# Zhangliang (Leon) LI

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### **EDUCATION**

**Washington University in St Louis** 

St. Louis, MO

Master of Science in Mechanical Engineering | GPA: 4.0/4.0

Sep 2021-May 2023

**Wuhan University of Technology** 

Wuhan, China

Bachelor of Science in Mechanical Engineering

Sep 2021 - Jun 2023

Honors: Second-class Scholarship of 2019-2020; Triple-A Student of 2019-2020

### TECHNICAL SKILLS

Programming Language: C++, Java, SolidWorks, CAD, ANSYS, MATLAB

**Mechanical Engineer:** Material Testing and Analysis, Finite Element Analysis (FEA), Failure Analysis, Corrosion and Wear, Material Processing and Selection, Composite Materials, Product Development, Quality Control

### **WORK EXPERIENCES**

CRRC MA, Springfield, MA, US

May 2023-Present

## **Configuration Engineer**

- > Manage, review, and maintain all changes to CRRC MA Configuration Management System.
- ➤ Responsible for day-to-day activities of the configuration management process, including prioritization and work allocation, ensuring all deliverables are completed on time.
- ➤ Develop, maintain, and track compliance with configuration management policies and procedures. Responsible for resolving and escalating any compliance issues as necessary for leadership review.
- ➤ Establish and manage the Configuration Control Board (CCB) and facilitate ongoing communication with functional management to enhance configuration management compliance.
- > Report vehicle configuration status at each stage and prepare the project's configuration management plan for customer use and approval.

## **PROJECT EXPERIENCES**

### Truss Design Robot System Structural Design

May 2021-Jul 2021

- > Designed a truss robot system with high-speed and high-precision position control using SolidWorks and ANSYS Workbench.
- ➤ Performed static finite element analysis to generate cloud diagrams of the truss robot's equivalent stress and displacement.
- Achieved a refined design with a truss robot system that could reach 0.5m/s running speed with positioning accuracy within 0.1mm.

### Fluid Dynamics in Covid-19

Mar 2020-May 2020

- ➤ Collaborated on a research project to measure the effectiveness of wearing a mask in restricting the spread of COVID-19.
- ➤ Analyzed particle motion trajectory using ANSYS platform to measure the effectiveness of wearing a mask in restricting the spread of COVID-19.
- > Co-authored a published paper titled "The Effects of Whether Wearing the Mask in the Spreading Process of COVID-19."

### **PUBLICATION**

[1] Junyi Lin, Sharui Zhang, **Zhangliang Li**, *The Effects of Whether Wearing the Mask in the Spreading Process of COVID-19*, Accepted to publish in International Core Journal of Engineering.

https://dx.doi.org/10.6919/ICJE.202012 6(12).0025

[2] Cunzhong Li, **Zhangliang Li**, Haoran Wang, Guorong Zhu, and Huai Wang, Multi-objective Optimization of Capacitor Bank Considering the Parasitic Parameters of Capacitors. 8th Renewable Power Generation Conference (RPG 2019), Shanghai.

IET Digital Library: Multi-objective Optimization of Capacitor Bank Considering the Parasitic Parameters of Capacitors

### **PATENTS**

- [1] The Revolute Joints of Industrial Robots (Patent No.: 202020837572.6)
- [2] A Balanced Training Platform that Combines Testing and Active-Passive Training (Patent No.: 201921748204.8)
- [3] Movement Detection of Patients During Weight Loss Training (Patent No.: 201921748053.6)

### **ADDITIONAL**

Language: Chinese (Native), English (Fluency)