Theoretical and Experimental Study of Adaptive Control for Fixed-wing UAV Arrested Recovery on the USV

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- Shipborne recovery of fixed-wing UAV is an important technology for UAV.
- An adaptive control method combined **with LPV model** and **α - β filter** for fixed-wing UAV arrested recovery.
- Flight experiments under different conditions are completed to verify the performance of the controller.
- The UAV with the proposed method can satisfy the requirements of recovery on the USV.

Recovery of UAV on USV in real environment