# Data-efficient Deep Reinforcement Learning Method Toward Scaling Continuous Robotic Task with Sparse Rewards

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- A model-free, off-policy RL algorithm TD3MHER is proposed to solve continuous tasks with sparse rewards.
- TD3MHER motivates the agent to learn the potential physical model of the robot .
- TD3MHER use the previously collected samples to train the agent.
- TD3MHER is convenient to be applied because it requires no extra exploration.

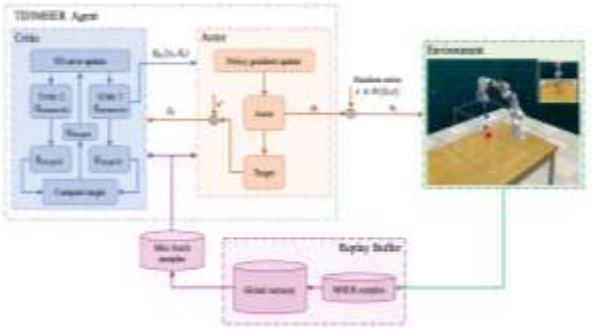

Figure 1. The structure of our proposed method TD3MHER.