

some points

$$\begin{aligned} \kappa &= \frac{1}{2(m_0a + 4)} \\ &\downarrow \\ 2\kappa\mathcal{M}[U_\mu]_{x,y} &= \sigma_{x,y} - \kappa\Sigma_{\mu=1}^4[(1 - \gamma_\mu)U_\mu(x)\sigma_{x+\mu,y} + (1 + \gamma_\mu)U_\mu^\dagger(x - \mu)\sigma_{x-\mu,y}] \\ &\downarrow \dagger(\gamma_\mu \text{ is Hermitic}) \\ \sigma_{x,y} - \kappa\Sigma_{\mu=1}^4[(1 - \gamma_\mu)U_\mu^\dagger(x)\sigma_{y+\mu,x} + (1 + \gamma_\mu)U_\mu(x - \mu)\sigma_{y-\mu,x}] \\ &\downarrow \text{reform equation} \\ \sigma_{x,y} - \kappa\Sigma_{\mu=1}^4[(1 - \gamma_\mu)U_\mu^\dagger(x - \mu)\sigma_{x-\mu,y} + (1 + \gamma_\mu)U_\mu(x)\sigma_{x+\mu,y}] \\ &\downarrow \text{reform equation} \\ \sigma_{x,y} - \kappa\Sigma_{\mu=1}^4[(1 + \gamma_\mu)U_\mu(x)\sigma_{x+\mu,y} + (1 - \gamma_\mu)U_\mu^\dagger(x - \mu)\sigma_{x-\mu,y}] \end{aligned}$$

Fig. 1: 24850c8ae14ac5bfc3ad2a9a56528a0a.png

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even-odd

all in all

$x - 1$ (backward x)

parity\eo	0	1
0	$\underline{b} \ x$	x
1	x	$\underline{b} \ x$

$x + 1$ (forward x) \

parity\eo	0	1
0	x	$\underline{f} \ x$
1	$\underline{f} \ x$	x

Fig. 2: b6914007e64b53434f905acbea83e392.png

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$$A_{ee}x_e - \kappa D_{eo}x_o = b_e$$

$$(A_{oo} - \kappa^2 D_{oe} A_{ee}^{-1} D_{eo})x_o = \kappa D_{oe} A_{ee}^{-1} b_e + b_o$$

origin one : $\mathcal{M}x = b$

$$\begin{pmatrix} 1 - \kappa T_{ee} & -\kappa D_{eo} \\ -\kappa D_{oe} & 1 - \kappa T_{oo} \end{pmatrix} \begin{pmatrix} x_e \\ x_o \end{pmatrix} = \begin{pmatrix} b_e \\ b_o \end{pmatrix}$$

$$A = 1 + T$$

in this case, $T = 0$, so $A = 1$

so,

$$\begin{pmatrix} 1 & -\kappa D_{eo} \\ -\kappa D_{oe} & 1 \end{pmatrix} \begin{pmatrix} x_e \\ x_o \end{pmatrix} = \begin{pmatrix} b_e \\ b_o \end{pmatrix}$$

$$x_e - \kappa D_{eo}x_o = b_e$$

$$x_o - \kappa D_{oe}x_e = b_o$$

so,

$$x_e - \kappa D_{eo}x_o = b_e$$

$$x_o - \kappa D_{oe}(\kappa D_{eo}x_o + b_e) = b_o$$

then

$$x_e - \kappa D_{eo}x_o = b_e$$

$$x_o - \kappa^2 D_{oe}(D_{eo}x_o) = \kappa D_{oe}b_e + b_o$$

so,

$$\text{just solve } x_o - \kappa D_{oe}(\kappa D_{eo}x_o) = \kappa D_{oe}b_e + b_o$$

$$\text{then will easily get } x_e \text{ by } x_e - \kappa D_{eo}x_o = b_e$$

so,

give Dslash :

$$tmp = D_{eo}src_o$$

$$dest_o = src_o - \kappa D_{oe}(\kappa D_{eo}src_o) = src_o - \kappa^2 D_{oe}tmp$$

give b:

$$b_e = anw_e - \kappa D_{eo}anw_o$$

$$b_o = anw_o - \kappa D_{oe}anw_e$$

$$b'_o = b_o + \kappa D_{oe}b_e$$

so,

$$\text{Dslash}(x_o) = b'_o$$

then get x_o by BistabCg,

$$\text{finally get } x_e \text{ by } b_e + \kappa D_{eo}x_o$$

done!

