## An Introduction to Generic Programming

## **Global Goals**

- I Become acquainted with the generic programming model
- I Develop and use template code in C++
- Learn main functionality in STL (Standard Template Library)
- Use Generic Programming together with OOP

## An Introduction to Generic Programming (GP)

- 1 OOP is based on classes, instances and inheritance
- I GP = data + algorithms
- 1 The data is generic
- In C++, we call it template programming
- ı STL, Boost, your own template classes

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#### What is OOP?

Classes and inheritance

Subtype polymorphism (virtual functions in base class)

- These are the interfaces requirements
- I Most C++ programmers know and use this technique

#### What is GP?

- Separates data structure and algorithms
- Use abstract requirements specification
- ı We can use parametric polymorphism
- ı Similar to Abstract Data Type (ADT) behaviour
- 1 Focus is on efficiency and compile-time behaviour

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## **Shape Hierarchy**

```
class Shape
{
public:
    virtual void draw() const = 0;
};

class Line : public Shape
{
public:
    void draw() const { cout << "Line" << endl; }
};

class Circle : public Shape
{
public:
    void draw() const { cout << "Circle" << endl; }
};</pre>
```

# **Subtype Polymorphism**

```
void draw(const list<Shape*>& v)
{
  cout << "\nSubtype polymorphism\n";
  list<Shape*>::const_iterator it;

  for (it = v.begin(); it != v.end(); ++it)
   {
    (*it)->draw();
  }
}
```

## Features of this Solution

- ı Traditional OO code
- Works with derived classes of Shape
- Run-time bahaviour (vtabl)
- Not highly reusable code

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## Valve Hierarchy

```
class Valve
{
public:
    virtual void draw() const = 0;
};

class BallValve: public Valve
{
public:
    void draw() const { cout << "Ball valve" << endl; }
};

class CheckValve: public Valve
{
public:
    void draw() const { cout << "Check valve" << endl; }
};</pre>
```

Parametric Polymorphism

### Features of this Solution

- Operates with any class that implements a draw function
- Simple example of a policy
- ı Compile-time behaviour
- Code is reusable, and it depends on standardised interface

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# Usage, Hierarchy I

```
cout << "\nNow printing Valves\n";
BallValve bv1;
CheckValve cv1;

vector<Valve*> network(2);
network[0] = &bv1;
network[1] = &cv1;
draw(network);
```

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## Usage, Hierarchy II

```
Line lin;
Circle cir;
cout << "\nNow printing shapes\n";
vector<Valve*> figure(2);
figure[0] = &lin;
figure[1] = &cir;
draw(figure);
```

# **Traditional Usage**

```
Line lin;
Circle cir;

// Now the traditional 00 approach
list<Shape*> figure2;
figure2.push_back(&lin);
figure2.push_back(&cir);
draw(figure2);
Using virtual function is slower than using template
```

## Comparing OOP and GP

- Virtual functions are slower than function templates
- Run-time dispatching or compile-time dispatching?
- Risk of code bloat with template-based programs
- Reusability: too much inheritance limits it

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## **Discovery and Documentation**

- Need to switch mindset from traditional OOP
- I Instead of inheritance hierarchies, think of contracts between ADTs
- Will formalise this process later
- I Document using UML components diagrams

#### OOP or GP?

- Can simulate inheritance with generics
- Can simulate genericity with inheritance (common in GOF patterns)
- Can mix the two paradigms using inheritance, aggregation
- I OOP support run-time subtype polymorphism, GP supports compile-time parametric polymorphism

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# Example Generic Function

```
template <typename N>
N Max(const N& x, const N& y)
{ // N is generic type
  if (x > y) return x;
  return y;
}
```

## **Using Template Function**

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### Remarks

- We can integrate OOP and GP in later modules
- ı Inheritance, aggregation and composition possible
- I Most developers feel comfortable with OOP
- I GP is necessary for the future