(a)

The key difference is that AWS Lambda is a serverless compute service where you run code in response to events without managing servers, while AWS EC2 provides virtual machines where you have full control over the server, including provisioning, configuration, and management.

(b)

AWS Lambda's pricing is based on request count and duration, while AWS Spot Instances use bidding for variable pricing. Lambda functions are short-lived and event-driven, while Spot Instances can run longer but may be terminated with a two-minute notice.

(c)

Azure functions and Google cloud functions

(d)

For simple event-driven tasks and lightweight processing, choose serverless options like AWS Lambda or Azure Functions. For complex, long-running applications (like game server) requiring customizability and computational power, AWS EC2 is a better choice.

From https://azure.microsoft.com/en-us/pricing/details/machine-learning/, https://cloud.google.co
m/compute/docs/gpus, and https://cloud.google.co

(a)

	AWS	Azure	Google Cloud
Name	g5.16xlarge	NC6s	a2-highgpu-1g
GPU Memory Size (GB)	24	32	40

The a2-highgpu-1g

(b)

	AWS	Azure	Google Cloud
Name	g4ad.xlarge / g3.4xlarge	NC6s v2 / Nv6 / Nv12s v3 / NC4as T4 v3	P4
GPU Memory Size (GB)	8	16	8

Either g4ad.xlarge, g3.4xlarge, or P4.

(c)

GPUs are versatile, widely used for various tasks for its parallel execution ability (primarily graphic rendering), including machine learning. TPUs, specific to Google Cloud, excel in deep learning due to optimized architecture and faster performance for matrix operations, making them ideal for Al workloads, but less versatile and widely available than GPUs.

```
    Map1(a, b)
    Output (key = a, value = (OUT, b))
    Output (key = b, value = (IN, a))
    Reduce1(key = x, values = V)
    Collect s_out set of all (OUT, *) value items from V
    Collect s_in set of all (IN, *) value items from V
    If sizeof(s_out) < 10 and sizeof(s_in) >= 100 million then
    For each (_, followed_user) of s_in
    Output (followed_user, (user = x, type = "followed"))
    If sizeof(s_in) >= 100 million
    Return (x, (user = x, type = "following"))
    Map2 = identity()
    Reduce2(key = x, values)
    If exist (user = x, type = "following") in values
```

■ Then foreach (user = y, type = "followed") in value

Output y

- Map1(a, b)
 - Output (key = a, value = (OUT, b))
 - Output (key = b, value = (IN, a))
- Reduce1(key = x, values = V)
 - Collect s_out set of all (out, *) value items from V
 - Collect S_in set of all (IN, *) value items from V
 - If sizeof(S_in) >= 100 million then
 - Output (1, (x, S_in))
- Map2 = Identity()
- Reduce2(key = 1, values = V)
 - For all combination pair ((x, Sx_in), (y, Sy_in)) in V
 - If sizeof(Intersection(Sx_in, Sy_in)) >= 100
 - Output (x, y)

Note: Similar to Exercise 3's construction

```
• Map1(a, b) Read from D1
```

```
Output (key = b, value = a)
```

- Reduce1(key = x, values = V)
 - Read from D2, get the time_intervals from user x
 - o For all a in V
 - Output (lexicographic_sorted_pair(x, a), time_intervals)
- Map2 = Identity
- Reduce2(key = (a, b), values = {time_intervals_1, time_intervals_2 ...})
 - o If sizeof(values) = 1,
 - Output Nothing
 - o If sizeof(values) = 2
 - If the HasIntersection(time_intervals_1, time_intervals_2) is true
 - Output (a, b)
 - where HasIntersection is a common function that checks whether two list of ranges has intersections (this could be a naïve algorithm, could be a dynamic programming algorithm learned in CS374, etc. It's just a black-box utility function, and its finer detail is not concerned / very important here)

```
• Map1(V):
```

```
Output (key = (v.1, v.2), value = 1)
```

