

### Question 1

In the Example 3.17 we showed that  $[\sigma_1, \sigma_2] = 2i\sigma_3$ . Following the same procedure, show that  $[\sigma_2, \sigma_3] = 2i\sigma_1$  and  $[\sigma_3, \sigma_1] = 2i\sigma_2$

$$[\sigma_2, \sigma_3] = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} - \begin{pmatrix} 0 & -i \\ -i & 0 \end{pmatrix} = 2i\sigma_1$$
$$[\sigma_3, \sigma_1] = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} - \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = 2i\sigma_2$$

and write down the uncertainty principle corresponding to simultaneous measurements of  $\sigma_1$  and  $\sigma_2$ . Is the uncertainty principle for  $\sigma_2$  and  $\sigma_3$  different?

$$\Delta\sigma_1\Delta\sigma_2 \geq \frac{1}{2} |\langle 2i\sigma_3 \rangle|$$

The general uncertainty principle works for all operators, so it should follow the same equation that

$$\Delta A \Delta B \geq \frac{1}{2} |\langle [A, B] \rangle|$$

which is

$$\Delta\sigma_2\Delta\sigma_3 \geq \frac{1}{2} |\langle 2i\sigma_1 \rangle|$$

### Question 2

Write  $Z$  in terms of its projection operators (in the  $|0\rangle$  and  $|1\rangle$  basis). Using this form of  $Z$ , calculate the probability of obtaining the result  $|1\rangle$  if you measure  $Z$  for the (unnormalized) state  $2|0\rangle + 3i|1\rangle$

$Z$  is equal to

$$Z = |0\rangle\langle 0| - |1\rangle\langle 1|$$

and

$$|\psi\rangle = Z(2|0\rangle + 3i|1\rangle) = 2|0\rangle - 3i|1\rangle$$

the probability is

$$\text{Pr} = \frac{(3i)(-3i)}{4 + (3i)(-3i)} = \frac{9}{4 + 9} = \frac{9}{13}$$

### Question 3

$$\{\sigma_i, \sigma_j\} = \sigma_i\sigma_j + \sigma_j\sigma_i$$

we could find out that

$$\begin{aligned}
\sigma_X \sigma_Y &= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} \\
\sigma_Y \sigma_X &= \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} -i & 0 \\ 0 & i \end{pmatrix} \\
\sigma_X \sigma_Z &= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \\
\sigma_Z \sigma_X &= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \\
\sigma_Y \sigma_Z &= \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} \\
\sigma_Z \sigma_Y &= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} 0 & -i \\ -i & 0 \end{pmatrix} \\
\sigma_X \sigma_X &= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\
\sigma_Y \sigma_Y &= \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\
\sigma_Z \sigma_Z &= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}
\end{aligned}$$

and thus

$$\begin{aligned}
\{\sigma_X, \sigma_X\} &= \sigma_X \sigma_X + \sigma_X \sigma_X = 2I \\
\{\sigma_Y, \sigma_Y\} &= \sigma_Y \sigma_Y + \sigma_Y \sigma_Y = 2I \\
\{\sigma_Z, \sigma_Z\} &= \sigma_Z \sigma_Z + \sigma_Z \sigma_Z = 2I \\
\{\sigma_X, \sigma_Y\} &= \sigma_X \sigma_Y + \sigma_Y \sigma_X = 0 \\
\{\sigma_Y, \sigma_X\} &= \sigma_Y \sigma_X + \sigma_X \sigma_Y = 0 \\
\{\sigma_X, \sigma_Z\} &= \sigma_X \sigma_Z + \sigma_Z \sigma_X = 0 \\
\{\sigma_Z, \sigma_X\} &= \sigma_Z \sigma_X + \sigma_X \sigma_Z = 0 \\
\{\sigma_Y, \sigma_Z\} &= \sigma_Y \sigma_Z + \sigma_Z \sigma_Y = 0 \\
\{\sigma_Z, \sigma_Y\} &= \sigma_Z \sigma_Y + \sigma_Y \sigma_Z = 0
\end{aligned}$$

and thus it's proved.

#### Question 4

Given that  $\langle a|b \rangle = 1/2$  and  $\langle c|d \rangle = 3/4$ , calculate  $\langle \psi|\phi \rangle$ , where  $|\psi\rangle = |a\rangle \otimes |c\rangle$  and  $|\phi\rangle = |b\rangle \otimes |d\rangle$

$$\langle \psi|\phi \rangle = (\langle a| \otimes \langle c|)(|b\rangle \otimes |d\rangle) = \langle a|b\rangle \langle c|d\rangle = 3/8$$

#### Question 5

Calculate the tensor product of

$$|\psi\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \text{and} \quad |\phi\rangle = \frac{1}{2} \begin{pmatrix} 1 \\ \sqrt{3} \end{pmatrix}$$

$$|\psi\rangle \otimes |\phi\rangle = \frac{1}{2\sqrt{2}} = \begin{pmatrix} 1 \\ \sqrt{3} \\ 1 \\ \sqrt{3} \end{pmatrix}$$

### Question 6

Can  $|\psi\rangle = \frac{1}{2}(|0\rangle|0\rangle - |0\rangle|1\rangle - |1\rangle|0\rangle + |1\rangle|1\rangle)$  be written as a product state?

Yes,

$$|\psi\rangle = |-\rangle \otimes |-\rangle = \frac{1}{\sqrt{2}}(|0\rangle - |1\rangle) \otimes \frac{1}{\sqrt{2}}(|0\rangle - |1\rangle) = |\psi\rangle = \frac{1}{2}(|0\rangle|0\rangle - |0\rangle|1\rangle - |1\rangle|0\rangle + |1\rangle|1\rangle)$$

### Question 7

Can

$$|\psi\rangle = \frac{|0\rangle|0\rangle + |1\rangle|1\rangle}{2}$$

be written as a product state?

No, write the state as vector

$$|\psi\rangle = \begin{pmatrix} 1/2 \\ 0 \\ 0 \\ 1/2 \end{pmatrix}$$

Suppose it could be written as a product of two states  $|x\rangle$  and  $|y\rangle$

$$|x\rangle \otimes |y\rangle = \begin{pmatrix} a \\ b \end{pmatrix} \otimes \begin{pmatrix} c \\ d \end{pmatrix} = \begin{pmatrix} ac \\ ad \\ bc \\ bd \end{pmatrix} = \begin{pmatrix} 1/2 \\ 0 \\ 0 \\ 1/2 \end{pmatrix}$$

which means

$$ac \cdot bd = 1/4 \quad \text{and} \quad ad \cdot bc = 0$$

$$abcd = 1/4 \quad \text{and} \quad abcd = 0$$

and that is contradiction. Thus, there are no such states  $|x\rangle$  and  $|y\rangle$  that  $|x\rangle \otimes |y\rangle = |\psi\rangle$ . and thus  $|\psi\rangle$  could not be written as product of state.