CS2810 Mathematics of Data Models	Gold
Spring 2019	January 30, 2019

#### Homework 03

**Due:** February 6, 9PM

Point total: 60

#### **Instructions:**

• Submit your PDF and/or .py file to Blackboard by the due date and time. Please do not zip your files together, as this interferes with Blackboard's preview functionality. Always show all your work, and for full credit, you must use the method that the problem instructs you to use (unless none is mentioned). Handwritten or typeset solutions are both acceptable, but unreadable submissions will be penalized. You may discuss problems with other students, but you may not write up solutions together, copy solutions from a common whiteboard, or otherwise share your written work or code. Do not use code or language that is copied from the Internet or other students; attribute the ideas and rephrase in your own words.

### Problem 1 (12 points, 4 each)

For each matrix, find the rank of each matrix using Gauss-Jordan elimination; then also report the number of dimensions in the kernel and the number of dimensions in the range space.

i. 
$$\begin{bmatrix} 1 & 2 & 1 \\ 3 & 1 & -1 \\ 8 & 6 & 0 \end{bmatrix}$$

<u>Solution</u>: rank 2 (the third row is a linear combination of the previous two), thus dimensions of kernel and range space are 3-2=1 and 2, respectively

ii. 
$$\begin{bmatrix} 2 & 2 & 3 & 4 \\ 5 & 1 & -1 & 0 \\ 0 & -2 & 1 & 2 \\ 3 & 4 & 1 & 1 \end{bmatrix}$$

<u>Solution:</u> rank 3 (Gauss-Jordan elimination produces a matrix in reduced echelon form with 3 leading 1's), thus dimensions of kernel and range space are 4-3=1 and 3, respectively

iii. 
$$\begin{bmatrix} 1 & 2 & 3 & 4 \\ 3 & 6 & 9 & 12 \\ 9 & 18 & 27 & 36 \end{bmatrix}$$

<u>Solution:</u> rank 1 (rows 2 and three are just multiples of row 1; the same is true for the columns), thus dimensions of kernel and range space are 4-1=3 and 1, respectively

#### Problem 2 (10 points, 2 each)

For each matrix, find the two-sided inverse, or explain how you know there isn't one. (You may wish to check your work with a matrix multiplication.)

$$\mathbf{i.} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{bmatrix}$$

Solution: 
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}$$
 (these are the rotation matrices for  $\pi/2$  and  $-\pi/2$ )

ii. 
$$\begin{bmatrix} 1 & 3 \\ 2 & 9 \end{bmatrix}$$

Solution: 
$$\begin{bmatrix} 3 & -1 \\ -2/3 & 1/3 \end{bmatrix}$$

iii. 
$$\begin{bmatrix} 1 & 2 & 3 \\ 3 & 6 & 8 \\ 4 & 8 & 11 \end{bmatrix}$$

<u>Solution:</u> No inverse because the rows aren't linearly independent (the third is the sum of the first two). Of course, that means the columns aren't either (the second is a multiple of the first).

$$\mathbf{iv.} \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

<u>Solution:</u> The matrix is its own inverse. This is a permutation that switches items 1 and 2, and items 3 and 4; applying the permutation again switches them back.

$$\mathbf{v.} \begin{bmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \\ 3 & 3 & 3 \end{bmatrix}$$

<u>Solution:</u> Gauss-Jordan reveals this matrix has rank 2, so it has no inverse. (Alternately: summing the first two rows gives [4 4 4], a multiple of the third.)

## Problem 3 (9 points, 3 each)

In each case, project  $\vec{v}$  onto the line that is the span of  $\vec{s}$  to get  $\text{proj}_{\vec{s}}v$ . Then, subtract to find the component of  $\vec{v}$  orthogonal to that line.

**i.** 
$$\vec{v} = \begin{bmatrix} 1 \\ 4 \end{bmatrix}, \vec{s} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

Solution:  $\vec{v} \cdot \vec{s} = 9, \vec{s} \cdot \vec{s} = 5$ , so c = 9/5 and the projection is  $\begin{bmatrix} 9/5 \\ 18/5 \end{bmatrix}$  with orthogonal component  $\begin{bmatrix} 1 \\ 4 \end{bmatrix} - \begin{bmatrix} 9/5 \\ 18/5 \end{bmatrix} = \begin{bmatrix} -4/5 \\ 2/5 \end{bmatrix}$  (Notice that we can check that this component is orthogonal with a dot product. The projection is very likely to be correct as well if this checks out.)

ii. 
$$\vec{v} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \vec{s} = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}$$

