

# YIMING LI

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## EDUCATION

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- **Tongji University, Shanghai, China** *2015.9 - 2020.6(expected)*  
B.Eng. in Mechanical Engineering
  - GPA: *3.77/4.0* (equivalent to *90/100*)
  - Supervisor: Prof. Changhong Fu (Director of Vision4Robotics Group)
  - Scholarship: National Scholarship (top 1%), Shanghai Scholarship (top 1%), National Endeavor Scholarship, Excellent Student Scholarship, School Practice Scholarship.
- **Tsinghua University, Beijing, China** *2019.9 - 2019.10*  
Visiting Student in Department of Automation
  - Supervisor: Prof. Geng Lu (Director of UAV Lab)

## RESEARCH INTERESTS

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Robot Vision and Learning, Visual Tracking, Visual Navigation, Multi-Model Perception

## RESEARCH EXPERIENCES

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### **Developing Robust and Real-Time Aerial Tracking Algorithms on CPU** *2018.7 - present*

- Proposed a general automatic spatio-temporal regularization method. (*accepted by CVPR 2020*)
- Incorporated memory augmentation to tackle filter corruption issues. (*submitted to IROS 2020*)
- Proposed to repress the aberrance in correlation filter framework. (*published in ICCV 2019*)

### **Investigating Deep Learning-based Visual Tracking for UAV** *2019.3 - present*

- Exploited the keyframe technique and proposed a keyfilter-aware tracker for mitigating filter corruptions and lowering the redundancy of context learning. Utilized lightweight convolution features to efficiently and effectively raise the tracking robustness. (*accepted by ICRA 2020*)
- Explored the multi-frame strategy and developed the multi-frame consensus verification for achieving long-term tracking. Fused features from different layers of CNN including both spatial and semantic information to achieve accurate tracking. (*published in IROS 2019*)
- Designed a collaborative multi-recommender scheme to unlock CNN's potential. (*under revision*)

### **Localization by Tracking: A Monocular Pose Estimation System** *2019.7 - present*

- Developed fast trackers on C++ platform to track the markers observed by a moving camera.
- Developed a monocular pose estimation system with high versatility and accuracy.
- Tested the monocular localization system in ROS Gazebo and validated it on quanser platform.

## SELECTED PROJECTS

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### UAV-loaded Serpentine Manipulator for Search and Rescue 2018.5 - 2018.7

- Designed the overall structure of separable UAV-loaded Serpentine Manipulator.
- Finished writing the specification and submitted the National Patent for Invention application.

### Structure Design for Drone's Wireless Charging 2018.5 - 2018.7

- Conducted the overall structure design of a 3-DOF wireless charging facility for drones.
- Enhanced the accuracy when the drone approached the ground with imprecise poses.

### ZEAL Eco-Power Racing Vehicle Team 2016.10 - 2019.10

- Committed to designing and manufacturing Eco-Power car, specifically the control system.
- Designed velocity sensor, SD data logger and automatic throttle controller using ARM Cortex-M.

### Design of a Hiking Assistance Device 2016.7 - 2017.7

- Completed the overall structure design of the light-weight hiking assistance foldable drone.
- Applied the finite element analysis (FEA) methods to check the strength of all stressed parts.

## PUBLICATIONS

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### Journals:

- Changhong Fu\*, Fuling Lin, **Yiming Li**, Guang Chen. *Correlation Filter-Based Visual Tracking for UAV with Online Multi-Feature Learning*, Remote Sensing, 11.5 (2019): 549.
- **Yiming Li**, Changhong Fu\*, Ziyuan Huang, Yinqiang Zhang, Jia Pan. *Intermittent Contextual Learning for Keyfilter-Aware UAV Object Tracking Using Deep Convolutional Feature*, IEEE Transactions on Multimedia, 2019. Accepted.
- Changhong Fu\*, Ziyuan Huang, **Yiming Li**, Ran Duan, Peng Lu. *Online Enhanced Background Learning for Boundary Effect-Aware Visual Tracking for UAV with Consensus Verification*, IEEE Transactions on Knowledge and Data Engineering, 2019. Under preparation.