so $Dslash : (1 - \kappa^2 D_{oe} D_{eo})$
then $Dslash^\dagger : (1 - \kappa^2 D_{oe} D_{eo})^\dagger = (1 - \kappa^2 D_{eo}^\dagger D_{oe}^\dagger)$
let $Dslash^\dagger Dslash x_\alpha = Dslash^\dagger b'_\alpha$

Fig. 3: f01486a17a32914c803c6e92667e2753.png

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clover dslash

本文的研究工作在 u, d 夸克不很轻的条件下进行，我们实际上选用了四叶草作用量进行后续的数值计算，暂不考虑其对手征对称性的影响。结合 (1-49)，最终得到了格点上的 QCD 作用量：

$$\begin{aligned}
S_{\text{LQCD}} &= \frac{2}{g^2} \sum_x \sum_{\mu < \nu} \left[\frac{5}{3u_0^4} P_{\mu\nu}(x) - \frac{1}{12u_0^6} R_{\mu\nu}(x) - \frac{1}{12u_0^6} R_{\nu\mu}(x) \right] + a^4 \bar{\psi} \mathcal{M} \psi. \\
2\kappa a \mathcal{M}_{xy} &= \left[1 + \sum_{\mu < \nu} \frac{a^2 \kappa}{u_0^4} \sigma_{\mu\nu} \hat{F}_{\mu\nu}(x) \right] \delta_{x,y} \\
&\quad - \frac{\kappa}{u_0} \sum_{\mu=1}^4 \left[(1 - \gamma_\mu) U_\mu(x) \delta_{x+\mu,y} + (1 + \gamma_\mu) U_\mu^\dagger(x - \mu) \delta_{x-\mu,y} \right].
\end{aligned} \tag{1-60}$$

Fig. 4: ee0e5623a05ece2d5df411c3b521aeef.png

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其中 c_{SW} 参数即为 Sheikholeslami-Wohlert 系数，其值在微扰树图阶为 1； $\sigma_{\mu\nu} = -\frac{i}{2}[\gamma_\mu, \gamma_\nu]$ ； $\hat{F}_{\mu\nu}$ 为格点上的场强张量形式。 c_{SW} 也可以使用平均场方法^[32] 或者非微扰地^[34] 确定。

$$\begin{aligned}
\hat{F}_{\mu\nu}(x) &= \frac{1}{a^2} \frac{1}{8i} \left[U_\mu(x) U_\nu(x + \mu) U_\mu^\dagger(x + \nu) U_\nu^\dagger(x) \right. \\
&\quad + U_\nu(x) U_\mu^\dagger(x + \nu - \mu) U_\nu^\dagger(x - \mu) U_\mu(x - \mu) \\
&\quad + U_\mu^\dagger(x - \mu) U_\nu^\dagger(x - \mu - \nu) U_\mu(x - \mu - \nu) U_\nu(x - \nu) \\
&\quad \left. + U_\nu^\dagger(x - \nu) U_\mu(x - \nu) U_\nu(x - \nu + \mu) U_\mu^\dagger(x) - h.c. \right].
\end{aligned} \tag{1-55}$$

