## A Repetitive Learning Controller for PAM-Actuated Exoskeleton Robots With Motion Constraints

Tong Yang, Yiheng Chen, Ning Sun\*, and Yanding Qin Institute of Robotics and Automatic Information Systems (IRAIS), College of Artificial Intelligence, Nankai University, China

- New repetitive learning-based error-constrained control for uncertain PAM-actuated exoskeleton robot systems
- Accurate tracking control and effective error constraints
- Asymptotic convergence of tracking errors by Lyapunovbased stability analysis