### Conferences:

- Ziyuan Huang, Changhong Fu\*, **Yiming Li**, Fulin Lin, Peng Lu. *Learning Aberrance Repressed Correlation Filters for Real-Time UAV Tracking*, in IEEE International Conference on Computer Vision (ICCV'19), Seoul, Korea, Oct. 2019.
- Changhong Fu\*, Ziyuan Huang, **Yiming Li**, Ran Duan, Peng Lu. *Boundary Effect-Aware Visual Tracking for UAV with Online Enhanced Background Learning and Multi-Frame Consensus Verification*, in IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS'19), Macau, China, Nov. 2019.
- **Yiming Li**, Changhong Fu\*, Ziyuan Huang, Yinqiang Zhang, Jia Pan. *Keyfilter-Aware Real-Time UAV Object Tracking*, in IEEE International Conference on Robotics and Automation (ICRA'20). Accepted.
- Fan Li, Changhong Fu\*, Fuling Lin, **Yiming Li**, Peng Lu. *Training-set Distillation for Real-Time UAV Object Tracking*, in IEEE International Conference on Robotics and Automation (ICRA'20). Accepted.

- **Yiming Li**, Changhong Fu\*, Fangqiang Ding, Ziyuan Huang, Geng Lu. *AutoTrack: Towards High-Performance Visual Tracking for UAV with Automatic Spatio-Temporal Regularization*, in IEEE Conference on Computer Vision and Pattern Recognition (**CVPR'20**). Accepted.
- **Yiming Li**, Changhong Fu\*, Fangqiang Ding, Ziyuan Huang, Jia Pan. *Augmented Memory for Correlation Filters in Real-time UAV Tracking*, in IEEE/RSJ International Conference on Intelligent Robots and Systems (**IROS'20**). Under review.
- Yujie He, Changhong Fu\*, Fuling Lin, **Yiming Li**, Peng Lu. *Towards Robust Visual Tracking for Unmanned Aerial Vehicle with Tri-Attentional Correlation Filters*, in IEEE/RSJ International Conference on Intelligent Robots and Systems (**IROS'20**). Under review.
- Changhong Fu\*, Fangqiang Ding, **Yiming Li**, Jin Jin, Chen Feng. *DR<sup>2</sup>Track: Towards Real-Time Visual Tracking for UAV via Distractor Repressed Dynamic Regression*, in IEEE/RSJ International Conference on Intelligent Robots and Systems (**IROS'20**). Under review.
- Fangqiang Ding, Changhong Fu\*, **Yiming Li**, Jin Jin, Chen Feng. *Towards Robust Real-Time Visual Tracking for UAV with Joint Scale and Aspect Ratio Optimization*, in IEEE/RSJ International Conference on Intelligent Robots and Systems (**IROS'20**). Under review.
- Changhong Fu\*, Jin Jin, Fangqiang Ding, **Yiming Li**. *Learning Spatial Reliability Enhanced Correlation Filters for Real-Time UAV Tracking*, in IEEE/RSJ International Conference on Intelligent Robots and Systems (**IROS'20**). Under review.

## AWARDS

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- Top 10 Undergraduate Researchers in Tongji University<sup>1</sup> 2019.12
- Model of Outstanding Students in Tongji University (0.15 %) 2019.1
- Second Prize of National Undergraduate Innovation and Entrepreneurship Competition 2018.11
- First Prize of the 3rd Shanghai Mechanics Competition 2018.6
- First Prize of the 8th Shanghai Innovation Design Competition 2018.5
- Meritorious Winner in 2018 Mathematics Contest in Modeling 2018.3
- Champion of 2017 Honda Eco Mileage Challenge (GS Group) 2017.10
- Third Prize of China Undergraduate Mathematical Competition in Modeling 2017.10
- Second Prize of Tongji Undergraduate Mathematical Competition in Modeling 2017.5
- Third Prize of Tongji Undergraduate General Physics Competition 2016.5

## SERVICE

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Reviewer:

IEEE International Conference on Advanced Robotics and Mechatronics (ARM), 2019

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2020

## KEY SKILLS

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**Language:** English: TOEFL **105**(R29,L27,S24,W25), GRE **324**(V156+Q168+AW4.0); German(B1).

**Programming:** C/C++, Python, Matlab.

**Tools:** Robot Operating System, LaTeX, Autodesk Inventor, Adobe After Effects, Adobe Premiere.

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<sup>1</sup>10 out of 35 candidates from 18,115 undergraduate students