Fig. 5: b85b86a0502bc2e32d8fc8a2e7229f11.png

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$$A = 1 - \kappa T : \{A_{ee} = 1 - \kappa T_{ee}; A_{oo} = 1 - \kappa T_{oo}\}$$

for the coeffi for T:

$$(-a^2/\mu_0^4) * (-i/) * (1/a^2 * 1/(8 * i)) * \{\gamma_\mu * \gamma_\nu * u.....\} = (1/\mu_0^4) * (1/8) * \{\gamma_\mu * \gamma_\nu * u.....\}$$

$$\gamma_0 = \begin{pmatrix} 0 & 0 & 0 & i \\ 0 & 0 & i & 0 \\ 0 & -i & 0 & 0 \\ -i & 0 & 0 & 0 \end{pmatrix} \gamma_1 = \begin{pmatrix} 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \end{pmatrix} \gamma_2 = \begin{pmatrix} 0 & 0 & i & 0 \\ 0 & 0 & 0 & -i \\ -i & 0 & 0 & 0 \\ 0 & i & 0 & 0 \end{pmatrix} \gamma_3 = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$$

$$\begin{aligned} \sum_{\mu < \nu} \sigma_{\mu\nu} F_{\mu\nu} \delta_{x,y} [x=y] &= 2\gamma_\mu \gamma_\nu \frac{1}{4} \sum_p \frac{1}{2} [U_p(x) - U_p^\dagger(x)] \\ &= \frac{1}{4} \gamma_\mu \gamma_\nu [\\ &\quad u(x, \mu) u(x + \mu, \nu) u^\dagger(x + \nu, \mu) u^\dagger(x, \nu) \\ &\quad + u(x, \nu) u^\dagger(x - \mu + \nu, \mu) u^\dagger(x - \mu, \nu) u(x - \mu, \mu) \\ &\quad + u^\dagger(x - \mu, \mu) u^\dagger(x - \mu - \nu, \nu) u(x - \mu - \nu, \mu) u(x - \nu, \nu) \\ &\quad + u^\dagger(x - \nu, \nu) u(x - \nu, \mu) u(x - \nu + \mu, \nu) u^\dagger(x, \mu) - BEFORE^\dagger] \\ &= \frac{1}{4} \gamma_0 \gamma_1 [U(x, y, z, t; x) U(x + 1, y, z, t; y) U^\dagger(x, y + 1, z, t; x) U^\dagger(x, y, z, t; y) \\ &\quad + U(x, y, z, t; y) U^\dagger(x - 1, y + 1, z, t; x) U^\dagger(x - 1, y, z, t; y) U(x - 1, y, z, t; x) \\ &\quad + U^\dagger(x - 1, y, z, t; x) U^\dagger(x - 1, y - 1, z, t; y) U(x - 1, y - 1, z, t; x) U(x, y - 1, z, t; y) \\ &\quad + U^\dagger(x, y - 1, z, t; y) U(x, y - 1, z, t; x) U(x + 1, y - 1, z, t; y) U^\dagger(x, y, z, t; x) - BEFORE^\dagger] \\ &\quad + \frac{1}{4} \gamma_0 \gamma_2 [U(x, y, z, t; x) U(x + 1, y, z, t; y) U^\dagger(x, y, z + 1, t; x) U^\dagger(x, y, z, t; z) \\ &\quad + U(x, y, z, t; y) U^\dagger(x - 1, y, z + 1, t; x) U^\dagger(x - 1, y, z, t; z) U(x - 1, y, z, t; x) \\ &\quad + U^\dagger(x - 1, y, z, t; x) U^\dagger(x - 1, y, z - 1, t; z) U(x - 1, y, z - 1, t; x) U(x, y, z - 1, t; z) \\ &\quad + U^\dagger(x, y, z - 1, t; z) U(x, y, z - 1, t; x) U(x + 1, y, z - 1, t; z) U^\dagger(x, y, z, t; x) - BEFORE^\dagger] \\ &\quad + \frac{1}{4} \gamma_0 \gamma_3 [U(x, y, z, t; x) U(x + 1, y, z, t; t) U^\dagger(x, y, z, t + 1; x) U^\dagger(x, y, z, t; y) \\ &\quad + U(x, y, z, t; t) U^\dagger(x - 1, y, z, t + 1; x) U^\dagger(x - 1, y, z, t; t) U(x - 1, y, z, t; x) \\ &\quad + U^\dagger(x - 1, y, z, t; x) U^\dagger(x - 1, y, z, t - 1; t) U(x - 1, y, z, t - 1; x) U(x, y, z, t - 1; t) \\ &\quad + U^\dagger(x, y, z, t - 1; t) U(x, y, z, t - 1; x) U(x + 1, y, z, t - 1; t) U^\dagger(x, y, z, t; x) - BEFORE^\dagger] \\ &\quad + \frac{1}{4} \gamma_1 \gamma_2 [U(x, y, z, t; y) U(x, y + 1, z, t; z) U^\dagger(x, y, z + 1, t; y) U^\dagger(x, y, z, t; z) \\ &\quad + U(x, y, z, t; z) U^\dagger(x, y - 1, z + 1, t; y) U^\dagger(x, y - 1, z, t; z) U(x, y - 1, z, t; y) \\ &\quad + U^\dagger(x, y - 1, z, t; y) U^\dagger(x, y - 1, z - 1, t; z) U(x, y - 1, z - 1, t; y) U(x, y, z - 1, t; z) \\ &\quad + U^\dagger(x, y, z - 1, t; z) U(x, y, z - 1, t; y) U(x, y + 1, z - 1, t; z) U^\dagger(x, y, z, t; y) - BEFORE^\dagger] \\ &\quad + \frac{1}{4} \gamma_1 \gamma_3 [U(x, y, z, t; y) U(x, y + 1, z, t; t) U^\dagger(x, y, z, t + 1; y) U^\dagger(x, y, z, t; t) \\ &\quad + U(x, y, z, t; t) U^\dagger(x, y - 1, z, t + 1; y) U^\dagger(x, y - 1, z, t; t) U(x, y - 1, z, t; y) \\ &\quad + U^\dagger(x, y - 1, z, t; y) U^\dagger(x, y - 1, z, t - 1; t) U(x, y - 1, z, t - 1; y) U(x, y, z, t - 1; t) \\ &\quad + U^\dagger(x, y, z, t - 1; t) U(x, y, z, t - 1; y) U(x, y + 1, z, t - 1; t) U^\dagger(x, y, z, t; y) - BEFORE^\dagger] \\ &\quad + \frac{1}{4} \gamma_2 \gamma_3 [U(x, y, z, t; z) U(x, y, z + 1, t; t) U^\dagger(x, y, z, t + 1; z) U^\dagger(x, y, z, t; t) \\ &\quad + U(x, y, z, t; t) U^\dagger(x, y, z - 1, t + 1; z) U^\dagger(x, y, z - 1, t; t) U(x, y, z - 1, t; z) \\ &\quad + U^\dagger(x, y, z - 1, t; z) U^\dagger(x, y, z - 1, t - 1; t) U(x, y, z - 1, t - 1; z) U(x, y, z, t - 1; t) \\ &\quad + U^\dagger(x, y, z, t - 1; t) U(x, y, z, t - 1; z) U(x, y, z + 1, t - 1; t) U^\dagger(x, y, z, t; z) - BEFORE^\dagger] \end{aligned}$$

Fig. 6: 578c344355637a18ca77561ba0e18e51.png

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成奇偶两部分，

$$\begin{aligned} e &= \{(x, y, z, t), x + y + z + t \equiv 0(\text{mod } 2)\}, \\ o &= \{(x, y, z, t), x + y + z + t \equiv 1(\text{mod } 2)\}. \end{aligned} \quad (1-160)$$

