## 并行与分布式计算基础:第七讲

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### 课程基本情况

• 课程名称: 并行与分布式计算基础

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#### 授课内容(暂定)

- 引言
- 硬件体系架构
- 并行计算模型
- 编程与开发环境
- MPI 编程与实践
- OpenMP 编程与实践
- GPU 编程与实践
- 前沿问题选讲

# 上课时间(地点: 二教 211)

上课时间	星期一	星期二	星期三	星期四	星期五
第1节(8:00-8:50)					
第 2 节 (9:00-9:50)					
第 3 节 (10:10-11:00)				单周	
第 4 节 (11:10-12:00)				单周	
第 5 节 (13:00-13:50)		每周			
第6节(14:00-14:50)		每周			
第7节 (15:10-16:00)					
第 8 节 (16:10-17:00)					
第 9 节 (17:10-18:00)					
第 10 节 (18:40-19:30)					
第 11 节 (19:40-20:30)					
第 12 节 (20:40-21:30)					

## 内容提纲

- ① MPI 基础知识回顾
- ② MPI 集合通信-1
- ③ MPI 集合通信-2
- 4 辅助函数

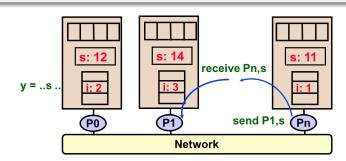
### MPI 基础知识回顾

- ① MPI 基础知识回顾
- ② MPI 集合通信-1
- ③ MPI 集合通信-2
- 4 辅助函数

### 什么是 MPI?

#### MPI = Message Passing Interface

- 是一组由学术界和工业界联合发展的、面向主流并行计算机的、标准化和可移植的消息传递接口标准;
- 适用于目前几乎所有主流并行计算机,已经成为事实上的工业标准;
- 每个进程拥有私有的存储空间,进程间只能通过消息传递通信;
- 程序往往采用 SPMD (single program multiple data) 方式编写。



### MPI 的六个基本函数

#### • 初始化/终止:

```
int MPI_Init(int *argc, char ***argv)
int MPI_Finalize()
```

#### • 获取进程信息:

```
int MPI_Comm_size(MPI_Comm comm, int *size)
int MPI_Comm_rank(MPI_Comm comm, int *rank)
```

#### • 发送/接收消息:

```
int MPI_Send(void *buf, int count, MPI_Datatype datatype, int
    dest, int tag, MPI_Comm comm)
int MPI_Recv(void *buf, int count, MPI_Datatype datatype, int
    source, int tag, MPI_Comm comm, MPI_Status *status)
```

### MPI 点对点通信

#### • 两个进程进行数据交换:

```
int MPI_Sendrecv(void *sendbuf, int sendcount, MPI_Datatype
   senddatatype, int dest, int sendtag, void *recvbuf, int
   recvcount, MPI_Datatype recvdatatype, int source, int recvtag,
   MPI_Comm comm, MPI_Status *status)
int MPI_Sendrecv_replace(void *buf, int count, MPI_Datatype
   datatype, int dest, int sendtag, int source, int recvtag,
   MPI_Comm comm, MPI_Status *status)
```

#### • 非阻塞 (non-blocking) 通信:

```
int MPI_Isend(void *buf, int count, MPI_Datatype datatype, int dest,
   int tag, MPI_Comm comm, MPI_Request *request)
int MPI_Irecv(void *buf, int count, MPI_Datatype datatype, int
   source, int tag, MPI_Comm comm, MPI_Request *request)
```

#### request 变量用来标记通信任务。

## 非阻塞通信状态的检测与控制

• 取消非阻塞通信:

```
int MPI_Cancel(MPI_Request *request)
```

• 检测非阻塞通信是否已经结束 (flag 值为 0 表示未结束):

• 等待非阻塞通信结束:

```
int MPI_Wait(MPI_Request *request, MPI_Status *status)
int MPI_Waitall(int count, MPI_Request requests[], MPI_Status
    statuses[])
int MPI_Waitany(int count, MPI_Request requests[], int *index,
    MPI_Status *status)
```