- Output (key = (v.2, v.3), value = 1)
- Output (key = (v.1, v.3), value = 1)
- Reduce1(key = K, values = count)
- Output (1, (K, count))
- Map2 = Identity()
- Reduce2(key = 1, values = P)
 - Initialize 6 variables
 - If ((A, B), count) exists, set AB = count else AB = 0
 - If ((A, C), count) exists, set AC = count else AC = 0
 - If ((B, A), count) exists, set BA = count else BA = 0
 - If ((B, C), count) exists, set BC = count else BC = 0
 - If ((C, A), count) exists, set CA = count else CA = 0
 - If ((C, B), count) exists, set CB = count else CB = 0
 - Note, AB means the number of votes that rate A higher than B
 - o Initialize three counts, A_condor = 0, B_condor = 0, C_condor = 0, then
 - If AB > BA, then A_condor ++
 - If BA > AB, then B_condor ++
 - If AC > CA, then A_condor ++
 - If CA > AC, then C_condor ++
 - If BC > CB, then B_condor ++
 - If CB > BC, then C_condor ++
 - Make list condors = [A_condor, B_condor, C_condor] and names = [A, B, C]. Get
 maxIndices = MaxIndices(condors).
 - If sizeof(maxIndices) = 1
 - Return names[maxIndices[0]]
 - Else
 - Return names.filter(index in maxIndices) (that is, return list of elements where its index is in maxIndices)

The claim is half-correct. As lecture 5 slides proved, both form of gossip have a time complexity of $O(\log N)$ for spreading the N/2 of all nodes. Yet, for the second half of the pull gossip, the pull gossip takes $O(\log \log N)$ rather than $O(\log N)$ in pull gossip. (For the proof, it will just refer the slides rather than proving it again)

- In all forms of gossip, it takes O(log(N)) rounds before about N/2 processes get the gossip
 - Why? Because that's the fastest you can spread a message – a spanning tree with fanout (degree) of constant degree has O(log(N)) total nodes (height of tree)
- Thereafter, pull gossip is faster than push gossip
- After the ith, round let \mathcal{P}_i be the fraction of non-infected processes. Let each round have k pulls. Then

$$p_{i+1} = (p_i)^{k+1}$$
This is super-exponential Second half of pull gossip fine

- Second half of pull gossip finishes in time $O(\log(\log(N))$

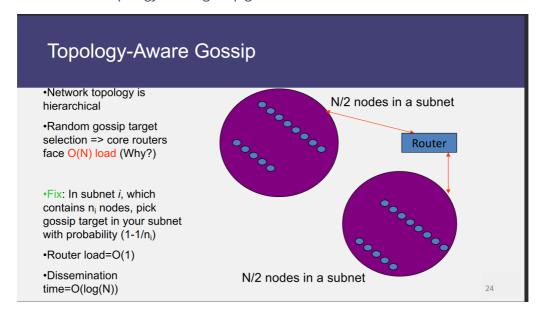
So, for the first half of the gossip, the claim is not correct, the time complexity between is both $O(\log N)$, for the second half of the gossip, the claim is correct.

(a)

No, you couldn't. Since foreach subnet, you could only infect your next subnet. That means, suppose we start at subnet 1, then it could only infect subnet 2. For subnet 2, the shortest time that it must wait before infecting subnet 3 is $O(\log \sqrt{N}) \cdot$ time. We notice that to infect next subnet, we have to take $O(\sqrt{N})$ time. Since we start from S(0) subnet, and we need to infect all the way to the $S(\sqrt{N}-1)$ subnet, that means, we have to take $O(\log \sqrt{N}) \cdot \sqrt{N}$ time at minimum, that is $O(\sqrt{N} \cdot \log \sqrt{N})$, this minimum time is even bigger than the $O(\log N)$ we aim for. So, it's **impossible** to have an $O(\log N)$

(b)

We know that for the topology-aware gossip given in the lecture 5



If we want to achieve router load of O(1), then we need to pick the gossip target with probability $(1-1/n_i)$. The reason why it's the case is because for each node in subnet i, it has a probability choosing a target outside of the node of $1/n_i$, therefore, all the nodes in that subnet has a expectation value of choosing the outside node for single gossip round is $n_i \cdot 1/n_i = 1$, since in the example given in lecture, there are only 2 nodes (therefore the expected inter-subnet gossips is 2), therefore the router load is O(1).

However, in the problem cases, considering one scenario where there are half of the subnet $\frac{1}{2}\sqrt{N}$ infected, and all of them passed that 'restriction' cool down period. (This scenario is rare, but possible) In this case, foreach subnet, the expected value of choosing the target outside that subnet is $\sqrt{N}\cdot 1/\sqrt{N}=1$, and there are $\frac{1}{2}\sqrt{N}$ subnet, so the total load of the router will be $O(\sqrt{N})$. That means we couldn't maintain O(1) load on router at any time