自然的，可以将费米子矩阵按照行列指标的奇偶性拆成四个部分，

$$2\kappa a_t \mathcal{M}_{xy} = \begin{pmatrix} M_{ee} & M_{eo} \\ M_{oe} & M_{oo} \end{pmatrix} = \begin{pmatrix} 1 - \kappa T_{ee} & -\kappa D_{eo} \\ -\kappa D_{oe} & 1 - \kappa T_{oo} \end{pmatrix}, \quad (1-161)$$

$$T_{xy} = \left[c_{\text{SW}}^t \sum_i \sigma_{i4} \hat{F}_{i4} + \frac{c_{\text{SW}}^s}{\xi_0} \sum_{i < j} \sigma_{ij} \hat{F}_{ij} \right] \delta_{x,y}, \quad (1-162)$$

$$\begin{aligned} D_{xy} &= \left[(1 - \gamma_4) U_4(x) \delta_{x+\hat{4},y} + (1 + \gamma_4) U_4(x - \hat{4}) \delta_{x-\hat{4},y} \right] \\ &+ \frac{\nu}{\xi_0} \sum_i \left[(1 - \gamma_i) U_i(x) \delta_{x+i,y} + (1 + \gamma_i) U_i(x - i) \delta_{x-i,y} \right]. \end{aligned} \quad (1-163)$$

那么 D 就是 Wilson 作用量的非对角部分， T 就是四叶草部分。在实践中，我们称呼这里的 D 矩阵为 Dslash。现在对上述分离成四部分的矩阵进行 LDU 分解，定义 $A = 1 + T$ ，

$$\begin{pmatrix} A_{ee} & -\kappa D_{eo} \\ -\kappa D_{oe} & A_{oo} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ -\kappa D_{oe} A_{ee}^{-1} & 1 \end{pmatrix} \begin{pmatrix} A_{ee} & 0 \\ 0 & A_{oo} - \kappa^2 D_{oe} A_{ee}^{-1} D_{eo} \end{pmatrix} \begin{pmatrix} 1 & -\kappa A_{ee}^{-1} D_{eo} \\ 0 & 1 \end{pmatrix}. \quad (1-164)$$

左边下三角矩阵的逆可以轻松得到，

$$\begin{pmatrix} 1 & 0 \\ -\kappa D_{oe} A_{ee}^{-1} & 1 \end{pmatrix}^{-1} = \begin{pmatrix} 1 & 0 \\ \kappa D_{oe} A_{ee}^{-1} & 1 \end{pmatrix}. \quad (1-165)$$

考虑将 x 和 b 也分成奇偶两部分，初始的线性方程组 $\mathcal{M}x = b$ 变为

$$\begin{cases} A_{ee} x_e - \kappa D_{eo} x_o = b_e, \\ (A_{oo} - \kappa^2 D_{oe} A_{ee}^{-1} D_{eo}) x_o = \kappa D_{oe} A_{ee}^{-1} b_e + b_o. \end{cases} \quad (1-166)$$

由于 A 关于时空指标是对角的，它的逆矩阵就是对每个对角部分求逆。而这些对角元是一个颜色指标上复矩阵（四叶草是小方格的线性组合）和 Dirac 指标上

Fig. 7: 26facbb878f5726ce648784aaecd648b.png

奇偶预处理中的 LDU 分解并不是唯一的。上文中介绍的是奇奇非对称的形式。偶偶非对称形式会使式 (1-164) 分解中间项对角变为 $A_{ee} - \kappa^2 D_{eo} A_{oo}^{-1} D_{oe}$ 和 A_{oo} ，自然左右两侧的三角矩阵也需要做相应的改变。另外还有奇奇对称形式和偶偶对称形式，以前者为例，分解结果为

$$\begin{pmatrix} A_{ee} & 0 \\ -\kappa D_{oe} & A_{oo} \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 - \kappa^2 A_{oo}^{-1} D_{oe} A_{ee}^{-1} D_{eo} \end{pmatrix} \begin{pmatrix} 1 & -\kappa A_{ee}^{-1} D_{eo} \\ 0 & 1 \end{pmatrix}. \quad (1-171)$$

这时中间对角项有一个变成了单位矩阵。

Fig. 8: f271fdc93b6303ffba82c28d13ce8575.png

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