## **Question 1: Air force practice**

The zero order motion is

$$\ddot{x}_0(t) = 0$$
 $\ddot{y}_0(t) = 0$ 
 $\ddot{z}_0(t) = -g$ 

and with initial condition

$$x(0) = 0$$
 $y(0) = 0$ 
 $z(0) = h$ 
 $\dot{x}(0) = \frac{u}{\sqrt{2}}$ 
 $\dot{y}(0) = -\frac{u}{\sqrt{2}}$ 
 $\dot{z}(0) = 0$ 

and thus

$$x_0(t)=rac{u}{\sqrt{2}}t$$
  $y_0(t)=-rac{u}{\sqrt{2}}t$   $z_0(t)=h-rac{1}{2}gt^2$ 

and for the first order

$$\ddot{x}_1 = 2\omega(-rac{u}{\sqrt{2}})\sin heta - 2\omega\cdot 0\cos heta = -\sqrt{2}\omega u\sin heta$$
  $\ddot{y}_1 = -2\omega(rac{u}{\sqrt{2}})\sin heta = -\sqrt{2}\omega u\sin heta$   $\ddot{z}_1 = -g + 2\omega(rac{u}{\sqrt{2}})\cos heta = \sqrt{2}\omega u\cos heta$ 

and thus

$$egin{aligned} x_1 &= -rac{\sqrt{2}}{2}\omega u\sin heta t^2 \ y_1 &= -rac{\sqrt{2}}{2}\omega u\sin heta t^2 \ z_1 &= rac{\sqrt{2}}{2}\omega u\cos heta t^2 \end{aligned}$$

and thus, combining the terms, we got

$$egin{align} x(t) &= rac{u}{\sqrt{2}}t - rac{\sqrt{2}}{2}\omega u\sin heta t^2 \ y(t) &= -rac{u}{\sqrt{2}}t - rac{\sqrt{2}}{2}\omega u\sin heta t^2 \ z(t) &= h - rac{1}{2}gt^2 + rac{\sqrt{2}}{2}\omega u\cos heta t^2 \ \end{cases}$$

thus, the time when Humvee lands is

$$z(t) = 0$$
  $(rac{1}{2}g - rac{\sqrt{2}}{2}\omega u\cos\theta)t^2 = h$   $t^* = \sqrt{rac{2h}{g - \sqrt{2}\omega u\cos\theta}}$ 

and it thus lands on

$$x(t^*) = \frac{u}{\sqrt{2}} \sqrt{\frac{2h}{g - \sqrt{2}\omega u \cos \theta}} - \frac{\sqrt{2}}{2}\omega u \sin \theta \frac{2h}{g - \sqrt{2}\omega u \cos \theta}$$
$$y(t^*) = -\frac{u}{\sqrt{2}} \sqrt{\frac{2h}{g - \sqrt{2}\omega u \cos \theta}} - \frac{\sqrt{2}}{2}\omega u \sin \theta \frac{2h}{g - \sqrt{2}\omega u \cos \theta}$$

and, trying to simplify a bit

$$egin{aligned} x(t^*) &= \sqrt{rac{u^2 h}{g - \sqrt{2} \omega u \cos heta}} - rac{\sqrt{2} h \omega u \sin heta}{g - \sqrt{2} \omega u \cos heta} \ y(t^*) &= - \sqrt{rac{u^2 h}{g - \sqrt{2} \omega u \cos heta}} - rac{\sqrt{2} h \omega u \sin heta}{g - \sqrt{2} \omega u \cos heta} \end{aligned}$$

## Question 2: Golf on an alien planet

The period T is  $2*3600=7200\mathrm{s}$ , and thus  $\omega=rac{2\pi}{T}=rac{\pi}{3600}pprox0.000873\mathrm{rad/s}$ 

We could just use the formula  $R=rac{|v|}{2\omega\sin heta}$  , and thus

$$R=rac{v}{2\cdot\omega\sin45^\circ}=rac{v}{\sqrt{2}\omega}$$

notice that since the ground is frictionless, so the golf ball will continue to move on the ground, and since the Coriolis force is  $F=-2m\vec{\omega}\times\vec{v}\text{, it's always perpendicular to the motion (thus doesn't change it's speed). Therefore$ 

$$T = rac{2\pi R}{v} = rac{2\pi}{\sqrt{2}\omega} = rac{\sqrt{2}\pi}{\omega} pprox 5091.17 ext{s}$$

## **Question 3: Great circles**

Show that the shortest distance between two points on a sphere is a great circle. Start with the expression for the line element in spherical polar coordinates  $(r, \theta, \phi)$ , given by

$$dl^2 = dr^2 + r^2(d\theta^2 + \sin^2\theta d\phi^2)$$

Consider two points on the sphere for which  $r=R={
m const}$  (and  ${
m d} r=0$ ), specified by  $P_1=( heta_1,\phi_1)$ 

