

Force Tracking Control for Elector-Hydraulic Actuators Based On RBF Neural Networks

Xinhui Tian, Honglei An, Zhitong Zhang, Xu Chang, Hongxu Ma and
Qing Wei

Robot Research Center, College of Intelligence Science and Technology,
National University of Defense Technology, China

- The static relationship between velocity-force-input has been demonstrated in hydraulic actuators.
- The least square method and RBF neural network are used to identify this relationship.
- The performances of force-tracking and disturbance-rejection have been improved.

