TOWARDS GENERALISABLE TIME SERIES UNDER-STANDING ACROSS DOMAINS

Özgün Turgut¹, Philip Müller¹, Martin J. Menten,^{1,2} & Daniel Rueckert^{1,2}

¹School of Computation, Information and Technology, Technical University of Munich, Germany

²Department of Computing, Imperial College London, United Kingdom

{oezguen.turgut, daniel.rueckert}@tum.de

ABSTRACT

In natural language processing and computer vision, self-supervised pre-training on large datasets unlocks foundational model capabilities across domains and tasks. However, this potential has not yet been realised in time series analysis, where existing methods disregard the heterogeneous nature of time series characteristics. Time series are prevalent in many domains, including medicine, engineering, natural sciences, and finance, but their characteristics vary significantly in terms of variate count, inter-variate relationships, temporal dynamics, and sampling frequency. This inherent heterogeneity across domains prevents effective pre-training on large time series corpora. To address this issue, we introduce OTiS, an open model for general time series analysis, that has been specifically designed to handle multi-domain heterogeneity. We propose a novel pre-training paradigm including a tokeniser with learnable domain-specific signatures, a dual masking strategy to capture temporal causality, and a normalised cross-correlation loss to model long-range dependencies. Our model is pre-trained on a large corpus of 640, 187 samples and 11 billion time points spanning 8 distinct domains, enabling it to analyse time series from any (unseen) domain. In comprehensive experiments across 15 diverse applications - including classification, regression, and forecasting - OTiS showcases its ability to accurately capture domain-specific data characteristics and demonstrates its competitiveness against state-of-the-art baselines. Our code and pre-trained weights are publicly available at https://github.com/oetu/otis.

1 Introduction

In natural language processing (NLP) or computer vision (CV), generalisable language features, e.g. semantics and grammar (Radford et al., 2018; Touvron et al., 2023; Chowdhery et al., 2023), or visual features, e.g. edges and shapes (Geirhos et al., 2019; Dosovitskiy et al., 2021; Oquab et al., 2024), are learned from large-scale data. Self-supervised pre-training paradigms are designed to account for the specific properties of language (Radford et al., 2018; Touvron et al., 2023; Chowdhery et al., 2023) or imaging (Zhou et al., 2022; Cherti et al., 2023; Oquab et al., 2024), unlocking foundational model capabilities that apply to a wide range of domains and downstream tasks. This potential, however, remains largely unrealised in time series due to the lack of self-supervised pre-training paradigms that account for the heterogeneity of time series across domains.

Time series are widespread in everyday applications and play an important role in various domains, including medicine (Pirkis et al., 2021), engineering (Gasparin et al., 2022), natural sciences (Ravuri et al., 2021), and finance (Sezer et al., 2020). They differ substantially with respect to the number of variates, inter-variate relationships, temporal dynamics, and sampling frequency (Fawaz et al., 2018; Ismail Fawaz et al., 2019; Ye & Dai, 2021; Wickstrøm et al., 2022). For instance, standard 10-20 system electroencephalography (EEG) recordings come with up to 256 variates (Jurcak et al., 2007), while most audio recordings have only 1 (mono) or 2 (stereo) variates. Weather data shows high periodicity, whereas financial data is exposed to long-term trends. Both domains encompass low-frequency data recorded on an hourly (278 mHz), daily ($12\,\mu$ Hz), or even monthly (386 nHz) basis, while audio data is sampled at high frequencies of $44.1\,\mathrm{kHz}$ or more. Overall, this heterogeneity across domains renders the extraction of generalisable time series features difficult (Fawaz et al., 2018; Gupta et al., 2020; Iwana & Uchida, 2021; Ye & Dai, 2021).

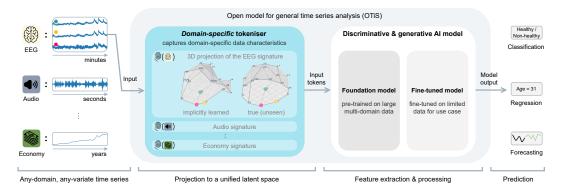


Figure 1: Overview of OTIS. Pre-trained on a large corpus of time series from diverse domains, OTIS enables general time series analysis. Its domain-specific tokeniser addresses time series heterogeneity across domains - including different numbers of variates, inter-variate relationships, temporal dynamics, and sampling frequencies - by learning unique domain signatures. After pre-training, the model can be fine-tuned on limited data from any domain, including previously unseen ones, to perform various tasks such as classification, regression, and forecasting.

While most existing self-supervised pre-training methods for time series are limited to single domains (Wu et al., 2021; 2022a; Nie et al., 2023; Dong et al., 2024; Jiang et al., 2024), recent works propose simple techniques to incorporate time series from multiple domains (Yang et al., 2024; Das et al., 2024; Woo et al., 2024; Liu et al., 2024). These works for instance crop all time series into segments of unified size (Jiang et al., 2024), resample them to a uniform frequency (Yang et al., 2024), or analyse each variate of a multi-variate time series independently (Liu et al., 2024). While these naive techniques address differences in sampling frequency and variate count, they degrade the original time series and neglect the critical inter-variate relationships and temporal dynamics required for effective real-world analysis. Consequently, there is a clear need for pre-training strategies that adequately handle heterogeneity in time series to unlock foundational model capabilities.

In this work, we propose a novel multi-domain pre-training paradigm that addresses the full spectrum of time series heterogeneity across domains. Our approach facilitates the comprehensive extraction of generalisable features from diverse time series. Pre-trained on a large corpus of publicly available data, our open model for general time series analysis (OTiS) can be fine-tuned on limited data of any (unseen) domain to perform a variety of downstream tasks, as showcased in Figure 1.

Our key contributions can be summarised as follows:

- 1. We present OTiS, an open model for general time series analysis, with our entire pipeline and pre-trained weights publicly available at https://github.com/oetu/otis.
- 2. We propose a novel pre-training paradigm based on masked data modelling to address heterogeneity in multi-domain time series. Our approach includes a novel tokeniser with learnable signatures to capture domain-specific data characteristics, a dual masking strategy to learn temporal causality, and a normalised cross-correlation loss to model long-range dependencies.
- 3. We pre-train OTiS on a large corpus of publicly available time series from 8 domains, spanning medicine, engineering, natural sciences, and finance. With 640, 187 samples and 11 billion time points, this corpus represents diverse time series characteristics, enabling generalisable feature extraction.
- 4. We evaluate OTiS across 15 downstream applications, including classification, regression, and forecasting. Our comprehensive analysis demonstrates that OTiS accurately captures domain-specific data characteristics and is competitive with both specialised and general state-of-the-art (SOTA) models, achieving new SOTA performance in 10 tasks. Notably, none of the baselines is capable of performing all the tasks covered by OTiS.

