













## EDUCATION

<b>Technical University of Munich</b>	2019 - 2022
<b>Harbin Engineering University</b>	2017 - 2019
Ph.D. (Joint-Training) - Computer Science, Information & Technology	
<ul style="list-style-type: none"> <li>Machine Learning: Bayesian Learning, Deep Learning, Safe Learning, Fusion Learning</li> <li>Control Theory: Linear &amp; Nonlinear Control, Underactuated Control, Model Predict Control (MPC)</li> <li>Distributed Systems: Cooperative Learning, Coordination Control, Communication Effect Analysis</li> </ul>	
<b>Northeast Forestry University</b>	2015 - 2017
M.Sc. - Mechanical and Electrical Engineering	
<b>Harbin University of Science and Technology</b>	2010 - 2014
B.Sc. - Electrical Engineering and Automation	

## EXPERIENCE

<b>Data Scientist Retreat</b> 	Berlin, Germany
<b>Data Scientist</b>	Jan 2023 - April 2023
<ul style="list-style-type: none"> <li>Statistical Learning <ul style="list-style-type: none"> <li>Built and deployed a ML App with data pre-processing and feature engineering </li> <li>Predicted disease spread via time series models and evaluated different models via MLflow </li> </ul> </li> <li>Deep Learning <ul style="list-style-type: none"> <li>Real-time object detection, action detection and gesture analysis for sign language recognition </li> <li>Trained image classification models using the state-of-the-art vision transformer</li> </ul> </li> <li>Natural Language Processing <ul style="list-style-type: none"> <li>Extracted and visualized character relationship with named entity recognition for book series </li> <li>Fine-tuned language models for segmentation and text generation tasks</li> <li>Found similar researchers using node and word embeddings for collaboration recommendations </li> </ul> </li> </ul>	
<b>Technical University of Munich - Chair of Information-oriented Control</b> 	Munich, Germany
<b>Doctoral Researcher</b>	Sep 2019 - Nov 2022
<ul style="list-style-type: none"> <li>Total publications: 48, patents: 12, citations: 250+, h-index: 9 (Google Scholar </li> <li>Supervised 10+ student theses with several projects being graded with the highest score</li> <li>Teaching Curriculum: Advanced Control and Robotics</li> <li><b>European Union's Horizon 2020 - SeaClear</b>  <p><i>Search, Identification and Collection of Marine Litter with Autonomous Robots 1.0 (5 Million €), 2.0 (9 Million €)</i></p> <ul style="list-style-type: none"> <li>Developed a data-driven model for Autonomous Underwater Vehicles (AUVs) with safe quantification</li> <li>Created a simulation platform for control testing of AUVs</li> <li>Contributed hardware tests, e.g., grabbing bottles in various currents, in Marseilles and Hamburg port</li> </ul> </li> <li><b>European Union's Horizon 2020 - REHYB</b>  <p><i>Rehabilitation Based on Hybrid Neuroprosthesis (7 Million €)</i></p> <ul style="list-style-type: none"> <li>Detected the abnormal movements for people with disability through DNN using multiple sensors, e.g., EMG</li> <li>Studied the safe control of human muscles by FES to achieve functional movements</li> </ul> </li> <li><b>DFG &amp; NSFC - COVEMAS</b>  <p><i>Control and Optimization for Event-triggered Networked Autonomous Multi-Agent Systems</i></p> <ul style="list-style-type: none"> <li>Designed novel cooperative learning algorithms for centralized and distributed systems</li> <li>Delivered the learning-based control protocols for the coordination of multiple interacting agents</li> <li>Developed mode-free distributed MPC and shared distributed MPC control laws</li> </ul> </li> </ul>	
<b>Harbin Engineering University - College of Intelligent Systems Science and Engineering</b> 	Harbin, China
<b>Principal Investigator</b>	May 2019 - Jun 2022

- **Ph.D. Student Research & Innovation Fund of Fundamental Research Funds for Central Universities**  
*Research on the Coordinated Control Method of AUV Swarm (70k ¥)*
  - Teamed up a research team and successfully completed the project with top-tier publications
  - Proposed novel formation control methods for AUV swarm using the consensus algorithm