## 使用非阻塞通信避免死锁

• 使用非阻塞发送避免死锁:

```
Process: 0

isend(a, 10, 1, tag1, &req1)
isend(b, 10, 1, tag2, &req2)
...

wait(&req1, &sta1)
wait(&req2, &sta2)

Process: 1
recv(b, 10, 0, tag2)
recv(a, 10, 0, tag1)
```

• 或者, 使用非阳塞接收避免死锁:

```
Process: 0
send(a, 10, 1, tag1)
send(b, 10, 1, tag2)

Process: 1
irecv(b, 10, 0, tag2, &req1)
irecv(a, 10, 0, tag1, &req2)
...
wait(&req1, &sta1)
wait(&req2, &sta2)
```

## MPI 墙钟时间

• 返回当前进程的时钟时间:

```
double MPI_Wtime()
```

• 用法:

```
1 ...
2 t0 = MPI_Wtime();
3 ... // do some works
4 t1 = MPI_Wtime();
5 ...
```



• 返回 MPI\_Wtime 的时钟刻度:

```
double MPI_Wtick()
```

## MPI 集合通信-1

- ① MPI 基础知识回顾
- ② MPI 集合通信-1
- ③ MPI 集合通信-2
- 4 辅助函数

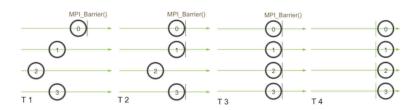
## MPI 集合通信 (collective communication) 概述

- MPI 集合通信是指涉及到通信器中所有进程的通信,有三类:
  - ▶ 同步 (synchronization): barrier 等;
  - ▶ 数据移动: broadcast, scatter/gather, all to all 等;
  - ▶ 规约 (reduction): reduce, all reduce, reduce scatter 等。
- MPI 集合通信的一些特点:
  - ▶ 通信器中所有进程必须同时调用该操作;
  - ▶ 不需要指定 tag;
  - ▶ 所有的集合通信都是某种意义的同步操作。

### MPI 栅栏同步

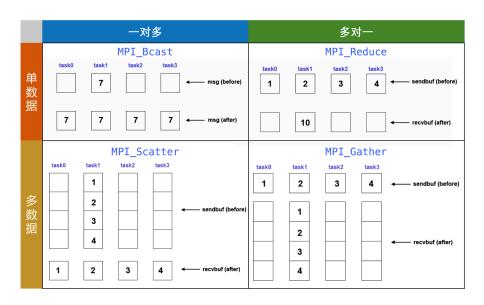
• 通信器中所有进程相互等待至某个同步点:

int MPI\_Barrier(MPI\_Comm comm)



• 思考: 这种栅栏同步底层是怎么实现的呢?

## MPI "一对多"与"多对一"通信概览



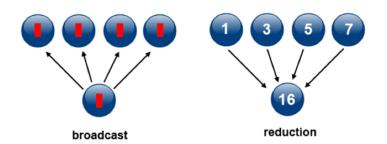
### MPI 广播与规约

● 广播 (broadcast):

```
int MPI_Bcast(void *buf, int count, MPI_Datatype datatype, int
    source, MPI_Comm comm)
```

• 规约 (reduce):

```
int MPI_Reduce(void *sendbuf, void *recvbuf, int count,
    MPI_Datatype datatype, MPI_Op op, int target, MPI_Comm comm)
```



## 规约操作的类型

• MPI\_Op 是 MPI 自定义操作,主要有:

Operation Meaning		Datatypes			
MPI_MAX	Maximum	C integers and floating points			
MPI_MIN	Minimum	C integers and floating points			
MPI_SUM	Sums the elements	C integers and floating points			
MPI_PROD	Multiplies the elements	C integers and floating points			
MPI_LAND	Logical AND	C integers			
MPI_BAND	Bit-wise AND	C integers and bytes			
MPI_LOR	Logical OR	C integers			
MPI_BOR	Bit-wise OR	C integers and bytes			
MPI_LXOR	Logical XOR	C integers			
MPI_BXOR	Bit-wise XOR	C integers and bytes			
MPI_MAXLOC	Max value and the rank	Data-pairs			
MPI_MINLOC	Min value and the rank	Data-pairs			