2 RELATED WORKS

2.1 Self-Supervised Learning for Time Series

Time series vary significantly across domains, with differences in the number of variates, inter-variate relationships, temporal dynamics, and sampling frequencies. Due to this inherent heterogeneity, most existing works focus on pre-training models within a single domain (Oreshkin et al., 2019; Tang et al., 2020; Wu et al., 2021; Zhou et al., 2021; Wu et al., 2022a; Woo et al., 2022; Yue et al., 2022; Zhang et al., 2022; Li et al., 2023; Nie et al., 2023; Zeng et al., 2023; Dong et al., 2024). To develop more generalisable time series models, recent methods have explored multi-domain pre-training by addressing certain aspects of the heterogeneity, such as differences in variate count and sampling frequency. For instance, Liu et al. (2024) treat each variate in multi-variate time series independently to standardise generative tasks like forecasting, while Goswami et al. (2024) extend uni-variate analysis to discriminative tasks like classification. Similarly, Jiang et al. (2024) and Yang et al. (2024) standardise time series by cropping them into segments of predefined size and resampling them to a uniform frequency, respectively, to enable general classification capabilities in medical domains.

While partially addressing time series heterogeneity, these methods limit model capabilities for general time series analysis. Standardisation techniques like cropping or resampling may distort inter-variate relationships, temporal dynamics, and long-range dependencies. Additionally, many of these approaches are tailored to specific applications, such as generative tasks (Das et al., 2024; Liu et al., 2024; Woo et al., 2024), or focused on particular domains like medicine (Jiang et al., 2024; Yang et al., 2024). Moreover, recent foundational models (Das et al., 2024; Goswami et al., 2024; Liu et al., 2024) focus on uni-variate analysis, ignoring crucial inter-variate relationships essential for real-world applications, such as disease prediction (Schoffelen & Gross, 2009; Wu et al., 2022b). Our study aims to overcome these limitations by fully addressing heterogeneity of multi-domain time series, establishing a foundation for general time series analysis across domains and tasks.

2.2 TIME SERIES TOKENISATION

Transformers (Vaswani et al., 2017) have emerged as the preferred architecture for foundational models in NLP and CV due to their scalability (Kaplan et al., 2020; Gordon et al., 2021; Alabdulmohsin et al., 2022), enabling the training of models in the magnitude of 100 billion parameters (Chowdhery et al., 2023; Touvron et al., 2023; Oquab et al., 2024; Ravi et al., 2024). To utilise a Transformer for time series analysis, a tokeniser is required to map the time series into a compact latent space. Current methods (Jin et al., 2023; Nie et al., 2023; Zhou et al., 2023; Das et al., 2024; Goswami et al., 2024; Jiang et al., 2024; Liu et al., 2024; Woo et al., 2024; Yang et al., 2024) follow established techniques from NLP and CV, dividing time series into patches of pre-defined size. These patches are then flattened into a 1D sequence, with positional embeddings used to retain positional information. While uni-variate models (Nie et al., 2023; Das et al., 2024; Goswami et al., 2024; Liu et al., 2024) consider only temporal positions, multi-variate approaches (Woo et al., 2024; Yang et al., 2024; Jiang et al., 2024) account for both temporal and variate positions. However, none of these methods address the unique characteristics of variates, mistakenly assuming that the relationships between variates are identical across domains. Our work seeks to adapt the tokenisation process to preserve the domain-specific relationships between variates.

3 Methods

In this work, we present a novel multi-domain pre-training paradigm that enables generalisable feature extraction from large, heterogeneous time series corpora. We introduce a domain-specific tokeniser with learnable signatures to address heterogeneity in multi-domain time series, as described in Section 3.1. We tailor masked data modelling (MDM) for multi-domain time series to pre-train our open model for general time series analysis (OTiS) on a large, heterogeneous corpus, as detailed in Section 3.2. In particular, we propose normalised cross-correlation as a loss term to capture global temporal dynamics in time series, as explained in Section 3.3. Moreover, we introduce a dual masking strategy to capture bidirectional relationships and temporal causality, essential for general time series analysis, as described in Section 3.4. After pre-training, we fine-tune OTiS on limited data to perform a variety of downstream tasks in any - including previously unseen - domain, as outlined in Section 3.5. A graphical visualisation of our method is provided in Figure 2.

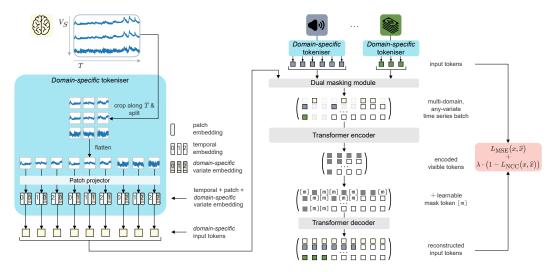


Figure 2: Architecture of OTiS. During pre-training, batches of time series from diverse domains are processed using a domain-specific tokeniser. This tokeniser splits a time series into fixed-size patches, which are then embedded using a patch projector shared across all variates and domains. A temporal embedding and a domain-specific variate embedding are added to each patch embedding. A dual masking strategy is employed to mask the resulting input tokens. The reconstruction of the multi-domain input tokens is guided using an auxiliary normalised cross-correlation (NCC) loss.

3.1 Domain-Specific Tokeniser

Overview. Assume a time series sample $\boldsymbol{X} \in \mathbb{R}^{V_S \times T}$ from domain S, where V_S denotes the number of variates specific to S and T denotes the number of time points. We randomly crop or zero-pad \boldsymbol{X} to a fixed context length of \overline{T} time points. We then split it into T' temporal patches of size P along the time dimension, resulting in $V_S \cdot T'$ patches $\boldsymbol{x}_{v,t} \in \mathbb{R}^{1 \times P}$, where $v \in \{1, \dots, V_S\}$ and $t \in \{1, \dots, T'\}$.

Next, we embed these patches using a shared patch projector across all variates and domains, resulting in patch embeddings $e^{\mathcal{P}}(\boldsymbol{x}_{v,t}) = e^{\mathcal{P}}_{v,t} \in \mathbb{R}^{1 \times D}$, where D denotes the model dimension. The patch projector consists of a 1D convolutional layer followed by layer normalisation and GELU activation.

The permutation-equivariant nature of Transformers (Vaswani et al., 2017) requires the use of positional embeddings to accurately capture the inherent relationships in the input data. Initially introduced for 1D textual token sequences (Vaswani et al., 2017), positional embeddings simply introduce an ordering into the input sequence. Modern implementations further extend their capabilities to encode more complex geometric information, such as 2D spatial (Dosovitskiy et al., 2021) or graph (Kreuzer et al., 2021) structures. For the analysis of any-variate time series, we distinguish between the temporal and variate structure. The temporal structure is equivalent to a sequential 1D structure, such that we use standard 1D sinusoidal embeddings $e^{\mathcal{T}}(x_{v,t}) = e_t^{\mathcal{T}} \in \mathbb{R}^{1 \times D}$.

