Simulation Performance Evaluation of Pure Pursuit, Stanley, LQR, MPC Controller for Autonomous Vehicles

Jia Liu, Zhiheng Yang, Zhejun Huang, Wenfei Li, Shaobo Dang, and Huiyun Li

Shenzhen Institutes of Advanced Technology, Chinese Academy of Sciences, China

- Build geometry path tracking methods based on Ackerman steering model
- Build optimal path tracking methods based on Ackerman steering model
- Carry on simulation experiments on different paths

