

## 9.23 A CLOSER LOOK AT THE SPINOR REPRESENTATION

This discussion builds the structure of the Lorentz group and its representations by following a common train of thought, correcting key misconceptions along the way.

### THE FOUNDATION: ROTATIONS, $SO(3)$ , AND $SU(2)$

We begin with the non-relativistic case of 3D rotations.

- At the **group level**, we have  $SO(3)$ , the group of 3x3 real orthogonal matrices that act on vectors. We also have  $SU(2)$ , the group of 2x2 complex unitary matrices that act on spinors.  $SU(2)$  is the **universal double-cover** of  $SO(3)$ .
- Both groups are 3-parameter groups, generated by 3 generators.
- At the **algebra level**, their Lie algebras are **isomorphic**:  $\mathfrak{su}(2) \cong \mathfrak{so}(3)$ . They share the same commutation relations  $[J_i, J_j] = i\epsilon_{ijk}J_k$ .

This 2-to-1 group covering, backed by an algebraic isomorphism, is the template for the relativistic case.

### THE LORENTZ CASE: $SO(1, 3)$ AND $SL(2, \mathbb{C})$

We now extend this analogy to spacetime, which includes boosts.

- At the **group level**, we have  $SO^+(1, 3)$ , the proper orthochronous Lorentz group, which acts on 4-vectors ( $x^\mu$ ). We also have  $SL(2, \mathbb{C})$ , the group of 2x2 complex matrices with determinant 1, which acts on 2-component Weyl spinors.
- $SL(2, \mathbb{C})$  is the **universal double-cover** of  $SO^+(1, 3)$ .
- Both are 6-parameter groups, generated by 6 generators (3 rotations  $J_i$ , 3 boosts  $K_i$ ).
- At the **algebra level**, their 6-dimensional *real* Lie algebras are **isomorphic**:  $\mathfrak{so}(1, 3) \cong \mathfrak{sl}(2, \mathbb{C})$ .

### A CRITICAL DISTINCTION: $\mathfrak{so}(1, 3)$ VS. $\mathfrak{so}(4)$

A very common point of confusion is to assume  $\mathfrak{so}(1, 3) \cong \mathfrak{su}(2) \times \mathfrak{su}(2)$ . This is incorrect. The algebra  $\mathfrak{su}(2) \times \mathfrak{su}(2)$  is isomorphic to the 4D *Euclidean* rotation algebra,  $\mathfrak{so}(4)$ , not the Lorentz algebra.

The difference lies in a single, crucial minus sign.

- **The  $\mathfrak{so}(4) \cong \mathfrak{su}(2) \times \mathfrak{su}(2)$  Algebra:** Let the generators be  $J_i = A_i + B_i$  and  $K_i = A_i - B_i$ , where  $[A_i, B_j] = 0$ . The boost-like commutator is:

$$[K_i, K_j] = [A_i - B_i, A_j - B_j] = [A_i, A_j] + [B_i, B_j] = i\epsilon_{ijk}A_k + i\epsilon_{ijk}B_k = +i\epsilon_{ijk}J_k$$

- **The  $\mathfrak{so}(1, 3) \cong \mathfrak{sl}(2, \mathbb{C})$  Algebra:** The physical Lorentz algebra has the defining relation:

$$[K_i, K_j] = -i\epsilon_{ijk}J_k$$

Because their algebraic structure is fundamentally different,  $\mathfrak{so}(1, 3) \not\cong \mathfrak{so}(4)$  and  $\mathfrak{so}(1, 3) \not\cong \mathfrak{su}(2) \times \mathfrak{su}(2)$  as real algebras.

## THE IMPOSSIBILITY OF DECOMPOSING THE REAL ALGEBRA

---

The fact that  $\mathfrak{so}(1, 3) \not\cong \mathfrak{su}(2) \times \mathfrak{su}(2)$  is the entire problem. It means that the physical Lorentz algebra, as a *real* algebra, does not decompose into a direct product. The rotations ( $J_i$ ) and boosts ( $K_i$ ) are inextricably linked by  $[J_i, K_j] = i\epsilon_{ijk}K_k$ . We cannot find a simple set of commuting generators using only real numbers.

## THE COMPLEXIFICATION TRICK

---

Since we cannot decompose the *real* algebra, we employ a mathematical trick: we complexify it. We move from  $\mathfrak{so}(1, 3)$  to  $\mathfrak{so}(1, 3)_{\mathbb{C}}$  by allowing complex linear combinations of the generators.

