# Algorithms & Data Structures I CSC 225

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 Now let's take a look at the transitive closure and all-pairs shortest paths (APSP) problems.

• We will describe a dynamic programming approach that solve APSP in  $\Theta(n^3)$  time and works even on weighted graphs.

• So, it's efficiency is the best among the four approaches that we discussed.

• The algorithm is named Floyd-Warshall and was invented

in 1962:



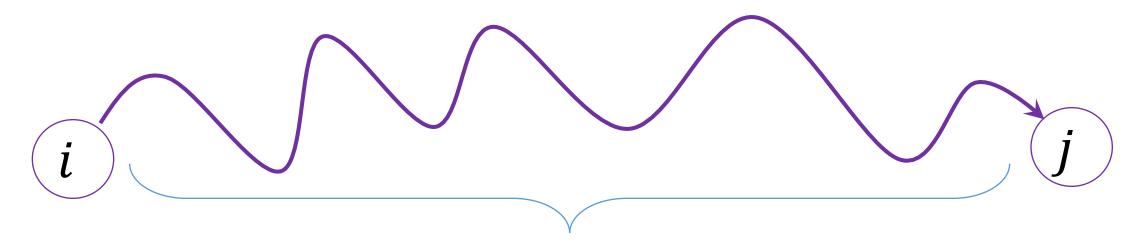
Robert Floyd



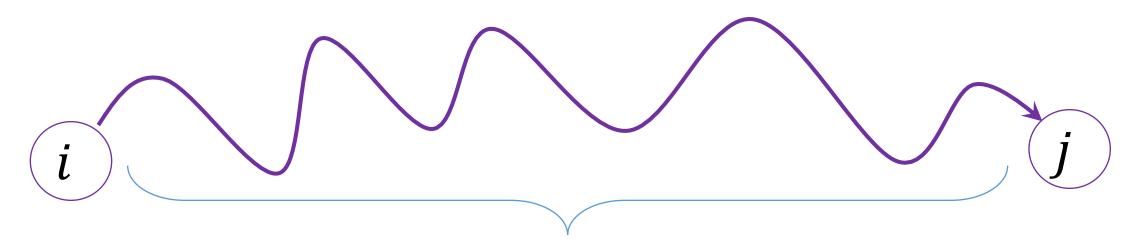
Stephen Warshall

• Let's assume that the nodes are numbered from 1 to n.

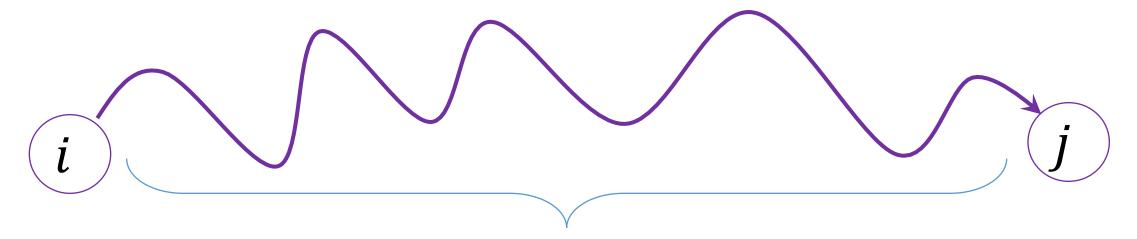
• Also, assume that p is a shortest path from i to j such that all intermediate vertices in p belong to the set  $\{1,2,\ldots,k\}$ 



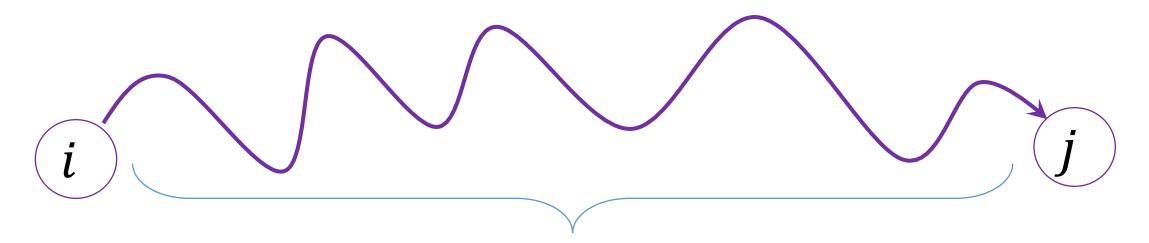
 Note 1: i and j are not considered intermediate vertices themselves



• Note 2: There might be no intermediate vertex on the shortest path at all. What we mean here is that if there is any, that vertex is in  $\{1, ..., k\}$ 



• Let's denote the length of such path with  $d_{ij}^{(k)}$  from now on.