Solution: 
$$\vec{v} \cdot \vec{s} = 1, \vec{s} \cdot \vec{s} = 3$$
, so  $c = 1/3$  and the projection is  $\begin{bmatrix} 1/3 \\ 1/3 \\ -1/3 \end{bmatrix}$ . That makes the

orthogonal part 
$$\begin{bmatrix} 1\\1\\1 \end{bmatrix} - \begin{bmatrix} 1/3\\1/3\\-1/3 \end{bmatrix} = \begin{bmatrix} 2/3\\2/3\\4/3 \end{bmatrix}$$

iii. 
$$\vec{v} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \vec{s} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$

Solution: 
$$\vec{v} \cdot \vec{s} = 6$$
,  $\vec{s} \cdot \vec{s} = 3$ , so  $c = 6/3 = 2$  and the projection is  $\begin{bmatrix} 2 \\ 2 \\ 2 \\ 0 \end{bmatrix}$  with orthogonal part

$$\vec{v} - \vec{v'} = \begin{bmatrix} -1\\0\\1\\4 \end{bmatrix}$$

# Problem 4 (11 points [4, 4, 3])

i. Which weights (if any) can change in a perceptron in response to a training input with all zeroes for features  $(\vec{0})$ ? Why can't the others change?

<u>Solution:</u> The bias can change, but the others can't, because the perceptron learning rule multiplies the size of the change by the value of the input feature.

ii. Suppose we would like to have a perceptron that responds TRUE (1) to the binary input

pattern 
$$\begin{bmatrix} 1\\0\\1\\0 \end{bmatrix}$$
, and FALSE to all other binary inputs. (We don't care about its behavior

for inputs that are not vectors of 1's and 0's.) Give the parameters  $w_1, \ldots, w_4, b$  for a 4-input perceptron that will respond TRUE to this input and false to all other binary inputs. (Assume the underlying function is of the form  $w_1x_1 + \ldots + w_4x_4 + b \ge 0$ .) Just the five working parameters are necessary; you don't need to show that they can be learned.

<u>Solution:</u> The weights 1, -1, 1, -1 and bias -2 will ensure that the perceptron only fires when the two desired bits are active, and the other two bits aren't.

iii. Suppose I have a machine learning problem where the most relevant feature is an angle in the range  $[-\pi/2, \pi/2]$ . The perceptron ultimately should return TRUE only for examples

3

in the range  $[-\pi/4, \pi/4]$ , and FALSE for all other examples. Unfortunately, a single linear classifier can't have both an upper and lower threshold, so it won't be able to learn that range. Suggest a trigonometric function that I can apply to this feature before presenting it to the perceptron, so that the modified input is now linearly separable.

<u>Solution</u>: If I take the cosine of this feature, the desired concept just becomes "value greater than  $\sqrt{2}/2$ " which is something the perceptron can learn.

#### Problem 5 (18 points)

For this part, download perceptron.py. You'll fill in the learning function that adapts the perceptron to the data.

To help visualize the data, we'll work with some three-dimensional data: color values, which are triples of (red, green, blue). The goal will be to train a perceptron classifier to respond "yes" (1) to gold or yellow colors, and "no" (0) to other colors. Since perceptrons can only represent linear decision surfaces - in this case, a plane - it will not be able to classify points with 100% accuracy; we'll shoot for simply having accuracy in excess of 70%.

The representation of the perceptron is just 4 numbers in a list, [a, b, c, d]. They represent the decision function  $ax + by + cz + d \ge 0$ , where (x, y, z) is the color triple of the input.

First, fill in the function perceptron\_predict(). This function takes a perceptron [a, b, c, d] and a color value (x, y, z), and returns 1 if  $ax + by + cz + d \ge 0$ , and 0 otherwise. (This won't work very well as a predictor before training.)

Then fill in the function perceptron\_learn(). This function should take a 4-element list representing a perceptron, a training example (color triple), a classification (1 for gold, 0 for otherwise), and a learning rate which you should just set to 0.01. If the perceptron's prediction matches the true classification, nothing should happen, and the function should just return the perceptron unchanged. But if the perceptron was wrong, apply the perceptron learning rule covered in class, and return a new perceptron.

It's often a good idea in machine learning to go through the training data in a random order, as well as to scale all the values to lie in [0,1]; but this code has already been written for you as a part of the create\_data() function. In addition, I've written some matplotlib code to show you graphically what your perceptron's decision surface looks like. Once you're done, the following sequence of commands should serve to show you the perceptron's decision surface both before and after training.

```
import perceptron
ptron = perceptron.new_perceptron()
examples, classes = perceptron.create_data()
perceptron.plot_everything(ptron, examples)
ptron = perceptron.perceptron_train(ptron, examples, classes, 0.01, 100)
perceptron.plot_everything(ptron, examples)
```

The colors of the points are the actual colors of those triples. You should see gold points mostly on one side of your plane, and the other colors mostly on the other.

Submit your .py code along with your assignment PDF.