Question 1 Bumpy Road

Consider a unicycle fitted with a damped, shock-absorbing spring with spring constant k and damping coefficient c. When a rider of mass $m=80{\rm kg}$ sits on the unicycle. the spring compresses and the seat sags by $0.02{\rm m}$. Recall $g=9.81{\rm m/s^2}$

The unicycle (including the rider) goes over a crack that sets the spring in motion. It takes $au=5{
m s}$ for the amplitude of the underdamped spring oscillations to decay by a factor of 1/e .

Hint: recall the equation for a free, damped spring

$$m\ddot{x} + c\dot{x} + kx = 0$$
, or, equivalently $\ddot{x} + 2\zeta\omega_n\dot{x} + \omega_n^2x = 0$

with $\omega_n=\sqrt{\frac{k}{m}}$ and $\zeta=\frac{c}{2m\omega_n}$. When underdamped, this has the general (homogeneous) solution $x(t)=e^{-\zeta\omega_nt}\left(A\exp\Bigl(i\omega_n\sqrt{1-\zeta^2}t\Bigr)+B\exp\Bigl(-i\omega_n\sqrt{1-\zeta^2}t\Bigr)\right)$.

(a)

Find the dimensionless damping parameter ζ . Justify calling the system "underdamped".

Call the distance seat sags $\Delta h = 0.02 \mathrm{m}$, thus

$$mg = k\Delta h$$
 $k = rac{mg}{\Delta h}$

we know t2hat after $\tau=5\mathrm{s}$, the oscillation decay by a factor of 1/e. Thus

$$e^{-\zeta\omega_n au}=e^{-1}$$

and that

$$\zeta = rac{1}{w_n au} = au^{-1} \sqrt{rac{m}{k}} = au^{-1} \sqrt{rac{\Delta h}{g}}$$

$$\zeta = 0.2 \cdot \sqrt{\frac{0.02}{9.81}} \approx 0.00903$$

which is less than 1, and this shows that the system is indeed "underdamped".

(b)

Find the damping coefficient c

$$c=\zeta\cdot 2m\omega_n=2\zeta m\sqrt{rac{k}{m}}=2 au^{-1}\sqrt{rac{\Delta h}{g}mk}=2 au^{-1}m$$

and thus

$$c=2rac{m}{ au}=32 ext{kg/s}$$

Now suppose that the unicycle is ridden over a "washboard" road with bump spaced 1m apart. Treat the surface of the road as sinusoidal. At what speed must the unicycle go for the spring to be forced into resonance?

Then the frequency of bumping ω_b should be equal to natural frequency ω_n . Thus

$$w_b=w_n=\sqrt{rac{k}{m}}=\sqrt{rac{mg}{m\Delta h}}=\sqrt{rac{g}{\Delta h}}$$

and thus

$$v=\omega_b d=\sqrt{rac{9.81}{0.02}}\cdot 1pprox 22.15 ext{m/s}$$

(d)

Calculate the steady-state phase difference between the spring oscillations and the driving force caused by the bumps in the road near the resonance.

we know that $\omega_b = \omega_n$, and thus from lecture notes 15,

$$ilde{G}(\omega) = rac{1}{k} rac{1}{2i\zeta} = -rac{1}{2k\zeta}i$$

and thus

$$\phi(\omega) = -rg ilde{G}(\omega) = -rac{3}{2}\pi^{
m equiv}rac{1}{2}\pi$$

Question 2 Wave Rectifier

A full-wave rectifier acting on a sinusoidal function of the form $F(t)=F_0\sin(\omega t)$, with $F_0>0$ constant, will produce a rectified function $F_{\rm rec}=|F_0\sin(\omega t)|$

(a)

Find the Fourier series representation of $F_{
m rec} = |F_0 \sin(\omega t)|$

The period of the function is $T=\frac{\pi}{\omega}$, and for $t\in[0,\pi]$, the $F_{\rm rec}=F_0\sin(\omega t)$. For the function, we could see that is purely even, and thus $b_n=0$. For a_n , they are

$$egin{aligned} a_n &= rac{2}{T} \int_0^{\pi/\omega} F_0 \sin(\omega t) \cos(n\omega t) \mathrm{d}t \ &= rac{\omega}{\pi} F_0 igg(rac{1}{(2n+1)\omega} \cos((2n+1)\omega t) + rac{1}{(2n-1)\omega} \cos((2n-1)\omega t)igg)igg|_0^{\pi/\omega} \ &= rac{-4F_0}{\pi (4n^2-1)} \end{aligned}$$

and thus

$$F_{
m rec} = \sum_{n=0}^{\infty} rac{-4F_0}{\pi(4n^2-1)} {
m sin}(n\omega t)$$

Using mathematica

$$\begin{split} &\text{In}[18]\text{:= DSolve}[\text{m}*\text{x}''[\text{t}] + \text{k}*\text{x}[\text{t}] == \text{a}*\text{Sin}[\text{O}*\text{t}], \text{x}[\text{t}], \text{t}] \\ &\text{Out}[18]\text{=} \ \left\{ \left\{ \text{x}[\text{t}] \rightarrow \text{c}_1 \text{Cos}\left[\frac{\sqrt{\text{k}} \text{ t}}{\sqrt{\text{m}}}\right] + \text{c}_2 \text{Sin}\left[\frac{\sqrt{\text{k}} \text{ t}}{\sqrt{\text{m}}}\right] + \\ & \frac{\text{Cos}\left[\frac{\sqrt{\text{k}} \text{ t}}{\sqrt{\text{m}}}\right]^2 \text{Sin}[\text{O} \text{ t}] + \text{Sin}\left[\frac{\sqrt{\text{k}} \text{ t}}{\sqrt{\text{m}}}\right]^2 \text{Sin}[\text{O} \text{ t}]}{\text{k} - \text{m} \text{O}^2} \right\} \right\} \end{split}$$

