PA2

February 19, 2020

1 PA2 - ID3 Decision Tree

Zhanchong Deng

A15491777

Necessary Imports

```
[1]: %load_ext autoreload
%autoreload 2
import numpy as np
import pandas as pd
import ID3 as pa2
from scipy.stats import entropy
from scipy import stats
import matplotlib.pyplot as plt
```

Import Data

```
[2]: training = pa2.loadData('pa2train.txt')
validation = pa2.loadData('pa2validation.txt')
test = pa2.loadData('pa2test.txt')
```

Training, without Pruning

```
[3]: tree = pa2.id3()
```

Created a new ID3 tree

```
[4]: %time tree.fit(training)
```

```
Wall time: 15.9 s
```

1) Visualizing resulted Tree

Below is my representation of the tree

Number of **tabs** indicates which level the node is at.

```
For non leaves: (label)Section ??
    For leaves: (label)Section??
[5]: # If root does not count as a level
     print(tree.printTreeAt(3))
    (root)[is feature at 5 < 0.5?](num_data:2000)</pre>
             (yes)[is feature at 1 < 415000.0?](num_data:1319)
                      (yes)[is feature at 17 < 2506.5?](num_data:1284)
                      (no)[is feature at 21 < 208.0?](num_data:35)</pre>
             (no)[is feature at 5 < 1.5?](num_data:681)</pre>
                      (yes)[is feature at 20 < 584.5?](num_data:292)
                      (no)[is feature at 21 < 2006.0?](num_data:389)
    2) Validation/Test Errors
    Validation Error:
[6]: tree.error(validation)
[6]: 0.179
    Test Error:
[7]: tree.error(test)
[7]: 0.173
    3) Pruning decision tree with Greedy apprach in BFS order
    Prune 1 and 2 nodes with validation/test errors:
[8]: tree.pruneTree(validation, test, 2)
    Pruned 1 time(s) with error:
             Validation error: 0.122
             Test error: 0.117
    Pruned 2 time(s) with error:
             Validation error: 0.107
             Test error: 0.103
    Tree after two pruned nodes:
[9]: print(tree.printTree())
    (root)[is feature at 5 < 0.5?](num_data:2000)</pre>
```

(yes) [0.0] (num_data:1319)

```
(no)[1.0](num_data:681)
```

4) Most prominent feature:

The most prominent feature must be the feature selected as threshold at root.

```
[10]: features_name = open('pa2features.txt')
    features_name.seek(0)
    columns = features_name.read().split('\n')[:-1]
[11]: columns[tree.root.feature]
```

[11]: 'PAYMENT_DELAY_SEPTEMBER'

5) Code from ID3.py:

