



Lecture 1: Introduction

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SIST, ShanghaiTech
Fall, 2022

Outline

- Course logistics
 - Overall objective
 - Grading policy
 - Pre-requisite / Syllabus
- Introduction to deep learning
- Machine learning review
- Artificial neurons

Course objectives

- Learning to use deep networks
 - How to write from scratch, debug and train neural networks
 - Toolboxes commonly used in practice
- Understanding deep models
 - Key concepts and principles
- State of the art
 - Some new topics from research field
 - Focusing on vision-related problems

Syllabus & Schedule

- Piazza:
 - <https://piazza.com/shanghaitech.edu.cn/fall2022/cs280/>
 - The schedule for the latter half of the semester may vary a bit
- Part I: Basic neural networks (1~1.5 weeks)
 - Linear models
 - Multiple layer networks
 - Gradient descent and BP
- Part II: Convolutional neural networks
- Part III: Recurrent neural networks
- Part IV: Transformer
- Part V: Generative neural networks
- Part VI: Advanced Topics

Syllabus & Schedule

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 - <https://piazza.com/shanghaitech.edu.cn/fall2022/cs280/>
 - The schedule for the latter half of the semester may vary a bit
- Part I: Basic neural networks (1~1.5 weeks)
- Part II: Convolutional neural networks (4 weeks)
 - CNN basics
 - Understanding CNN
 - CNN in Vision
- Part III: Recurrent neural networks
- Part IV: Transformer
- Part V: Generative neural networks
- Part VI: Advanced Topics

Syllabus & Schedule

- Piazza:
 - <https://piazza.com/shanghaitech.edu.cn/fall2022/cs280/>
 - The schedule for the latter half of the semester may vary a bit
- Part I: Basic neural networks (1~1.5 weeks)
- Part II: Convolutional neural networks (4 weeks)
- Part III: Recurrent neural networks (1.5 weeks)
 - LSTM, GRU
 - Attention modeling
 - RNN in Vision/NLP
- Part IV: Transformer
- Part V: Generative neural networks
- Part VI: Advanced Topics

Syllabus & Schedule

- Piazza:
 - <https://piazza.com/shanghaitech.edu.cn/fall2022/cs280/>
 - The schedule for the latter half of the semester may vary a bit
- Part I: Basic neural networks (1~1.5 weeks)
- Part II: Convolutional neural networks (4 weeks)
- Part III: Recurrent neural networks (1.5 weeks)
- Part IV: Transformer (2 weeks)
 - Transformer Architecture
 - Transformer Application
- Part V: Generative neural networks
- Part VI: Advanced Topics
- Note: no lectures in the following weeks
 - Nov 7 ~ Nov 14 (CVPR)

Syllabus & Schedule

- Piazza:
 - <https://piazza.com/shanghaitech.edu.cn/fall2022/cs280/>
 - The schedule for the latter half of the semester may vary a bit
- Part I: Basic neural networks (1~1.5 weeks)
- Part II: Convolutional neural networks (4 weeks)
- Part III: Recurrent neural networks (1.5 weeks)
- Part IV: Transformer(2 weeks)
- Part IV: Generative neural networks (3 weeks)
 - Variational Auto Encoder (VAE)
 - Generative deep nets (GAN)
 - Diffusion model
- Part V: Advanced Topics (1.5 weeks)
- Note: no lectures in the following weeks
 - Nov 9 ~ Nov 16 (CVPR)

Reference books and materials

- Deep learning:

- <http://www.deeplearningbook.org/>

- <https://d2l.ai/>

- Online deep learning courses:

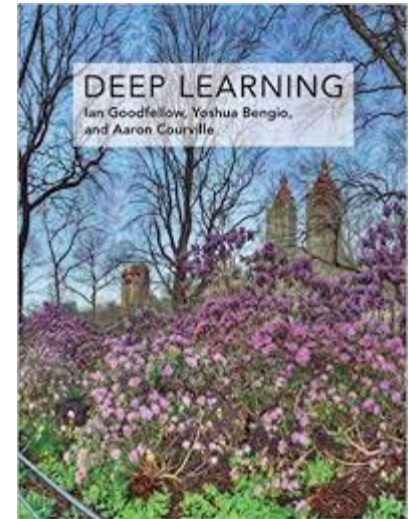
- Stanford: CS230, CS231n

- CMU: 11-785

- MIT: 6.S191

- Additional reading materials on Piazza

- Survey papers, tutorials, etc.



Instructor and TAs

- Instructor: Prof Lan Xu
 - xulan1@shanghaitech.edu.cn
 - SIST 1C-303D
- TAs:
 - Han Liang, Suyi Jiang, Zhitong Gao, Chenyu Wang, Kehao Deng, Chenfeng Zhao
- Office hours: To be announced on Piazza
- We will use Piazza as the main communication platform

Grading policy

- 4 Problem sets: $7.5\% \times 4 = 30\%$
 - Write-up problem sets + Programming tasks
- Final course project: $40\% (+10\%)$
 - Proposal
 - Final report (Conference format)
 - Presentation
 - Bonus points for impressive and novel results: 10%
- 10 Quizzes (in class): $3\% \times 10 = 30\%$
- Late policy
 - A total of 7 free late (calendar) days to use, but no more than 4 late days can be used on any single assignment.
 - After that, 25% off per day late
 - Does not apply to Final course project/Quizzes
- Collaboration policy
 - Project team: 4~5 students
 - Grading according to each member's contribution

Course Roadmap

MLP CNN RNN Transformer

VAE GAN Diffusion Neural Rendering

- Quiz (30%), HW (30%), Project (40%)
- More Important: relate the course to your research

	八月	九月					十月					十一月				十二月				一月			
星期一	22	29	5	12	19	26	3	10	17	24	31	7	14	21	28	5	12	19	26	2	9	16	23
星期二	23	30	6	13	20	27	4	11	18	25	1	8	15	22	29	6	13	20	27	3	10	17	24
星期三	24	31	7	14	21	28	5	12	19	26	2	9	16	23	30	7	14	21	28	4	11	18	25
星期四	25	1	8	15	22	29	6	13	20	27	3	10	17	24	1	8	15	22	29	5	12	19	26
星期五	26	2	9	16	23	30	7	14	21	28	4	11	18	25	2	9	16	23	30	6	13	20	27
星期六	27	3	10 中秋节	17	24	1 国庆节	8	15	22	29	5	12	19	26	3	10	17	24	31	7	14	21	28
星期日	28	4	11	18	25	2	9	16	23	30	6	13	20	27	4	11	18	25	1 元旦节	8	15	22 春节	29
周数	6	7	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	1	2	3
学期	暑假		秋学期																				寒假

Administrative Stuff

■ Plagiarism

☐ All assignments must be done individually

- You may not look at solutions from any other source
- You may not share solutions with any other students
- Plagiarism detection software will be used on all the programming assignments
- You may discuss together or help another student but you cannot give the exact solution

■ Plagiarism punishment

- ☐ When one student copies from another student, both students are responsible
- ☐ Zero point on the assignment or exam in question
- ☐ Repeated violation will result in an F grade for this course as well as further discipline at the school/university level

Pre-requisite

- Proficiency in Python
 - All class assignments will be in Python (and use numpy)
 - A Python tutorial available on Piazza
- Calculus, Linear Algebra, Probability and Statistics
 - Undergrad course level
- Equivalent knowledge of Andrew Ng's CS229 (Machine Learning)
 - Formulating cost functions
 - Taking derivatives
 - Performing optimization with gradient descent
- Will be evaluated in next quiz (Wednesday)

Outline

- Course logistics
- Introduction to deep learning
 - What & Why deep learning?
- Machine Learning review
- Artificial neurons

Acknowledgement: Bhiksha Raj@CMU's course notes

Introduction

- Our goal: Build intelligent algorithms to make sense of data
 - Example: Recognizing objects in images



red panda (*Ailurus fulgens*)

- Example: Predicting what would happen next



Vondrick et al. CVPR2016

Introduction

- Our goal: Build intelligent algorithms to make sense of data
 - Example: Recognizing objects in images
 - Example: Predicting what would happen next

