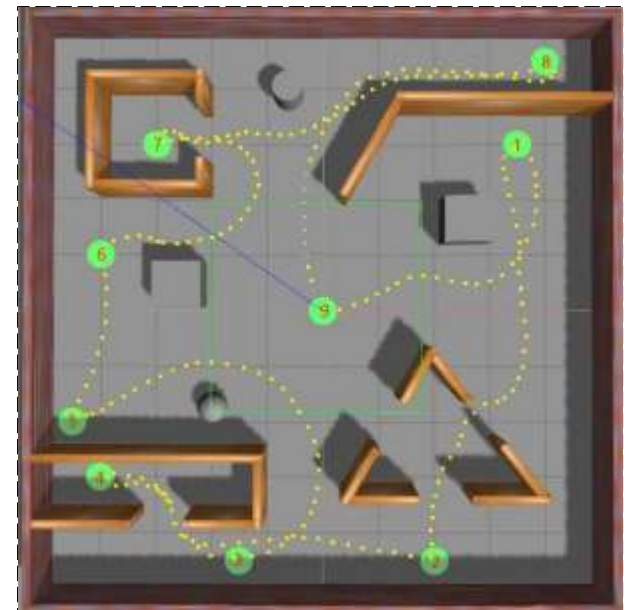


# Autonomous mobile robot navigation in uncertain dynamic environments based on deep reinforcement learning

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- This paper proposes E2E navigation based on deep reinforcement learning.
- Use multi-time environmental information to ensure continuous navigation.
- The proposed method has the property of safe and fast navigation in uncertain dynamic environments.
- Simulation results have verified the efficacy of the proposed method.



Global navigation route