

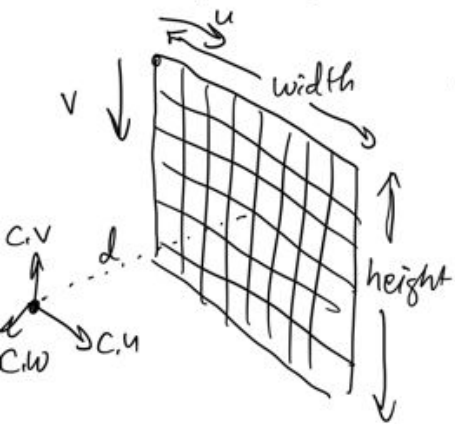
# CSC 317

Tutorial: Ray Casting

## src/viewing\_ray.cpp

- Output: ray.origin, ray.direction (in worldspace)
- Input:
  - (i, j): pixel index of the pixel we want to shoot a ray through
  - (height, width): pixel size of the image
  - (camera.height, camera.width): worldspace (physical) size of the image
  - camera.d: focal length (we want to make sure ray.direction lands on the image plane)
  - (camera.u, camera.v): camera axes oriented in worldspace
- Ray origin is at the camera location
  - Look at Camera.h
- Careful:
  - We want the ray going through the MIDDLE of the pixel (not the top left corner), need to have an offset

Viewing-ray :



Suppose we want  $(u, v)$  of the top-left corner.

$$u = -\frac{c.width}{2}$$

$$v = +\frac{c.height}{2}$$

Now, shift it by half a pixel to get  $(u, v)$  of the pixel  $(0, 0)$ :

$$u = -\frac{c.width}{2} + \underbrace{\frac{c.width}{width}}_{\text{pixel width}} * 0.5$$

$$v = +\frac{c.height}{2} - \underbrace{\frac{c.height}{height}}_{\text{pixel height}} * 0.5$$

Now, shift it by  $(i, j)$  pixels:  
Well, we already know pixel size so:

$$u = -\frac{c.width}{2} + \frac{c.width}{width} (j + 0.5)$$

$$v = +\frac{c.height}{2} - \frac{c.height}{height} (i + 0.5)$$

But  $u, v$  are scalars along the direction of  $c.u, c.v$   
(and  $c.d$  is along  $c.w$ )

So:

$$\text{direction} = -c.d * c.w$$

$$+ u * c.u$$

$$+ v * c.v$$

scalars      vectors

## src/first\_hit.cpp

- Output:
  - hit\_id: index of object first hit
  - t: parametric distance of the ray hit (ie  $\text{ray.origin} + t * \text{ray.direction}$  gives the surface hit)
  - n: surface normal at the location of first hit
  - return bool: if the ray hit any object (false if not)
- Input:
  - ray: ray to search
  - min\_t: minimum value of t to accept (culls surfaces behind and too close to the camera)
  - objects: list of objects in scene
- Loop through all the objects, call the object intersect with the ray, and see which object gives the smallest (greater than min\_t) t value
- Note: no actual intersection checks should be done here, just call the object intersects and compare

# src/Sphere.cpp

## Ray-Sphere Intersect

Implicit eqn of a sphere

$$(\bar{p} - \bar{c})^2 - r^2 = 0$$

$$(\bar{p} - \bar{c}) \cdot (\bar{p} - \bar{c}) - r^2 = 0$$

$$(\bar{e} + d\bar{t} - \bar{c}) \cdot (\bar{e} + d\bar{t} - \bar{c}) - r^2 = 0$$

$$\underbrace{(\bar{d} \cdot \bar{d})}_{a} t^2 + \underbrace{(2\bar{d} \cdot (\bar{e} - \bar{c}))}_{b} t + \underbrace{(\bar{e} - \bar{c}) \cdot (\bar{e} - \bar{c}) - r^2}_{c} = 0$$

$$at^2 + bt + c = 0$$

p = point  
c = center  
r = radius

## Quadratic Formula

$$t = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

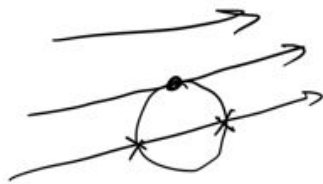
Discriminant

$$b^2 - 4ac$$

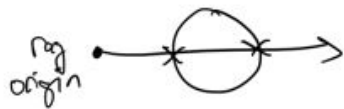
↳  $< 0 \Rightarrow$  no hits

↳  $= 0 \Rightarrow$  one hit

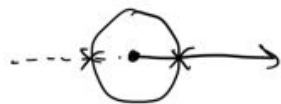
↳  $> 0 \Rightarrow$  two hits



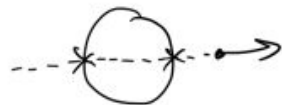
Note with two hits you have three cases:



both in front  
( $> \text{min}_t$ )



one in front



none in front

check  $t$  against  $\text{min}_t$ !

