

1453 9.22 FURTHER DISCUSSION ON 1454 THE SPINOR 1455 REPRESENTATION

1456 This discussion unifies the proper orthochronous Lorentz group $SO^+(1, 3)$,
1457 its Lie algebra $\mathfrak{so}(1, 3)$, its universal cover $SL(2, \mathbb{C})$, and the classification of
1458 its fundamental representations.

1459 THE PHYSICAL ALGEBRA $\mathfrak{so}(1, 3)$

1460 The proper orthochronous Lorentz group, $SO^+(1, 3)$, is the group of 4x4
1461 real matrices Λ that preserve the Minkowski metric $g = \text{diag}(-1, +1, +1, +1)$
1462 and satisfy $\det(\Lambda) = 1$ and $\Lambda_0^0 \geq 1$.

Its Lie algebra, $\mathfrak{so}(1, 3)$, is a 6-dimensional real algebra spanned by the
generators of rotations, $\mathbf{J} = (J_1, J_2, J_3)$, and boosts, $\mathbf{K} = (K_1, K_2, K_3)$. These
obey the commutation relations:

$$[J_i, J_j] = i\epsilon_{ijk}J_k$$

$$[J_i, K_j] = i\epsilon_{ijk}K_k$$

$$[K_i, K_j] = -i\epsilon_{ijk}J_k$$

1463 The minus sign in the $[K_i, K_j]$ commutator is the defining feature of this
1464 Minkowskian algebra. It is the mathematical expression of the fact that
1465 two successive boosts do not equal a single boost, but also involve a
1466 rotation (Thomas precession). Crucially, because $[J_i, K_j] \neq 0$, the algebra is
1467 not a direct sum (product) and does not trivially decompose. Boost
1468 generators K_i are anti-Hermitian (for finite dimensional representation of
1469 this non-compact group).

1470 THE NON-RELATIVISTIC ANALOGY: $SU(2)$ AND $SO(3)$

1471 Before solving the full algebra, we examine its rotation subgroup. The
1472 generators \mathbf{J} form a closed subalgebra, $\mathfrak{su}(2) \cong \mathfrak{so}(3)$.

- 1473 • The group of 3D rotations is $SO(3)$, which acts on 3-component
1474 vectors.
- 1475 • The group $SU(2)$ is the group of 2x2 complex unitary matrices with
1476 determinant 1, which acts on 2-component spinors.

1477 $SU(2)$ is the **universal double-cover** of $SO(3)$. This means there is a 2-to-1
1478 homomorphism from $SU(2)$ to $SO(3)$. For any rotation $R \in SO(3)$, there are
1479 two matrices, U and $-U$, in $SU(2)$ that map to it.

This is evident in the transformation of a vector \mathbf{x} mapped to a matrix $X = \mathbf{x} \cdot \boldsymbol{\sigma}$ (where $\boldsymbol{\sigma}$ are the Pauli matrices):

$$X \rightarrow X' = UXU^\dagger$$

Replacing U with $-U$ yields the same X' :

$$X' = (-U)X(-U)^\dagger = (-1)(-1)UXU^\dagger = UXU^\dagger$$

1480 Physically, a 2π rotation returns a (3-)vector to its original state, but a
 1481 spinor by an additional phase of -1 . A 4π rotation is required to return a
 1482 spinor to its original state. This $SU(2) \rightarrow SO(3)$ relationship is the template
 1483 for the full Lorentz group.

1484 THE UNIVERSAL COVER $SL(2, \mathbb{C})$

1485 The group $SL(2, \mathbb{C})$ is the group of 2×2 complex matrices M with $\det(M) = 1$.
 1486 This group is the **universal double-cover** of the Lorentz group, $SO^+(1, 3)$.
 1487 This is the direct relativistic analogue of $SU(2)$ covering $SO(3)$. For every
 1488 Lorentz transformation $\Lambda \in SO^+(1, 3)$, there are two matrices, M and $-M$,
 1489 in $SL(2, \mathbb{C})$ that map to it. The fundamental representations of $SL(2, \mathbb{C})$ are
 1490 the 2-component Weyl spinors.