The variate structure exhibits great heterogeneity across domains. In domains with uni-variate and two-variate data, such as mono and stereo audio, the structure is either trivial or only requires a basic distinction between variates. In other domains, however, the variate structure may represent more complex relationships, such as 3D manifolds for electroencephalography (EEG) or electrocardiography (ECG) data, or be of non-spatial nature, such as for financial data. Hence, we introduce learnable domain-specific variate embeddings to adequately address the heterogeneity across domains. These embeddings, denoted as $e_{\mathcal{S}}^{\mathcal{V}}(\boldsymbol{x}_{v,t}) = e_{\mathcal{S},v}^{\mathcal{V}} \in \mathbb{R}^{1 \times D}$ for each variate v in domain s, are designed to model the unique properties of a domain. They capture the inter-variate relationships and temporal dynamics specific to domain s, forming what can be considered as the *signature* of the very domain.

Finally, the patch, temporal, and domain-specific variate embeddings are summed to form the input token $e_{v,t} = e_{v,t}^{\mathcal{P}} + e_t^{\mathcal{T}} + e_{\mathcal{S},v}^{\mathcal{V}} \in \mathbb{R}^{1 \times D}$. These input tokens collectively constitute the final input sequence $E \in \mathbb{R}^{(V_S \cdot T') \times D}$. To support batches of any-variate time series from multiple domains, we

pad the variate dimension to the maximum number of variates in a batch $\overline{V} = \max_S V_S$. For samples where $V_S < \overline{V}$ or $T < \overline{T}$, attention masking is used to ensure that padded variate or temporal tokens are ignored. The domain-specific tokeniser is trained end-to-end with the Transformer layers.

Definition of (Sub-)Domains. The domain-specific tokeniser is designed to integrate different datasets within a domain. Consider two EEG datasets, TDBrain (Van Dijk et al., 2022) and SEED (Zheng & Lu, 2015), which share 19 identical variates but have different sampling frequencies of 500 Hz and 200 Hz, respectively. In this case, a single EEG-specific tokeniser ($V_{\text{EEG}} = 19$) is sufficient to accommodate both sampling frequencies, i.e. $E^{\mathcal{V}}_{\text{EEG-TDBrain}} = E^{\mathcal{V}}_{\text{EEG-SEED}} = [e^{\mathcal{V}}_{\text{EEG,1}},\ldots,e^{\mathcal{V}}_{\text{EEG,19}}]^{\top} \in \mathbb{R}^{19 \times D}$, as demonstrated in our experiments in Section 4. Note that while these positional embeddings are agnostic to variate ordering, we simplify processing by aligning the variate order across datasets within the same domain. Consider another EEG dataset, LEMON (Babayan et al., 2019), which includes 62 electrodes. Of these, 15 overlap with the electrodes in TDBrain (Van Dijk et al., 2022) and SEED (Zheng & Lu, 2015), while the remaining 47 are unique to LEMON (Babayan et al., 2019). In this scenario, the EEG-specific tokeniser can be extended by the 47 new variates ($V_{\text{EEG}} = 66$), such that $E^{\mathcal{V}}_{\text{EEG-LEMON}} = [e^{\mathcal{V}}_{\text{EEG,1}},\ldots,e^{\mathcal{V}}_{\text{EEG,15}},e^{\mathcal{V}}_{\text{EEG,20}},\ldots,e^{\mathcal{V}}_{\text{EEG,66}}]^{\top} \in \mathbb{R}^{62 \times D}$. In this way, different datasets can be combined to approximate the underlying data distribution of a domain S, e.g. EEG, enabling the creation of large and diverse time series corpora.

Multi-Variate or Uni-Variate Analysis? Consider the Electricity dataset (UCI, 2024), which contains electricity consumption data for 321 households recorded from 2012 to 2014. These 321 observations are sampled from an underlying population and are assumed to be independent and identically distributed (*i.i.d.*). In this scenario, we perform a uni-variate analysis ($V_{\rm Electricity} = 1$) of the data, initialising a single Electricity-specific variate embedding that models the hourly consumption of a household. In contrast, the Weather dataset (Wetterstation, 2024) contains 21 climatological indicators, such as air temperature, precipitation, and wind speed, which are not *i.i.d.* because they directly interact and correlate with one another. Therefore, a multi-variate analysis ($V_{\rm Weather} = 21$) is conducted to account for the dependencies and interactions between the observations.

3.2 PRE-TRAINING ON MULTI-DOMAIN TIME SERIES

We pre-train our model using masked data modelling (MDM) (He et al., 2022) to learn generalisable time series features across domains. We mask a subset of input tokens and only encode the visible (i.e. non-masked) tokens using an encoder $f(\cdot)$. Afterwards, we complement the encoded tokens with learnable mask tokens and feed them to a decoder $g(\cdot)$, reconstructing the original input tokens.

More precisely, we draw a binary mask $\boldsymbol{m} \in \{0,1\}^{V_S \cdot T'}$, following the dual masking strategy proposed in Section 3.4, and apply it to the input sequence $\boldsymbol{E} \in \mathbb{R}^{(V_S \cdot T') \times D}$. Thus, we obtain a visible view $\boldsymbol{E}[\boldsymbol{m}] \in \mathbb{R}^{N_1 \times D}$, where $N_1 = \sum_{v=1}^{V_S} \sum_{t=1}^{T'} m_{v,t}$ and $N_0 = (V_S \cdot T') - N_1$ denote the number of visible and masked tokens, respectively. The visible view $\boldsymbol{E}[\boldsymbol{m}]$ is then fed to the encoder $f(\cdot)$ to compute the token features $\boldsymbol{H} \in \mathbb{R}^{N_1 \times D}$:

$$\boldsymbol{H} = f(\boldsymbol{E}[\boldsymbol{m}]). \tag{1}$$

To reconstruct the original input, these token features are fed to the decoder $g(\cdot)$ together with a special, learnable mask token $e^{\mathcal{M}} \in \mathbb{R}^{1 \times D}$, that is inserted at the masked positions where $m_{v,t} = 0$:

$$\boldsymbol{h}'_{v,t} = \begin{cases} \boldsymbol{h}_{v,t} & \text{if } m_{v,t} = 1\\ \boldsymbol{e}^{\mathcal{M}} & \text{if } m_{v,t} = 0 \end{cases},$$
 (2)

such that $m{H}' \in \mathbb{R}^{(V_S \cdot T') \times D}$. The decoder $g(\cdot)$ then predicts the reconstructed input $\widehat{m{X}} \in \mathbb{R}^{V_S \times (T' \cdot P)}$:

$$\widehat{X} = g(\mathbf{H}'),\tag{3}$$

where $(T' \cdot P) = \overline{T}$, i.e. the context length specified in time points. Eventually, the domain-specific tokeniser described in Section 3.1, the encoder $f(\cdot)$, and the decoder $g(\cdot)$ are optimised end-to-end using the mean squared error (MSE) loss on all reconstructed input tokens:

$$\mathcal{L}_{MSE} = \frac{1}{V_S \cdot T'} \sum_{v=1}^{V_S} \sum_{t=1}^{T'} \| \boldsymbol{x}_{v,t} - \widehat{\boldsymbol{x}}_{v,t} \|_2^2.$$
 (4)

