** provides, for example, **python3.6dist(detox)**. These virtual provides are used by packages that are specified by the `%python_enable_dependency_generator` macro.

18.5. HANDLING INTERPRETER DIRECTIVES IN PYTHON SCRIPTS

In Red Hat Enterprise Linux 8, executable Python scripts are expected to use interpreter directives (also known as hashbangs or shebangs) that explicitly specify at a minimum the major Python version. For example:

```
#!/usr/bin/python3
#!/usr/bin/python3.6
#!/usr/bin/python3.8
#!/usr/bin/python3.9
#!/usr/bin/python3.11
#!/usr/bin/python3.12
#!/usr/bin/python2
```

The `/usr/lib/rpm/redhat/brp-mangle-shebangs` buildroot policy (BRP) script is run automatically when building any RPM package, and attempts to correct interpreter directives in all executable files.

The BRP script generates errors when encountering a Python script with an ambiguous interpreter directive, such as:

—

```
#!/usr/bin/python
```

or

```
#!/usr/bin/env python
```

18.5.1. Modifying interpreter directives in Python scripts

Modify interpreter directives in the Python scripts that cause the build errors at RPM build time.

Prerequisites

- Some of the interpreter directives in your Python scripts cause a build error.

Procedure

To modify interpreter directives, complete one of the following tasks:

- Apply the **pathfix.py** script from the **platform-python-devel** package:

```
# pathfix.py -pn -i %(__python3) PATH ...
```

Note that multiple **PATHs** can be specified. If a **PATH** is a directory, **pathfix.py** recursively scans for any Python scripts matching the pattern `^[a-zA-Z0-9_]+\.py$`, not only those with an ambiguous interpreter directive. Add this command to the **%prep** section or at the end of the **%install** section.

- Modify the packaged Python scripts so that they conform to the expected format. For this purpose, **pathfix.py** can be used outside the RPM build process, too. When running **pathfix.py** outside an RPM build, replace **%(__python3)** from the example above with a path for the interpreter directive, such as **/usr/bin/python3**.

If the packaged Python scripts require a version other than Python 3.6, adjust the preceding commands to include the required version.

18.5.2. Changing **/usr/bin/python3** interpreter directives in your custom packages

By default, interpreter directives in the form of **/usr/bin/python3** are replaced with interpreter directives pointing to Python from the **platform-python** package, which is used for system tools with Red Hat Enterprise Linux. You can change the **/usr/bin/python3** interpreter directives in your custom packages to point to a specific version of Python that you have installed from the AppStream repository.

Procedure

- To build your package for a specific version of Python, add the **python*-rpm-macros** subpackage of the respective **python** package to the **BuildRequires** section of the **spec** file. For example, for Python 3.6, include the following line:

```
BuildRequires: python36-rpm-macros
```

As a result, the **/usr/bin/python3** interpreter directives in your custom package are automatically converted to **/usr/bin/python3.6**.



NOTE

To prevent the BRP script from checking and modifying interpreter directives, use the following RPM directive:

```
%undefine __brp_mangle_shebangs
```

18.6. USING THE PHP SCRIPTING LANGUAGE

Hypertext Preprocessor (PHP) is a general-purpose scripting language mainly used for server-side scripting, which enables you to run the PHP code using a web server.

In RHEL 8, the PHP scripting language is provided by the **php** module, which is available in multiple streams (versions).

Depending on your use case, you can install a specific profile of the selected module stream:

- **common** - The default profile for server-side scripting using a web server. It includes several widely used extensions.
- **minimal** - This profile installs only the command line for scripting with PHP without using a web server.
- **devel** - This profile includes packages from the **common** profile and additional packages for development purposes.

18.6.1. Installing the PHP scripting language

You can install a selected version of the **php** module.

Procedure

- To install a **php** module stream with the default profile, use:

```
# yum module install php:stream
```

Replace *stream* with the version of PHP you wish to install.

For example, to install PHP 8.0:

```
# yum module install php:8.0
```

The default **common** profile installs also the **php-fpm** package, and preconfigures PHP for use with the **Apache HTTP Server** or **nginx**.

- To install a specific profile of a **php** module stream, use:

```
# yum module install php:stream/profile
```

Replace *stream* with the desired version and *profile* with the name of the profile you wish to install.

For example, to install PHP 8.0 for use without a web server:

```
# yum module install php:8.0/minimal
```

Additional resources

- If you want to upgrade from an earlier version of PHP available in RHEL 8, see [Switching to a later stream](#).
- For more information about managing RHEL 8 modules and streams, see [Installing, managing, and removing user-space components](#).

18.6.2. Using the PHP scripting language with a web server

18.6.2.1. Using PHP with the Apache HTTP Server

In Red Hat Enterprise Linux 8, the **Apache HTTP Server** enables you to run PHP as a FastCGI process server. FastCGI Process Manager (FPM) is an alternative PHP FastCGI daemon that allows a website to manage high loads. PHP uses FastCGI Process Manager by default in RHEL 8.

You can run the PHP code using the FastCGI process server.