We know that line elements is  ${
m d}l^2={
m d}r^2+r^2({
m d}\theta^2+\sin^2\theta{
m d}\phi^2).$  Since  $r=R={
m const}$ 

$$dl^2 = R^2(d\theta^2 + \sin^2\theta d\phi^2)$$

and thus

$$rac{\mathrm{d}l}{\mathrm{d} heta} = \sqrt{R^2 \left(rac{\mathrm{d} heta^2}{\mathrm{d} heta^2}
ight) + \sin^2 heta \left(rac{\mathrm{d}\phi^2}{\mathrm{d} heta^2}
ight)}$$
 $\mathrm{d}l = R\sqrt{1 + \sin^2 heta \left(rac{\mathrm{d}\phi}{\mathrm{d} heta}
ight)^2} \mathrm{d} heta$ 

Then, the path between two points is

$$L = \int_{ heta_1}^{ heta_2} \mathrm{d}l = R \int_{ heta_1}^{ heta_2} \sqrt{1 + \sin^2 heta igg( rac{\mathrm{d}\phi}{\mathrm{d} heta} igg)^2} \mathrm{d} heta$$

etaand sietance the Euler-Lagrange equation in this case is

$$\frac{\mathrm{d}}{\mathrm{d}\theta} \left( \frac{\partial L}{\partial \dot{\phi}} \right) = \frac{\partial L}{\partial \phi} = 0$$

because L is not dependent directly on  $\phi$ . Thus

$$egin{aligned} rac{\partial L}{\partial \dot{\phi}} &= c \ &rac{1}{2}(1+\sin^2 heta \dot{\phi}^2)^{-1/2} \cdot 2 \sin^2 heta \dot{\phi} &= c \ &rac{\sin^2 heta \dot{\phi}}{\sqrt{1+\sin^2 heta \dot{\phi}^2}} &= c \end{aligned}$$

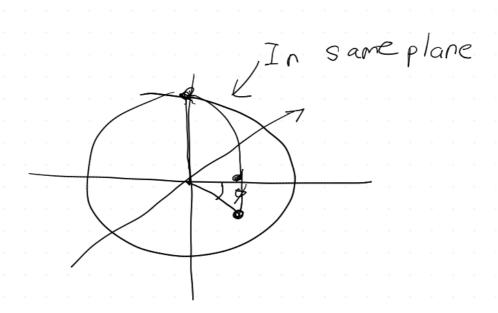
Without loss of generality, we could see set z axis to pass the  $P_1=(\theta_1,\phi_1)$  where  $\theta_1=0$ , and thus

$$\frac{\sin^2 0\dot{\phi}}{\sqrt{1+\sin^2 0\dot{\phi}^2}} = c$$

and thus it is evident that c=0, and thus

$$\sin \theta = 0 \quad \text{or} \quad \dot{\phi} = 0$$

If  $\theta=0$ , then both points are on same location, it is trivially the great circle. If  $\dot{\phi}=0$ , then two points only different in  $\theta$ , which should roughly looks like this:



so they are indeed in the same great circle.

## **Question 4 Variational derivatives**

Using the same technique in Lecture Notes 21

$$\delta F = \int_0^1 rac{\partial f(x,y,y',y'')}{\partial y''} \delta y'' \mathrm{d}x = \int_0^1 2 y'' \delta y'' \mathrm{d}x$$

We find that

$$2y''\delta y''=rac{\mathrm{d}}{\mathrm{d}x}(2y''\delta y')-2y'''\delta y'$$

$$2y'''\delta y'=rac{\mathrm{d}}{\mathrm{d}x}(2y'''\delta y)-2y''''\delta y$$

and thus

$$\delta F = \int_0^1 \mathrm{d}x rac{\mathrm{d}}{\mathrm{d}x} (2y''\delta y' - 2y'''\delta y) + \int_0^1 2y''''\delta y \mathrm{d}x$$

and thus

$$\delta F = \int_0^1 2y'''' \delta y \mathrm{d}x + 2y'' \delta y'igg|_0^1 - 2y''' \delta yigg|_0^1$$

As question indicate, we must satisfy that

$$\eta'(0)y''(0) = 0, \quad \eta'y''(1) = 0 \quad \eta(0)y'''(0) = 0, \quad \eta(1)y'''(1) = 0$$

$$\eta(0) = \eta(1) = \eta'(0) = 0$$

and  $\eta'(1)$  doesn't necessarily to be 0. This means y''(1) must be 0.

and thus we have the equation and the boundary conditions

$$y'''' = 0$$
  
 $y(0) = y(1) = y'(0) = y''(1) = 0$ 

and thus

$$y=Ax^3+Bx^2+Cx+D$$
  
 $y'=3Ax^2+2Bx+C$   
 $y''=6Ax+2B$ 

and applying boundary condition, we know

$$D = 0$$

$$A + B + C = 0$$

$$C = 0$$

$$6A + 2B = 0$$

and thus

$$A = B = C = D = 0$$

and thus

$$y = 0$$

which turns out to be really simple.