3.3 NORMALISED CROSS-CORRELATION LOSS

MDM focuses on reconstructing masked parts of the data, emphasising *local* patterns through the MSE loss (4). However, time series often exhibit long-range dependencies, where past values influence future outcomes over extended periods. To accurately capture these *global* patterns, we introduce normalised cross-correlation (NCC) as a loss term in MDM for time series:

$$\mathcal{L}_{NCC} = \frac{1}{V_S \cdot \overline{T}} \sum_{v=1}^{V_S} \sum_{t=1}^{\overline{T}} \frac{1}{\sigma_{\boldsymbol{x}_v} \sigma_{\widehat{\boldsymbol{x}}_v}} (x_{v,t} - \mu_{\boldsymbol{x}_v}) (\widehat{x}_{v,t} - \mu_{\widehat{\boldsymbol{x}}_v}) \in [-1, 1],$$
 (5)

where μ and σ denote the mean and standard deviation, respectively. Hence, to capture both local and global temporal dynamics, the total loss used to optimise OTiS is defined as

$$\mathcal{L} = \mathcal{L}_{MSE} + \lambda \cdot (1 - \mathcal{L}_{NCC}), \qquad (6)$$

where λ is empirically set to 0.1 during pre-training.

3.4 DUAL MASKING STRATEGY

We design the masking strategy to enhance foundational model capabilites in time series analysis. Specifically, we randomly select between two masking schemes during pre-training, namely random masking and post-fix masking. In 75 % of cases, we apply random masking, where each $m_{v,t}$ is independently sampled from a Bernoulli distribution with probability $p=1-\rho$, with ρ denoting the masking ratio (i.e. $m_{v,t}\sim \text{Bernoulli}(1-\rho)$). This encourages the model to learn complex inter-variate relationships across the entire time series. In the remaining 25 % of cases, we employ post-fix masking, which masks the second half of the temporal dimension, leaving only the first half visible (i.e. $m_{v,t}=\mathbbm{1}_{[t\leq T'/2]}$). The prediction of future values solely based on past observations simulates real-world forecasting conditions, helping the model to capture temporal causality. Overall, this dual masking strategy enables OTiS to learn both bidirectional relationships and temporal causality, which are essential for general time series analysis.

3.5 Fine-Tuning & Inference on (Unseen) Target Domains

Inclusion of Unseen Domains. For a new domain S, a randomly initialised variate embedding $E_S^{\mathcal{V}} \in \mathbb{R}^{V_S \times D}$ is introduced. The domain-specific tokeniser is then fine-tuned alongside the encoder $f(\cdot)$, and, if required, the decoder $g(\cdot)$, for the specific downstream task, as described in the following.

Classification & Regression. We use the encoder $f(\cdot)$ and the unmasked input sequence E to compute all token features $H = f(E) \in \mathbb{R}^{(V_S \cdot T') \times D}$. We average-pool these features into a global token $h^* \in \mathbb{R}^{1 \times D}$, which we feed through a linear layer to obtain the final model prediction. We optimise a cross-entropy and MSE loss for the classification and regression tasks, respectively.

Forecasting. We apply post-fix masking to generate a binary mask $m \in \{0,1\}^{V_S \cdot T'}$ for the forecasting task. The encoder $f(\cdot)$ is used to compute the visible token features $\boldsymbol{H} \in \mathbb{R}^{N_1 \times D}$. We then concatenate the sequence with learnable mask tokens to form $\boldsymbol{H}' \in \mathbb{R}^{(V_S \cdot T') \times D}$, which is passed through the decoder $g(\cdot)$ to produce the final output. We optimise the MSE loss together with the NCC loss term over all reconstructed input tokens.

4 Experiments & Results

4.1 MODEL VARIANTS AND IMPLEMENTATION DETAILS

We introduce OTiS in three different configurations, Base, Large, and Huge, with their specific architectures described in Appendix C.1, to explore scaling laws with respect to the model size. We set the patch size and stride to P=24, respectively, to split the time series into $T'=\frac{\overline{T}}{P}$ non-overlapping patches along the time dimension. For pre-training, the context length specified in time points is set to $\overline{T}=1008$, resulting in T'=42 sinusoidal temporal embeddings. If longer context lengths are

Table 1: Overview of our large and diverse pre-training corpus. The corpus is built with unlabelled data from eight domains, encompassing medicine, engineering, natural sciences, and finance.

Domain	Name	Samples	Variates	Time points	Frequency	Disk size
S			V_S			
ECG	MIMIC-IV-ECG 2023	400,000	12	5,000	500 Hz	90 GB
Temperature	DWD 2024	203, 340	1	720	(hourly) 278 mHz	$614\mathrm{MB}$
Audio (stereo)	AudioSet-20K 2017	16,123	2	441,000	$44.1\mathrm{kHz}$	$53\mathrm{GB}$
Audio (mono)	AudioSet-20K 2017	3,491	1	441,000	$44.1\mathrm{kHz}$	$6\mathrm{GB}$
Electromechanics	FD-A 2016	13,640	1	5,120	$64\mathrm{kHz}$	$161\mathrm{MB}$
EEG	TDBrain 2022	2,692	19	60,000	500 Hz	$12\mathrm{GB}$
EEG	SEED 2015	675	19	37,000	$200\mathrm{Hz}$	$2\mathrm{GB}$
Banking	NN5 2012	111	1	971	(daily) $12\mu{\rm Hz}$	$370 \mathrm{KB}$
Economics	FRED-MD 2016	107	1	728	(monthly) 386 nHz	$330\mathrm{KB}$
Economics	Exchange 2018	8	1	7, 588	(daily) $12\mu{\rm Hz}$	240 KB
		640,187		11,052,756,981		164 GB

required during fine-tuning, these embeddings are linearly interpolated (i.e. $T'_{\rm ft} \geq 42$) to offer greater flexibility for downstream applications. We tune the hyperparameters for pre-training and fine-tuning as described in Appendix C. An overview of the computational costs is provided in Appendix D.

4.2 Large and Diverse Pre-Training Corpus

We aim to develop a general time series model that fully handles the heterogeneity in real-world data. Specifically, our model is designed to handle time series with different variate counts V_S , inter-variate relationships, temporal dynamics, and sampling frequency, ensuring flexibility for downstream tasks. To this end, we pre-train our model on a large and diverse corpus of publicly available data spanning 8 domains, with a total of 640, 187 samples and 11 billion time points, as summarised in Table 1. A detailed description of the datasets included in our pre-training corpus can be found in Appendix A. The time series corpus is split into 612, 394 training and 27, 793 validation samples for pre-training.

