

YIMING LI

Cao'an Highway, Jiading District, Shanghai, 201804

◇ Personal Page: <https://roboticsyimingli.github.io/>

◇ Telephone: (86)15316575579 ◇ Email: yimingli9702@gmail.com

Google Scholar: https://scholar.google.com.hk/citations?user=i_aajNoAAAAJ&hl=zh-CN

EDUCATION

- **Tongji University, Shanghai, China** *2015.9 - 2020.6(expected)*
B.Eng. in Mechanical Engineering
 - GPA Overall: *3.77/4.0* (equivalent to *90/100*)
 - GPA Major: *3.91/4.0* (equivalent to *92/100*)
 - Supervisor: Prof. Changhong Fu (Director of Vision4Robotics Group)
 - Scholarship: National Scholarship, Shanghai Scholarship, National Endeavor Scholarship, Excellent Student Scholarship, School Practice Scholarship.
- **Tsinghua University, Beijing, China** *2019.9 - 2019.10*
Visiting Student in Department of Automation
 - Supervisor: Prof. Geng Lu (Director of UAV Lab)

RESEARCH INTERESTS

- Robotic Vision, Aerial Robotics, Machine Learning, Visual Tracking, Pose Estimation
- Semantic Analytics, 3D and 4D Vision, Multi-Robot System, Multi-Sensor Fusion

RESEARCH EXPERIENCES

Developing Robust and Real-Time Aerial Tracking Algorithms on CPU *2018.7 - present*

- Proposed a general automatic spatio-temporal regularization method. (*submitted to CVPR 2020*)
- Incorporated memory augmentation to tackle filter corruption issues. (*submitted to ICRA 2020*)
- Proposed to repress the aberrance in correlation filter framework. (*published in ICCV 2019*)
- Exploited the part-based method to deal with partial appearance variation. (*under revision*)
- Fused multiple features to construct robust representation. (*published in Remote Sensing*)

Investigating Deep Learning-based Visual Tracking for UAV *2019.3 - present*

- Exploited the keyframe technique and proposed a keyfilter-aware tracker for mitigating filter corruptions and lowering the redundancy of context learning. Utilized lightweight convolution features to efficiently and effectively raise the tracking robustness. (*submitted to ICRA 2020*)
- Explored the multi-frame strategy and developed the multi-frame consensus verification for achieving long-term tracking. Fused features from different layers of CNN including both spatial and semantic information to achieve accurate tracking. (*published in IROS 2019*)
- Designed a collaborative multi-recommender scheme to unlock CNN's potential. (*under revision*)

Localization by Tracking: A Monocular Pose Estimation System

2019.7 - present

- Developed fast trackers on C++ platform to track the markers observed by a moving camera.
- Developed a monocular pose estimation system with high versatility and accuracy.
- Tested the monocular localization system in ROS Gazebo and validated it on quanser platform.

SELECTED PROJECTS

UAV-loaded Serpentine Manipulator for Search and Rescue

2018.5 - 2018.7

- Designed the overall structure of separable UAV-loaded Serpentine Manipulator.
- Finished writing the specification and submitted the National Patent for Invention application.

Structure Design for Drone's Wireless Charging

2018.5 - 2018.7

- Conducted the overall structure design of a 3-DOF wireless charging facility for drones.
- Enhanced the accuracy when the drone approached the ground with imprecise poses.

ZEAL Eco-Power Racing Vehicle Team

2016.10 - 2019.10

- Committed to designing and manufacturing Eco-Power car, specifically the control system.
- Designed velocity sensor, SD data logger and automatic throttle controller using ARM Cortex-M.

Design of a Hiking Assistance Device

2016.7 - 2017.7

- Completed the overall structure design of the light-weight hiking assistance foldable drone.
- Applied the finite element analysis (FEA) methods to check the strength of all stressed parts.

PUBLICATIONS

(* highlights my supervisor.)

Journals:

- Changhong Fu*, Fuling Lin, **Yiming Li**, Guang Chen. *Correlation Filter-Based Visual Tracking for UAV with Online Multi-Feature Learning*, Remote Sensing, 11.5 (2019): 549.
- **Yiming Li**, Changhong Fu*, Ziyuan Huang, Yinqiang Zhang, Jia Pan. *Intermittent Contextual Learning for Keyfilter-Aware UAV Object Tracking Using Deep Convolutional Feature*, IEEE Transactions on Multimedia, 2019. Under revision¹.

Conferences:

- Ziyuan Huang, Changhong Fu*, **Yiming Li**, Fulin Lin, Peng Lu. *Learning Aberrance Repressed Correlation Filters for Real-Time UAV Tracking*, in IEEE International Conference on Computer Vision (**ICCV'19**), Seoul, Korea, Oct. 2019.
- Changhong Fu*, Ziyuan Huang, **Yiming Li**, Ran Duan, Peng Lu. *Boundary Effect-Aware Visual Tracking for UAV with Online Enhanced Background Learning and Multi-Frame Consensus Verification*, in IEEE/RSJ International Conference on Intelligent Robots and Systems (**IROS'19**), Macau, China, Nov. 2019.
- *Automatic Spatio-Temporal Regularization: A General Approach in Correlation Filters for Fast UAV Tracking*, in IEEE Conference on Computer Vision and Pattern Recognition (**CVPR'20**). Under review. (first author)

¹Evaluations from three reviewers: novel enough for publication, technically sound and significant contribution.

- **Yiming Li**, Changhong Fu*, Fangqiang Ding, Ziyuan Huang, Jia Pan. *Augmented Memory for Correlation Filters in Real-time UAV Tracking*, in IEEE International Conference on Robotics and Automation (**ICRA'20**). Under review.
- **Yiming Li**, Changhong Fu*, Ziyuan Huang, Yinqiang Zhang, Jia Pan. *Keyfilter-Aware Real-Time UAV Object Tracking*, in IEEE International Conference on Robotics and Automation (**ICRA'20**). Under review.
- Yujie He, Changhong Fu*, Fuling Lin, **Yiming Li**, Peng Lu. *Tri-Attention Correlation Filter for Effective UAV Object Tracking*, in IEEE International Conference on Robotics and Automation (**ICRA'20**). Under review.
- Fan Li, Changhong Fu*, Fuling Lin, **Yiming Li**, Peng Lu. *Training-set Distillation for Real-Time UAV Object Tracking*, in IEEE International Conference on Robotics and Automation (**ICRA'20**). Under review.

AWARDS

- Model of Outstanding Students in Tongji university (0.15 %) 2019.1
- Second Prize of National Undergraduate Innovation and Entrepreneurship Competition 2018.11
- First Prize of the 3rd Shanghai Mechanics Competition 2018.6
- First Prize of the 8th Shanghai Innovation Design Competition 2018.5
- Meritorious Winner in 2018 Mathematics Contest in Modeling 2018.3
- Champion of 2017 Honda Eco Mileage Challenge (GS Group) 2017.10
- Third Prize of China Undergraduate Mathematical Competition in Modeling 2017.10
- Second Prize of Tongji Undergraduate Mathematical Competition in Modeling 2017.5
- Third Prize of Tongji Undergraduate General Physics Competition 2016.5

SERVICE

Reviewer: IEEE International Conference on Advanced Robotics and Mechatronics (ARM), 2019

KEY SKILLS

Language: English: TOEFL 105(R29,L27,S24,W25), GRE(V156+Q168+AW4.0); German(B1).

Programming: C/C++, Python, Matlab.

Tools: Robot Operating System (ROS), LaTeX.