

```
discount=0.99999, discountB=0.99):
```

```
structure = np.array([
['E', 'E', 'E', 'E'],
['E', 'E', 'E', 'T'],
['E', 'E', 'E', 'E'],
['T', 'E', 'T', 'E'],
['E', 'E', 'E', 'E']
])

# Labels of the states
label = np.array([
[(), (), ('c',),()],
[(), (), ('a',),('b',)],
[(), (), ('c',),()],
[(('b',),), (), ('a',),()],
[(), ('c',), (), ('c',)]
], dtype=object)
```

Q = csrl.q_learning(T=100,K=100000)

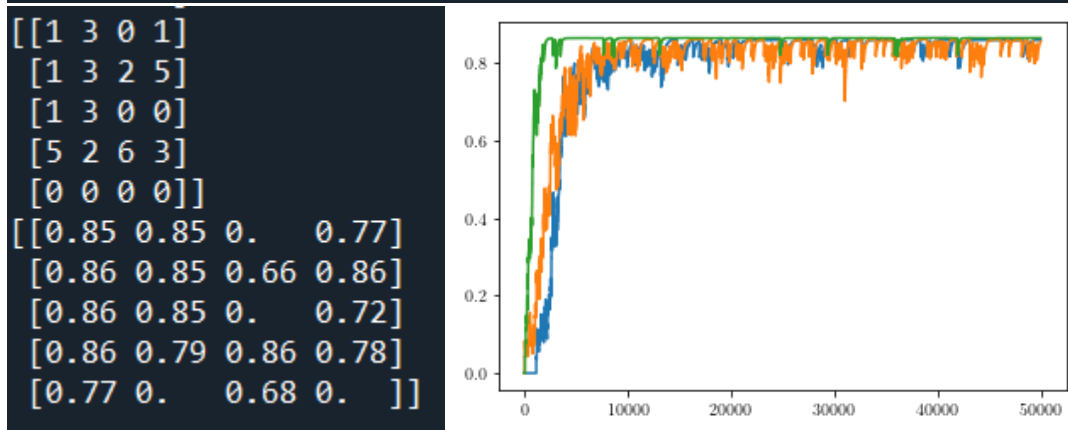
[1 3 0 2]	[1. 1. 0. 1.]
[1 3 2 5]	[1. 1. 0.81 1.]
[1 3 0 2]	[1. 1. 0. 1.]
[5 0 6 0]	[1. 1. 1. 1.]
[3 0 0 0]	[1. 0. 0.8 0.]

PG

```
T = 100
K = 50000

PG_state = np.prod(gamma_hist[0:t3:1])*(G_t_hist[t3] - V[state]) * Grad_Pi
PG[state][0:len(PG_state):1] += PG_state.flatten()
Grad_V[state] = G_t_hist[t3] - V[state]

theta = theta + 0.1*PG
V      = V      + alpha * Grad_V
```



```
T = 100
K = 50000
```

```

PG_state = np.prod(gamma_hist[0:t3:1])*(G_t_hist[t3]) * Grad_Pi
PG[state][0:len(PG_state):1] += PG_state.flatten()
Grad_V[state] = G_t_hist[t3] - V[state]

theta = theta + 0.2*PG
V      = V      + alpha * Grad_V

```

```

[[1 1 0 1]
 [2 2 2 5]
 [1 3 0 0]
 [1 2 6 3]
 [3 0 0 0]]
[[0.71 0.63 0.  0.77]
 [0.7  0.7  0.7 0.86]
 [0.81 0.79 0.  0.76]
 [0.81 0.78 0.86 0.77]
 [0.78 0.  0.66 0.  ]]

```

