Dynamic Modeling and Vibration Analysis of a 6-DOFs Industrial Robot Considering Joint Flexibility

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- This paper is concerned with the dynamic modeling and vibration analysis of multi-DOFs industrial robot considering joint flexibility.

- A dynamic model based on Kane method developed to analyze the vibration characteristics under different joint stiffnes parameters.

- The results of the proposed strategy can b used to design an accurate model-based controller for an industrial robot.
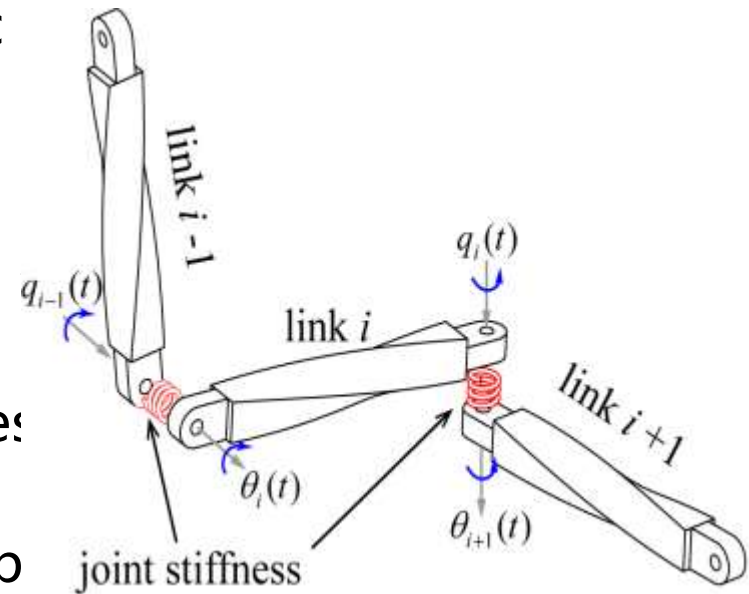
The schematic diagram of the joint flexibility