Node for Decision Tree

111

```
111
Contains all methods for a ID3 Decision Tree.
@Author: Zhanchong Deng
@Date: 2/15/2020
import numpy as np
import pandas as pd
from scipy.stats import entropy
from scipy.stats import mode
Return numpy arrays representing the dataset.
Oparam fp is the file path.
Oreturn 2D numpy array, (#entry, 23).
def loadData(fp):
   newfile = open(fp, 'r')
    newfile.seek(0)
    raw_strings = newfile.read().split("\n")[:-1]
    return np.array([np.array(entry[0:-1].split(" "), dtype="float") for entry in raw_strings]
```

```
class idNode():
    # how many data in this node
   numPoints = 0
    data = []
    # Branches
    yes = None
   no = None
   parent = None
    # Is is a leaf?
    isLeaf = False
    # How to get here
   route = "root"
    # For non Leaves
   threshold = -1
    feature = -1
    # For leaves
    rule = -1
    def pruneNode(self):
        self.yes = None
        self.no = None
        self.isLeaf = True
        self.rule = mode(self.data[:, -1])[0][0]
    def toString(self):
        if not self.isLeaf:
            return "(" + self.route + ")" + "[is feature at " + str(self.feature + 1) + " < " -</pre>
                   + "?](num_data:" + str(self.numPoints) + ")\n"
            return "(" + self.route + ")" + "[" + str(self.rule) + "](num_data:" + str(self.nu
111
Decision Tree Object.
class id3():
    # Default Constructor
    def __init__(self):
       self.root = idNode()
        print("Created a new ID3 tree")
    111
        Training methods
    111
    def fit(self, training_data):
```

```
self.build(self.root, training_data)
def build(self, node, v):
    # Base case: Stop if it is pure
    if self.isPure(v):
        # Make it a leaf node.
        node.isLeaf = True
        node.rule = v[0][-1]
        node.numPoints = len(v)
    # Parse them according to H(entropy)
    else:
        node.numPoints = len(v)
        node.data = v
        # Pick a feature f and threshold t
        node.feature = 0
        minEntropy = float("inf")
        for thisfeature in range(0, len(v[0]) - 1):
            v_at_f = v[:, [thisfeature, -1]]
            list_of_threshold = self.generateThreshold(v_at_f)
            # This feature is not fit for splitting, pick another
            if len(list of threshold) == 0:
                continue
            # Set Threshold as the current best
            result = self.maxIG(list_of_threshold, v_at_f)
            if result[1] < minEntropy:</pre>
                minEntropy = result[1]
                node.feature = thisfeature
                node.threshold = result[0]
        # Split them according to the rule
        v_yes = v[v[:, node.feature] < node.threshold]</pre>
        v_no = v[v[:, node.feature] >= node.threshold]
        # Create new nodes
        node.yes = idNode()
        node.yes.route = "yes"
        node.yes.parent = node
        self.build(node.yes, v_yes)
        node.no = idNode()
        node.no.route = "no"
        node.no.parent = node
        self.build(node.no, v_no)
def isPure(self, vec):
    return len(np.unique(vec[:, -1])) == 1
def generateThreshold(self, feature):
    # Generate based solemnly on the feature vector
    distinct_val = np.sort(np.unique(feature[:, 0]))
```

```
return (distinct_val[:-1] + distinct_val[1:]) / 2
def maxIG(self, list_of_threshold, v_at_f):
    # Initialize as the first threshold
    minthreshold = list_of_threshold[0]
    minEntropy = self.entropy_with_threshold(minthreshold, v_at_f)
    for i in range(1, len(list_of_threshold)):
        newEntropy = self.entropy_with_threshold(list_of_threshold[i], v_at_f)
        # update the threshold with the minimum entropy
        if minEntropy > newEntropy:
            minthreshold = list_of_threshold[i]
            minEntropy = newEntropy
    return (minthreshold, minEntropy)
def entropy_with_threshold(self, threshold, v_at_f):
    # Slice v according to the given threshold
    v_yes = v_at_f[v_at_f[:, 0] < threshold]</pre>
    v_no = v_at_f[v_at_f[:, 0] >= threshold]
    # Calculate\ H(X/Z=yes)
    margin_yes = [np.sum(v_yes[:, -1] == num_labels) / len(v_yes) for num_labels in np.unio
    h_yes = entropy(margin_yes)
    # Calculate\ H(X/Z=no)
    margin_no = [np.sum(v_no[:, -1] == num_labels) / len(v_no) for num_labels in np.unique
    h_no = entropy(margin_no)
    # Calculate\ H(X|Z)
    return len(v_yes) / len(v_at_f) * h_yes + len(v_no) / len(v_at_f) * h_no
    Validation methods
def pruneTree(self, validation, test, maxprune):
    num_pruned = 0 # Specify how many prune can be done
    queue = [self.root] # For BFS
    while len(queue) > 0:
        # Calculate Current Error
        oldError = self.error(validation)
        # Use list as a queue
        curNode = queue.pop(0)
        # Create a deep copy
        original = idNode()
        original = self.copyNode(curNode)
        # Prune it
        curNode.pruneNode()
        # Compare errors
        newError = self.error(validation)
        # We screwed up, revert prune
        if oldError < newError:</pre>
```

```
# Edge for root
            if curNode.parent is None:
                self.root = original
                original.yes.parent = self.root
                original.no.parent = self.root
            else:
                if curNode.route == "yes":
                    curNode.parent.yes = original
                else:
                    curNode.parent.no = original
            if not original.yes.isLeaf:
                queue.append(original.yes)
            if not original.no.isLeaf:
                queue.append(original.no)
        # We pruned new node
        else:
            num_pruned += 1 # Increment counter
            # Display new error and how many node pruned
            print("Pruned", num_pruned, "time(s) with error:\n\tValidation error:", newError
                  self.error(test))
            # End pruning immediately if reached max
            if num_pruned >= maxprune:
                break
def copyNode(self, node):
   newNode = idNode()
    newNode.numPoints = node.numPoints
   newNode.data = np.copy(node.data)
   newNode.yes = node.yes
   newNode.no = node.no
   newNode.parent = node.parent
   newNode.isLeaf = node.isLeaf
   newNode.route = node.route
   newNode.threshold = node.threshold
    newNode.feature = node.feature
    newNode.rule = node.rule
    return newNode
    Testing methods
def predict(self, features):
    return np.apply_along_axis(self.predictOne, 1, features)
```

```
def error(self, test_data):
    return np.mean(self.predict(test_data[:, :-1]) != test_data[:, -1])
def predictOne(self, v):
    node = self.root
    while not node.isLeaf:
        # Yes branch
        if v[node.feature] < node.threshold:</pre>
            node = node.yes
        else:
            node = node.no
    # This should never happen
    if node.rule == -1:
        print("There is something wrong with your tree")
    return node.rule
    Visualization methods.
def printTree(self):
    tree_str = self.printTreeR(self.root, 0, float("inf"))
    return tree_str
def printTreeAt(self, maxlevel):
    return self.printTreeR(self.root, 0, maxlevel)
def printTreeR(self, curNode, level, maxlevel):
    # do yourself
    curStr = '\t' * level + curNode.toString()
    # do yes
    if not curNode.yes.isLeaf and level + 1 < maxlevel - 1:</pre>
        curStr += self.printTreeR(curNode.yes, level + 1, maxlevel)
    else:
        curStr += '\t' * (level + 1) + curNode.yes.toString()
    # do no
    if not curNode.no.isLeaf and level + 1 < maxlevel - 1:</pre>
        curStr += self.printTreeR(curNode.no, level + 1, maxlevel)
    else:
        curStr += '\t' * (level + 1) + curNode.no.toString()
    return curStr
```