An Integrated Virtual Hand Platform for Evaluation of Model-Based Control of Hand Prosthesis

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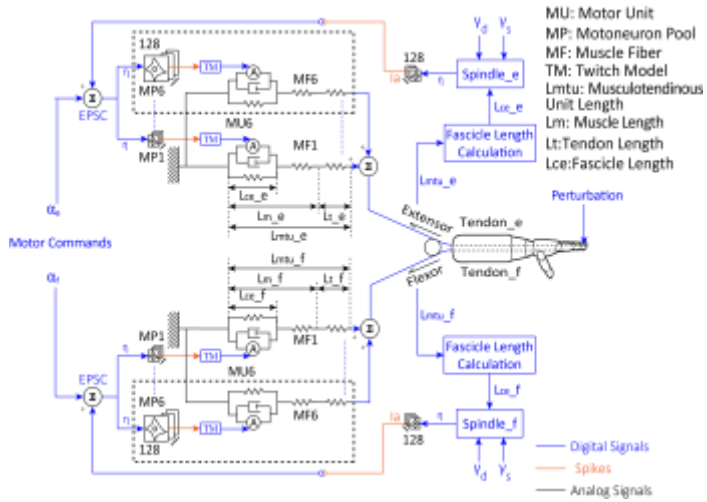
- Integrate the neuromorphic model of muscles with the ETS-based sensory feedback in the virtual hand platform.
- Explore the compliant properties of the model-based biomimetic control system using the tendon-driven virtual hand.
- The control mode of the biomimetic controller was automatic switched depending on the external load conditions.



Detailed architecture of the model-based controller.