

Zhaoyang Li

 6083205509

 zhl165@ucsd.edu

 LinkedIn

 Github

 Homepage

Education

MS University of California San Diego

Sep 2023 - Jun 2025

- Electrical and Computer Engineering (Intelligent Systems, Robotics & Control)

BS University of Wisconsin-Madison,

Jan 2021 - May 2023

- **Double Major** in Computer Science & Mathematics

Research Interests

My research focuses on developing embodied agents that perceive, reason, and act in the physical world. I work at the intersection of **multimodal learning**, **robot learning**, **vision-language-action (VLA) integration**, and **preference alignment**, with a focus on **(1).** improving the robustness of vision-language models and their applications, **(2).** developing efficient control and planning policies, **(3).** integrating VLA systems into unified embodied agents, and **(4).** aligning agent behavior with human intentions through feedback and preferences. Ultimately, I aim to build reliable, interpretable agents that generalize to real-world environments.

Publications & Preprints

* indicates equal contributions.

1. **Zhaoyang Li***, Zhan Ling*, Yuchen Zhou, Litian Gong, Erdem Biyik, Hao Su. "ORIC: Benchmarking Object Recognition under Contextual Incongruity in Large Vision-Language Models.", in Proceedings of the IEEE / CVF Computer Vision and Pattern Recognition Conference (**CVPR**) [\[Paper\]](#) [\[Code\]](#) [\[Code\]](#)
2. **Zhaoyang Li**, Sushaanth Srinivasan, Ninad Ekbote, Pengtao Xie. "A Multi-modal Large Language Model for Predicting Mechanisms of Drug Interactions." Submitted to **Nature Biomedical Engineering**.
3. Tongzhou Mu*, **Zhaoyang Li***, Stanisław Wiktor Strzelecki*, Xiu Yuan, Yunchao Yao, Litian Liang, Aditya Gulati, Hao Su. "When Should We Prefer State-to-Visual DAgger Over Visual Reinforcement Learning?", in Proceedings of the AAAI Conference on Artificial Intelligence (**AAAI**), 2025 [\[Paper\]](#) [\[Code\]](#) [\[Code\]](#)
4. Yifei Zhang, Yusen Jiao, Jiayi Chen, **Zhaoyang Li**, Huaxiu Yao, Jieyu Zhang, Frederic Sala. "Just Select Twice: Leveraging Low-Quality Data to Improve Data Selection.", ATTRIB Workshop at **NeurIPS 2024**; extended version in submission. [\[Paper\]](#) [\[Code\]](#)

Research Experience & Project

Bayesian Flow Networks for Robotic Manipulation (Project Lead)

Advisor: Prof. Erdem Biyik, USC

Dec 2025 – present
Los Angeles, CA

- Investigating Bayesian Flow Networks as a generative modeling framework for robotic manipulation, with a focus on uncertainty-aware action generation.
- Designed and implemented simulation experiments in Push-T and RoboMimic, and real-world evaluations on Push-T and object insertion tasks using the WidowX robot.
- Project ongoing; targeting submission to the International Conference on Intelligent Robots and Systems (IROS) 2026.

Contextual Override in VLA Agents: Analysis and Mitigation (Project Lead)

Advisor: Prof. Erdem Biyik, USC

Sep 2025 – present
Los Angeles, CA

- Identified contextual override in VLA agents, where scene affordances dominate language instructions.
- Proposed a conflicting-affordance benchmark and mitigated bias via reward-model fine-tuning (DROID, LIBERO).
- Project ongoing; targeting submission to the International Conference on Intelligent Robots and Systems (IROS) 2026.

Context-Incongruity Robustness for Large Vision Language Models (Project Lead)

Advisor: Prof. Hao Su (UC San Diego); Prof. Erdem Biyik (USC)

- Developed ORIC to generate context-incongruous object-context data for training and evaluation, and built ORIC-Bench via dual LLM and CLIP sampling.
- Evaluated 18 LVLMs and 2 open-vocabulary detectors; improved Qwen3-VL-8B-Instruct with Visual-RFT on ORIC-style data for stronger human-aligned predictions.
- Submitted the extended ORIC study to CVPR 2026.

Aug 2024 - Sep 2025
San Diego, CA**Multi-modal Language Model for Drug Interaction Prediction (Project Lead)**

Advisor: Prof. Pengtao Xie; UC-San Diego

- Fine-tuned a multi-modal LLM with SMILES inputs to predict drug interaction status, degree, and mechanisms, integrating chemical informatics and NLP.
- Achieved strong performance: METEOR 0.42, BLEU-1 0.25, semantic similarity 0.57; outperforming GPT-4o (METEOR 0.16, BLEU-1 0.11, semantic similarity 0.30).

Dec 2024 - May 2025
San Diego, CA**Empirical Analysis of State-to-Visual (S2V) Imitation vs. Visual RL (Project Co-Lead)**

Advisor: Prof. Hao Su, UC-San Diego

- Benchmarked State-to-Visual DAgger vs. visual RL across 16 tasks from ManiSkill, DM-Control, and Adroit.
- Analyzed performance trade-offs, efficiency, and computational costs.
- Built a standardized S2V pipeline and derived practical recommendations.

Feb 2024 - Sep 2024
San Diego, CA**Simulation of the Connected and Automated Driving Systems**

Advisor: Prof. Bin Ran; The Connected Automated Vehicle Highway System Group

- Simulated and optimized traffic systems in CARLA, enhancing traffic management models for improved efficiency.
- Refined object detection algorithms, including YOLO and Faster R-CNN, to improve vehicle detection and traffic control systems.

Sep 2021 - May 2022
Madison, WI

Industry Experiences

Computer Vision Algorithm Engineer | Mech-Mind Robotics Technologies Ltd.

- Developed algorithms for structured light 3D cameras, improving image accuracy and optimizing point cloud reconstruction for laser systems.
- Led the refinement of internal camera distortion models, significantly enhancing imaging fidelity and calibration precision.

Jun 2023 - Sep 2023
Beijing, China

Teaching

Teaching Assistant at UW-Madison

- CS540: Introduction to Artificial Intelligence

Spring 2023

Peer Mentor at UW-Madison

- CS537: Introduction to Operating System

Fall 2022

Professional Services

Reviewer

- AAAI Conference on Artificial Intelligence
- AAAI Workshop: Large Language Models and Generative AI for Health

Technical Skills

- **Languages:** English (Proficient; TOEFL 108, GRE 330 + 3.5), Chinese (Native)
- **Programming:** Python, C++, C, Java, Matlab, R, LaTeX, SQL
- **ML and Vision Frameworks:** PyTorch, TensorFlow, OpenCV, scikit-learn, SimpleITK, SPM12, TorchIO
- **Simulation and Robotics:** CARLA, MuJoCo, ManiSkill, DMControl, RoboMimic, WidowX, Adroit.
- **Developer Tools:** VS Code, Vim, IntelliJ IDEA, Visual Studio, Git, Docker, Kubernetes