

## Nondeterministic Finite Automata

*Nondeterminism* is an abstraction which allows us to consider extensions of ordinary computation. We allow simultaneous execution paths, and accept if *at least one* path is an accepting path.

Ways to think about this:

- Concurrent (parallel) executions
- Execution tree
- “Guessing” an accepting computation

Questions: Can nondeterminism be eliminated with no loss of expressive power? What is the cost?

## NFA – Example

To model nondeterminism, transitions go from states to *sets of states*. Also, allow  $\epsilon$ -*transitions* that do not consume any input.

$q_1$  is the start state and  $q_4$  is the only accept state.

	0	1	$\epsilon$
$q_1$	$\{q_1\}$	$\{q_1, q_2\}$	$\emptyset$
$q_2$	$\{q_3\}$	$\emptyset$	$\{q_3\}$
$q_3$	$\emptyset$	$\{q_4\}$	$\emptyset$
$q_4$	$\{q_4\}$	$\{q_4\}$	$\emptyset$

## NFA Examples

- All strings over  $\{0, 1\}$  containing a 1 in the next-to-last position.
- Using  $\epsilon$  for OR.
- Another example:

	a	b	$\epsilon$
$q_1$	$\emptyset$	$\{q_2\}$	$\{q_3\}$
$q_2$	$\{q_2, q_3\}$	$\{q_3\}$	$\emptyset$
$q_3$	$\{q_1\}$	$\emptyset$	$\emptyset$

where  $q_1$  is the start state and the only accept state.

## Formal Definition

A *nondeterministic finite automaton (NFA)* is a 5-tuple  $M = (Q, \Sigma, \delta, q_0, F)$ , where

- $Q$  is a finite set of *states*,
- $\Sigma$  is a finite alphabet,
- $\delta : Q \times (\Sigma \cup \{\epsilon\}) \rightarrow \mathcal{P}(Q)$  is the *transition function*, i.e.,  $\delta(q, a) \subseteq Q$  where  $q, q' \in Q$  and  $a \in \Sigma \cup \{\epsilon\}$
- $q_0 \in Q$  is the *start state*,
- $F \subseteq Q$  is the set of *accept states* or *final states*.

## Formal Definition of Computation

Let  $N = (Q, \Sigma, \delta, q_0, F)$  be a finite automaton and let  $w = w_1w_2...w_n$  be a string over  $\Sigma$ .

Then  $N$  *accepts*  $w$  if we can write  $w = y_1y_2...y_m$  where each  $y_i \in \Sigma \cup \{\epsilon\}$  and there is a sequence of states  $r_0, ..., r_m$  in  $Q$  s.t.

1.  $r_0 = q_0$
2.  $r_{i+1} \in \delta(r_i, y_{i+1})$
3.  $r_m \in F$

## Language Recognized by an NFA

The language of the machine  $M$  is the set  $L$  of all strings the language accepts. We write  $L(M) = L$  and say  $M$  *accepts (or recognizes)*  $L$ . If the machine  $M$  accepts no strings then  $L(M) = \emptyset$ .

## Converting NFA's to DFA's

Two DFA's or NFA's  $M_1$  and  $M_2$  are *equivalent* if  $L(M_1) = L(M_2)$

**Theorem** For every NFA, there is an equivalent DFA

**Proof** Given an NFA  $N = (Q, \Sigma, \delta, q_0, F)$ , we want to construct a DFA  $D = (Q_D, \Sigma, \delta_D, q'_0, F_D)$  with  $L(N) = L(D)$ .

- *Basic idea*: states of DFA correspond to *sets* of states in NFA
- Current “set” of states = all states reachable from start state using input seen so far
- We start with the easier case of assuming there are no  $\epsilon$  transitions in the NFA.

## Defining $D$

- Alphabet is unchanged
- $Q_D$  is defined to be  $\mathcal{P}(Q)$ , i.e., the set of all subsets of  $Q$
- $F_D$  is simply the set of all states in  $Q_D$  which contain (as sets) some state in  $F$ , i.e.

$$F_D = \{S \subseteq Q \mid S \cap F \neq \emptyset\}$$

- The start state is  $\{q_0\}$ .
- What about  $\delta_D$ ?



## Defining the Transition Function

- Idea: To determine  $\delta_D(S, a)$ , look at all the states  $p \in S$  and see what states  $N$  takes  $p$  to, and then take their union.
- $\delta_D(S, a) = \bigcup_{p \in S} \delta(p, a)$

## Example 1

Consider the following NFA.

$N = (Q, \Sigma, \delta, q_0, F)$  where  $Q = \{q_0, q_1, q_2, q_3, q_4, q_5\}$

$\Sigma = \{0, 1\}$ ,

$F = \{q_3\}$ , and

$\delta$  is specified by the following transition table:

$q$	0	1
$q_0$	$\{q_0, q_1\}$	$\{q_0, q_4\}$
$q_1$	$q_2$	$\emptyset$
$q_2$	$q_3$	$\emptyset$
$q_3$	$q_3$	$q_3$
$q_4$	$\emptyset$	$q_5$
$q_5$	$\emptyset$	$q_3$

## Generating the Corresponding DFA

- How many possible states?
- Do we really need to generate every possible state?
  - Only need to consider states that are reachable for some input.
- Use *lazy evaluation*
  - The start state is always reachable.
  - At a given step, add states reachable in one step from current states.
  - When can we stop? When we no longer discover new states.

## Converting a DFA into an Equivalent NFA

- If  $\delta_D(p, a) = q$  then set  $\delta_N(p, a) = \{q\}$ .
- Conclude: A language is accepted by a DFA iff it is accepted by an NFA without  $\epsilon$  transitions.

## Adding $\epsilon$ transitions

- For any state  $S \in Q_D$ , let  $E(S)$  denote the set of states already in  $S$  or that can be reached from some state  $r \in S$  by traveling along one or more  $\epsilon$  arrows.
- Now, we modify  $\delta_D$ :
  - $\delta_D(S, a) = \bigcup_{r \in S} E(\delta(r, a))$
- The new start state is  $E(\{q_0\})$ .

## Correctness of the Construction

- Why does this work? At every step the state of the DFA constructed contains exactly all the states of the NFA that it could be in so far. In particular, if it could be in an accept state at the end of the computation, then it will be in an accept state at the end of the DFA computation.
- Note: this can be formalized by an induction argument.
- **Corollary:** A language is regular iff some NFA with  $\epsilon$ -transitions recognizes it.

## Example: Converting an NFA into a DFA

Another example:

	$a$	$b$	$\epsilon$
$q_1$	$\emptyset$	$\{q_2\}$	$\{q_3\}$
$q_2$	$\{q_2, q_3\}$	$\{q_3\}$	$\emptyset$
$q_3$	$\{q_1\}$	$\emptyset$	$\emptyset$

where  $q_1$  is the start state and the only accept state.

## Applications of Nondeterminism: Closure under Union

1. Add new start state with  $\epsilon$  arrows to both original start states.
2. Modify  $\delta$  accordingly.
3. Accept states = union of previous accept states.



## Closed under Concatenation

## Closed under Star