4.3 BENCHMARKING ACROSS DOMAINS AND TASKS

To assess the utility of OTiS in real-world settings, we conduct experiments on three key use cases in time series analysis: classification, regression, and forecasting. For classification, we perform binary epilepsy detection using EEG (Epilepsy 2001), multi-class fault detection in rolling bearings from vibration signals (FD-B 2016), multi-class hand-gesture classification with accelerometer signals (Gesture 2009), and multi-class muscular disease classification using electromyographie (EMG 2000). In regression, we predict five imaging-derived cardiac phenotypes from 12-lead ECG (LVEDV, LVESV, LVSV, LVEF, LVM 2020). For forecasting, we predict electricity transformer temperature (ETT 2021), weather (Weather 2024), and electricity consumption (Electricity 2024). Further dataset details are provided in Appendix B. We adhere to the established data splitting and evaluation procedures for the classification (Zhang et al., 2022), regression (Turgut et al., 2023), and forecasting (Zhou et al., 2021) tasks. All experiments are reported as mean and standard deviation across five seeds set during fine-tuning.

OTIS demonstrates strong classification capabilities, setting two new benchmarks, as shown in Table 2a. Additionally, OTIS excels in predicting imaging-derived cardiac phenotypes, even surpassing multimodal baselines that incorporate imaging data during pre-training, as summarised in Table 2b. Our model outperforms the baselines in 4 out of 5 regression tasks. As shown in Table 3, OTIS also exhibits strong forecasting capabilities, outperforming current models in 4 out of 6 benchmarks. Notably, all of the forecasting tasks are performed in previously unseen domains. A visualisation of the forecast predictions can be found in Appendix F. Overall, OTIS outperforms both specialised and general state-of-the-art baselines in 10 out of 15 diverse applications across 8 domains, demonstrating its strong utility and generalisability across (unseen) domains and tasks.

Table 2: Classification and regression performance on a total of 9 benchmark tasks. OTIS is competitive with specialised baselines, setting new state-of-the-art on 6 tasks and even outperforming the multimodal CM-AE and MMCL. This demonstrates the capability of OTIS to extract high-level semantics. Best score in **bold**, second best <u>underlined</u>. • indicates tasks in previously unseen domains.

(a) Classification [Accuracy (ACC ↑) in %]

(b) Regression [R-squared $(R^2 \uparrow)$]

Model	Epilepsy	FD-B	Gesture*	EMG*	Model	LVEDV	LVESV	LVSV	LVEF	LVM
SimCLR 2020	90.71	49.17	48.04	61.46	ViT 2023	0.409	0.396	0.299	0.175	0.469
CoST 2022 TS2Vec 2022	88.40 93.95	47.06 47.90	68.33 69.17	53.65 78.54	MAE 2023	0.486	0.482	0.359	0.237	0.573
TF-C 2022	94.95	69.38	76.42	81.71	CM-AE* 2023	0.451	0.380	0.316	0.103	0.536
Ti-MAE 2023 SimMTM 2024	89.71 95.49	60.88 69.40	71.88 80.00	69.99 97.56	MMCL* 2023	0.504	0.503	0.370	0.250	0.608
OTiS-Base OTiS-Large OTiS-Huge	94.25 94.03 91.48	99.24 98.62 98.32	63.61 62.50 63.61	97.56 <u>98.37</u> 98.37	OTiS-Base OTiS-Large OTiS-Huge	0.509 0.504 <u>0.505</u>	0.512 0.503 0.510	0.391 0.371 0.376	0.292 0.267 <u>0.281</u>	0.592

^{*} Models that incorporate paired imaging data during pre-training.

Table 3: Forecasting performance on 6 benchmark tasks. OTiS is competitive with specialised and general baselines, setting new state-of-the-art on 4 tasks and showcasing its ability to capture local time series features. A forecasting horizon of 96 time points is predicted from the past 336 (*512, $^{+}904$) time points. Mean squared error (MSE \downarrow) is reported. Best score in **bold**, second best <u>underlined</u>. • indicates tasks in previously unseen domains.

Model	ETTh1°	ETTh2°	ETTm1°	ETTm2°	Weather*	Electricity*
N-BEATS 2019	0.399	0.327	0.318	0.197	0.152	0.131
Autoformer 2021	0.435	0.332	0.510	0.205	0.249	0.196
TimesNet 2022a	0.384	0.340	0.338	0.187	0.172	0.168
DLinear 2023	0.375	0.289	0.299	0.167	0.176	0.140
PatchTST 2023	0.370	0.274	0.293	0.166	0.149	0.129
Time-LLM 2023	0.408	0.286	0.384	0.181	†	†
GPT4TS 2023	0.376	0.285	0.292	0.173	0.162	0.139
MOMENT* 2024	0.387	0.288	0.293	0.170	0.154	0.136
MOIRAI ⁺ 2024	<u>0.375</u>	0.277	0.335	0.189	0.167	0.152
OTiS-Base	0.424	0.212	0.337	0.161	0.139	0.128
OTiS-Large	0.446	$\overline{0.205}$	0.362	0.173	0.142	$\overline{0.127}$
OTiS-Huge	0.461	0.215	0.384	0.181	0.149	0.132

[†] Experiments could not be conducted on a single NVIDIA RTX A6000-48GB GPU.

4.4 Domain Signature Analysis

A key component of OTiS is its use of domain-specific variate embeddings. While these embeddings are randomly initialised, we expect them to capture unique domain characteristics during training, eventually serving as the signature of their respective domain. To validate this hypothesis, we analyse the domain-specific variate embeddings after pre-training using principal component analysis (PCA).

First, we find that OTiS unifies time series from diverse domains into a meaningful latent space, where embeddings of domains with shared high-level semantics cluster together, as depicted in Appendix E.1. For example, embeddings of mono and stereo audio group closely, as do those of banking and economics. Moreover, EEG-specific embeddings are clearly separated and ECG-specific embeddings form a tight cluster.

Second, OTiS preserves low-level semantics specific to each domain, such as the relationships between variates. To explore this, we focus on the learned variate embeddings of EEG, the most complex domain in our corpus. EEG variates correspond to actual electrodes, each associated with a 3D position in space or a 2D position on the scalp, which is ideal for studying inter-variate relationships. Our analysis covers both (i) variate embeddings for 10-20 system EEG recordings with 19 electrodes learned during multi-domain pre-training, and (ii) variate embeddings for previously

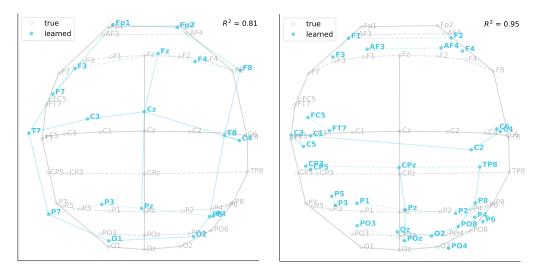


Figure 3: 2D PCA projections of the learned EEG-specific variate embeddings, overlaid on the actual EEG electrode layout. (**Left**) Embeddings for 10-20 system EEG recordings with 19 electrodes learned during pre-training. (**Right**) Embeddings for previously unseen EEG recordings with 32 electrodes learned during fine-tuning. The embeddings accurately reflect the spatial electrode layout, as confirmed by high correlations (\mathbb{R}^2) between the PCA projections \bullet and the true layout \circ .