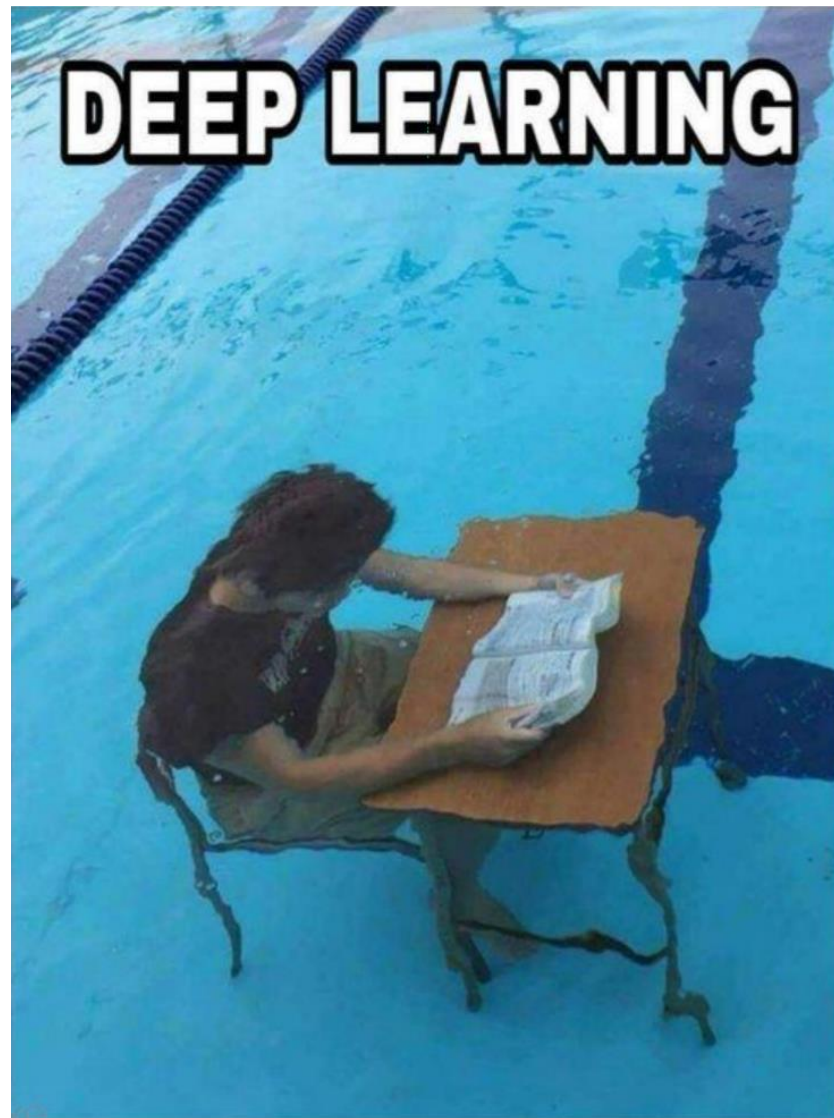
Given an initial still frame,



Introduction

- A broad range of real-world applications
 - Speech recognition
 - Input: sound wave → Output: transcript
 - Language translation
 - Input: text in language A (Eng) → Output: text in language B (Chs)
 - Image classification
 - Input: images → Output: image category (cat, dog, car, house, etc.)
 - Autonomous driving
 - Input: sensory inputs → Output: actions (straight, left, right, stop, etc.)
- Main challenges: difficult to manually design the algorithms

A data-driven approach



A data-driven approach

Deep Learning



What society thinks I do



What my friends think I do



What other computer scientists think I do



What mathematicians think I do



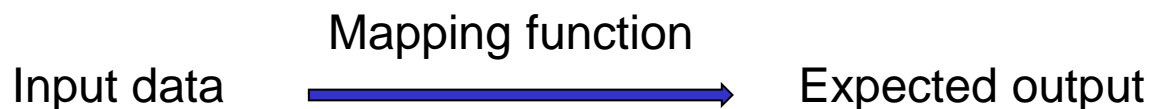
What I think I do

```
from theano import *
```

What I actually do

A data-driven approach

- Each task as a mapping function (or a model)



- input data: images
- expected output: object or action names

- Building such mapping functions from data



red panda (*Ailurus fulgens*)

$\xrightarrow{\text{Mapping function}}$

A data-driven approach

- Building a **mapping function** (model)

$$y = f(x; \theta)$$

- x: input data
- y: expected output
- θ : parameters to be estimated

- **Learning** the model from data

- Given a dataset $\mathcal{D} = \{(x_n, y_n)\}_{n=1}^N$
- Find the ‘best’ parameter $\hat{\theta}$, such that

$$y_n \simeq f(x_n; \hat{\theta}) \quad \forall n$$

- And it can be generalized to unseen input data

What is deep learning?

- Using deep neural networks as the mapping function
- Model: Deep neural networks
 - A family of parametric models
 - Consisting of many ‘simple’ computational units
 - Constructing a multi-layer representation of input

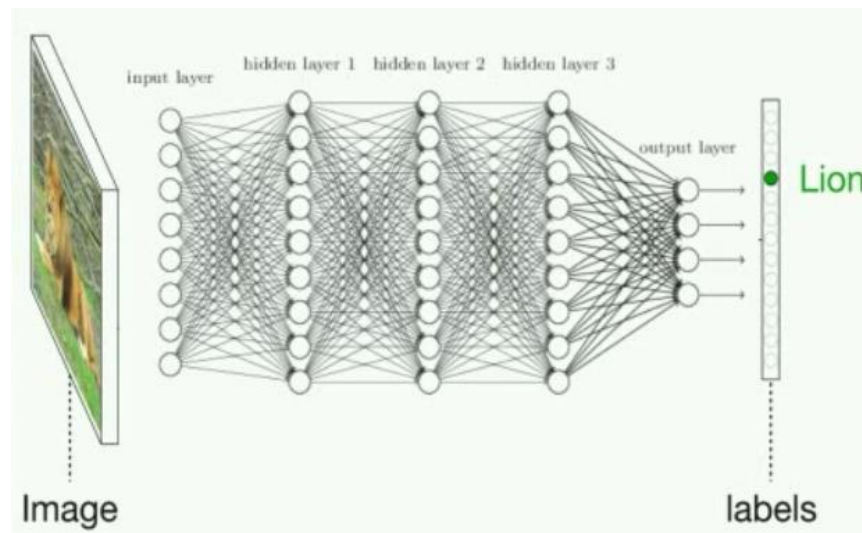
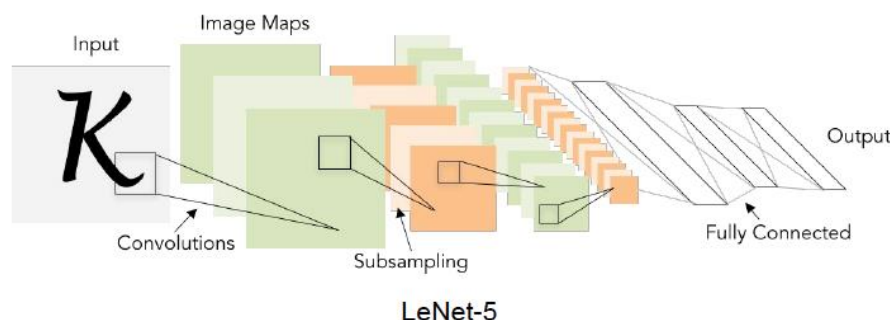


Image from Jeff Clune's Deep Learning Overview

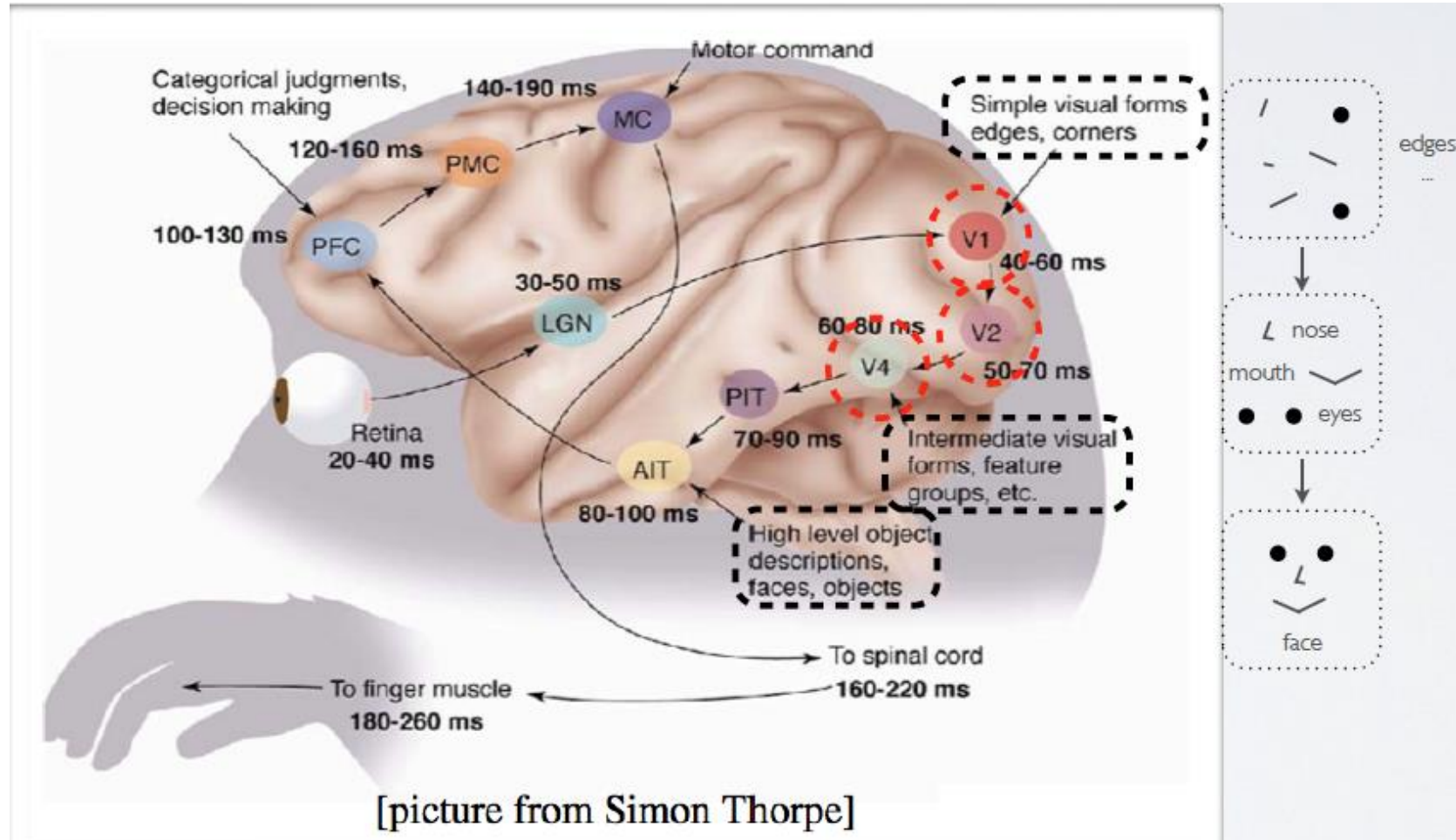
What is deep learning?

