Documentation

Q2

$$V = mgh_1 + mgh_2 = -mg\ell(2\cos\theta_1 + \cos\theta_2),$$

$$T = \frac{1}{2}mv_1^2 + \frac{1}{2}mv_2^2 = m\ell^2 \left[\dot{\theta}_1^2 + \frac{1}{2}\dot{\theta}_2^2 + \dot{\theta}_1\dot{\theta}_2\cos(\theta_1 - \theta_2) \right],$$

Thus E=T+V to be

$$m\ell^2 \left[\dot{\theta}_1^2 + \frac{1}{2}\dot{\theta}_2^2 + \dot{\theta}_1\dot{\theta}_2\cos(\theta_1 - \theta_2) \right] - mg\ell(2\cos\theta_1 + \cos\theta_2).$$

- 2.2 just do the basic RK4 with 4 simultaneous equations and do the E+T+V
- 2.3 one wired thing is that if simply use code from 2.2 the r is not changing so I put it into a function and it generates the right Rs and then just do the animation, rate 450 seems to be a good rate for human to follow the motion and the motion is indeed chaotic.