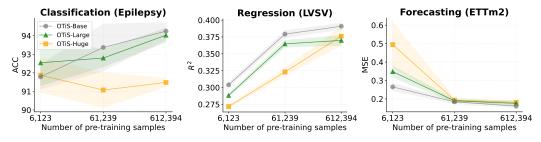


Figure 4: Performance of OTiS with different numbers of pre-training samples. Shaded regions indicate the standard deviation across 5 seeds. Increasing dataset size generally improves downstream performance. Scaling model size requires even larger pre-training corpora to be effective.

unseen EEG recordings with 32 electrodes learned during fine-tuning of the pre-trained OTiS. We find that the first three principal components explain (i) 74.7% and (ii) 87.9% of the variance, indicating that the 3D PCA projections of the variate embeddings correspond closely to the actual electrode positions. A visualisation of the learned 3D electrode layout is provided in Appendix E. Additionally, we linearly align these positions with the true EEG electrode layout on the 2D scalp manifold, as depicted in Figure 3. The alignment yields R^2 values of (i) 0.81 and (ii) 0.95, confirming a strong correspondence between the learned variate embeddings and the actual electrode layout.

4.5 SCALING STUDY

We analyse the scaling behaviour of OTiS with respect to model and dataset size. To this end, we subsample the pre-training data to $10\,\%$ and $1\,\%$ of its original size, ensuring that each subset is fully contained within the corresponding superset. We evaluate the downstream performance of all OTiS variants across classification, regression, and forecasting tasks, as depicted in Figure 4.

The experiments demonstrate that downstream performance generally scales with dataset size, achieving the best results with the full pre-training dataset. This trend, however, does not directly apply to model size, which is in line with the scaling behaviour observed in current time series foundational models (Woo et al., 2024; Goswami et al., 2024). Given that performance generally improves across all models with increasing data size, we hypothesise that scaling the model size could prove beneficial with even larger pre-training corpora.

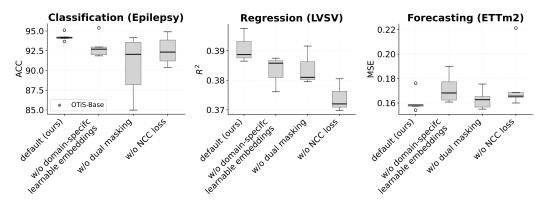


Figure 5: Ablation study on key components of OTiS. Downstream performance is analysed across 5 seeds. A leave-one-out approach is used to evaluate the influence of each component. The default setting, which includes all components, demonstrates superior model capabilities across tasks.

4.6 ABLATION STUDY

We perform an ablation study to analyse the impact of OTiS' key components: the domain-specific tokeniser, dual masking strategy, and normalised cross-correlation (NCC) loss. As shown in Figure 5, the best and most robust performance is achieved when all components are used during pre-training.

Replacing the domain-specific variate embeddings with domain-agnostic embeddings (i.e. learnable embeddings shared across all domains) consistently led to inferior performance across all tasks, demonstrating the importance of capturing domain-specific data characteristics during tokenisation. Switching from dual masking to random masking resulted in performance degradation, although the impact was less notable for generative tasks than for discriminative tasks. We hypothesise that the NCC loss already captures temporal causality, which is particularly crucial for generative tasks like forecasting. Overall, removing the NCC loss caused performance declines across all downstream tasks, emphasising the role of long-range dependencies for general time series understanding.

5 DISCUSSION & CONCLUSION

In this study, we explore the problem of effective pre-training on heterogeneous time series corpora. Time series vary substantially across domains, e.g. with respect to inter-variate relationships and temporal dynamics, rendering generalisable feature extraction from multi-domain time series difficult. To address this issue, we present OTiS, an open model for general time series analysis, specifically designed to handle multi-domain heterogeneity. Our novel multi-domain pre-training paradigm, including a domain-specific tokeniser with learnable signatures, a dual masking strategy, and a normalised cross-correlation (NCC) loss, enables OTiS to extract generalisable time series features.

In extensive experiments, we demonstrate that OTiS generalises well across 15 diverse downstream applications spanning 8 distinct domains, achieving competitive performance with both specialised and general state-of-the-art (SOTA) models. In a qualitative analysis, we further show that OTiS unifies time series from diverse domains in a meaningful latent space, while preserving low-level semantics of a domain including the inter-variate relationships. Thereby, our work establishes a strong foundation for future advancements in interpretable and general time series analysis.

Limitations. While OTiS outperforms SOTA models across 10 tasks, our experiments in low-data regimes suggest that larger pre-training corpora could further enhance its performance. Unlike in NLP and CV, where large datasets are curated from web-crawled data, foundational models in time series, including OTiS, still rely on manually curated datasets. Future work could explore fully automatic pipelines, e.g. using embedding similarity, to filter and rebalance multi-domain time series from the web. OTiS could further benefit from processing domain signatures during inference, potentially unlocking zero-shot capabilities, similarly to those seen in foundational models in NLP and CV.

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A LARGE MULTI-DOMAIN PRE-TRAINING CORPUS

In this section, we present an overview of our large and diverse pre-training corpus. The corpus consists of publicly available data spanning eight domains, with a total of 640, 187 samples and 11 billion time points. In the following, we provide a detailed breakdown of the domains and the datasets they encompass. Note that we apply channel-wise standard normalisation to the datasets unless otherwise specified.

ECG. The MIMIC-IV-ECG dataset (Gow et al., 2023) contains diagnostic 10-second, 12-lead ECG recordings sampled at a frequency of 500 Hz. While the entire dataset comprises 800, 035 samples, we include only the first half of the recordings available in the database, preventing the ECG data from predominating in the pre-training corpus. To remove the baseline drift from the ECG data, we use the asymmetric least square smoothing technique (Zhang et al., 2010). Note that we apply standard normalisation separately to the Einthoven, Goldberger, and Wilson leads.

Temperature. The Deutscher Wetterdienst (DWD) dataset (Wetterdienst, 2024) contains hourly air temperature measurements from 629 weather stations across Germany. Since the recording length varies significantly, ranging from 763 to 1, 148, 290 hours per station, we split the data into chunks of 720 hours (approximately one month).

Audio. The AudioSet dataset (Gemmeke et al., 2017) contains 10-second YouTube clips for audio classification, featuring 527 types of audio events that are weakly annotated for each clip. The full training set includes a class-wise balanced subset (AudioSet-20K, 22, 176 clips) and an unbalanced (AudioSet-2M 2, 042, 985 clips) set. For our pre-training corpus, we use the balanced AudioSet-20K, which contains 3, 491 mono and 16, 123 stereo recordings, all sampled at 44, 100 Hz.