- Using deep neural networks as the mapping function
- Learning: Parameter estimation from data
 - Parameters: **connection weights between units**
 - Formulated as an **optimization** problem
 - Efficient algorithms for handling **large-scale models & datasets**



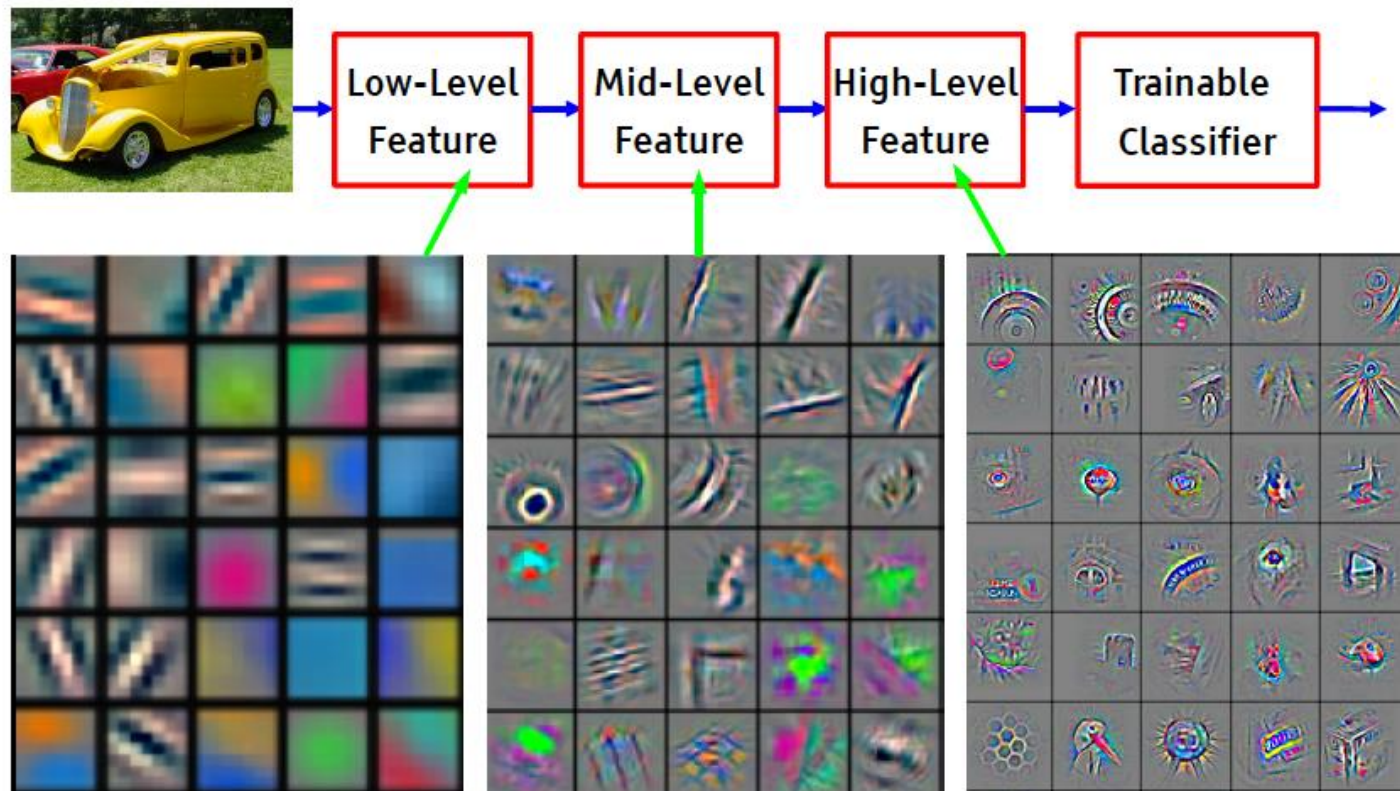
Why deep networks?

- Inspiration from visual cortex



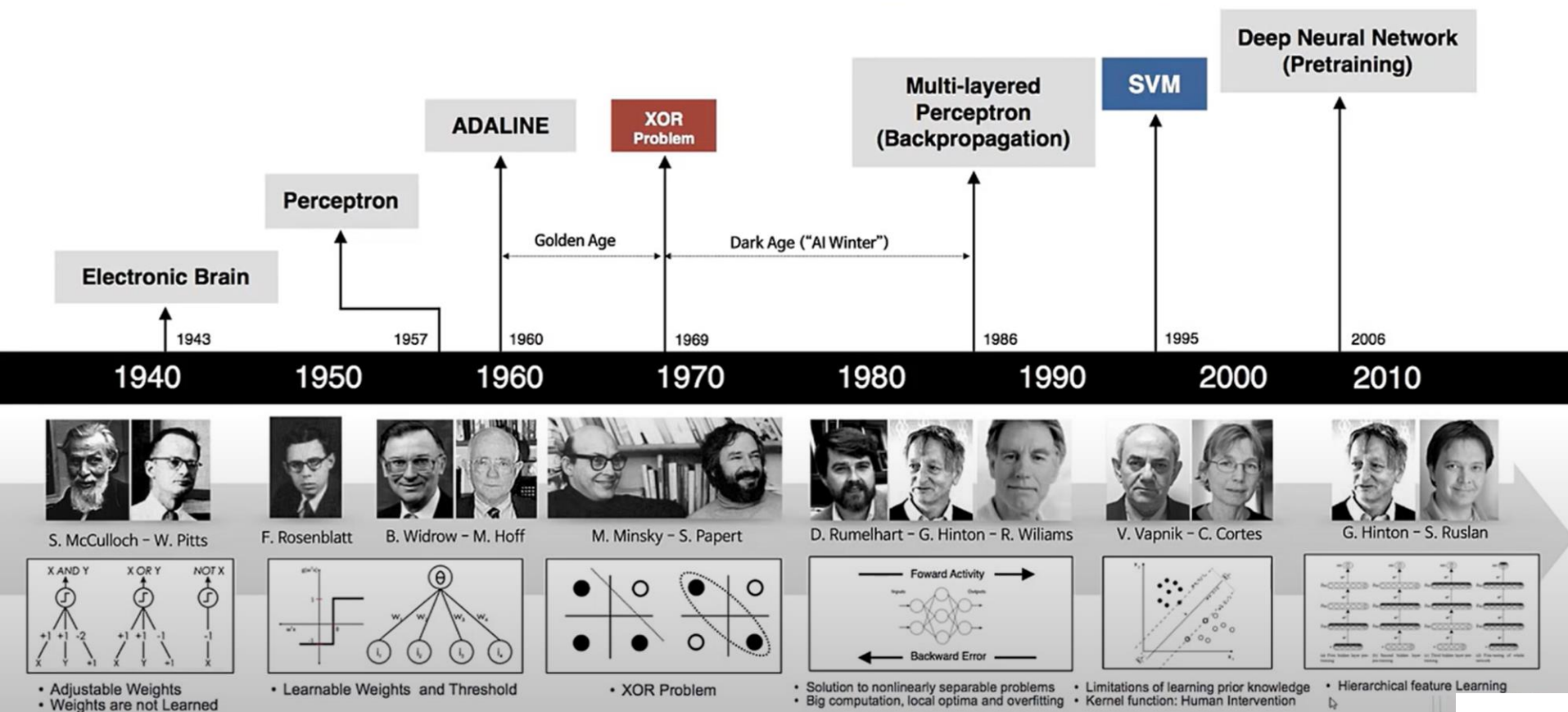
Why deep networks?

- A deep architecture can represent certain functions (exponentially) more compactly
- Learning a rich representation of input data



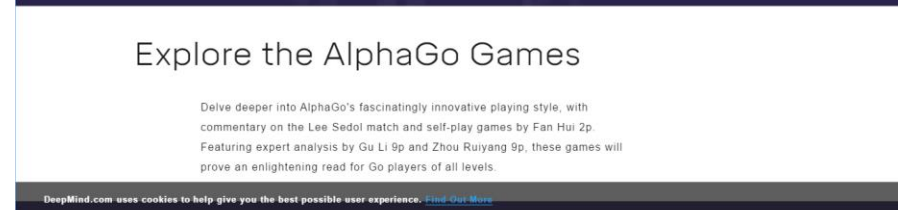
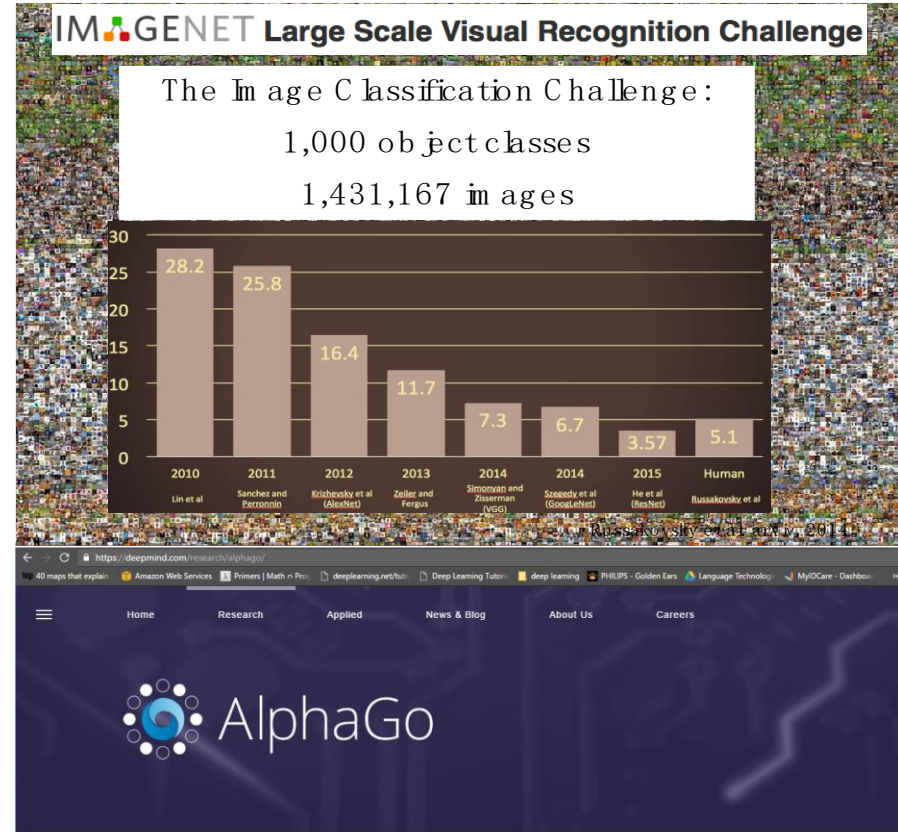
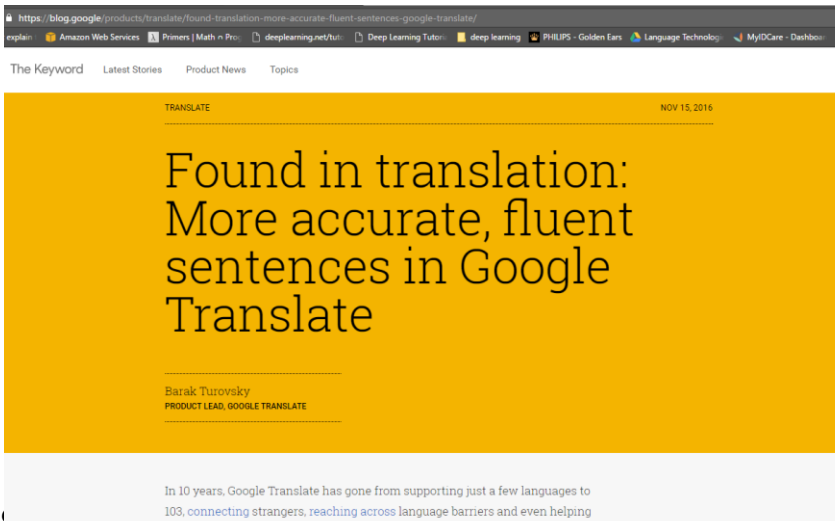
Feature visualization of convolutional net trained on ImageNet from [Zeiler & Fergus 2013]