Prerequisites

- The PHP scripting language is installed on your system.
See [Installing the PHP scripting language](#).

Procedure

1. Install the **httpd** module:

```
# yum module install httpd:2.4
```

2. Start the **Apache HTTP Server**:

```
# systemctl start httpd
```

Or, if the **Apache HTTP Server** is already running on your system, restart the **httpd** service after installing PHP:

```
# systemctl restart httpd
```

3. Start the **php-fpm** service:

```
# systemctl start php-fpm
```

4. Optional: Enable both services to start at boot time:

```
# systemctl enable php-fpm httpd
```

5. To obtain information about your PHP settings, create the **index.php** file with the following content in the **/var/www/html/** directory:

```
# echo '<?php phpinfo(); ?>' > /var/www/html/index.php
```

6. To run the **index.php** file, point the browser to:

```
http://<hostname>/
```

7. Optional: Adjust configuration if you have specific requirements:

- **/etc/httpd/conf/httpd.conf** – generic **httpd** configuration
- **/etc/httpd/conf.d/php.conf** – PHP-specific configuration for **httpd**
- **/usr/lib/systemd/system/httpd.service.d/php-fpm.conf** – by default, the **php-fpm** service is started with **httpd**
- **/etc/php-fpm.conf** – FPM main configuration
- **/etc/php-fpm.d/www.conf** – default **www** pool configuration

Example 18.1. Running a "Hello, World!" PHP script using the Apache HTTP Server

1. Create a **hello** directory for your project in the **/var/www/html/** directory:

```
# mkdir hello
```

2. Create a **hello.php** file in the **/var/www/html/hello/** directory with the following content:

```
# <!DOCTYPE html>
<html>
<head>
<title>Hello, World! Page</title>
</head>
<body>
<?php
    echo 'Hello, World!';
?>
</body>
</html>
```

3. Start the **Apache HTTP Server**:

```
# systemctl start httpd
```

4. To run the **hello.php** file, point the browser to:

```
http://<hostname>/hello/hello.php
```

As a result, a web page with the "Hello, World!" text is displayed.

Additional resources

- [Setting up the Apache HTTP web server](#)

18.6.2.2. Using PHP with the nginx web server

You can run PHP code through the **nginx** web server.

Prerequisites

- The PHP scripting language is installed on your system.
See [Installing the PHP scripting language](#).

Procedure

1. Install an **nginx** module stream:

```
# yum module install nginx:stream
```

Replace *stream* with the version of **nginx** you wish to install.

For example, to install **nginx** version 1.18:

```
# yum module install nginx:1.18
```

2. Start the **nginx** server:

```
# systemctl start nginx
```

Or, if the **nginx** server is already running on your system, restart the **nginx** service after installing PHP:

```
# systemctl restart nginx
```

3. Start the **php-fpm** service:

```
# systemctl start php-fpm
```

4. Optional: Enable both services to start at boot time:

```
# systemctl enable php-fpm nginx
```

5. To obtain information about your PHP settings, create the **index.php** file with the following content in the **/usr/share/nginx/html/** directory:

```
# echo '<?php phpinfo(); ?>' > /usr/share/nginx/html/index.php
```

6. To run the **index.php** file, point the browser to:

```
http://<hostname>/
```

7. Optional: Adjust configuration if you have specific requirements:

- **/etc/nginx/nginx.conf** - **nginx** main configuration
- **/etc/nginx/conf.d/php-fpm.conf** - FPM configuration for **nginx**
- **/etc/php-fpm.conf** - FPM main configuration

- `/etc/php-fpm.d/www.conf` – default **www** pool configuration

Example 18.2. Running a "Hello, World!" PHP script using the nginx server

1. Create a **hello** directory for your project in the `/usr/share/nginx/html/` directory:

```
# mkdir hello
```

2. Create a **hello.php** file in the `/usr/share/nginx/html/hello/` directory with the following content:

```
# <!DOCTYPE html>
<html>
<head>
<title>Hello, World! Page</title>
</head>
<body>
<?php
    echo 'Hello, World!';
?>
</body>
</html>
```

3. Start the **nginx** server:

```
# systemctl start nginx
```

4. To run the **hello.php** file, point the browser to:

```
http://<hostname>/hello/hello.php
```

As a result, a web page with the "Hello, World!" text is displayed.

Additional resources

- [Setting up and configuring NGINX](#)

18.6.3. Running a PHP script using the command line

A PHP script is usually run using a web server, but also can be run using the command line.

If you want to run **php** scripts using only command-line, install the **minimal** profile of a **php** module stream.

See [Installing the PHP scripting language](#).

Prerequisites

- The PHP scripting language is installed on your system.
See [Installing the PHP scripting language](#).

Procedure

1. In a text editor, create a **filename.php** file
Replace *filename* with the name of your file.
2. Execute the created **filename.php** file from the command line:

```
# php filename.php
```

Example 18.3. Running a "Hello, World!" PHP script using the command line

1. Create a **hello.php** file with the following content using a text editor:

```
<?php
echo 'Hello, World!';
?>
```

2. Execute the **hello.php** file from the command line:

```
# php hello.php
```

As a result, "Hello, World!" is printed.

