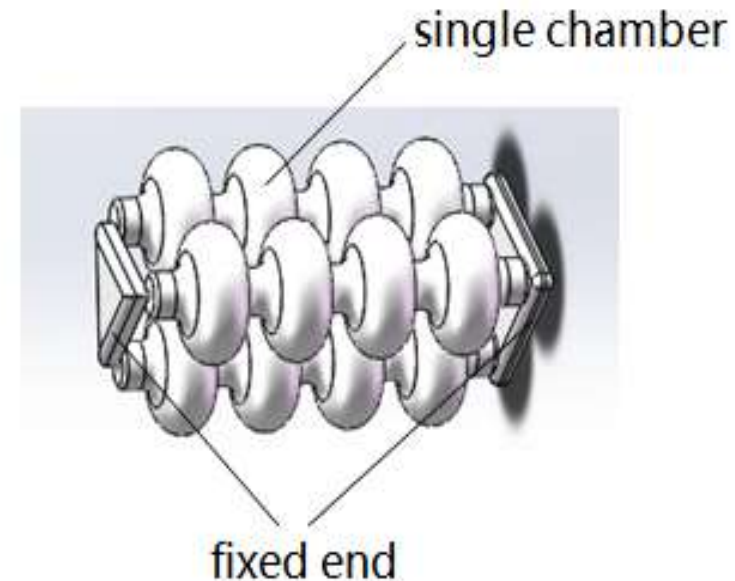


Multi-chamber Pneumatic Actuator for Peristaltic Soft Robot

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- Designed and fabrication the pneumatic corrugated structure driver for squirmy soft robots
- Built a set of controller systems to control actuator deformation
- Completed the action of forwarding and turning with the actuator on experiments



Structure of the actuator