Deep Learning History



Recent success with DL

■ Some recent success with neural networks



Recent success with DL

- Some recent success with neural networks



ACM Turing Award 2019 (Nobel Prize of Computing)
Yann LeCun, Geoffrey Hinton, and Yoshua Bengio

Recent success with DL

- Some recent success with neural networks



This guy didn't know
about neural networks



This guy learned
about neural networks

Summary: Why deep learning?

- One of the major thrust areas recently in various pattern recognition, prediction and data analysis
 - Efficient representation of data and computation
 - Other key factors: large datasets and hardware
- The state of the art in many problems
 - Often exceeding previous benchmarks by large margins
 - Achieve better performances than human for certain “complex” tasks.
- But also somewhat controversial ...
 - Lack of theoretical understanding
 - Sometimes difficult to make it work in practice

Is it alchemy?

Science Home News Journals Topics Careers

Webinar
The power of RNA:
Broad application of RNA-based sequencing for transcriptome and genome analysis

Recorded live on September 4, 2018
[Click to view](#)

Science
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Gradient descent relies on trial and error to optimize an algorithm, aiming for minima in a 3D landscape.
ALEXANDER AMINI, DANIELA RUS. MASSACHUSETTS INSTITUTE OF TECHNOLOGY, ADAPTED BY M. ATAROD/SCIENCE

AI researchers allege that machine learning is alchemy

Questions to ask

■ Understanding neural networks

- ☐ What is different from traditional ML methods?
- ☐ How it works for specific problems?
- ☐ Why get great performance?

■ Future development

- ☐ Its limitation and weakness?
- ☐ After more than 10 years, what is on-going or next?
- ☐ The road to general-purpose AI?

Outline

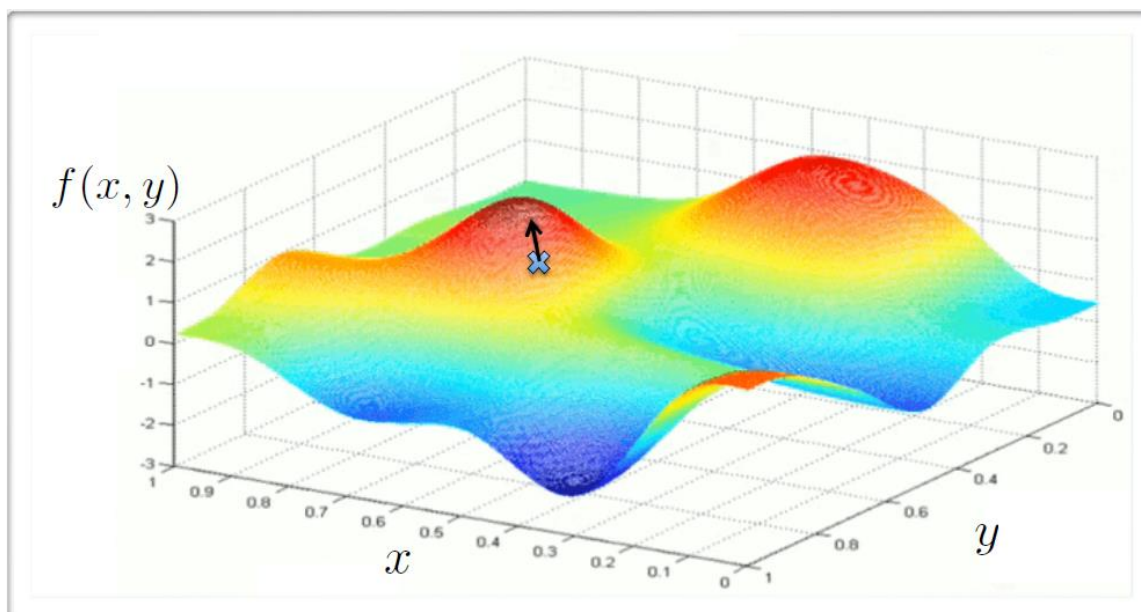
- Course logistics
- Introduction to deep learning
- Machine learning review
 - Math review
 - Supervised learning
- Artificial neurons

Acknowledgement: Hugo Larochelle's, Mehryar Mohri@NYU's & Yingyu Liang@Princeton's course notes

Math review – Calculus

■ Gradient

$$\nabla_{\mathbf{x}} f(\mathbf{x}) = \left[\frac{\partial}{\partial x_1} f(\mathbf{x}), \dots, \frac{\partial}{\partial x_d} f(\mathbf{x}) \right]^\top = \begin{bmatrix} \frac{\partial}{\partial x_1} f(\mathbf{x}) \\ \vdots \\ \frac{\partial}{\partial x_d} f(\mathbf{x}) \end{bmatrix}$$



Math review – Calculus

■ Local and global minima

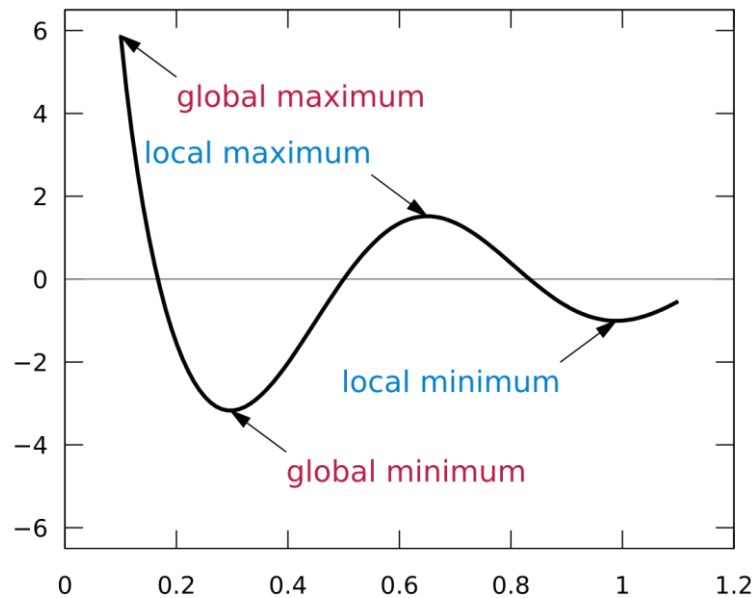
□ Necessary condition

$$\nabla_{\mathbf{x}} f(\mathbf{x}) = 0$$

□ Sufficient condition

■ Hessian is positive definite

$$f(\mathbf{x}) \approx f(\mathbf{x}^*) + (\mathbf{x} - \mathbf{x}^*)^\top \nabla_{\mathbf{x}} f(\mathbf{x}) + \frac{1}{2}(\mathbf{x} - \mathbf{x}^*)^\top \nabla_{\mathbf{x}}^2 f(\mathbf{x})(\mathbf{x} - \mathbf{x}^*)$$



Math review – Probability

■ Factorization

- Probability chain rule: $p(s, o) = p(s|o)p(o) = p(o|s)p(s)$

- in general:

$$p(\mathbf{x}) = \prod_i p(x_i | x_1, \dots, x_{i-1})$$

- Bayes rule:

$$p(O = o | S = s) = \frac{p(S=s|O=o)p(O=o)}{\sum_{o'} p(S=s|O=o')p(O=o')}$$

Math review – Probability

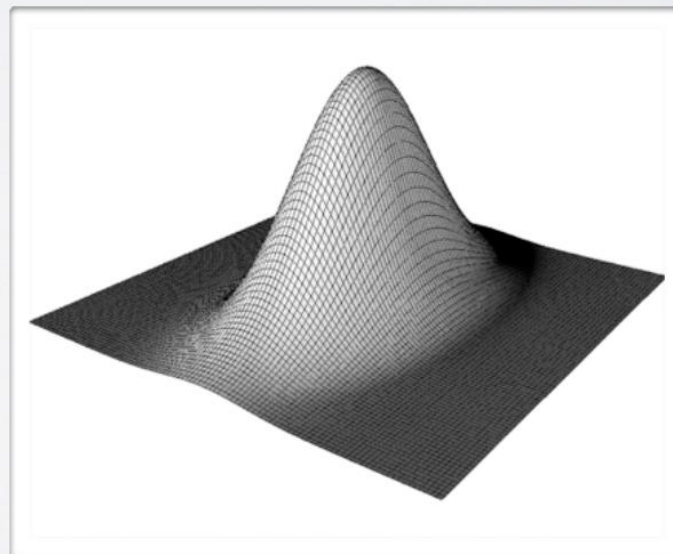
■ Common distributions

- Gaussian variable: $\mathbf{X} \in \mathbb{R}^d$

- $p(\mathbf{x}) = \frac{1}{\sqrt{(2\pi)^d \det(\Sigma)}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^\top \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right)$