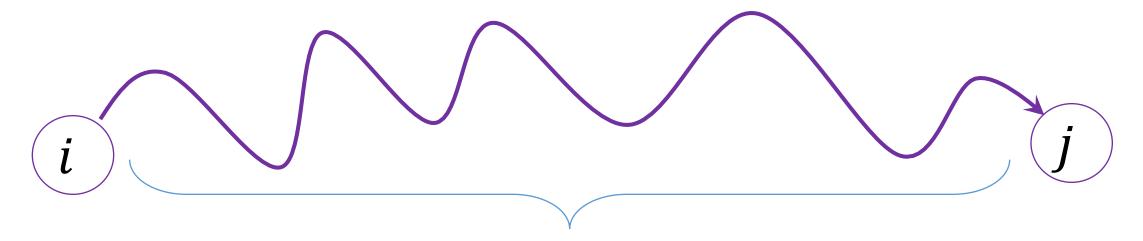


p: All intermediate vertices in  $\{1, ..., k\}$ 

• Observation:  $d_{ij}^{(n)}$  is the length of the actual shortest path from i to j, since we know that all intermediate vertices must be in the actual shortest path are in  $\{1, 2, ..., n\}$ 

• So, our goal is to compute  $d_{ij}^{(n)}$  for all pairs (i,j) of vertices!

• Question: How can we compute  $d_{ij}^{(k)}$  recursively? Or, how can we express  $d_{ij}^{(k)}$  in terms of smaller k's?



• Answer: There are two cases:

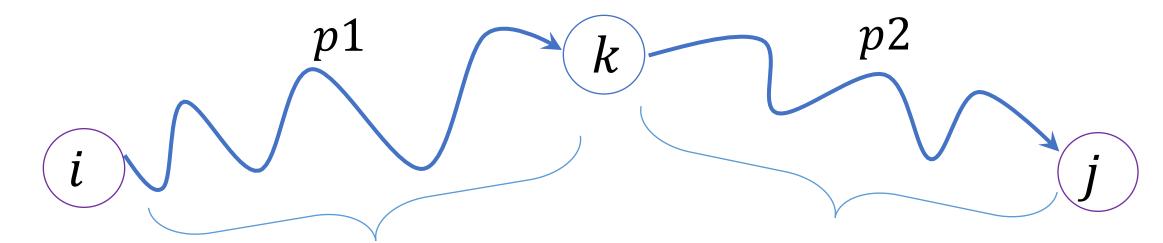
- Case 1: k is not an intermediate vertex.
- In this case  $d_{ij}^{(k)}=d_{ij}^{(k-1)}$  since we know that all intermediate vertices must be in  $\{1,2,\dots,k-1\}$

• Case 2: k is an intermediate vertex. In this case we can break the path i to j to two subpaths from i to k and from k to j.

• Since k is not a part of these subpaths, the intermediate vertices in both of these subpaths belong to  $\{1,2,\ldots,k-1\}$ .

• As a result,  $d_{ij}^{(k)} = d_{ik}^{(k-1)} + d_{kj}^{(k-1)}$ .

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all intermediate vertices are in  $\{1,2,...,k-1\}$ 

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ullet Now, we can describe  $d_{ij}^{(k)}$  recursively, as follows:

• Initially, when k=0 the shortest distance between i and j is the weight of the edge (i,j).

# FLOYD-WARSHALL(W) 1. D = W

- 2. **for** k = 1 **to** n
- 3. **for** i = 1 **to** n
- 4. **for** j = 1 **to** n
- 5.  $D[i][j] = \min(D[i][j], D[i][k] + D[k][j])$
- 6. return D

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The for loop for k has to be first, so when we want to update D[i][j] (i.e.  $d_{ij}^{(k)}$ ) all necessary entries are already computed.

• Before the loop for k we have finished the loop for k-1. So, the values we use on line 5, i.e.

$$D[i][j]$$
,  $D[i][k]$ , and  $D[k][j]$  correspond to  $d_{ij}^{(k-1)}$ ,  $d_{ik}^{(k-1)}$ ,  $d_{kj}^{(k-1)}$ , respectively.

• Even if these values are updated on the current for loop for k, we know that  $d_{ij}^{(k)} \leq d_{ij}^{(k-1)}$ ; so, it won't create a problem and the algorithm is still correct.

#### Printing the paths

#### FLOYD-WARSHALL(W)

- 1. D = W
- 2. P// path matrix initialized with NULL
- 3. **for** k = 1 **to** n
- 4. **for** i = 1 **to** n
- 5. **for** j = 1 **to** n
- 6. if D[i][j] > D[i][k] + D[k][j]
- 7. D[i][j] = D[i][k] + D[k][j]
- P[i][j] = k

9. return D

We keep the value of k that caused the update

#### Print-Path(i, j)

- 1. print i
- 2. Print-Intermediate-Vertices (i, j)
- 3. **print** *j*

#### Print-Intermediate-Vertices (i, j)

- 1. **if** P[i][j] == NULL
- 2. return
- 3. k = P[i][j]
- 4. Print-Intermediate-Vertices(i, k)
- 5. Print k
- 6. Print-Intermediate-Vertices(k, j)