For this assignment, we did not expect student to give formal proofs, unless the question clearly said so. However, in these solutions, we are giving both an informal argument as well as a complete formal proof. As a result, the solutions are longer than necessary.

# Part 1: Both sequences a and b are concave.

(a)

To understand intuitively how concave sequences look like we give some examples of concave sequences in Figure 1 and some examples of sequences that are not concave in Figure 2.

Figure 1: Three concave sequences.

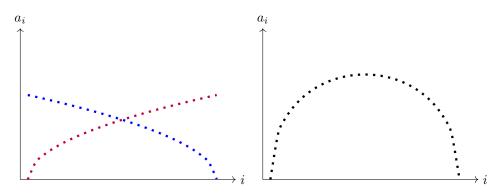
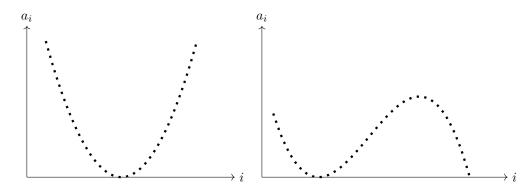


Figure 2: Two sequences that are not concave.



If both a and b are concave, we have

$$a_i - a_{i-1} \ge a_{i+1} - a_i \tag{1}$$

$$b_{k-i} - b_{k-i+1} \ge b_{k-i-1} - b_{k-i} \tag{2}$$

Adding (1) and (2) we get

$$a_{i} - a_{i-1} + b_{k-i} - b_{k-i+1} \ge a_{i+1} - a_{i} + b_{k-i-1} - b_{k-i}$$

$$(a_{i} + b_{k-i}) - (a_{i-1} + b_{k-i+1}) \ge (a_{i+1} + b_{i+1}) - (a_{i} + k - i - 1)$$

$$y_{i} - y_{i-1} \ge y_{i+1} - y_{i}$$

for  $1 \le i < n$ . Thus, the sequence  $y_i$  is also concave as a function of i.

**(b)** 

### 1. High Level Idea.

Computing  $v_k$  corresponds to finding the maximum of the sequence  $y_i = a_i + b_{k-i}$  for  $1 \le i < k$ . To find the maximum element of a sequence in general one needs to check all its elements (even if you read n-1 elements you still need to check whether the last one is the maximum). This lower bound holds when the sequence is arbitrary. Our sequence has *structure* which we can exploit to get an efficient search algorithm. We proved in the previous question that  $y_i$  is a concave sequence. How does a concave sequence look like? It can be increasing

or decreasing

or first increasing and then decreasing

Can it be first decreasing and then increasing?

The answer is no. In this case the minimum element of our sequence has greater elements both on its left and its right. Therefore, the concavity constraint is violated at the minimum.

Once a concave sequence starts decreasing it can never increase again. Suppose that we check element  $y_i$ : if  $y_{i+1}$  is smaller than  $y_i$  we are then sure that all elements right of  $y_i$  will also be smaller and therefore we do not have to check them. It only makes sense to continue our search for the maximum in the elements left of  $y_i$ . On the other hand if we find out that  $y_{i+1}$  is larger than  $y_i$  then we know that we are still in the increasing part of our sequence and therefore we need to check the elements right of  $y_i$ . This nice property suggests that we solve this problem recursively (divide and conquer). It remains to find a way to choose the point  $y_i$ . Since at each round we will be throwing away either the elements left of  $y_i$  or those on its right it makes sense to look at the middle point so that we throw away exactly half of the elements each time (exactly like binary search).

The algorithm FINDMAX uses these ideas to find the maximum element in a concave sequence. To compute  $v_k$  we call FINDMAX([0,...,k]).

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Algorithm 1 FINDMAX(i_{\ell}, i_{h}))
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Input: i_\ell, i_h, a, b

Output: The maximum value of the concave sequence y_i for i \in \{i_\ell, \dots, i_h\} if i_h - i_\ell \leq 2 then