- $E[\mathbf{X}] = \boldsymbol{\mu}$

- $\text{Cov}[\mathbf{X}] = \Sigma$



Math review – Statistics

■ Monte Carlo estimation

- a method to approximate an expensive expectation

$$\mathbb{E}[f(\mathbf{X})] = \sum_{\mathbf{x}} f(\mathbf{x}) p(\mathbf{x}) \approx \frac{1}{K} \sum_k f(\mathbf{x}^{(k)})$$

- the $\mathbf{x}^{(k)}$ must be sampled from $p(\mathbf{x})$

■ Maximum likelihood

$$\hat{\theta} = \arg \max_{\theta} p(\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(T)})$$

- Independent and identically distributed

$$p(\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(T)}) = \prod_t p(\mathbf{x}^{(t)})$$

ML tasks

- **Classification:** assign a category to each item (e.g., document classification)
- **Regression:** predict a real value for each item (e.g., prediction of stock values, economic variables)
- **Ranking:** order items according to some criterion (e.g., relevant web pages returned by a search engine)
- **Clustering:** partition data into 'homogenous' regions (e.g., analysis of very large data sets)
- **Dimensionality reduction:** find lower-dimensional manifold preserving some properties of the data

Standard learning scenarios

- **Unsupervised learning:** no labeled data
- **Supervised learning:** uses labeled data for prediction on unseen points
- **Semi-supervised learning:** uses labeled and unlabeled data for prediction on unseen points
- **Reinforcement learning:** uses reward to learn prediction on action policies.
- ...

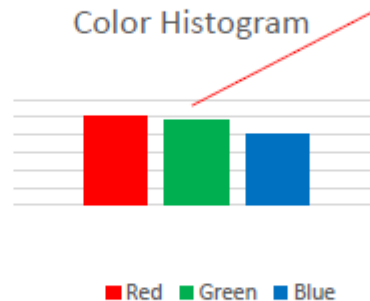
Supervised learning

■ Task formulation

- Learning example: (\mathbf{x}, y)
- Task to solve: predict target y from input \mathbf{x}
 - classification: target is a class ID (from 0 to nb. of class - 1)
 - regression: target is a real number



Extract
features



Feature vector: x_i

Label: y_i

Indoor

0

Supervised learning

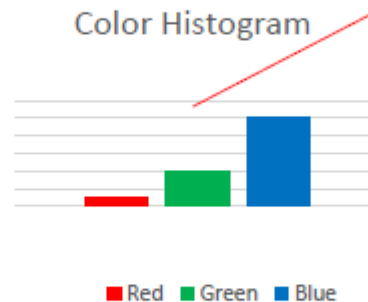
■ Task formulation

- Learning example: (\mathbf{x}, y)
- Task to solve: predict target y from input \mathbf{x}
 - classification: target is a class ID (from 0 to nb. of class - 1)
 - regression: target is a real number



outdoor

Extract
features



Feature vector: x_j

Label: y_j

1

Learning problem

■ Problem setup

- Given training data $\{(x_i, y_i): 1 \leq i \leq n\}$
- Find $y = f(x)$ using training data
- s.t. f correct on test data

What kind of functions?

Learning problem

■ Problem setup

- Given training data $\{(x_i, y_i): 1 \leq i \leq n\}$
- Find $y = f(x) \in \mathcal{H}$ using training data
- s.t. f correct on test data



Hypothesis class

Learning problem

■ Problem setup

- Given training data $\{(x_i, y_i): 1 \leq i \leq n\}$
- Find $y = f(x) \in \mathcal{H}$ using training data
- s.t. f correct on test data

Connection between
training data and test data?

Learning problem

■ Problem setup

- Given training data $\{(x_i, y_i): 1 \leq i \leq n\}$ i.i.d. from distribution D
- Find $y = f(x) \in \mathcal{H}$ using training data
- s.t. f correct on test data i.i.d. from distribution D


They have the same
distribution

i.i.d.: independently
identically distributed

Learning problem

■ Problem setup

- Given training data $\{(x_i, y_i): 1 \leq i \leq n\}$ i.i.d. from distribution D
- Find $y = f(x) \in \mathcal{H}$ using training data
- s.t. f correct on test data i.i.d. from distribution D



What kind of performance measure?

Learning problem

■ Problem setup

- Given training data $\{(x_i, y_i): 1 \leq i \leq n\}$ i.i.d. from distribution D
- Find $y = f(x) \in \mathcal{H}$ using training data
- s.t. the expected loss is small

$$L(f) = \mathbb{E}_{(x,y) \sim D}[l(f, x, y)]$$

Various loss functions

Learning problem

■ Problem setup

- Given training data $\{(x_i, y_i): 1 \leq i \leq n\}$ i.i.d. from distribution D
- Find $y = f(x) \in \mathcal{H}$ using training data
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$$L(f) = \mathbb{E}_{(x,y) \sim D}[l(f, x, y)]$$

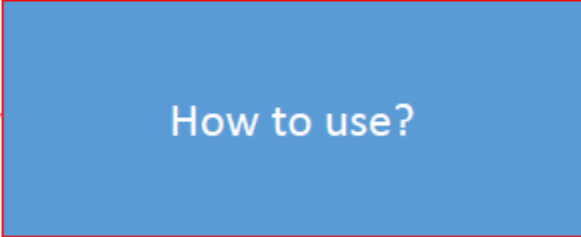
- Examples of loss functions:
 - 0-1 loss: $l(f, x, y) = \mathbb{I}[f(x) \neq y]$ and $L(f) = \Pr[f(x) \neq y]$
 - l_2 loss: $l(f, x, y) = [f(x) - y]^2$ and $L(f) = \mathbb{E}[f(x) - y]^2$

Learning problem

■ Problem setup

- Given training data $\{(x_i, y_i): 1 \leq i \leq n\}$ i.i.d. from distribution D
- Find $y = f(x) \in \mathcal{H}$ using training data
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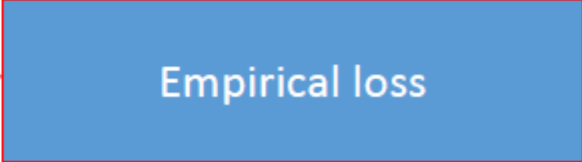
How to use?

Learning problem

■ Problem setup

- Given training data $\{(x_i, y_i): 1 \leq i \leq n\}$ i.i.d. from distribution D
- Find $y = f(x) \in \mathcal{H}$ that minimizes $\hat{L}(f) = \frac{1}{n} \sum_{i=1}^n l(f, x_i, y_i)$
- s.t. the expected loss is small

$$L(f) = \mathbb{E}_{(x,y) \sim D}[l(f, x, y)]$$



Empirical loss

Learning as iterative optimization

■ Gradient descent

- ▶ choose initial $w^{(0)}$, repeat

$$w^{(t+1)} = w^{(t)} - \eta_t \cdot \nabla L(w^{(t)})$$

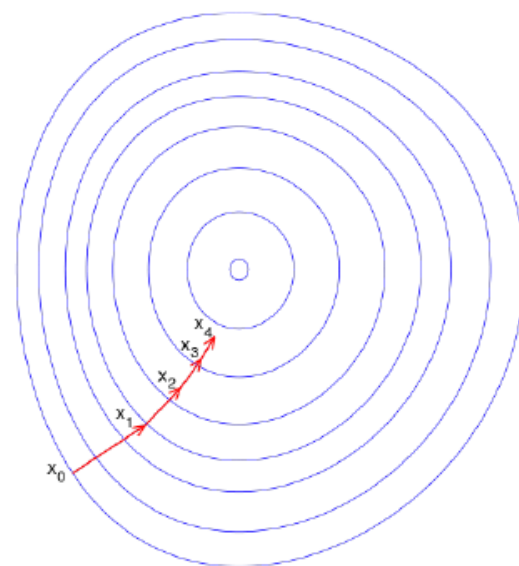
until stop

- ▶ η_t is the learning rate, and

$$\nabla L(w^{(t)}) = \frac{1}{n} \sum_i \nabla_w L_i(w^{(t)}; y_i, x_i)$$

- ▶ How to stop? $\|w^{(t+1)} - w^{(t)}\| \leq \epsilon$ or $\|\nabla L(w^{(t)})\| \leq \epsilon$

Two dimensional example:



Learning as iterative optimization

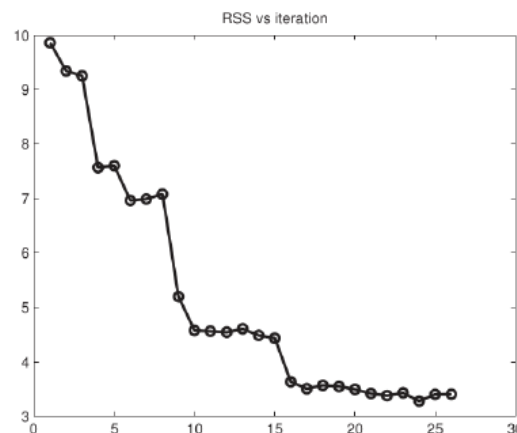
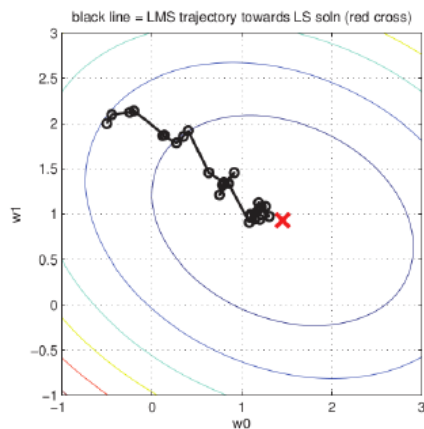
■ Stochastic gradient descent (SGD)

