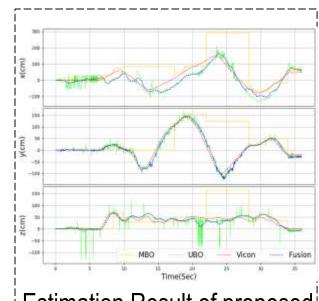
## A cooperative positioning approach of Unmanned Aerial Vehicles with Accuracy and Robustness

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- A novel cooperative positioning approach named is proposed, which is comprised of a marker-based position estimation and an endto-end UAV detection.
- A data fusion algorithm is applied to ensure the accuracy and robustness of the localization.
- Extensive experiments under different environments are carried out to verify the effectiveness of the proposed method.



Estimation Result of proposed method in dark environment