A Traffic Scene Object Detection Method Combining Deep Learning and Stereo Vision Algorithm

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- A method combining depth information with YOLOv5s object detection algorithm is proposed.
- The depth information is obtained by the disparity images which generated by the PSMNet.
- Add Attention Feature Fusion Module to YOLOv5s to improve the accuracy of small object detection.
- The depth information is fused with the object detection to obtain distance information.