Knee Joint Exoskeleton Device Based on Biological Motion Principle

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- A knee joint exoskeleton device that is designed based on the biological motion principle of human knee joint.
- In order to follow the powering patterns of human walking, two one-way bearings and one set of gears are adopted to construct the knee joint exoskeleton device.
- The biological motions of femoral-on-tibial extension and tibial-on-femoral flexion can be adaptively imitated by the proposed device.

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