A Non-zero-sum-based Neural-optimal control method for Modular and Reconfigurable Robot Systems

Tianjiao An, Xinye Zhu, Yuanchun Li and Bo Dong Department of Control Science and Engineering, Changchun University of Technology, Changchun, China

- Using non-zero-sum neural-optimal control on modular and reconfigurable robot.
- Extending ADP to non-zero-sum algorithm complete trajectory tracking task.
- Each module is regarded as one player in the game theory.