- Suppose data points arrive one by one

- $\hat{L}(w) = \frac{1}{n} \sum_{t=1}^n l(w, x_t, y_t)$, but we only know $l(w, x_t, y_t)$ at time t

- Idea: simply do what you can based on local information

- Initialize w_0
- $w_{t+1} = w_t - \eta_t \nabla l(w_t, x_t, y_t)$



Supervised learning pipeline

■ Three steps

- Collect data and extract features
- Build model: choose hypothesis class \mathcal{H} and loss function l
- Optimization: minimize the empirical loss

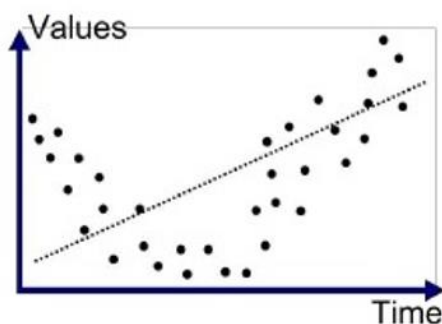
■ Datasets & hyper-parameters

- **Hyper-parameter:** a parameter of a model that is not trained (specified before training)

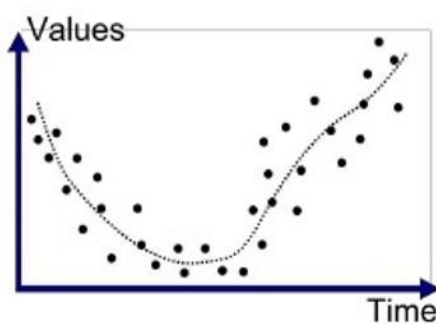
- Training set $\mathcal{D}^{\text{train}}$ serves to train a model
- Validation set $\mathcal{D}^{\text{valid}}$ serves to select hyper-parameters
- Test set $\mathcal{D}^{\text{test}}$ serves to estimate the generalization performance (error)

Generalization

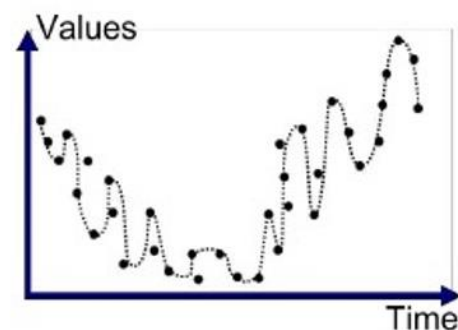
- Model selection for better generalization
 - **Capacity**: flexibility of a model
 - **Underfitting**: state of model which could improve generalization with more training or capacity
 - **Overfitting**: state of model which could improve generalization with less training or capacity
 - **Model Selection**: process of choosing the best hyper-parameters on validation set



Underfitted



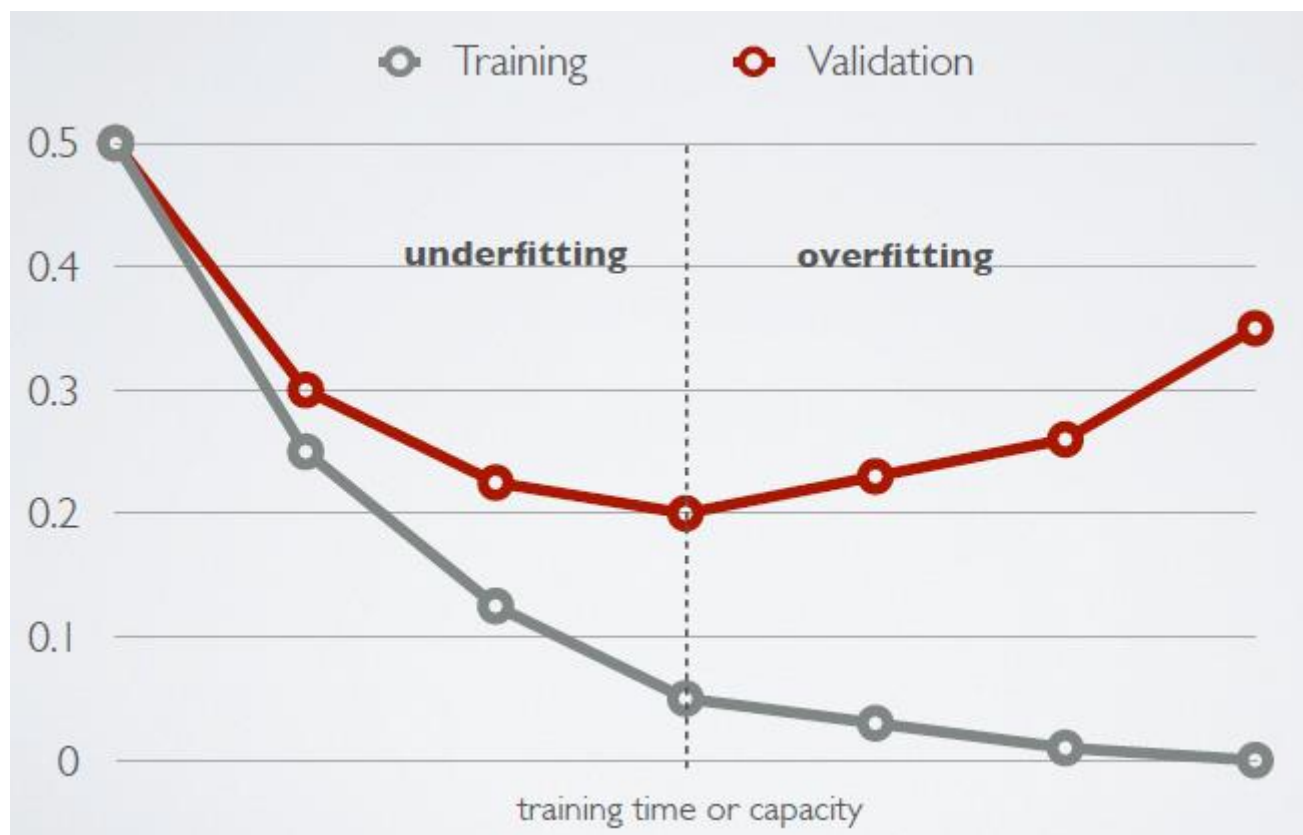
Good Fit/Robust



Overfitted

Generalization

- Training/Validation curves



Questions

- Generalization

- ☐ Interaction between training set size/capacity/training time and training error/generalization error

- If capacity increases:

- ☐ Training error will ?
- ☐ Generalization error will ?

- If training time increases:

- ☐ Training error will ?
- ☐ Generalization error will ?

- If training set size increases:

- ☐ Generalization error will ?
- ☐ Gap between the training and generalization error will ?