the first and then

Simplify[x[t]]

$$\texttt{c_1} \, \mathsf{Cos} \, \Big[\, \frac{\sqrt{k} \, \, \mathsf{t}}{\sqrt{\mathsf{m}}} \, \Big] \, + \, \mathsf{c_2} \, \mathsf{Sin} \, \Big[\, \frac{\sqrt{k} \, \, \mathsf{t}}{\sqrt{\mathsf{m}}} \, \Big] \, + \, \frac{\mathsf{Sin} \, [\, \mathsf{O} \, \mathsf{t} \,]}{k - \, \mathsf{m} \, \mathsf{O}^2}$$

two parts is just the homogeneous solution, we use the third part, and thus the particular solution should be

$$x_p(t) = \sum_{n=0}^{\infty} \frac{1}{k - m\omega^2} \sin(\omega t) = \infty$$

this makes sense because there is no damping, and external force is in resonance with motion.

Question 3

(a)

The frequency $\Omega=\frac{2\pi}{T}=2\pi.$ Note the function is odd from the graph, and the average value should be 0, and thus

$$F(t) = \sum_{n=1}^{\infty} b_n \sin(n\Omega t)$$

we know that

$$b_n = rac{2}{T} \int_{-rac{1}{2}}^{rac{1}{2}} 2F_0 t \sin(2\pi n t) = rac{2}{1} \cdot rac{F_0}{\pi}$$

and thus

$$F(t) = \frac{2F_0}{\pi} \sum_{n=1}^{\infty} \sin(2\pi nt)$$

(b)

the particular solution will have the form of

$$x_p(t) = \sum_{n=1}^{\infty} c_n \sin(n\Omega t)$$

and thus

$$\sum_{n=1}^{\infty} c_n (-mn^2\Omega^2 + cn\Omega + k) \sin(n\Omega t) = \sum_{n=1}^{\infty} rac{2F_0}{\pi} \sin(n\Omega t)$$

and thus

$$c_n = rac{2F_0}{(-mn^2\Omega^2 + cn\Omega + k)\pi}$$

and we could see the c_n decrease as n increase. That means c_1 term $c_1 \sin(\Omega t)$ (with frequency Ω) dominate the response.

Question 4

(a)

What is the period T of the force?

From the graph, we could see it's $T=2\mathrm{s}$

(b)

From the plot, we could see that the function is even. Thus, $F_{\mathrm{odd}}=0$, and all the b_n should thus vanish.

(c)

From (b), we know that the function reduced to

$$F(t) = rac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos\left(rac{2n\pi t}{T}
ight)$$

and thus a solution of

$$x_p(t) = c + d_n \sum_{n=1}^{\infty} \cos \left(rac{2n\pi t}{T}
ight) + \sum_{n=1}^{\infty} e_n \sin \left(rac{2n\pi t}{T}
ight)$$

the frequency is just $\Omega=rac{2\pi}{T}.$ For shorthand, just denote $\cos_n=\cos(n\Omega t)$ and $\sin_n=\sin(n\Omega t)$

and thus

$$x_p''(t) = -d_n(n\Omega)^2 \cos_n - e_n(n\Omega)^2 \sin_n x_p'(t) = -d_n(n\Omega) \sin_n + e_n(n\Omega) \cos_n$$

and thus

$$(-md_n(n\Omega)^2+ce_n(n\Omega)+kd_n)\cos_n+(-me_n(n\Omega)^2-cd_n(n\Omega)+ke_n)\sin_n+kc=rac{a_0}{2}+a_n\cos_n \ egin{cases} c=rac{a_0}{2k}\ a_n=-md_nA^2+ce_nA+kd_n\ 0=-me_nA^2-cd_nA+ke_n \end{cases}$$

with result

$$c = rac{a_0}{2k} \ d_n = rac{(k - mA^2)a_n}{(k - mA^2)^2 + (cA)^2} \ e_n = rac{cA \cdot a_n}{(k - mA^2)^2 + (cA)^2}$$

(d)

For a long time, the oscillator will result in steady-state $x_p(t)$. Therefore, we could just integrate over one period T for $x_p(t)$ and divide the time T to get the average position. Do notice that

$$\int_{ ext{period}} \sin(\omega t + \phi) \mathrm{d}t = \int_{ ext{period}} \cos(\omega t + \phi) \mathrm{d}t = 0$$

where ω and ϕ could be arbitrary constant, and thus

$$rac{1}{T}\int_{
m period}x_p(t){
m d}t=rac{cT}{T}=rac{a_0}{2k}$$