Electromechanics. The FD-A dataset (Lessmeier et al., 2016) collects vibration signals from rolling bearings in a mechanical system for fault detection purposes. Each sample consists of 5, 120 timestamps, indicating one of three mechanical device states. Note that the FD-B dataset is similar to FD-A but includes rolling bearings tested under different working conditions, such as varying rotational speeds.

EEG. The TDBrain dataset (Van Dijk et al., 2022) includes raw resting-state EEG data from 1, 274 psychiatric patients aged 5 to 89, collected between 2001 and 2021. The dataset covers a range of conditions, including Major Depressive Disorder (426 patients), Attention Deficit Hyperactivity Disorder (271 patients), Subjective Memory Complaints (119 patients), and Obsessive-Compulsive Disorder (75 patients). The data was recorded at 500 Hz using 26 channel EEG-recordings, based on the 10-10 electrode international system.

The SEED dataset (Zheng & Lu, 2015) contains EEG data recorded under three emotional states: positive, neutral, and negative. It comprises EEG data from 15 subjects, with each subject participating in experiments twice, several days apart. The data is sampled at 200 Hz and recorded using 62 channel EEG-recordings, based on the 10-20 electrode international system.

For simplicity, we only consider the 19 channels common to both datasets, i.e. the channels that correspond to the 10-20 electrode international system.

Banking. The NN5 competition dataset (Taieb et al., 2012) consists of daily cash withdrawals observed at 111 randomly selected automated teller machines across various locations in England.

Economics. The FRED-MD dataset (McCracken & Ng, 2016) contains 107 monthly time series showing a set of macro-economic indicators from the Federal Reserve Bank of St Louis. The data was extracted from the FRED-MD database.

The Exchange dataset (Lai et al., 2018) records the daily exchange rates of eight different nations, including Australia, Great Britain, Canada, Switzerland, China, Japan, New Zealand, and Singapore, ranging from 1990 to 2016.

B BENCHMARK DATASET DETAILS

We provide an overview of the datasets used to benchmark our model on 15 distinct downstream applications in Table 4. Our benchmarking experiments include classification, regression, and forecasting tasks.

Table 4: Experimental setup with all conducted downstream applications, evaluation metrics, and datasets used for benchmarking.

Task	Metric		Dataset									
1431	11101110	Domain S	Name	Samples	$oldsymbol{Variates}_{V_S}$	Time points	Frequency					
uo		EEG	Epilepsy 2001	11,500	1	178	174 Hz					
icati	ACC	Electromechanics	FD-B 2016	13,640	1	5,120	$64\mathrm{kHz}$					
Classification	ACC	Acceleration	Gesture 2009	560	3	206	$100\mathrm{Hz}$					
Cla		EMG	EMG 2000	204	1	1,500	$4\mathrm{kHz}$					
Regression	R^2	ECG	UK BioBank 2015	18,926	12	5,000	500 Hz					
			ETTh1 2021	1	7	17,420	(hourly) 278 mHz					
Forecasting		Energy	ETTh2 2021	1	7	17,420	(hourly) 278 mHz					
ast		Lifergy	ETTm1 2021	1	7	69,680	(minutely) 1.1 mHz					
e.	MSE		ETTm2 2021	1	7	69,680	(minutely) 1.1 mHz					
For	MISE	Weather	Weather 2024	1	21	52,696	(minutely) 2.8 mHz					
		Electricity	Electricity 2024	321	1	26, 304	(hourly) 278 mHz					

C EXPERIMENT DETAILS

C.1 MODEL VARIANTS

To explore the scaling laws with respect to the model size, we provide OTiS in three variants, as summerised in Table 5.

Table 5: Details of model variants.

Model	Layers	$\mathbf{Hidden}\ \mathbf{size}\ D$	MLP size	Heads	d_{kv}	Parameters
OTiS-Base	12	192	768	3	64	8 M
OTiS-Large	18	384	1536	6	64	$44\mathrm{M}$
OTiS-Huge	24	576	2304	8	72	$131\mathrm{M}$

C.2 PRE-TRAINING & FINE-TUNING PARAMETERS

We provide the hyperparameters used to pre-train all variants of OTiS in Table 6. The hyperparameters used to fine-tune our models for the classification, regression, and forecasting tasks are provided in Table 7, 8, and 9, respectively.

D COMPUTATION COSTS

We provide an overview of the computational resources used to train OTiS in Table 10.

Table 6: Hyperparameters used for pre-training. Pre-training is performed on 4 NVIDIA A100-80GB GPUs. A cosine learning rate scheduler is applied with a $10\,\%$ warmup. All OTiS configurations use a shallow decoder with 2 M parameters, consisting of 4 layers with a hidden size of 160, an MLP with size 640, and 5 heads.

Model	Epochs	Batch size	Base LR	LR decay	$NCC \lambda$	Mask ratio ρ	Weight decay
OTiS-Base	200	5120	3e-5	cosine	0.1	0.75	0.10
OTiS-Large	200	3328	1e-5	cosine	0.1	0.75	0.15
OTiS-Huge	200	2880	3e-6	cosine	0.1	0.75	0.05

Table 7: Hyperparameters used for fine-tuning the classification tasks on a single NVIDIA RTX A6000-48GB GPU. A cosine learning rate scheduler is applied with a $10\,\%$ warmup.

Dataset	Model	Epochs	Batch size	Base LR	Drop path	Layer decay	Weight decay	Label smoothing
	OTiS-Base	75	32	1e-3	0.2	0.75	0.2	0.1
Epilepsy	OTiS-Large	75 75	$\frac{32}{22}$	3e-3	0.2	$0.50 \\ 0.75$	$0.1 \\ 0.2$	$0.1 \\ 0.2$
	OTiS-Huge	75	32	3e-3	0.0	0.75	0.2	0.2
	OTiS-Base	75	32	3e-4	0.0	0.75	0.1	0.1
FD-B	OTiS-Large	75	32	1e-3	0.1	0.75	0.1	0.2
	OTiS-Huge	75	32	3e-4	0.1	0.75	0.2	0.1
	OTiS-Base	75	32	1e-2	0.1	0.25	0.2	0.1
Gesture	OTiS-Large	75	32	3e-3	0.2	0.75	0.1	0.0
	OTiS-Huge	75	32	1e-2	0.0	0.75	0.1	0.1
	OTiS-Base	75	32	1e-3	0.2	0.75	0.1	0.2
EMG	OTiS-Large	75	32	3e-3	0.1	0.75	0.2	0.1
	OTiS-Huge	75	32	3e-3	0.1	0.75	0.2	0.2

Table 8: Hyperparameters used for fine-tuning the regression tasks on a single NVIDIA RTX A6000-48GB GPU. A cosine learning rate scheduler is applied with a 10% warmup.