# 示例程序:广播与规约(1)

#### mpi\_bcast\_reduce.c

```
#define ROOT 0 // Rank of the root process
3
4
    int main(int argc, char **argv){
5
      . . .
6
      /* Set the data on root process */
      if (rank == ROOT) {
8
        data = 100;
        printf("On root proc %d, data to be broadcast: %d\n", rank,
         data):
10
      }
11
12
      /* Broadcast the data to everybody */
13
      MPI_Bcast(&data, 1, MPI_INT, ROOT, MPI_COMM_WORLD);
14
15
      /* Everybody shows the broadcast data */
16
      printf("On proc %d, data after broadcasting = %d\n", rank,
        data):
```

# 示例程序:广播与规约(2)

```
17
      MPI Barrier(MPI COMM WORLD);
18
19
      /* Modify the data to reduce */
20
      data = data + rank;
21
      printf("On proc %d, data to be reduced = %d\n", rank, data);
22
23
      /* Reduce everybody's data to root */
24
      MPI_Reduce(&data, &data_reduce, 1, MPI_INT, MPI_SUM, ROOT,
        MPI COMM WORLD);
25
26
      /* On root, show the reduced data */
27
      if (rank == ROOT) {
28
        printf("On root proc %d, data reduced: %d\n", rank,
        data_reduce);
29
30
```

# 示例程序:广播与规约(3)

运行 (请正确使用 sbatch 或者 salloc):

```
$ mpiexec -n 4 ./bcast_reduce
On root proc 0, data to be broadcast: 100
On proc 0, data after broadcasting = 100
On proc 2, data after broadcasting = 100
On proc 3, data after broadcasting = 100
On proc 1, data after broadcasting = 100
On proc 0, data to be reduced = 100
On proc 2, data to be reduced = 102
On proc 1, data to be reduced = 101
On proc 3, data to be reduced = 103
On root proc 0, data reduced: 406
```

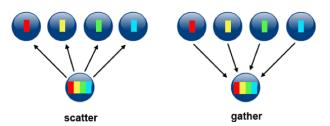
### MPI 分发与集中

• 分发 (scatter):

```
int MPI_Scatter(void *sendbuf, int sendcount, MPI_Datatype
  senddatatype, void *recvbuf, int recvcount, MPI_Datatype
  recvdatatype, int source, MPI_Comm comm)
```

• 集中 (gather):

```
int MPI_Gather(void *sendbuf, int sendcount, MPI_Datatype
  senddatatype, void *recvbuf, int recvcount, MPI_Datatype
  recvdatatype, int target, MPI_Comm comm)
```



## 示例程序:分发与集中(1)

#### mpi\_scatter\_gather.c

```
#define N 2 // Number of data per process
    #define ROOT 0 // Rank of the root process
4
5
    int main(int argc, char **argv){
6
      /* Set the data on root process */
      if (rank == ROOT) {
        printf("On root proc %d, data to be scattered:\n", rank);
10
        for ( j=0; j<size; j++) {</pre>
11
          for ( i=0; i<N; i++ ) {</pre>
12
            data_root[j][i] = j+i;
13
            printf("(%d, %d) = %d ", j, i, data_root[j][i]);
14
15
          printf("\n");
16
17
18
```

# 示例程序:分发与集中(2)

```
19
      /* Scatter the data to everybody */
20
      MPI_Scatter(&data_root[0][0], N, MPI_INT, &data[0], N,
        MPI_INT, ROOT, MPI_COMM_WORLD);
21
22
      /* Everybody shows the scatterd data */
23
      for (i=0; i<N; i++) {</pre>
24
        printf("On proc %d, scattered data[%d] = %d\n", rank, i,
        data[i]):
25
26
      MPI Barrier(MPI COMM WORLD);
27
28
      /* Gather everybody's data to root */
29
      MPI_Gather(&data[0], N, MPI_INT, &data_root[0][0], N, MPI_INT
        , ROOT, MPI COMM WORLD);
30
31
      /* On root, show the gathered data */
32
      if (rank == ROOT) {
33
        printf("On root proc %d, data gathered:\n", rank);
34
        for ( j=0; j<size; j++) {</pre>
```