## src/Plane.cpp

### Ray - Plane Intersect

$\bar{p}_0$  : point  
on the plane  
 $\bar{n}$  : plane normal

$$(\bar{p} - \bar{p}_0) \cdot \bar{n} = 0$$

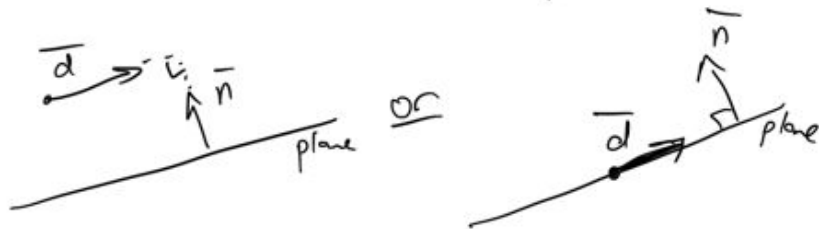
$$(\bar{e} + \bar{d}t - \bar{p}_0) \cdot \bar{n} = 0$$

solve for  $t$

$$\Rightarrow \bar{e} \cdot \bar{n} + (\bar{d} \cdot \bar{n})t - \bar{p}_0 \cdot \bar{n} = 0$$

$$\boxed{t = \frac{\bar{p}_0 \cdot \bar{n} - \bar{e} \cdot \bar{n}}{\bar{d} \cdot \bar{n}}}$$

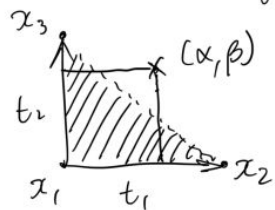
Note if  $\bar{d} \cdot \bar{n} = 0$  this is undefined!  
(either no hit or the  
camera is in the plane)



## src/Triangle.cpp

### Ray-Triangle Intersect

Canonical Triangle:



Any 3 corners  $x_1, x_2, x_3$   
form two vectors  
 $t_1, t_2$ .

$$\text{Then } \bar{p} = \alpha \bar{t}_1 + \beta \bar{t}_2$$

$$\bar{e} + d \bar{t} = \alpha \bar{t}_1 + \beta \bar{t}_2$$

$$\bar{e} = \alpha \bar{t}_1 + \beta \bar{t}_2 - d \bar{t}$$

unknown scalars

$$\begin{bmatrix} 1 & 1 & 1 \\ \bar{t}_1 & \bar{t}_2 & d \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ \bar{e} \\ 1 \end{bmatrix}$$

$$\text{Linear System } A \cdot x = b$$

Solve using eigen inverse

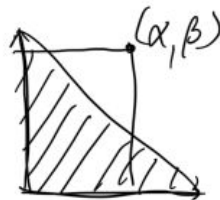
$$x = A \cdot \text{inverse} * b$$

Then Make sure  $\alpha \geq 0$

$$\beta \geq 0$$

$$\alpha + \beta \leq 1$$

$$t \geq \min_t$$



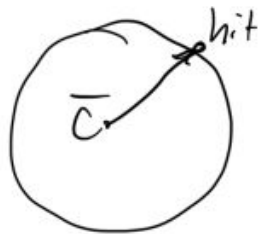
to check if the intersection is  
inside the triangle.

Note what happens if  $A$  is non-invertible?

# Normals

Normals

Sphere



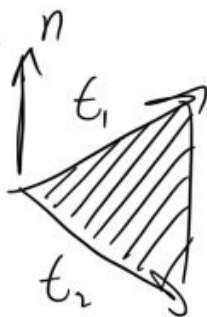
$$\frac{\text{hit} - \bar{c}}{\text{radius}}$$

↑  
normalize

Plane

plane normal (normalize just in case)

Triangle



$$\frac{\bar{t}_1 \times \bar{t}_2}{\|\bar{t}_1 \times \bar{t}_2\|}$$

↑  
normalize



## src/TriangleSoup.cpp

- Just call first hit on the list of triangles