# Joint Torque Feedback-based Decentralized Neuro-optimal Control of Input-constrained Modular Robot Manipulator System

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- A novel decentralized neuro-optimal control method of input-constrained MRM system is presented.

- Adaptive dynamic programming

- Joint torque feedback technique

- Actuator saturation constraints

- Experimental verification
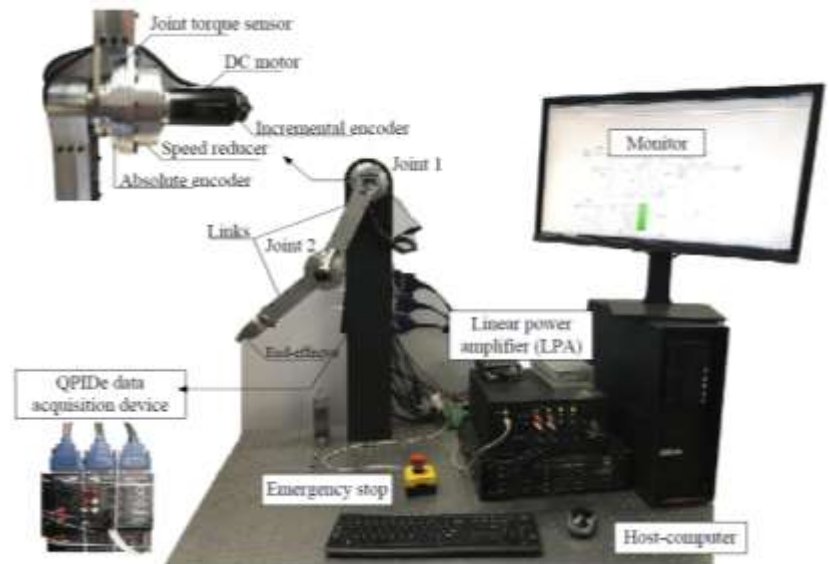
2-DOF MRM experimental platform for verification of the developed method