Harbin Engineering University - Institute of Marine Equipment & Control Technology   
**Doctoral Researcher**


Harbin, China  
Sep 2017 - Aug 2019

- **National Natural Science Foundation of China & National Key Innovation Project**  
*Environmental Prediction & Task Reconfiguration of AUV for Covert Operations in the Coastal Sea (600k ¥)*  
*Overall Technology Scheme of the Multiple AUVs System (50 Million ¥)*
  - Developed advanced control algorithms for AUVs
  - Investigated obstacle avoidance and recovery docking approaches for AUVs
  - Wrote a chapter ‘Reliability Analysis & Design Technology of AUV’ in the book “Control Technology of AUV”

Education Bureau of Hulan District  
**Teaching Assistant**


Hulan, China  
Mar 2017 - Jun 2017

- Examined and modified the physics lesson plans of high school, taught the physics course

Suzhou Electrical Apparatus Science Academy Co., Ltd.   
**Test & Analysis Engineer**

Suzhou, China  
Oct 2016 - Feb 2017

- Implemented and analyzed testing experiments for different characteristics of fiber optical current transformers

Harbin Turbine Co., Ltd.   
**Automation Engineer**

Harbin, China  
Mar 2014 - Jun 2014

- CNC lathe programming, quality inspection

## ACTIVITIES

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**Automatica** Munich (Germany), June 27–30, 2022

- Exhibited the **SeaClear** project

**The 40th Chinese Control Conference** Shanghai (China), Jul 26-28 2021

- Co-Chair of the Section “Multi-Agent Systems and Distributed Control”

**The 15th ‘Challenge Cup’ of University Students Extracurricular Academic Science and Technology Competition** Sep 2016 - July 2017

- Won the third prize of Heilongjiang Province, converted the results to 7 patents and 8 publications
- Contributed to the project ‘Multi-layer Micro-automatic plant factory’, designed and built the plant factory

## ACHIEVEMENTS

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**Outstanding Doctoral Graduate** Jun 2022  
Selected by Harbin Engineering University

**National Scholarship for Doctoral Student** Dec 2019  
Issued by Ministry of Education of the People’s Republic of China

**Province Merit Student** May 2019  
Selected by Ministry of Education of Heilongjiang Province

**Ministry of Industry and Information Technology Innovation and Entrepreneurship Scholarship** Feb 2019  
Issued by Ministry of Industry and Information Technology

**China State Shipbuilding Scholarship** Nov 2018  
Issued by China State Shipbuilding Corporation Limited

<b>Merit Student (four times)</b> Selected by Harbin Engineering University	2017 - 2021
<b>Doctoral Scholarship (four years)</b> Issued by Harbin Engineering University	2017 - 2021
<b>Outstanding Master Graduate</b> Selected by Northeast Forestry University	Jun 2017
<b>Outstanding Graduate Thesis</b> Selected by Northeast Forestry University	Sep 2017
<b>Excellent League Member (two times)</b> Selected by Northeast Forestry University	2015 - 2017
<b>Master Scholarship (two years)</b> Issued by Northeast Forestry University	2015 - 2017
<b>Bachelor Scholarship (four semesters)</b> Issued by Harbin University of Science and Technology	2010 - 2014

## SKILLS SUMMARY

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- **Programming & Markup Languages**
  - Python, Matlab & Simulink, C/C++, HTML/CSS, JavaScript, SQL, Latex, Markdown
- **Frameworks & Libraies**
  - PyTorch, TensorFlow, Keras, scikit-learn, statsmodels, PySpark, ROS
  - OpenCV, Gazebo, D3.js, Flask, FastAPI, Selenium, Beautiful Soup, matplotlib, seaborn, Plotly
  - Numpy, Pandas, spaCy, NLTK, Gensim, tokenizers, transformers, openai, fastai
- **Softwares & Tools**
  - Git, Jupyter, Docker, AWS, Azure, Databricks, MySQL, Postman, Streamlit, Render, Heroku, Qualisys, OpenSim
- **Language**
  - English, German, Chinese

## REFERENCE

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 College of Intelligent Systems Science and Engineering, Harbin Engineering University  
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**Heming Jia**, Full Professor  
 Department of Information Engineering, Sanming University  
 jiaheminglucky99@126.com