This is done *purely* to find a basis where the algebra decouples. We define the complex generators:

$$N_i = \frac{1}{2}(J_i + iK_i) \quad \text{and} \quad \tilde{N}_i = \frac{1}{2}(J_i - iK_i)$$

The crucial minus sign in  $[K_i, K_j] = -i\epsilon_{ijk}J_k$  is precisely what's needed to make these two new algebras commute:

$$[N_i, B_j] = 0$$

Thus, the *complexified* algebra **does** decompose:

$$\mathfrak{so}(1, 3)_{\mathbb{C}} \cong \mathfrak{sl}(2, \mathbb{C}) \times \mathfrak{sl}(2, \mathbb{C}) \cong \mathfrak{su}(2)_{\mathbb{C}} \times \mathfrak{su}(2)_{\mathbb{C}}$$

This allows us to classify all representations by two labels, one for each  $\mathfrak{su}(2)_{\mathbb{C}}$  factor.

## GENERATOR COUNTING: THE 12-DIMENSIONAL REAL SPACE

---

Let's be precise about dimensions.

- $\mathfrak{su}(2)$  is a 3-dimensional *real* algebra (basis, e.g.,  $\{\sigma_1, \sigma_2, \sigma_3\}$ ).
- $\mathfrak{su}(2)_{\mathbb{C}}$  is its complexification. As a *complex* algebra, it is 3-dimensional (basis, e.g.,  $\{\sigma_1, \sigma_2, \sigma_3\}$  with complex coefficients in the “rotation angles”). As a *real* algebra, it is 6-dimensional (basis, e.g.,  $\{\sigma_i, i\sigma_i\}$ ).

- 1575 • Therefore, the full decoupled space  $\mathfrak{so}(1, 3)_{\mathbb{C}} \cong \mathfrak{su}(2)_{\mathbb{C}} \times \mathfrak{su}(2)_{\mathbb{C}}$  is a  
 1576 12-dimensional *real* vector space. These are  $\{\sigma_i, i\sigma_i\}$  for  $\mathfrak{su}(2)_{\mathbb{C}}^L$  and  
 1577  $\{\sigma_i, i\sigma_i\}$  for  $\mathfrak{su}(2)_{\mathbb{C}}^R$ .

1578 **THE PHYSICAL SUBALGEBRA: PROJECTING BACK TO**  
 1579  **$\mathfrak{so}(1, 3)$**

---

1580 We are only interested in the physical world, which is described by the  
 1581 6-dimensional *real* algebra  $\mathfrak{so}(1, 3)$ , not the 12D complex space. Our  
 1582 physical algebra  $\mathfrak{so}(1, 3)$  must be a 6-dimensional “real slice” embedded  
 1583 within this 12D space.

We find this “slice” by inverting the definitions for  $N_i$  and  $B_i$ :

$$J_i = N_i + \tilde{N}_i$$

$$K_i = -i(N_i - \tilde{N}_i)$$

1584 These are our 6 physical generators, built from the 12 generators of the  
 1585 complex space. Which 6? 3 out of the 6 hermitian ones  $\sigma_i^L + \sigma_i^R$  and 3 out  
 1586 of the 6 anti-hermitian ones  $-i\sigma_i^L + i\sigma_i^R$  while maintaining the  
 1587 “rotation/boost coefficients” being real.

1588 The 6 physical generators are *not* just “two sets of Pauli matrices” (e.g.,  $N_i$   
 1589 and  $\tilde{N}_i$ ). They are this specific combination:

- **Rotations**  $J_i = N_i + \tilde{N}_i$ : In a representation where  $N_i$  and  $B_i$  are Hermitian, the  $J_i$  are also **Hermitian**. This is required so that rotations  $U_R = \exp(-i\theta_j J_j)$  are unitary.
- **Boosts**  $K_i = -i(N_i - \tilde{N}_i)$ : With  $N_i, \tilde{N}_i$  Hermitian, the  $K_i$  are **anti-Hermitian** (because of the  $i$ ). This is also required, so that boosts  $U_{\text{boost}} = \exp(-i\beta_j K_j) = \exp(-\beta_j(N_j - \tilde{N}_j))$  are non-unitary.

1590 Our 6D physical world  $\mathfrak{so}(1, 3)$  is this specific “slice” of the 12D  
 1591 complexified space that is spanned by 3 Hermitian generators (rotations)  
 1592 and 3 anti-Hermitian generators (boosts).