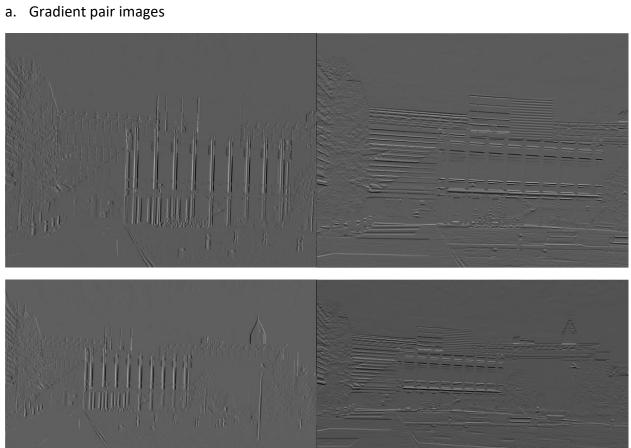
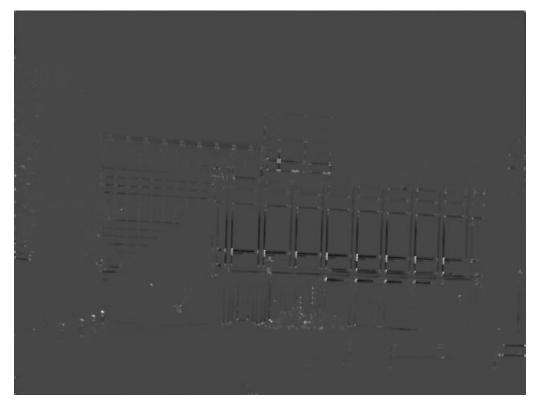
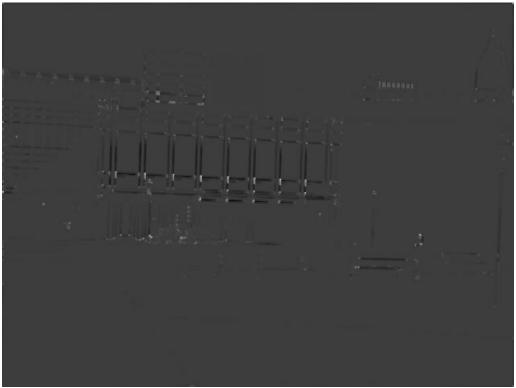
Homework Assignment 4: Harris, SIFT, RANSAC

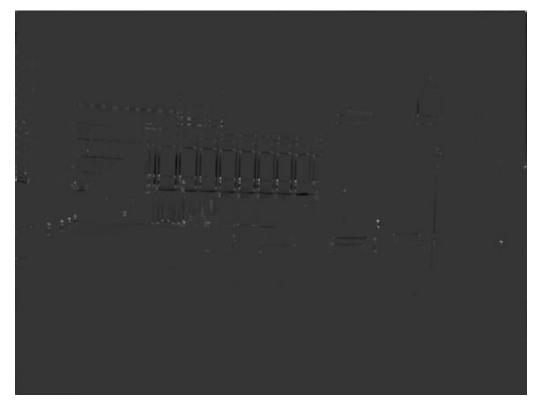
I. Harris corners



b. Harris value output image







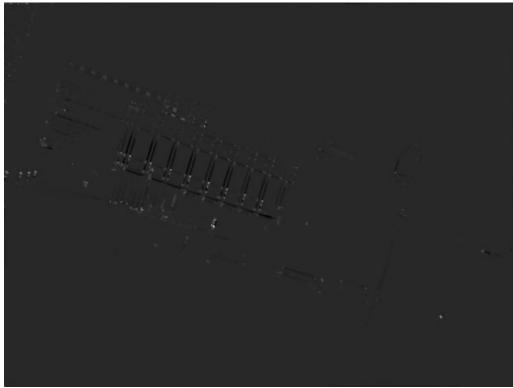
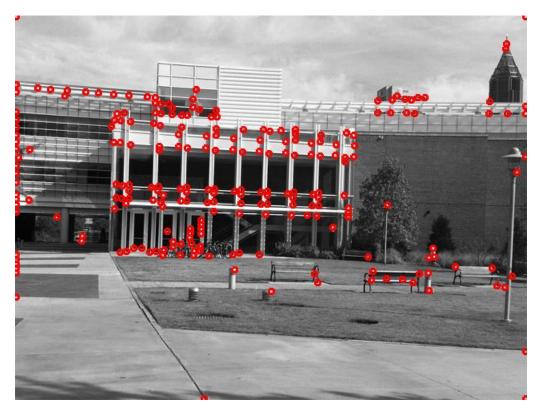


Image with marked Harris corners
Describe the behavior of your corner detector including anything surprising,
such as points not found in both images of a pair.

Corner detector finds a lot of similar points in both of the images. Corners that are located on the edges of an image are more easily located than the ones in the middle of an image, so each image find points on the edges of the image that aren't found in the transformed image. Additionally, in order to find approximately same number of points in the images, different threshold had to be used for each image (smaller threshold for similarity than translation). In this case, I set my thresholds to the following:

transA threshold = 0.35 * max_pixel_intensity transB threshold = 0.30 * max_pixel_intensity simA threshold = 0.25 * max_pixel_intensity simB threshold = 0.20 * max_pixel_intensity









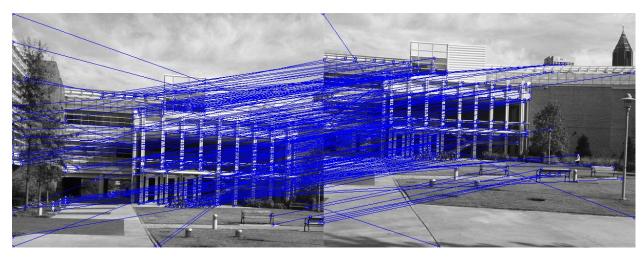
II. SIFT features

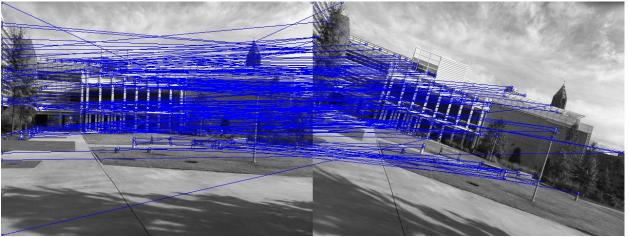
a. Interest points with angles shown





b. Putative pair image





III. RANSAC

a. Biggest consensus set lines drawn on translation pair
Threshold

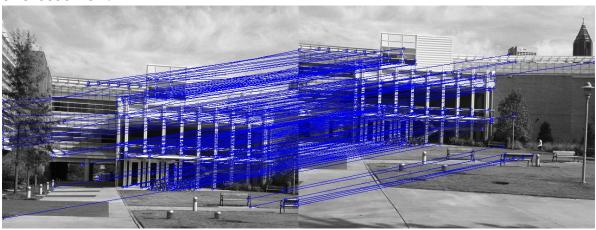
T = 200

What translation vector was used?

Best offset: [154 78]

What percentage of your matches was the biggest consensus set?

84.5493562232 %



b. Biggest consensus set lines drawn on similarity pair

Threshold

T = 1.5

What is the transform matrix for the best set?

Best similarity transform:

 $[[\ 0.97379613 \ -0.25874606 \ 36.03374949]$

[0.25874606 0.97379613 -55.04006036]]

What percentage of your matches was the biggest consensus set?

58.5585585586 %

