

1-(a). $\xrightarrow{x} \begin{array}{ccccccc} * & * & \circ & * & * & \circ & \rightarrow \end{array} \begin{array}{l} x_{S_1} \\ 0 \quad x_{S_2} \end{array}$

when $x \leq -1.5$,

$$\hat{P}_0(x|S_1) = \frac{kx/3}{\sqrt{3}} = \frac{3/3}{2(x-0)} = -\frac{1}{2x}$$

when $x \geq -1.5$.

$$\hat{P}_0(x|S_1) = \frac{kx/3}{\sqrt{3}} = \frac{3/3}{2(x+3)} = \frac{1}{2(x+3)}$$

(b) $\hat{P}(x|S_2) = \frac{1}{2} [\Delta(x+1) + \Delta(x-2)]$

$$= \begin{cases} \frac{1}{8} & -3 \leq x < 0 \cup 1 \leq x < 4 \\ \frac{1}{4} & 0 \leq x < 1 \\ 0 & \text{otherwise} \end{cases}$$

(c) $\hat{P}(S_1) = \frac{3}{5}$

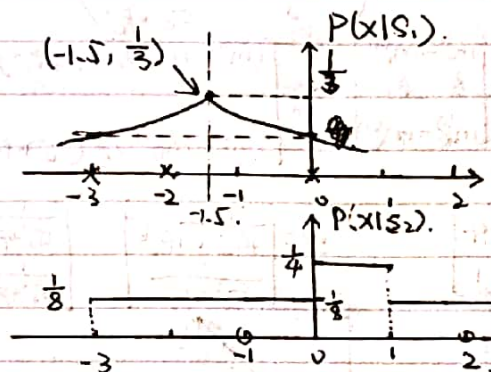
$\hat{P}(S_2) = \frac{2}{5}$

(d) $\hat{P}(x|S_1) \hat{P}(S_1) > \hat{P}(x|S_2) \hat{P}(S_2), \quad x \in S_1$

$\hat{P}(x|S_1) \hat{P}(S_1) < \hat{P}(x|S_2) \hat{P}(S_2), \quad x \in S_2$

~~when $x \in (-\infty, -1.5)$, $\frac{1}{2x} > \frac{1}{8}$, $x < -4$~~

~~when $x \in (-1.5, 0)$, $\frac{1}{2(x+3)} > \frac{1}{8}$, $x < 3$~~



(e) when $x \in (-\infty, -1.5)$, $P(x|S_1)P(S_1) = -\frac{3}{10x}$, solve for $-\frac{3}{10x} > \frac{2}{5} \cdot \frac{1}{8}, x > -6$

So, when $x \in (-6, -1.5)$, $x \in S_1$

when $x \in [-1.5, 0)$, $P(x|S_1)P(S_1) = \frac{3}{10(x+3)}$, solve for $\frac{3}{10(x+3)} > \frac{2}{5} \cdot \frac{1}{8}, x < 3$

So, when $x \in [-1.5, 0)$, $x \in S_1$

when $x \in [0, 1)$, $P(x|S_1)P(S_1) = \frac{3}{10(x+3)}$, solve $\frac{3}{10(x+3)} > \frac{2}{5} \cdot \frac{1}{4}, x < 0$

So, when $x \in [0, 1)$, $x \in S_2$

when $x \in (1, 3)$, $P(x|S_1)P(S_1) = \frac{3}{10(x+3)}$, solve $\frac{3}{10(x+3)} > \frac{2}{5} \cdot \frac{1}{8}, x < 3$

So, when $x \in (1, 3)$, $x \in S_1$, when $x \in (3, 4)$, $x \in S_2$, when $x \in (4, \infty)$, $x \in S_1$

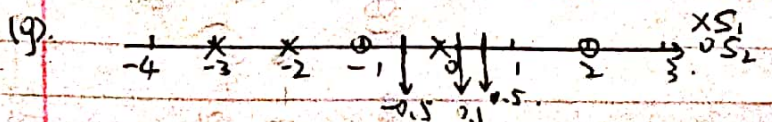
From all above, the decision ~~boundary~~ rule is:

if $x \in (-\infty, 0) \cup (1, 3) \cup (4, \infty)$, $x \in S_1$

if $x \in [0, 1) \cup (3, 4)$, $x \in S_2$

(f) From the plot and decision rules above,

$x = -0.5 \in S_1$, ~~$x = 0.1 \in S_1$~~ , $x = 0.5 \in S_2$



$x = -0.5$, the nearest 3 points, 2 belongs to S_1 , 1 belongs to S_2 .

So $x = -0.5 \in S_1$,

$x = 0.1$, $2 \in S_2$, $1 \in S_1$, so $x = 0.1 \in S_2$

$x = 0.5$, $2 \in S_2$, $1 \in S_1$, so $x = 0.5 \in S_2$

2. (a). $P(z|\theta) = P(x_1, x_2, \dots, x_N|\theta) \stackrel{iid}{=} \prod_{i=1}^N P(x_i|\theta) = \theta^N e^{-\theta \sum_{i=1}^N x_i}$. (for x_i drawn from θ , they all > 0 , so $p(x_i|\theta) = \theta e^{-\theta x_i}$.)