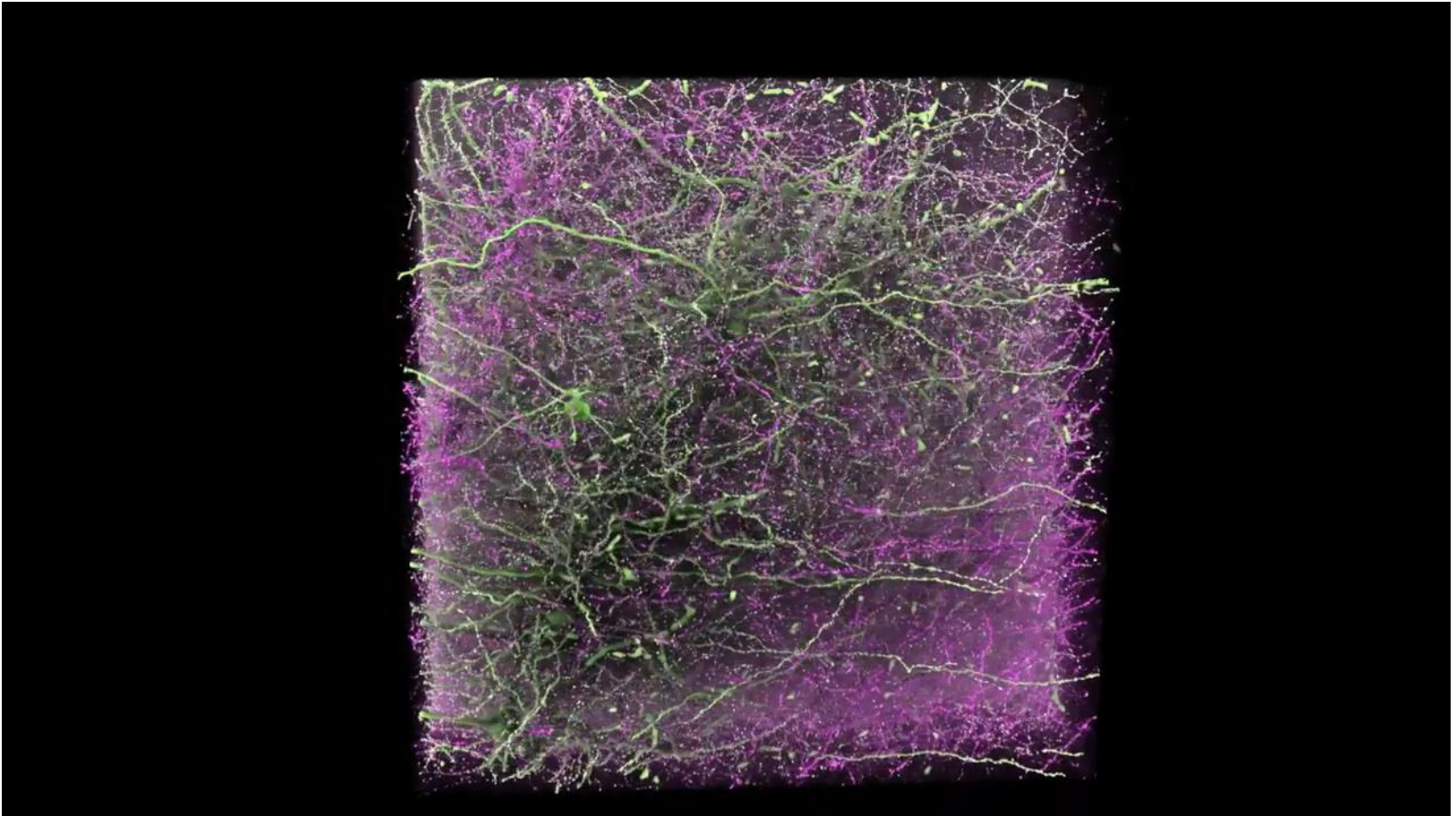
Outline

- Course logistics
- Introduction to deep learning
- Machine learning review
- Artificial neurons
 - Math model
 - Perceptron algorithm

Acknowledgement: Hugo Larochelle's, Mehryar Mohri@NYU's & Yingyu Liang@Princeton's course notes

Artificial Neuron

- Biological inspiration



https://www.youtube.com/watch?v=m0rHZ_RDdyQ

Artificial Neuron

■ Biological inspiration

- Our brain has $\sim 10^{11}$ neurons, each of which communicates (is connected) to $\sim 10^4$ other neurons

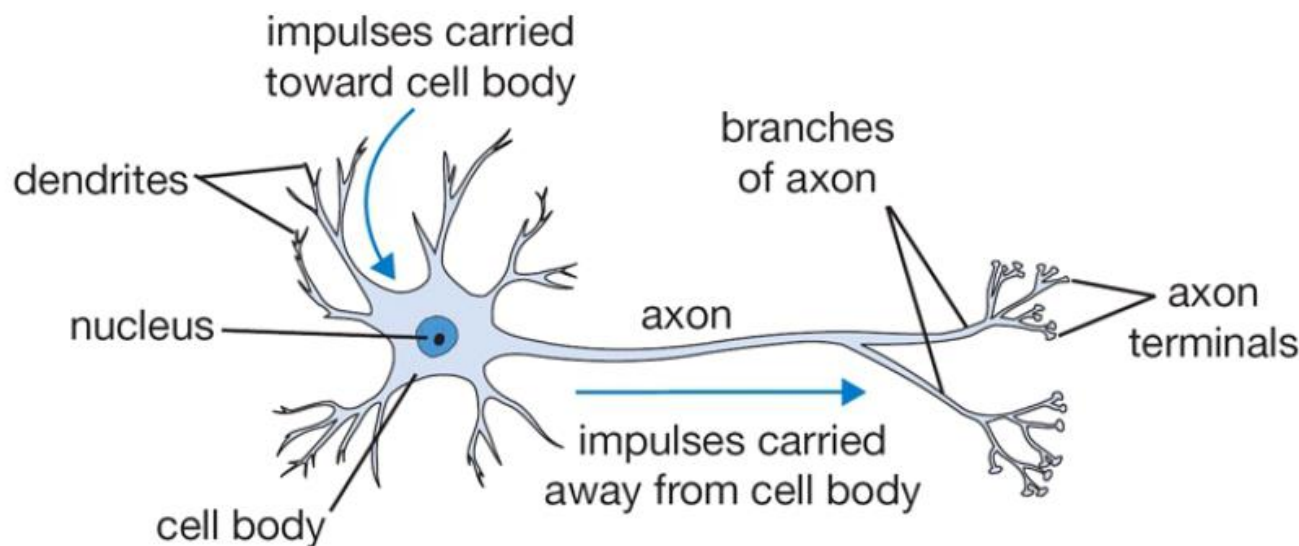
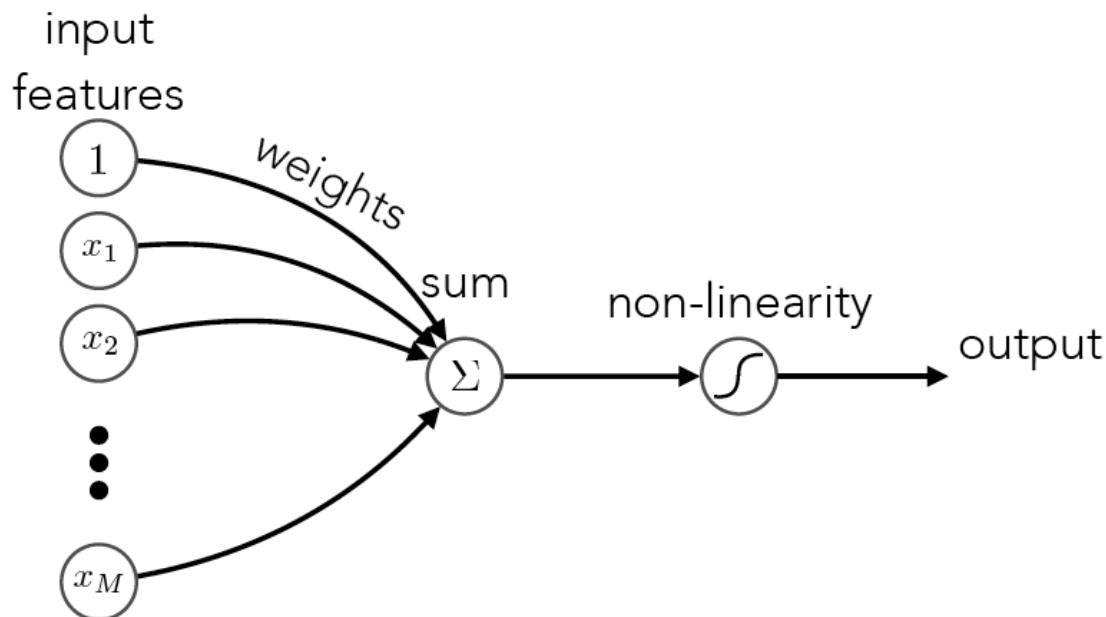


Figure : The basic computational unit of the brain: Neuron

Mathematical model of a neuron



artificial neuron: *weighted sum and non-linearity*

$$s = \underset{\substack{\text{bias} \\ \uparrow}}{b} + \underset{\substack{\text{weights} \\ \uparrow}}{w_1}x_1 + w_2x_2 + \cdots + w_Mx_M = \mathbf{w}^T \mathbf{x}$$

input features \rightarrow (pointing to x_1, x_2, \dots, x_M)

sum \rightarrow (pointing to s)

$$h = g(s)$$

output \rightarrow (pointing to h)

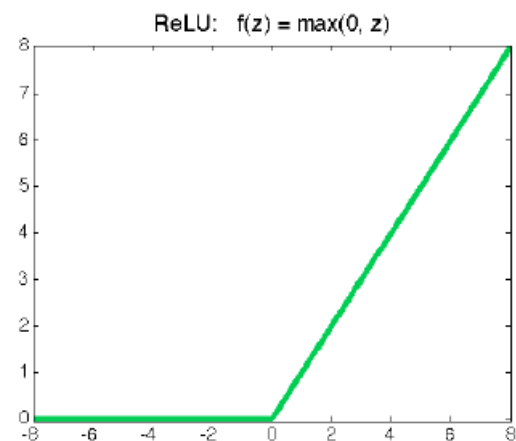
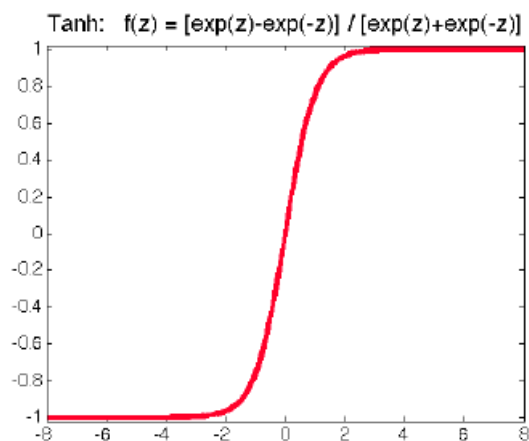
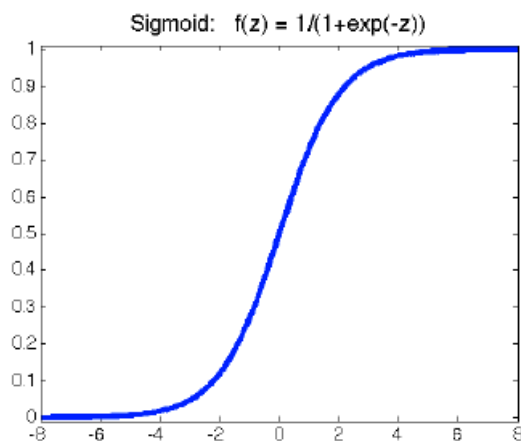
non-linearity \rightarrow (pointing to g)

sum \rightarrow (pointing to s)