Dataset	Model	Epochs	Batch size	Base LR	Drop path	Layer decay	Weight decay
	OTiS-Base	50	192	3e-4	0.2	0.75	0.1
UK BioBank	C	50	160	1e-4	0.2	0.75	0.1
	OTiS-Huge	50	200	1e-4	0.2	0.75	0.1

E DOMAIN SIGNATURE ANALYSIS

To analyse the domain signatures, we reduce the dimensionality of the domain-specific variate embeddings by employing a principal component analysis (PCA). Our analysis shows that OTiS unifies time series from diverse domains into a meaningful latent space, while accurately capturing the inter-variate relationships within a domain.

E.1 INTER-DOMAIN ANALYSIS

A visualisation of all domain-specific variate embeddings learned during pre-training is provided in Figure 6. We find that OTiS learns a meaningful latent space, where embeddings of domains with shared high-level semantics cluster closely together.

Table 9: Hyperparameters used for fine-tuning the forecasting tasks. A cosine learning rate scheduler is applied with a $10\,\%$ warmup.

Dataset	Model	Epochs	Batch size	Base LR	$\mathbf{NCC} \lambda$	Weight decay
	OTiS-Base	1000	1	1e-0	0.1	0.15
ETTh1	OTiS-Large	1000	1	1e-1	0.2	0.15
	OTiS-Huge	1000	1	3e-1	0.1	0.15
	OTiS-Base	1000	1	1e-0	0.2	0.25
ETTh2	OTiS-Large	1000	1	1e-1	0.1	0.25
	OTiS-Huge	1000	1	3e-1	0.0	0.25
	OTiS-Base	1000	1	3e-1	0.2	0.25
ETTm1	OTiS-Large	1000	1	3e-1	0.2	0.25
	OTiS-Huge	1000	1	1e-1	0.1	0.15
	OTiS-Base	1000	1	3e-1	0.1	0.25
ETTm2	OTiS-Large	1000	1	3e-1	0.2	0.25
	OTiS-Huge	1000	1	1e-1	0.2	0.25
	OTiS-Base	1000	1	3e-1	0.2	0.15
Weather	OTiS-Large	1000	1	3e-1	0.2	0.15
	OTiS-Huge	1000	1	1e-1	0.2	0.05
	OTiS-Base	250	32	3e-2	0.0	0.25
Electricity	OTiS-Large	250	32	3e-2	0.0	0.15
·	OTiS-Huge	250	32	3e-2	0.2	0.15

Table 10: Computational resources used to pre-train OTiS. Note that fine-tuning and inference of all OTiS variants on downstream applications were performed using a single NVIDIA RTX A6000-48GB and 32 CPUs.

Model Paramete		Parameters Power CP		GPU			
Model	Parameters	consumption	count	Count	Hours	Type	
OTiS-Base	8 M	700 W *	128	4	115^{\dagger}	NVIDIA A100-80GB	
OTiS-Large	$44\mathrm{M}$	800 W*	128	4	154^{\dagger}	NVIDIA A100-80GB	
OTiS-Huge	131 M	960 W *	128	4	219^{\dagger}	NVIDIA A100-80GB	

^{*} Total power consumption across all GPUs.

E.2 Intra-Domain Analysis

A visualisation of the domain-specific variate embeddings for EEG and ECG are given in Figure 7 and Figure 8, respectively. We find that OTiS preserves low-level semantics specific to each domain, accurately capturing the relationships between variates.

F FORECAST VISUALISATION

We visualise the performance of our model on 6 forecasting benchmarks in Figure 9.

[†] Total hours across all GPUs.

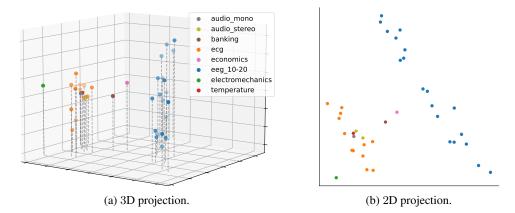


Figure 6: PCA projections of the domain-specific variate embeddings learned during pre-training. OTiS unifies time series from diverse domains in a meaningful latent space, while correctly encoding the inter-variate relationships within a domain. Mono (•) and stereo (•) audio-specific embeddings cluster closely together, as do those for banking (•) and economics (•). Clear separation is observed for EEG-specific embeddings (•), while also ECG-specific embeddings (•) form a tight cluster.

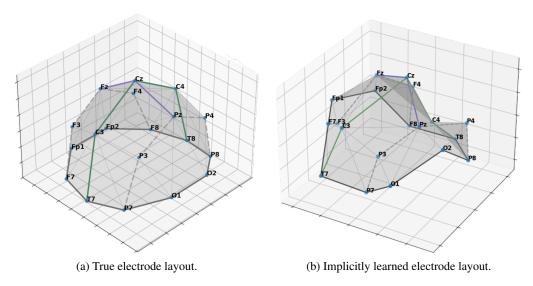


Figure 7: 3D PCA projections of the variate embeddings for 10-20 system EEG recordings with 19 electrodes learned during pre-training. The labels of each node correspond to the electrode names.

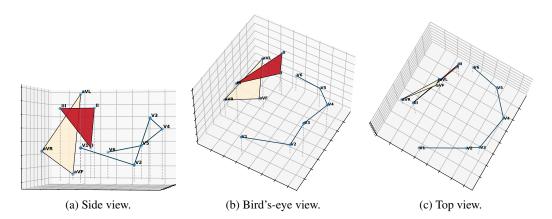


Figure 8: 3D PCA projections of the variate embeddings for standard 12-lead ECG learned during pre-training. The embeddings accurately reflect the true physiological structure of the ECG leads. The V1-V6 leads, arranged on the rib cage from the sternum to the mid-axillary line, represent a 3D view of the human heart. In contrast, the I-II-III leads and aVR-aVL-aVF leads, derived from electrodes placed on one foot and both arms, form a planar 2D triangle.

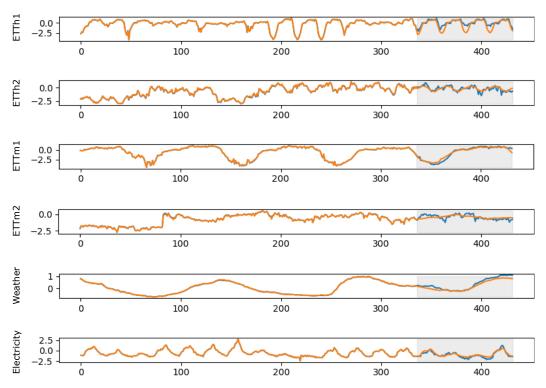


Figure 9: Visualisation of OTiS-Base forecast predictions on 6 benchmark datasets. A forecasting horizon of 96 time points is predicted from the past 336 time points. Ground truth in blue, prediction in orange. Areas highlighted in grey are not visible to the model.