## Evolving Gaussian Process based Learning of Knee Angle and Velocity

Jiantao Yang<sup>1</sup>, Yong He<sup>2</sup>, Chen He<sup>1</sup>, and Ping Shi<sup>1\*</sup>

- 1. Institute of Rehabilitation Engineering and Technology, University of Shanghai for Science and Technology, China
- 2. CAS Key Laboratory of Human-Machine Intelligence-Synergy Systems, Shenzhen Institutes of Advanced Technology, China
- Dependent Gaussian process is established to fuse multi-source information from each of the human-exoskeleton subsystems.
- Gradient estimation model is then performed to obtain the joint velocity.

The proposed model can achieve joint angle and velocity learning without

velocity measurement.