1491 COMPLEXIFICATION AND THE N, N^\dagger ALGEBRAS

To simplify the $\mathfrak{so}(1, 3)$ algebra, we move to its complexification, $\mathfrak{so}(1, 3)_\mathbb{C}$, by allowing complex coefficients. We define two new sets of generators. Following the textbook notation, we call them N and N^\dagger ³:

$$N_i = \frac{1}{2}(J_i + iK_i)$$

$$B_i \equiv (N_i^\dagger)_{\text{symbolic}} = \frac{1}{2}(J_i - iK_i)$$

By computing the commutators, we find the algebra completely decouples into two independent $SU(2)$ -like algebras:

$$[N_i, N_j] = i\epsilon_{ijk}N_k$$

$$[B_i, B_j] = i\epsilon_{ijk}B_k \quad (\text{or } [N_i^\dagger, N_j^\dagger] = i\epsilon_{ijk}N_k^\dagger)$$

$$[N_i, B_j] = 0 \quad (\text{or } [N_i, N_j^\dagger] = 0)$$

The complexified Lorentz algebra is therefore isomorphic to two copies of $\mathfrak{sl}(2, \mathbb{C})$, which is the complexification of $\mathfrak{su}(2)$.

$$\mathfrak{so}(1, 3)_\mathbb{C} \cong \mathfrak{sl}(2, \mathbb{C}) \cong \mathfrak{su}(2)_\mathbb{C} \times \mathfrak{su}(2)_\mathbb{C}$$

³Note that N^\dagger here is merely symbolic. A critical point of confusion is the N_i^\dagger notation for the B_i generators. This \dagger is **symbolic** and does *not* represent Hermitian conjugation. The N_i^\dagger notation is a mnemonic used to recall the relationship between the *finite group elements* for the left- and right-handed representations (L and R), which are related by $R = (L^\dagger)^{-1}$.

CLASSIFYING THE REPRESENTATIONS

We can now classify all irreducible representations by a pair of labels $(2n + 1, 2n' + 1)$, where $2n + 1$ is the dimension of the representation under the corresponding algebra (N or $B \equiv N_{\text{symbolic}}^\dagger$).

(2, 1) REPRESENTATION: THE LEFT-HANDED SPINOR

- **Generators:** This representation is built from $J_i = \frac{\sigma_i}{2}$ and $K_i = -\frac{i\sigma_i}{2}$.
- **Check:** $N_i = \frac{1}{2}(J_i + iK_i) = \frac{\sigma_i}{2}$ (non-trivial, dim 2) and $B_i = \frac{1}{2}(J_i - iK_i) = 0$ (trivial, dim 1).
- **Transformation:** A left-handed spinor ψ_L transforms as: $\psi_L \rightarrow L\psi_L$.

(1, 2) REPRESENTATION: THE RIGHT-HANDED SPINOR

- **Generators:** This representation is built from $J_i = \frac{\sigma_i}{2}$ and $K_i = +\frac{i\sigma_i}{2}$.
- **Check:** $N_i = \frac{1}{2}(J_i + iK_i) = 0$ (trivial, dim 1) and $B_i = \frac{1}{2}(J_i - iK_i) = \frac{\sigma_i}{2}$ (non-trivial, dim 2).
- **Transformation:** A right-handed spinor ψ_R transforms as: $\psi_R \rightarrow R\psi_R = (L^\dagger)^{-1}\psi_R$.

(2, 2) REPRESENTATION: THE 4-VECTOR

- **Interpretation:** A 4-vector x^μ is an object that transforms non-trivially under both algebras.
- **The Map:** We map x^μ to a 2x2 Hermitian matrix X using $\sigma_\mu = (\mathbb{I}, \boldsymbol{\sigma})$:

$$X = x^\mu \sigma_\mu = \begin{pmatrix} x^0 + x^3 & x^1 - ix^2 \\ x^1 + ix^2 & x^0 - x^3 \end{pmatrix}$$

- **The Invariant:** The Lorentz interval is the determinant: $\det(X) = (x^0)^2 - |\mathbf{x}|^2 = x_\mu x^\mu$.
- **Transformation:** The transformation $X \rightarrow X' = LXR$ applies the (2,1) rule from the left and the (1,2) rule from the right. This transformation preserves the determinant. This proves that $X \rightarrow LXR^\dagger$ is a Lorentz transformation $\Lambda(M)$ on the components x^μ .