$\frac{d}{d\theta} \ln P(z|\theta) = \arg \max_{\theta} (\ln P(z|\theta)) = \arg \max_{\theta} (N \ln \theta - \theta \sum_{i=1}^N x_i) = \arg \max_{\theta} (N \ln \theta - \theta Nm)$

$\frac{d}{d\theta} \ln P(z|\theta) = \frac{N}{\theta} - Nm$, solve $\frac{N}{\hat{\theta}_{ML}} - Nm = 0$, $\hat{\theta}_{ML} = \frac{1}{m}$

~~(b)~~

(b). $\hat{\theta}_{MAP} = \arg \max_{\theta} \{ \ln P(z|\theta) + \ln P(\theta) \}$.

~~but~~ $\ln P(z|\theta) + \ln P(\theta) = N \ln \theta - Nm\theta + \ln a - a\theta$

$\frac{d}{d\theta} (\ln P(z|\theta) + \ln P(\theta)) = \frac{N}{\theta} - Nm - a$, $\hat{\theta}_{MAP} = \frac{N}{Nm+a}$

(c) $\hat{\theta}_{MAP} = \frac{N}{N/\hat{\theta}_{ML} + a}$

$\lim_{\theta_0 \rightarrow \infty} \hat{\theta}_{MAP} = \lim_{\theta_0 \rightarrow \infty} \frac{N}{N/\hat{\theta}_{ML} + \frac{1}{\theta_0}} = \frac{N}{N/\hat{\theta}_{ML}} = \hat{\theta}_{ML}$

~~By using $\frac{d}{d\theta} \ln P(\theta)$, if $\theta_0 \rightarrow \infty$, corresponding to $a \rightarrow 0$.~~

~~lim~~
~~a \rightarrow 0~~

~~Because when $\theta_0 \rightarrow \infty$, $\hat{\theta}_{MAP} \rightarrow \hat{\theta}_{ML}$, so this map correspond to~~

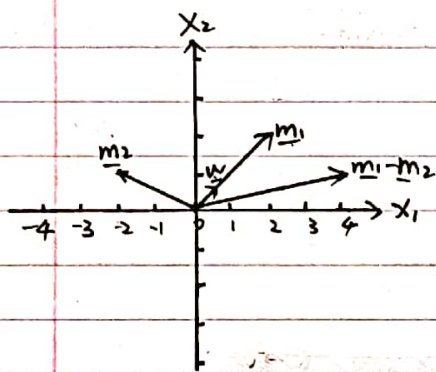
~~θ is also deterministic.~~

When $\theta_0 \rightarrow \infty$, $a \rightarrow 0$, which means for $\forall \theta > 0$, $p(\theta) \rightarrow 0$, so the prior distribution of θ is unknown to us.

$$3(a). \underline{S}_w = \underline{S}_1 + \underline{S}_2 = \begin{pmatrix} \sigma_1^2 + p_1^2 & 0 \\ 0 & \sigma_0^2 + p_0^2 \end{pmatrix} \quad \underline{S}_w^{-1} = \begin{pmatrix} \frac{1}{\sigma_1^2 + p_1^2} & 0 \\ 0 & \frac{1}{\sigma_0^2 + p_0^2} \end{pmatrix}$$

$$\underline{w} = \underline{S}_w^{-1} \begin{bmatrix} m_1^{(1)} - m_1^{(0)} \\ m_0^{(1)} - m_0^{(0)} \end{bmatrix} = \begin{bmatrix} (m_1^{(1)} - m_1^{(0)}) / (\sigma_1^2 + p_1^2) \\ (m_0^{(1)} - m_0^{(0)}) / (\sigma_0^2 + p_0^2) \end{bmatrix}$$

$$(b). \underline{m}_1 - \underline{m}_2 = \begin{bmatrix} 4 \\ 1 \end{bmatrix} \quad \underline{w} = \begin{bmatrix} \frac{4}{4\sigma_1^2 + 4p_1^2} \\ \frac{1}{\sigma_1^2 + p_1^2} \end{bmatrix} = \begin{bmatrix} \frac{1}{\sigma_1^2 + p_1^2} \\ \frac{1}{\sigma_1^2 + p_1^2} \end{bmatrix} \quad \text{normalize } \|\underline{w}\| \text{ to } 1, \underline{w}' = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$



(c). After projecting all data points on \underline{w} , the criterion function $J(\underline{w}) = \frac{|\tilde{m}_1 - \tilde{m}_2|^2}{\tilde{S}_1 + \tilde{S}_2}$ is maximized, where $\tilde{m}_i = \underline{w}^T \underline{m}_i$, $\tilde{S}_i = \underline{w}^T \underline{S}_i \underline{w}$, and the data points in the same class are projected closer, the data points in different classes are projected far away from each other. \underline{w} makes more sense because $\underline{m}_1 - \underline{m}_2$ is only a part of the criterion function, ~~they~~ it will be influenced by scatter matrices when computing the optimal projection. So \underline{w} ~~is a~~ makes more sense.