# 示例程序: 分发与集中 (3)

• 运行 (请正确使用 sbatch 或者 salloc):

```
$ mpiexec -n 4 ./scatter_gather

Data to be scattered on root proc 0:
(0, 0) = 0 (0, 1) = 1
(1, 0) = 1 (1, 1) = 2
(2, 0) = 2 (2, 1) = 3
(3, 0) = 3 (3, 1) = 4
On proc 0, scattered data[0] = 0
On proc 0, scattered data[1] = 1
```

## 示例程序:分发与集中(4)

```
On proc 2, scattered data[0] = 2
On proc 2, scattered data[1] = 3
On proc 1, scattered data[0] = 1
On proc 3, scattered data[0] = 3
On proc 3, scattered data[1] = 4
On proc 1, scattered data[1] = 2
Data gathered on root proc 0:
(0, 0) = 0 (0, 1) = 1
(1, 0) = 1 (1, 1) = 2
(2, 0) = 2 (2, 1) = 3
(3, 0) = 3 (3, 1) = 4
```

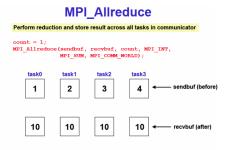
### MPI 集合通信-2

- 1 MPI 基础知识回顾
- 2 MPI 集合通信-1
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- 4 辅助函数

## MPI "多对多"通信 (1)

• 全规约 (allreduce):

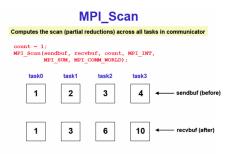
```
int MPI_Allreduce(void *sendbuf, void *recvbuf, int count,
    MPI_Datatype datatype, MPI_Op op, MPI_Comm comm)
```



## MPI "多对多"通信 (2)

• 前缀和 (scan, prefix-sum):

```
int MPI_Scan(void *sendbuf, void *recvbuf, int count, MPI_Datatype
   datatype, MPI_Op op, MPI_Comm comm)
```

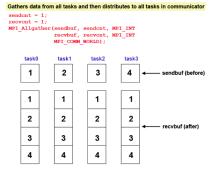


# MPI "多对多"通信 (3)

#### • 全集中 (allgather):

```
int MPI_Allgather(void *sendbuf, int sendcount, MPI_Datatype
  senddatatype, void *recvbuf, int recvcount, MPI_Datatype
  recvdatatype, MPI_Comm comm)
```

#### MPI\_Allgather

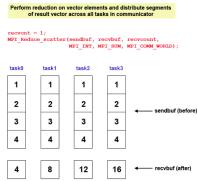


## MPI "多对多"通信 (4)

• 规约分发 (reduce\_scatter):

int MPI\_Reduce\_scatter(void \*sendbuf, void \*recvbuf, const int
 recvcount[], MPI\_Datatype datatype, MPI\_Op op, MPI\_Comm comm)

#### MPI\_Reduce\_scatter



# MPI "多对多"通信 (5)

#### • 全交换 (alltoall):

```
int MPI_Alltoall(void *sendbuf, int sendcount, MPI_Datatype
  senddatatype, void *recvbuf, int recvcount, MPI_Datatype
  recvdatatype, MPI_Comm comm)
```

#### MPI\_Alltoall

## Scatter data from all tasks to all tasks in communicator sendent = 1;

recvent = 1;
MPI\_Alltoall(sendbuf, sendent, MPI\_INT recvbuf, recvent, MPI\_INT MPI\_COMM\_WORLD);

task0	task1	task2	task3						
1	5	9	13	← sendbuf (before)	1	2	3	4	
2	6	10	14		5	6	7 8	← recvbuf (after)	
3	7	11	14		9	10	11	12	Teconii (arca)
4	8	12	16		13	14	15	16	

## 辅助函数

- ① MPI 基础知识回顾
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### 一些重要的辅助函数

