

A Fireworks Algorithm Based Path Planning Method for Amphibious Robot

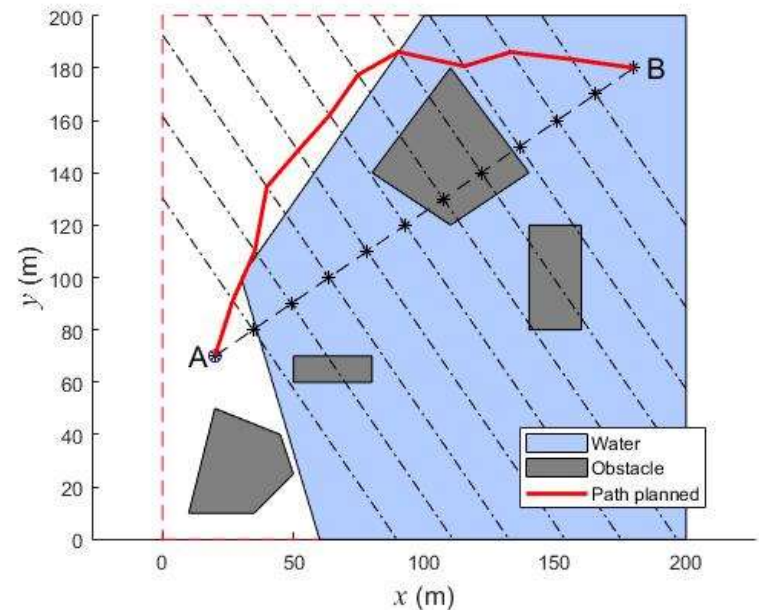
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- A path planning method adopting the Fireworks Algorithms (FWA) is proposed.
- An optimization model is designed aiming at the characteristics of path planning for amphibious robots.
- Simulation experiments are conducted to analyze and compare the performance of FWA variants.



Amphibious environment and path planned using proposed method