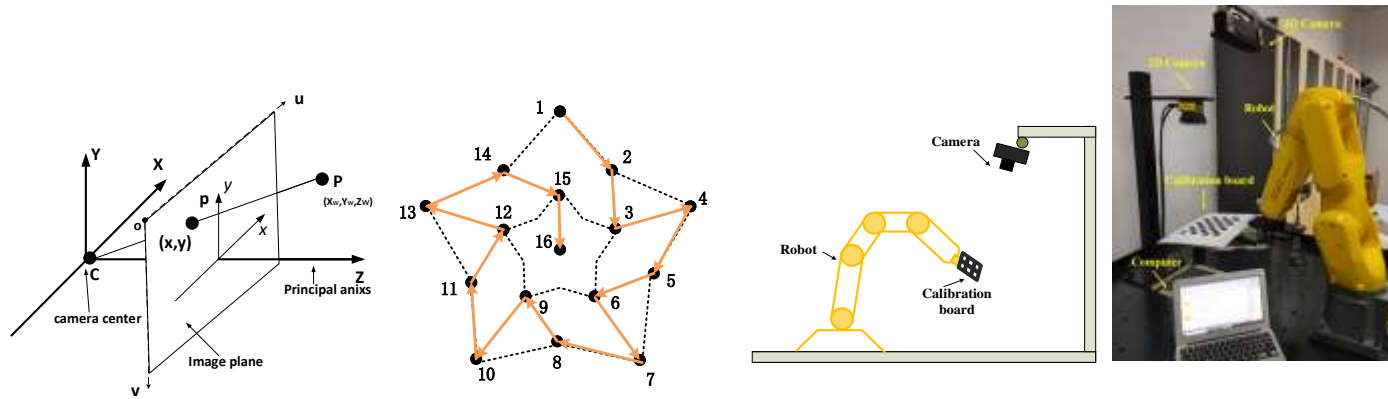
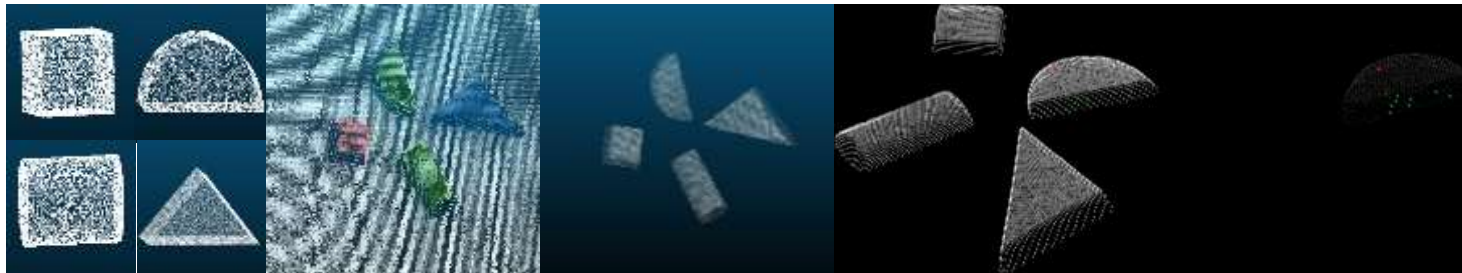


Robotic arm grasping through 3D point clouds recognition



The grasping environment combined with a 3D camera and a robotic arm



The pose estimation based on template point cloud