• 判断 MPI 是否已经初始化:

```
int MPI_Initialized(int *flag)
```

• 中止 MPI 环境:

```
int MPI_Abort(MPI_Comm comm, int errorcode)
```

• 获取 MPI 版本号:

```
int MPI_Get_version(int *version, int *subversion)
```

• 获取处理器名:

```
int MPI_Get_processor_name(char *name, int *resultlen);
```

## 示例程序: hello world 2! (1)

#### mpi\_hello2.c

```
1
      MPI_Init(&argc, &argv); // initialize MPI
3
      MPI_Comm_size(MPI_COMM_WORLD, &size); // get num of procs
4
      MPI_Comm_rank(MPI_COMM_WORLD, &rank); // get my rank
5
      MPI_Get_processor_name(name, &len); // get node name
6
      MPI_Get_version(&ver, &sver); // get mpi version
8
      if (size > 16) {
9
        printf("Number of processes %d is too large. Abort MPI!\n",
         size);
10
        MPI Abort (MPI COMM WORLD, 911); // abort mpi for large size
11
12
13
      t0 = MPI_Wtime(); // tick
14
      printf("On %s, from process %d of %d: Hello World!\n", name,
        rank, size);
15
      fflush(stdout); // flush standard output
```

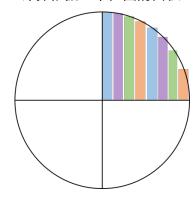
# 示例程序: hello world 2! (2)

#### • 运行结果:

```
On cu01, from process 2 of 4: Hello World!
On cu01, from process 0 of 4: Hello World!
On cu01, from process 3 of 4: Hello World!
On cu01, from process 1 of 4: Hello World!
MPI version is 3.1. Time elapsed is 0.000086.
That's all, folks!
```

## 示例程序: 计算 $\pi$ (1)

• 计算依据: 单位圆的面积。



• 并行策略: round-robin。

$$\pi = 4 \int_0^1 \sqrt{1 - x^2} dx$$
$$\approx 4h \sum_{i=0}^{N-1} \sqrt{1 - x_i^2},$$

where

$$x_i = (i + \frac{1}{2})h, \quad h = \frac{1}{N}.$$

## 示例程序: 计算 $\pi$ (2)

#### mpi\_cpi.c

```
1
      if (rank == 0) n = 10000000;
3
      MPI_Bcast(&n, 1, MPI_INT, 0, MPI_COMM_WORLD);
4
5
      t0 = MPI_Wtime();
6
      for (k = 0; k < REPEAT; k++) {
        h = 1.0 / (double) n;
8
        sum = 0.0:
9
        for (i = rank + 1; i <= n; i += size) {
10
          x = h * ((double)i - 0.5);
11
          sum += 4.0 * sqrt(1.-x*x);
12
13
        mypi = h * sum;
14
        MPI_Allreduce(&mypi, &pi, 1, MPI_DOUBLE, MPI_SUM,
        MPI_COMM_WORLD);
15
16
      t1 = MPI_Wtime();
```

# 示例程序: 计算 $\pi$ (3)

```
if (rank == 0) {
   printf("Number of processes = %d\n", size);
   printf(" pi is approximately %.16f\n", pi);
   printf(" Error is %.16f\n", fabs(pi-PI25DT));
   printf(" Wall clock time = %f\n", (t1-t0)/REPEAT);
}
...
```

#### ● 运行 (请正确使用 sbatch 或者 salloc):

```
$ mpiexec -n 1 ./cpi
$ mpiexec -n 2 ./cpi
$ mpiexec -n 4 ./cpi
$ mpiexec -n 8 ./cpi

Number of processes = 1
pi is approximately 3.1415926536003460
Error is 0.0000000000105529
```

## 示例程序: 计算 $\pi$ (4)

```
Wall clock time = 0.104462
Number of processes = 2
pi is approximately 3.1415926536009313
Error is 0.000000000111382
Wall clock time = 0.061566
Number of processes = 4
pi is approximately 3.1415926536006418
Error is 0.000000000108487
Wall clock time = 0.039160
Number of processes = 8
pi is approximately 3.1415926536006591
Error is 0.000000000108660
 Wall clock time = 0.026021
```

- 思考 1: 为什么加速比不是线性的?
- 思考 2: 为什么误差不同?