18.6.4. Additional resources

- **httpd(8)** – The manual page for the **httpd** service containing the complete list of its command-line options.
- **httpd.conf(5)** – The manual page for **httpd** configuration, describing the structure and location of the **httpd** configuration files.
- **nginx(8)** – The manual page for the **nginx** web server containing the complete list of its command-line options and list of signals.
- **php-fpm(8)** – The manual page for PHP FPM describing the complete list of its command-line options and configuration files.

18.7. GETTING STARTED WITH TCL/TK

18.7.1. Introduction to Tcl/Tk

Tool command language (Tcl) is a dynamic programming language. The interpreter for this language, together with the C library, is provided by the **tcl** package.

Using **Tcl** paired with **Tk (Tcl/Tk)** enables creating cross-platform GUI applications. **Tk** is provided by the **tk** package.

Note that **Tk** can refer to any of the following:

- A programming toolkit for multiple languages
- A Tk C library bindings available for multiple languages, such as C, Ruby, Perl and Python
- A wish interpreter that instantiates a Tk console

- A Tk extension that adds a number of new commands to a particular Tcl interpreter

For more information about Tcl/Tk, see the [Tcl/Tk manual](#) or [Tcl/Tk documentation web page](#).

18.7.2. Notable changes in Tcl/Tk 8.6

Red Hat Enterprise Linux 7 used **Tcl/Tk 8.5**. With Red Hat Enterprise Linux 8, **Tcl/Tk version 8.6** is provided in the Base OS repository.

Major changes in **Tcl/Tk 8.6** compared to **Tcl/Tk 8.5** are:

- Object-oriented programming support
- Stackless evaluation implementation
- Enhanced exceptions handling
- Collection of third-party packages built and installed with Tcl
- Multi-thread operations enabled
- SQL database-powered scripts support
- IPv6 networking support
- Built-in Zlib compression
- List processing
Two new commands, **lmap** and **dict map** are available, which allow the expression of transformations over **Tcl** containers.
- Stacked channels by script
Two new commands, **chan push** and **chan pop** are available, which allow to add or remove transformations to or from I/O channels.

Major changes in **Tk** include:

- Built-in PNG image support
- Busy windows
A new command, **tk busy** is available, which disables user interaction for a window or a widget and shows the busy cursor.
- New font selection dialog interface
- Angled text support
- Moving things on a canvas support

For the detailed list of changes between **Tcl 8.5** and **Tcl 8.6**, see [Changes in Tcl/Tk 8.6](#).

18.7.3. Migrating to Tcl/Tk 8.6

Red Hat Enterprise Linux 7 used **Tcl/Tk 8.5**. With Red Hat Enterprise Linux 8, **Tcl/Tk version 8.6** is provided in the Base OS repository.

This section describes migration path to **Tcl/Tk 8.6** for:

- Developers writing **Tcl** extensions or embedding **Tcl** interpreter into their applications
- Users scripting tasks with **Tcl/Tk**

18.7.3.1. Migration path for developers of Tcl extensions

To make your code compatible with **Tcl 8.6**, use the following procedure.

Procedure

1. Rewrite the code to use the **interp** structure. For example, if your code reads **interp** → **errorLine**, rewrite it to use the following function:

```
Tcl_GetErrorLine(interp)
```

This is necessary because **Tcl 8.6** limits direct access to members of the **interp** structure.

2. To make your code compatible with both **Tcl 8.5** and **Tcl 8.6**, use the following code snippet in a header file of your C or C++ application or extension that includes the **Tcl** library:

```
# include <tcl.h>
# if !defined(Tcl_GetErrorLine)
# define Tcl_GetErrorLine(interp) (interp → errorLine)
# endif
```

18.7.3.2. Migration path for users scripting their tasks with Tcl/Tk

In **Tcl 8.6**, most scripts work the same way as with the previous version of **Tcl**.

To migrate you code into **Tcl 8.6**, use this procedure.

Procedure

- When writing a portable code, make sure to not use the commands that are no longer supported in **Tk 8.6**:

```
tklconList_Arrange
tklconList_AutoScan
tklconList_Btn1
tklconList_Config
tklconList_Create
tklconList_CtrlBtn1
tklconList_Curselection
tklconList_DeleteAll
tklconList_Double1
tklconList_DrawSelection
tklconList_FocusIn
tklconList_FocusOut
tklconList_Get
tklconList_Goto
tklconList_Index
tklconList_Invoke
tklconList_KeyPress
tklconList_Leave1
```

```
tklconList_LeftRight  
tklconList_Motion1  
tklconList_Reset  
tklconList_ReturnKey  
tklconList_See  
tklconList_Select  
tklconList_Selection  
tklconList_ShiftBtn1  
tklconList_UpDown
```

Note that you can check the list of unsupported commands also in the **/usr/share/tk8.6/unsupported.tcl** file.