

# Zeyu Ren

*Ph.D. in Robotics*

Shangdi No.4 Street, Rokae  
Beijing, China

☎ +86 139 1280 4417

✉ renzeyu@rokae.com



## Work Experience

2020- **Rokae Robotics.**

**Mechatronics Engineer**, Robotic R&D Center, Beijing, China.

2019–2020 **Italian Institute of Technology (IIT).**

**Post Doc**, Humanoid and Human Centered Mechatronics (HHCM), Genoa, Italy.

## Education

2015–2019 **Italian Institute of Technology (IIT) & University of Genoa (UniGe).**

**Ph.D. in Robotics**, Advanced Robotics (ADVR), Genoa, Italy.

2011–2015 **Zhejiang University.**

**B.E in Mechatronics**, Chu Kochen Honors College (CKC), Hangzhou, China.

## Research Interests

Under-Actuated Robotic Hands, Series Elastic Actuator (SEA)

Tendon Driven Mechanism, Legged Robots, Actuators, Mechatronics Design

## Skills and Expertise

R & D Tools Design: PTC Creo, SolidWorks, AutoCAD

Simulation and Modeling: ANSYS, Adams, MATLAB Simulink, Gazebo & ROS

Programming: C/C++, Matlab

Engineering BOM & Assembly & Maintain Documentation, CNC Manufacturing Process, Precise Manual Assembly

Academic Latex + JabRef, Word + Zotero, Academical Presentation

Multimedia Filmora, Kdenlive, Inkscape, Powerpoint

Language English (fluent), Chinese (mother tongue), Italian and German (basic)

## Projects

2019-2020 **INAIL, IIT**, Genova, Italian Institute for Insurance against Workplace Injuries Project.

Develop a high-integrated and under-actuated Hand (HERI II-H) for HyQ-Real Robot.

2015-2019 **Pholus, IIT**, Genova, Italy-Singapore Military Project.

Develop two high-integrated and under-actuated Hands for (HERI II-P) Pholus Robot.

2015-2019 **CENTAURO, IIT**, Genova, European Project H2020-ICT-23-2014.

Design and develop an under-actuated and finger modular Hand (HERI II-C) for CENTAURO robot.

2016-2017 **WALK-MAN, IIT**, Genova, European Project FP7-ICT-2013-10.

Design and develop a novel 3-DoF leg (eLeg) powered by adjustable series and parallel compliant actuation principles for higher energy efficiency and explosive motion.

2013-2015 **ZJUNlict, Zhejiang University**, Hangzhou.

Design and develop omni-wheeled soccer robots for RoboCup SmallSize League.

## Awards

2014.07 **RoboCup, Championship.**

SmallSize League, Joao Pessoa, Brazil, Member of ZJUNlict

- 2014.04 **RoboCup IranOpen, Second-place.**  
SmallSize League, Tehran, Iran, Member of ZJUNlict
- 2015.08 **RoboCup, Third-place.**  
SmallSize League, Hefei, China, Member of ZJUNlict
- 2020.10 **Z-Park U30, Winner.**  
Zhong Guan Cun Science Park (Z-Park)

## Publications

- 2020 V. D. Amara, J. Malzahn, **Z. Ren**, W. Roozin, N. G. Tsagarakis, "*On the Efficient Control of Series-Parallel Compliant Articulated Robots*", in IEEE International Conference on Robotics and Automation (ICRA).
- 2019 W. Roozing, **Z. Ren**, N. G. Tsagarakis, "*An Efficient Leg with Series-Parallel and Biarticular Compliant Actuation: Design Optimisation, Modelling, and Control of the eLeg*", in International Journal of Robotics Research (IJRR).
- 2019 T. Klamt, D. Rodriguez, L. Baccelliere, Et al., **Z. Ren**, Et al., U. Suess, N. Tsagarakis and S. Behnke, "*Flexible Disaster Response of Tomorrow - Final Presentation and Evaluation of the CENTAURO System*", in IEEE Robotics and Automation Magazine (RAM).
- 2019 N. Kashiri, L. Baccelliere, L. Muratore, A. Laurenzi, **Z. Ren**, E. Hoffman, G. Rigano, Et al., N. G. Tsagarakis, "*CENTAURO: A Hybrid Locomotion and High Power Resilient Manipulation Platform*", in IEEE Robotics and Automation Letters (RAL)
- 2018 **Z. Ren**, W. Roozing and N. G. Tsagarakis, "*The eLeg: A Novel Efficient Leg Prototype Powered by Adjustable Parallel Compliant Actuation Principles*", in IEEE-RAS International Conference on Humanoid Robots (Humanoids).
- 2018 W. Roozing, **Z. Ren** and N. G. Tsagarakis, "*Design of a novel 3-dof leg with series and parallel compliant actuation for energy efficient articulated robots*", in IEEE International Conference on Robotics and Automation (ICRA).
- 2018 **Z. Ren**, N. Kashiri, C. Zhou and N. G. Tsagarakis, "*HERI II: A Robust and Flexible Robotic Hand based on Modular Finger design and Under Actuation Principles*", in IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).
- 2017 **Z. Ren**, C. Zhou, S. Xin and N. G. Tsagarakis, "*HERI Hand: A Quasi Dexterous and Powerful Hand with Asymmetrical Finger Dimensions and Under Actuation*", in IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).
- 2014 C. Li, R. Xiong, **Z. Ren**, T. Jian and Y. Zhao "*Zjunlict: Robocup 2014 small size league champion*", in Robot Soccer World Cup, Spring Cham, 47-59.

## The Robots That I Built



## More Information

Homepage: [Homepage: Zeyu Ren](#) Demos: [Youtube Channel: Zeyu Ren](#)