ROBT403 - Robotics II: Control, Modeling and Learning Lab sessions, 2021
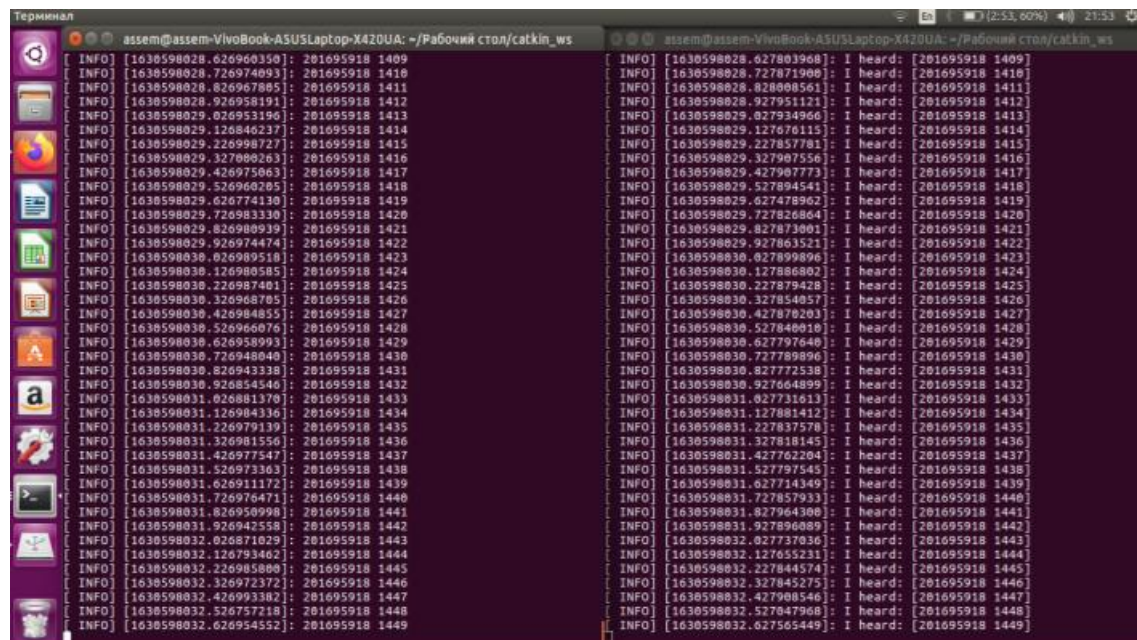
 Lab 2

1) What is ROS

2) Examples of robots that use ROS

3) Screenshots of the Publisher –Subscriber with the Topic name of your name that sends your NU id numbers one by one in the loop

1) The Robot Operating System (ROS) is an open-source framework that helps researchers and developers build and reuse code between robotics applications. ROS is also a global open-source community of engineers, developers and hobbyists who contribute to making robots better, more accessible and available to everyone.

2) TurtleBot, a mobile robotBaxter, A friendly two-armed robot, Crazygie and Bebop, flying robots.

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