\sqsubseteq Check all elements of the list and return the maximum. i = (i_h + i_\ell)/2 if y_i \geq y_{i-1} and y_i \geq y_{i+1} then
\sqsubseteq return y_i else if y_{i-1} < y_{i+1} then
\sqsubseteq return FINDMAX(i+1,i_h) else if y_{i-1} > y_{i+1} then
\sqsubseteq return FINDMAX(i_\ell, i-1)
```

### 2. Running Time.

The running time is: 
$$T(k) = T(k/2) + O(1) = O(\log k)$$

## 3. Correctness.

*Proof.* We have to prove that FINDMAX(0,k) correctly return  $v_k$ .

- Base Case: When  $k \leq 2$ ,  $i_h i_\ell \leq 2$  thus the algorithm run through each value then return the maximum value.
- Inductive Hypothesis: Assume that the algorithm return correctly when  $i_h i_\ell < n$
- Inductive Step: We have to prove that the algorithm also return correctly when  $i_{max} i_{min} = n$ .
  - $y_i \ge y_{i-1}$  and  $y_i \ge y_{i+1}$ : This implies that  $y_i$  is a local maxima on the sequence z. However, because the sequence  $y_i = a_i + b_{k-i}$  is also concave as a function of i,  $y_i$  is also the global maxima of the sequence. Thus, the algorithm return correctly.
  - $y_{i-1} < y_{i+1}$ : This implies that the sequence z is increasing at p i or the maximal value is on the right half of p i. Thus, it recursively calls the function for the right half of the remaining p which returns correctly (Inductive Hypothesis).
  - $y_{i-1} > y_{i+1}$ : Similar to the prior case, we recursively call the function to the left.

# Part 2: Only sequence b is concave while a is not.

Let's first argue that computing the value for a single k must take  $\Omega(k)$  time. Let's assume that we have an algorithm  $\mathcal A$  that takes as input the sequences a and b and computes  $v_k$ . Now consider an arbitrary sequence  $a_i$ . Can we use the algorithm  $\mathcal A$  to find the maximum element of  $a_i$ ? Yes, since we can set all elements of the sequence b to be 0. Then the constant sequence b is concave and  $b_i + a_{k-i} = a_{k-i}$ . Therefore, if we call  $\mathcal A$  with input lists  $b = (0, \dots, 0)$  and a it will simply return the maximum element of a. We showed that  $\mathcal A$  solves the problem of finding the maximum element in an arbitrary sequence. Does this imply anything about the running time of  $\mathcal A$ ? We already discussed in Part 1 that finding the maximum element in an arbitrary sequence of length k requires O(k) time since we have to check all its elements. Therefore, the running time of any such algorithm  $\mathcal A$  is  $\Omega(k)$ .

(a)

We will first introduce some convenient notation for this problem. Let  $y_i^k = a_i + b_{k-i}$ , that is  $y_i^k$  is the *total* value we obtain when we use i pounds on pixie dust and k-i pounds on dragon scales. Recall that in this problem we defined i(k) to be the *largest* index i that maximizes the sequence  $y_i^k$ . We want to prove that the sequence i(k) increases with k.

To prove our claim we first need to understand how the sequence  $y_i^k$  behaves as k increases. It makes sense to look at difference  $y_i^{k+1} - y_i^k$ ; we keep the amount of pounds that we use on pixie dust constant (=i) and use k+1-i pounds instead of k-i pounds on dragon scales. Since we spend the same amount on pixie dust, using this difference we just check whether spending more on dragon scales increases the total value. Indeed we have

$$y_i^{k+1} - y_i^k = a_i + b_{k+1-i} - a_i - b_{k-i} = b_{k+1-i} - b_{k-i}.$$

Now to prove that i(k+1) is greater than i(k), it suffices to show that in going from k to k+1, z increases more at index i(k) than at any index smaller than i(k). Then,  $y^{k+1}$  is still larger at i(k) than at any index smaller than i(k). Formally, we will show that for any j < i(k),

$$y_j^{k+1} - y_j^k \le y_{i(k)}^{k+1} - y_{i(k)}^k. \tag{3}$$

This will imply

$$y_j^{k+1} \le y_{i(k)}^{k+1} - (y_{i(k)}^k - y_j^k) \le y_{i(k)}^{k+1},$$

where for the second inequality we used the fact that  $y_{i(k)}^k - y_j^k \ge 0$  since  $y^k$  is maximum at i(k). We rewrite inequality (3) that we want to prove

$$y_j^{k+1} - y_j^k \le y_{i(k)}^{k+1} - y_{i(k)}^k$$

$$a_j + b_{k+1-j} - (a_j + b_{k-j}) \le a_{i(k)} + b_{k+1-i(k)} - (a_{i(k)} + b_{k-i(k)})$$

$$b_{k+1-j} - b_{k-j} \le b_{k+1-i(k)} - b_{k-i(k)}$$

$$(4)$$

Now this last inequality resembles the definition of a concave sequence. The only problem is that the definition has adjacent indices:  $b_{i+1} - b_i \le b_i - b_{i-1}$ . Let  $\delta(i) := b_{i+1} - b_i$ . From the definition of concavity we see that  $\delta(i)$  is a decreasing function i of i. Therefore if  $\ell \ge j$  we have

$$b_{\ell+1} - b_{\ell} \le b_i - b_{i-1}. \tag{5}$$

Now notice that in inequality (4) we have that i(k) > j and therefore k - i(k) < j - i(k). Now by equation (5) we conclude that

$$b_{k+1-j} - b_{k-j} \le b_{k+1-i(k)} - b_{k-i(k)}.$$

Therefore, inequality (3) is true and the proof is complete.