Activation functions

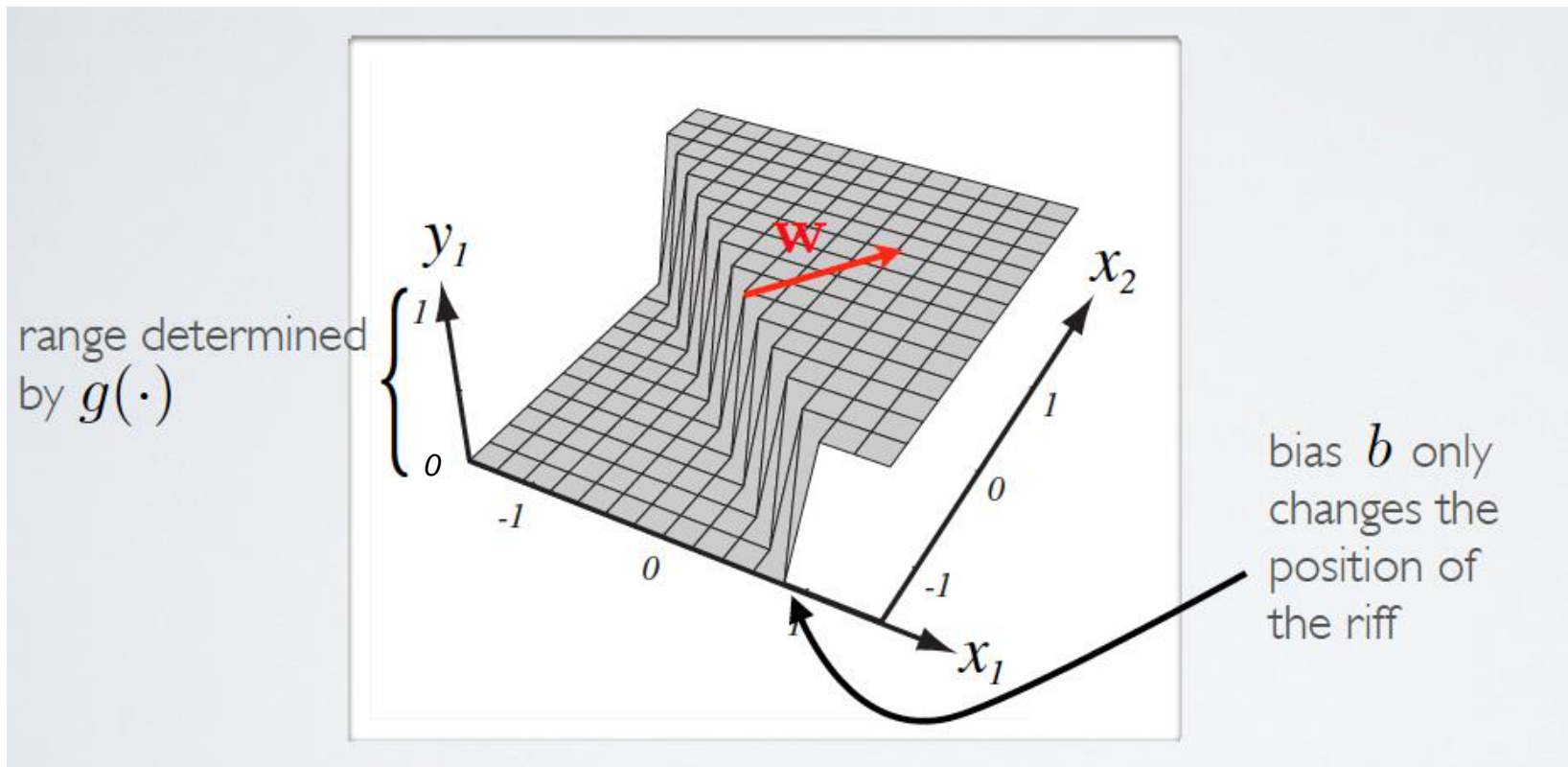
Most commonly used activation functions:

- Sigmoid: $\sigma(z) = \frac{1}{1+\exp(-z)}$
- Tanh: $\tanh(z) = \frac{\exp(z)-\exp(-z)}{\exp(z)+\exp(-z)}$
- ReLU (Rectified Linear Unit): $\text{ReLU}(z) = \max(0, z)$



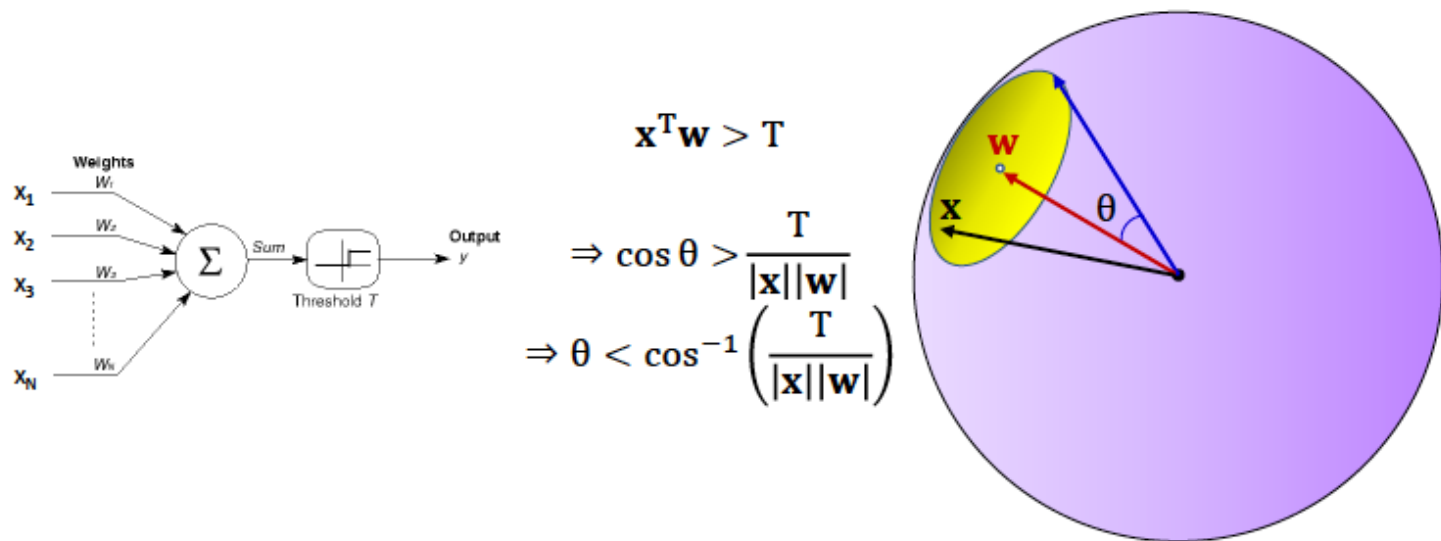
Capacity of single neuron

- Sigmoid activation function



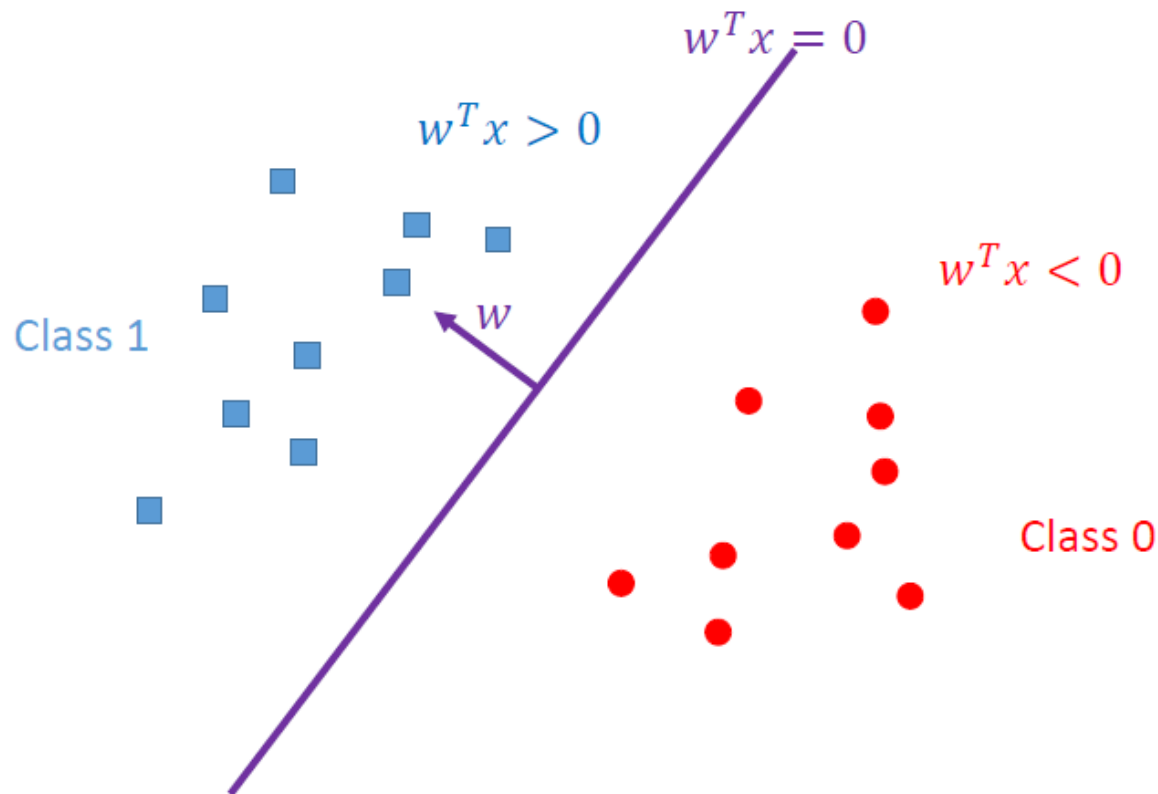
What a single neuron does?

- A neuron (perceptron) fires if its input is within a specific angle of its weight
 - If the input pattern matches the weight pattern closely enough



Single neuron as a linear classifier

- Binary classification



Summary

- Introduction to deep learning
- Course logistics
- Review of basic math & ML
- Artificial neurons

- Next time
 - Basic neural networks
 - First Quiz on prerequisite