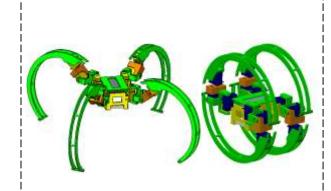
Simulation Study of a Spider-like Robot Based on Leg Reorganization

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- A four-legged bionic robot with wheel-foot integrated is designed.
- The principle of wheel-foot conversion was analyzed.
- The bionic motion simulation of the robot virtual. The foot movement and wheel prototype is realized.



movement of the robot.