**(b)** 

## 1. High Level Idea.

Using the fact that i(k) is non-decreasing as a function of k, we will reduce the size of the problem by dividing it into smaller subproblems. Sometimes one can guess the general idea of an algorithm by its time complexity. It is very useful to be able to roughly guess what an algorithm does just by looking at its time complexity. In this case the required bound on running time suggests that we should try a merge sort type recursive structure. The high level idea is to compute  $v_k$  (and therefore also i(k)) for some value of  $k \in \{0, \ldots, n\}$  and partition the computation of the rest of the  $v_j$ 's into two subproblems, one that computes  $v_1, \ldots, v_{k-1}$  and one that computes  $v_{k+1}, \ldots, v_n$ . Importantly, we want the inputs to these subproblems to be smaller than the input of the original problem. We now examine which parts of the initial lists a, b are relevant to these subproblems. In what follows we use the subscripts h and  $\ell$  as abbreviations of the words high and low. We start with two subproblems, that we solve recursively:

- $P_h$ : Compute  $v_j$  for  $j = k+1, \ldots, n$ . Using the monotonicity of i(k) we get that to compute these  $v_j$  we only need the lists  $A_h = [a_{i(k)}, \ldots, a_n]$  and  $B_h = [b_0, \ldots, b_{n-i(k)}]$ .
- $P_{\ell}$ : Compute  $v_j$  for  $j=0,\ldots,k-1$ . Again from the monotonicity of i(k) we get that to compute these  $v_j$  we only need  $A_{\ell}=[a_0,\ldots,a_{i(k)}]$  and  $B_{\ell}=[b_0,\ldots,b_{k-1}]$ .

Observe that to compute  $v_k$  each element of list a gets paired with exactly one element of list b. Therefore, naively computing any  $v_j$  of subproblem  $P_h$  requires  $O(\operatorname{length}(A_h))$  time, while computing any  $v_j$  of subproblem  $P_\ell$  requires  $O(\operatorname{length}(A_\ell))$  time. The lengths of the lists  $B_\ell$ ,  $B_h$  do not affect the running time of the subproblems, and therefore we can ignore them.

Algorithm FINDALL uses the above ideas to solve this problem. To find all the  $v_k$  for  $k=1,\ldots,n$  we call FINDALL(0,n,0,n). To simplify notation we do not include the lists a,b in the arguments of algorithm FINDALL. Therefore, we can express the running time informally as

$$T(n) = T(\operatorname{length}(A_{\ell})) + T(\operatorname{length}(A_{h})) + O(n)$$

At this point we note that it is not necessarily the case that  $\operatorname{length}(A_\ell) = \operatorname{length}(A_h) = n/2$ , even if we choose k = n/2. However, we have that  $\operatorname{length}(A_\ell) + \operatorname{length}(A_h) = n+1$ , which suggests that we are doing linear amount of work at every level of recursion. In order to bound the number of levels of recursion we choose k = n/2 (that is we halve the range of  $v_j$  to be computed at each round).

<sup>&</sup>lt;sup>1</sup>The (discrete) derivative of a concave function is a decreasing function.

#### 2. Correctness.

As we discussed above, since we decide which parts of the list a to keep for each subproblem using the monotonicity of i(k), the correctness of algorithm FINDALL follows from Question 4.

### 3. Running Time.

To upper bound the running time of Algorithm FINDALL, notice that we have  $\log_2(n)$  levels of recursion. At any level, the total amount of work done is O(1) times the sum of the lengths of the sublists of list a in recursive calls at that level. We would like to have that this sum of the lengths is O(n) for all levels of recursion. We already saw that for the first two subproblems we have

$$\operatorname{length}(A_{\ell}) + \operatorname{length}(A_h) = n + 2.$$

It is not exactly n+1 because  $a_{i(k)}$  appears in both  $A_\ell$  and  $A_h$ . Observe that at each level the two sublists of a that are created can share at most one element  $^2$ . At the i-th level of recursion of Algorithm FINDALL we have  $2^i$  subproblems. Therefore the number of repetitions is upper bounded by  $2^i-1$  (this is the case where all but the "lowest" and "highest" subproblems share one element). Therefore the sum of the lengths of the sublists of all  $2^i$  subproblems is upper bounded by

length(a) + 
$$(2^i - 1) \le 2(n+1)$$
,

since the maximum number of subproblems is n (at level  $i = \log n$ ). Since we do O(n) work  $\log n$  times we conclude that the overall running time is  $O(n \log n)$ .

**Algorithm 2** FINDALL $(p_{\ell}, p_h, k_{\ell}, k_h)$ 

**Input:**  $p_{\ell}, p_h, k_{\ell}, k_h, a, b$ 

**Output:** The entire sequence  $v_k = \max_{i \in \{p_\ell, \dots, p_h\}} a_i + b_{k-i}$  for all  $k \in \{k_\ell, \dots, k_h\}$ 

if  $k_h = k_\ell$  then

 $k = (k_h + k_\ell)/2$ 

Manually find the largest index i(k) that maximizes the sum  $a_i + b_{k-i}$  for all  $i \in \{p_\ell, ..., p_h\}$ 

return [FINDALL $(p_{\ell}, i(k), k_{\ell}, k-1), a_{i(k)} + b_{k-i(k)},$  FINDALL $(i(k), p_h, k+1, k_h)$ ]

<sup>&</sup>lt;sup>2</sup>this is because i(k) is just increasing and not strictly increasing